

ERASMUS UNIVERSITEIT ROTTERDAM

ECONOMETRISCH INSTITUUT

Report 7411/M,0

THREE (COUNTER) EXAMPLES CONCERNING (LINEAR) CONTINUITY OF
SOLUTIONS TO PROGRAMMING PROBLEMS

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September 27, 1974

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We consider programming problems: maximize $f(x)$ subject to $g(x) \leq b$, where f is a function $\mathbb{R}^n \rightarrow \mathbb{R}$, g a function $\mathbb{R}^n \rightarrow \mathbb{R}^m$ and b an m -vector. ($a \leq b$ for m -vectors is taken to mean $a_j \leq b_j$ for all j). One defines

$$S_b = \{x \in \mathbb{R}^n \mid g(x) \leq b\}$$

$$S_{b,0}^* = \{x \in \mathbb{R}^n \mid x \in S_b \text{ and } f(x) = \max_{z \in S_b} f(z)\}, \text{ the solution set,}$$

and for given $\varepsilon \geq 0$.

$$S_{b,\varepsilon}^* = \{x \in \mathbb{R}^n \mid x \in S_b \text{ and } f(x) \geq -\varepsilon + \max_{z \in S_b} f(z)\}, \text{ the } \varepsilon\text{-solution set.}$$

One is interested in upper and lower semicontinuity and linear upper and lower semicontinuity of S_b , $S_{b,0}^*$ and $S_{b,\varepsilon}^*$ as b varies. (Linear semicontinuity is defined below). The setting and motivation for the examples below is provided by [1]. These examples answer (in the negative) all the questions on page 26 of [1].

1. Definition. A set valued function $s \mapsto T_s$ from $S \subset \mathbb{R}^m$ to the power set of \mathbb{R}^n is said to be linearly upper semicontinuous at $s \in S$ if there exist $\delta > 0$ and $K > 0$ such that

$$\rho(z', T_{s'}) \leq K \|s - s'\| \text{ for all } z' \in T_{s'}, s' \in S, \|s - s'\| < \delta.$$

The function $s \mapsto T_s$ is said to be linearly lower semicontinuous at $s \in S$ if there exist $\delta > 0$ and $K > 0$ such that

$$\rho(z, T_{s'}) \leq K \|s - s'\| \text{ for all } z \in T_s, s' \in S, \|s' - s\| < \delta$$

These definitions are taken from [1]. The symbol $\| \cdot \|$ is the usual norm on \mathbb{R}^m and $\rho(z, T)$ is the distance of $z \in \mathbb{R}^n$ to $T \subset \mathbb{R}^n$, i.e.

$$\rho(z, T) = \inf_{t \in T} \|z - t\|.$$

2. Example. (g_j linear for all j , $-f$ convex, S_b compact but $S_{b,0}^*$ not lower semicontinuous).

In \mathbb{R}^3 with coordinates (x_1, x_2, x_3) let P be the parabola $x_1 = -1, x_3 = -x_2^2$. Let Q be the surface obtained by drawing all the lines joining the origin in \mathbb{R}^3 to a point of P . Let $f(x_1, x_2)$ be the function defined by the surface Q . The function f is welldefined on the open halfspace $x_1 < 0$, and $-f$ is clearly convex. It is not difficult to write down a formula for f .

Now let $g_1(x_1, x_2) = x_1, g_2(x_1, x_2) = -x_1, g_3(x_1, x_2) = x_2, g_4(x_1, x_2) = -x_2$, and let $b(0)$ be the vector $(-\frac{1}{2}, 1, 0, 1)$ and $b(\epsilon)$ the vector $(-\frac{1}{2}, 1, -\epsilon, 1)$. Then $S_{b(\epsilon)} = \{x | g(x) \leq b(\epsilon)\}$ is the box $\{(x_1, x_2) | -1 \leq x_1 \leq -\frac{1}{2}, -1 \leq x_2 \leq -\epsilon\}$ and ^(the) solution sets $S_{b(\epsilon), 0}^*$ of $\max f(x)$, subject to $g(x) \leq b(\epsilon)$, are equal to

$$S_{b(0), 0}^* = \{(x_1, x_2) | x_2 = 0, -1 \leq x_1 \leq -\frac{1}{2}\}$$

$$S_{b(\epsilon), 0}^* = \{(-1, -\epsilon)\} \text{ for all } \epsilon > 0.$$

Therefore $S_{b, 0}^*$ is not lower semicontinuous (with respect to b) in $b(0)$.

3. Example. (g_j linear for all j , $-f$ (strictly) convex, S_b compact, but $S_{b, 0}^*$ not linearly upper semicontinuous).

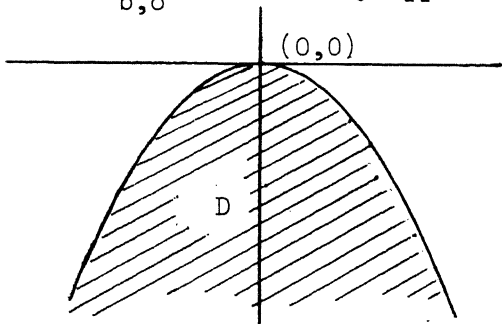


fig. 1

Let D in \mathbb{R}^2 be the region $x_2 + x_1^2 \leq 0$. Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ be the function defined by $f(x) = -d(x)$, where $d(x)$ is the distance of (x_1, x_2) to D . Then $-f$ is a convex function because D is a convex region. (cf. the lemma below).

Let $g_1(x) = x_1, g_2(x) = -x_1, g_3(x) = x_2, g_4(x) = -x_2$ and let $b(0)$ and $b(\epsilon)$ be the vectors $(1, 1, 1, 0)$ and $(1, 1, 1, \epsilon)$. The feasible regions $S_{b(\epsilon)}$ are the boxes

$$S_{b(\epsilon)} = \{x | g(x) \leq b(\epsilon)\} = \{(x_1, x_2) | -1 \leq x_1 \leq 1, -\epsilon \leq x_2 \leq 1\}$$

and the solution sets of $\max f(x)$ subject to $x \in S_{b(\epsilon)}$ are

$$S_{b(o),o}^* = \{(0,0)\}$$

$$S_{b(\epsilon),o}^* = \{(x_1, x_2) \mid x_2 + x_1^2 \leq 0, -\epsilon \leq x_2 \leq 0\}$$

Therefore

$$\max_{z \in S_{b(\epsilon),o}^*} \rho(z, S_{b(o),o}^*) = (\epsilon + \epsilon^2)^{\frac{1}{2}},$$

where $\rho(z, S_{b(o),o}^*)$ is the distance of z to $S_{b(o),o}^*$ and as $\|b(o) - b(\epsilon)\| = \epsilon$ it follows that $S_{b,o}^*$ is not linearly upper continuous in $b(o)$.

4. Lemma. Let C be a closed convex subject of \mathbb{R}^n and let $d(x)$ denote the distance of $x \in \mathbb{R}^n$ to C . Then $d: \mathbb{R}^n \rightarrow \mathbb{R}$ is a convex function.

Proof. Let $x, y \in \mathbb{R}^n$ and let a and b in C be points such that $\|x-a\| = d(x)$, $\|y-b\| = d(y)$. Let z be a point $z = \lambda x + (1-\lambda)y$, $0 \leq \lambda \leq 1$.

Let w be the point on the line through a and y obtained by intersecting this line with the line through z parallel to the line through x and a .

Let c be the point on the line through a and b obtained by intersecting this line with

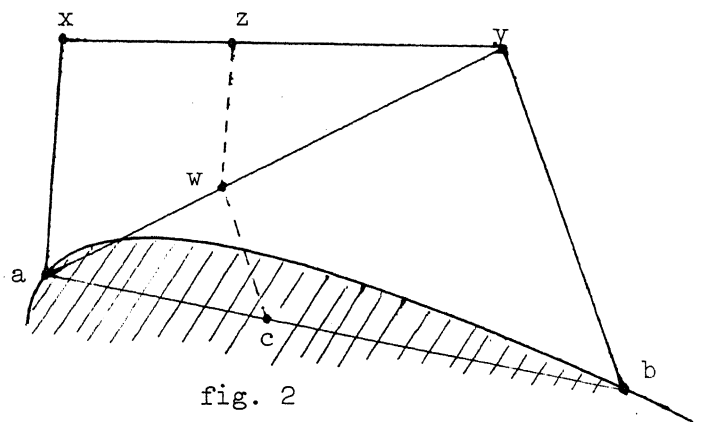


fig. 2

the line through w parallel to the line through y and b . Then

$$\|z-w\| = \lambda d(x) \text{ and } \|w-c\| = (1-\lambda)d(y)$$

and as c is a point of C (C being convex) we have that

$$d(z) \leq \|z-c\| \leq \|z-w\| + \|w-c\| = \lambda d(x) + (1-\lambda)d(y)$$

5. Example. ($-f$ (strictly) convex, $S_{b,o}$ compact and uniformly linearly continuous, but for all $0 \leq \epsilon \leq 1$, $S_{b,\epsilon}^*$ not linearly upper semicontinuous).

The function f of this example is the same as the function f in Example 4. There are five restriction functions

$$g_1(x) = \min(x_2 - x_1 + 3, -x_2)$$

$$g_2(x) = x_2$$

$$g_3(x) = -x_1$$

$$g_4(x) = x_1$$

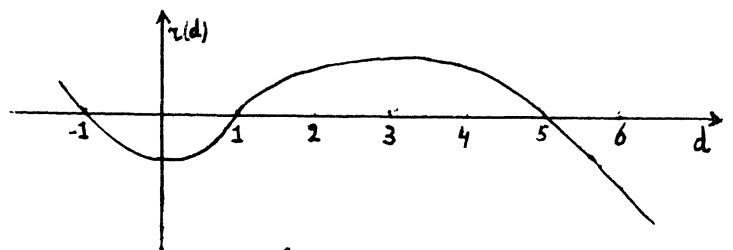


fig. 3

$g_5(x) = r(\|x - (0,6)\|)$, where r is a function of one variable like the one sketched in fig. 3.

Let $b(\epsilon, 0)$ be the vector $(-\epsilon, 2, 1, 1, 0)$. In fig. 4 below the region of $x \in \mathbb{R}^2$ satisfying $g_i(x) \leq b_i(\epsilon, 0)$ for $i = 1, 2, 3, 4$ is shaded and the region of $x \in \mathbb{R}^2$ satisfying $g(x) \leq b(\epsilon, 0)$ is crosshatched. The dotted line are the points where $f(x) = -\epsilon$.

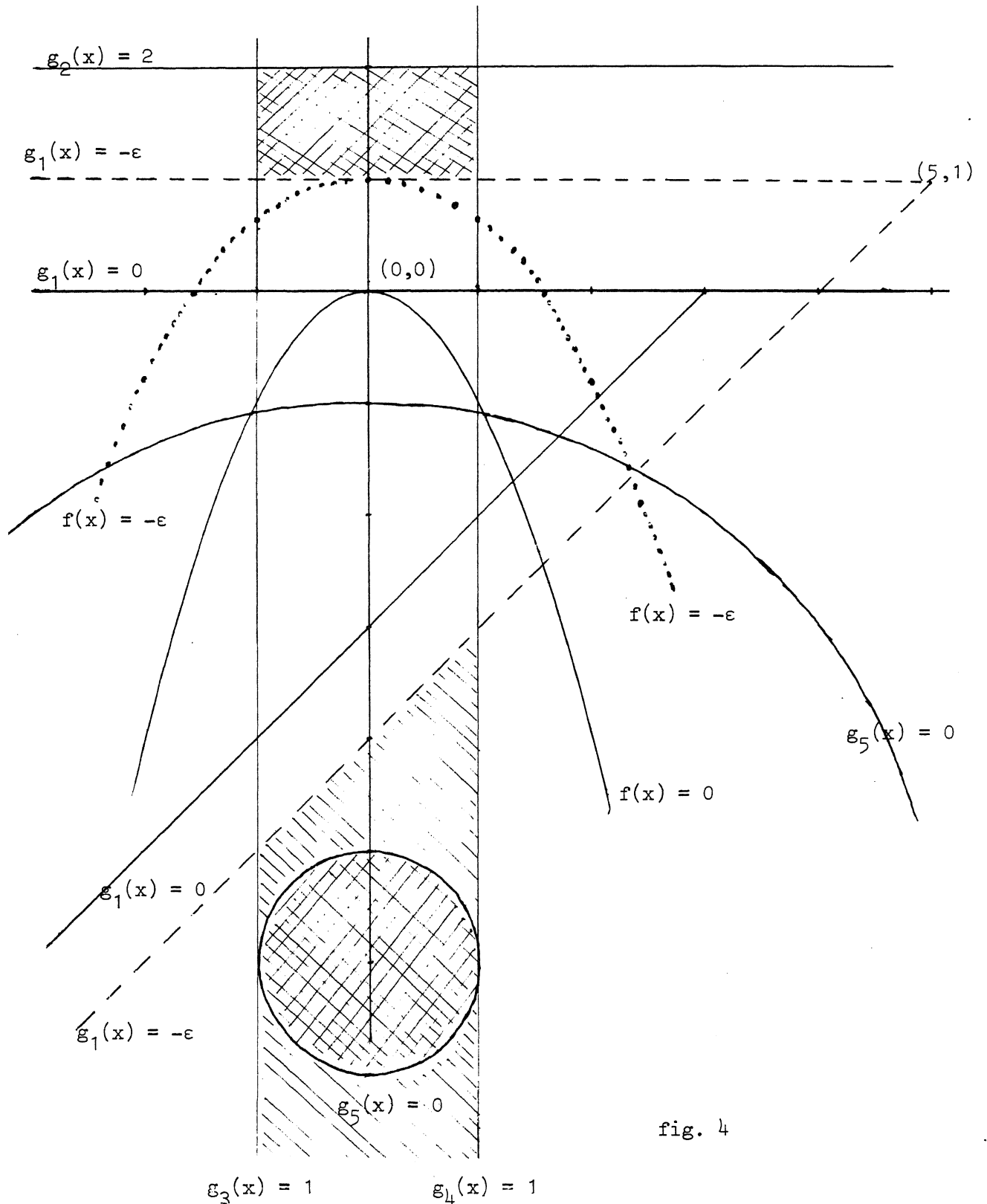


fig. 4

Now let

$$b(\epsilon, c) = (\epsilon(4c+1)^{-\frac{1}{2}} - c, 2, 1, 1, 0)$$

The sets $S_{b(\epsilon, c), \epsilon}^*$ are now equal to

$$S_{b(\epsilon, 0), \epsilon}^* = A \cup \{(0, \epsilon)\}$$

$$S_{b(\epsilon, c), \epsilon}^* = A \cup T$$

where T is the shaded region in fig. 5 below, and $A = \{x \in \mathbb{R}^2 \mid \|x - (0, 0)\| \leq 1\}$.

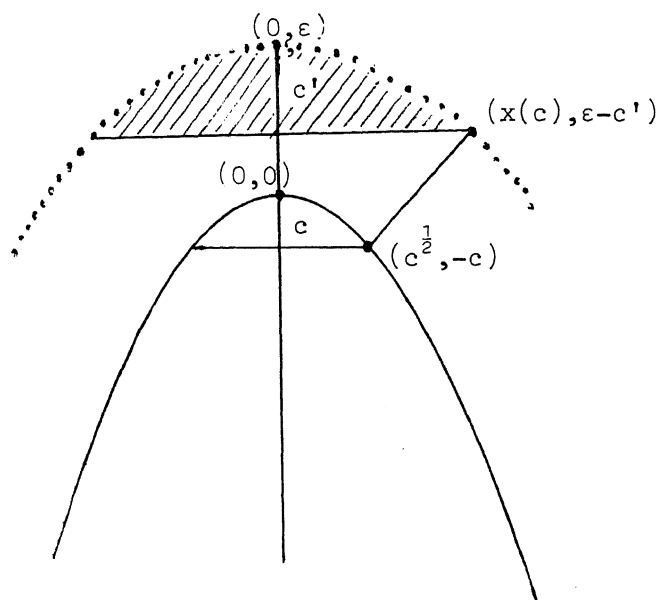


fig. 5

The point of $S_{b(\epsilon, c), \epsilon}^*$ furthest away from $S_{b(\epsilon, 0), \epsilon}^*$ is the point $(x_1(c), \epsilon - c')$ where

$$x_1(c) = c^{\frac{1}{2}} + 2\epsilon c^{\frac{1}{2}}(1+4c)^{-\frac{1}{2}} \text{ and } c' = c + \epsilon(1-(4c+1)^{-\frac{1}{2}})$$

(The point of the parabola $x_2 = -x_1^2$ closest to $(x_1(c), \epsilon - c')$ is the point $(c^{\frac{1}{2}}, -c)$).

The distance $\sqrt{(x_1(c), \epsilon - c')^2}$ is therefore $\geq c^{\frac{1}{2}}$. The distance between $b(\epsilon, c)$ and $b(\epsilon, 0)$ is

$$c + \epsilon(1-(4c+1)^{-\frac{1}{2}})$$

It follows that

$$\lim_{c \rightarrow 0} \frac{\rho((x(c), \varepsilon - c'), S_{b(\varepsilon, 0), \varepsilon}^*)}{\|b(\varepsilon, c) - b(\varepsilon, 0)\|} = \infty$$

and therefore $S_{b, \varepsilon}$ is not linearly upper semicontinuous in $b(\varepsilon, 0)$.

REFERENCES

1. M.H. Stern, Rates of stability in nonlinear programming.
D.M. Topkis