

- Complex Space," paper presented at the Sixth Annual Convention of the Operational Research Society of India, New Delhi, November 10-12, 1973.
3. O. P. JAIN AND P. C. SAXENA, "A Duality Theorem for a Special Class of Programming Problems in Complex Space," *J. Optim. Theory Appl.* **16**, 207-230 (1975).
  4. B. MOND, "On a Duality Theorem for a Nonlinear Programming Problem," *Opns. Res.* **21**, 369-370 (1973).
  5. B. MOND AND M. SCHECHTER, "On a Constraint Qualification in a Nondifferentiable Programming Problem," *Naval Res. Log. Quart.* **23**, 611-613, (1976).
  6. M. SCHECHTER, "Symmetric Duality via Conjugate Duality," *Zeitschrift fuer Angewandte Mathematik und Mechanik* (to appear).

## Some Examples Concerning Linear Continuity of Solutions to Programming Problems

MICHIEL HAZEWINKEL

*Erasmus University, Rotterdam, The Netherlands*

(Received original November 1974; final, December 1976)

In this note we construct some counterexamples concerning upper semicontinuity and linear upper and lower semicontinuity of the solution sets and  $\epsilon$ -solution sets of nonlinear programming programs:  $\max f(x)$ , subject to  $g(x) \leq b$ . These examples answer some of the questions in a recent paper by Stern and Topkis.

---

WE CONSIDER the programming problem  $\max f(x)$ ,  $g(x) \leq b$ , where  $f$  is a function  $\mathcal{R}^n \rightarrow \mathcal{R}$ ,  $g$  a function  $\mathcal{R}^n \rightarrow \mathcal{R}^m$ , and  $b$  an  $m$ -vector. Here  $g(x) \leq b$  means  $g_j(x) \leq b_j$  for all  $j = 1, \dots, m$ . We define  $S_b = \{x \in \mathcal{R}^n | g(x) \leq b\}$  and for all  $\epsilon \geq 0$  we define the  $\epsilon$ -solution set

$$S_{b,\epsilon}^* = \{x \in \mathcal{R}^n | x \in S_b \text{ and } f(x) \geq -\epsilon + \max_{z \in S_b} f(z)\}.$$

We are interested in upper and lower semicontinuity and linear upper and lower semicontinuity of  $S_{b,\epsilon}^*$  as  $b$  varies. For a definition of these notions see [2]. We will construct some examples that answer some of the questions asked in [2].

### 1. EXAMPLES

*Example 1.* In this example  $g_j$  is linear for all  $j$ ,  $-f$  is a convex differentiable function,  $S_b$  is compact, but  $S_{b,0}^*$  is not lower semicontinuous.

---

Let  $f$  be the function defined by  $f(x_1, x_2) = x_2^2/x_1$  on the open halfspace of  $\mathbb{R}^2$  where  $x_1 < 0$ . The function  $-f$  is convex on  $\{x \in \mathbb{R}^2 | x_1 < 0\}$ .

Now define  $g_1(x_1, x_2) = x_1$ ,  $g_2(x_1, x_2) = -x_1$ ,  $g_3(x_1, x_2) = x_2$ ,  $g_4(x_1, x_2) = -x_2$ . Let  $b(0)$  be the vector  $(-1/2, 1, 0, 1)$  and  $b(\delta)$  the vector  $(-1/2, 1, -\delta, 1)$ . Then  $S_{b(\delta)} = \{(x_1, x_2) | -1 \leq x_1 \leq -1/2, -1 \leq x_2 \leq -\delta\}$  and the solution sets  $S_{b(\delta),0}^*$  of the problem  $\max f(x)$ ,  $g(x) \leq b(\delta)$  are  $S_{b(0),0}^* = \{(x_1, x_2) | x_2 = 0, -1 \leq x_1 \leq -1/2\}$  and  $S_{b(\delta),0}^* = \{(-1, -\delta)\}$  for all  $\delta > 0$ . Therefore,  $S_{b,0}^*$  is not lower semicontinuous with respect to  $b$  in  $b(0)$ .

*Example 2.* In this example  $g_j$  is linear for all  $j$ ,  $-f$  is a convex differentiable function,  $S_b$  is compact, but  $S_{b,0}^*$  is not linearly upper semicontinuous. Let  $D \subset \mathbb{R}^2$  be the region  $x_1^2 + x_2^2 \leq 1$ . Let  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  be the function defined by  $f(x) = -(d(x))^2$ , where  $d(x)$  is the distance of  $x = (x_1, x_2)$  to  $D$ . A formula for  $f(x)$  is  $f(x) = -(\max\{0, (x_1^2 + x_2^2)^{1/2} - 1\})^2$ . The function  $f$  is continuously differentiable. Further,  $-f$  is a convex function. Now define  $g_1(x) = x_2$ ,  $g_2(x) = x_1$ ,  $g_3(x) = -x_2$ ,  $g_4(x) = -x_1$ . Let  $b(0)$  be the vector  $(2, 1, -1, 1)$  and  $b(\delta) = (2, 1, -1 + \delta, 1)$ ,  $\delta > 0$ . Then we have  $S_{b(0),0}^* = \{(0, 1)\}$  and  $S_{b(\delta),0}^* = \{(x_1, x_2) | x_1^2 + x_2^2 \leq 1, x_2 \geq 1 - \delta\}$ .

The point  $B = ((2\delta - \delta^2)^{1/2}, 1 - \delta)$  is in  $S_{b(\delta),0}^*$  and has distance  $\geq (2\delta - \delta^2)^{1/2}$  to  $A = (0, 1)$ . It follows that  $S_{b,0}$  is not linearly upper semicontinuous in  $b$  at  $b(0)$ .

*Example 3.* In this example  $-f$  is a convex differentiable function,  $S_b$  is compact and uniformly linearly continuous. For every  $\epsilon$  with  $0 \leq \epsilon \leq 1/6$  there is a  $b(\epsilon, 0)$  such that  $S_{b,\epsilon}^*$  is not linearly upper semicontinuous in  $b$  at  $b(\epsilon, 0)$ .

The function  $f$  in this example is the same as the function  $f$  in example 2 above. There are five restriction functions:

$$g_1(x) = \begin{cases} -(\frac{1}{2}x_1 + \frac{1}{2}x_2 + \frac{1}{8}) + \frac{1}{4}(\frac{1}{4} - 4(x_1 - x_2)(x_1 - x_2 + \frac{1}{2}))^{1/2} & \text{if } x_1 - x_2 \leq 0 \text{ and } x_2 - x_1 \leq \frac{1}{2} \\ -x_1 & \text{if } x_1 - x_2 \geq 0 \\ -x_2 + \frac{1}{4} & \text{if } x_2 - x_1 \geq \frac{1}{2}, \end{cases}$$

$g_2(x) = x_1$ ,  $g_3(x) = -x_2$ ,  $g_4(x) = x_2$ , and  $g_5(x) = -x_1$ .

The functions  $g_j$  are all continuously differentiable. The level curves of  $g_1$  are straight lines joined by a quarter circle of radius  $1/4$  (see Figure 1). Choose  $0 \leq \epsilon \leq 1/6$ . Let  $b(\epsilon, 0)$  be the vector  $(-3/4 - \epsilon^{1/2}, 9/4, 3/2, 9/4, 3/2)$  and  $b(\epsilon, \delta) = (-3/4 - \epsilon^{1/2} + \delta, 9/4, 3/2, 9/4, 3/2)$ . We then have for  $\delta \geq 0$  sufficiently small  $S_{b(\epsilon,\delta),\epsilon}^* = \{(x_1, x_2) | x_1^2 + x_2^2 \leq 1 + \epsilon, x_1 \geq 3/4 + \epsilon^{1/2} - \delta\} \cup \{(x_1, x_2) | x_1^2 + x_2^2 \leq 1 + \epsilon, x_2 \geq 1 + \epsilon^{1/2} - \delta\}$ . In Figure 1 the case  $\epsilon = 1/6$ ,  $\delta = 1/10$  is shown.  $S_{b(\epsilon,0),\epsilon}^*$  consists of the cross-hatched area and the point  $A$  and  $S_{b(\epsilon,\delta),\epsilon}^*$  is the union of the cross-hatched and shaded areas.

It now follows as in example 2 that  $S_{b,\epsilon}^*$  is not linearly upper semicontinuous in  $b$  at  $b(\epsilon, 0)$ .

2. REMARKS

*Example 4.1.* If one changes the function  $f$  of example 3 to  $\bar{f}(x) = -(e(x))^2$ , where  $e(x)$  is the distance of  $x$  to the region  $\{(x_1, x_2) | x_2 \leq -x_1^2 + 1\}$ , one can construct an example similar to example 3 such that for every  $\epsilon \geq 0$  there is a  $b(\epsilon)$  such that  $S_{b,\epsilon}^*$  is not linearly upper semicontinuous in  $b$  at  $b(\epsilon, 0)$ .

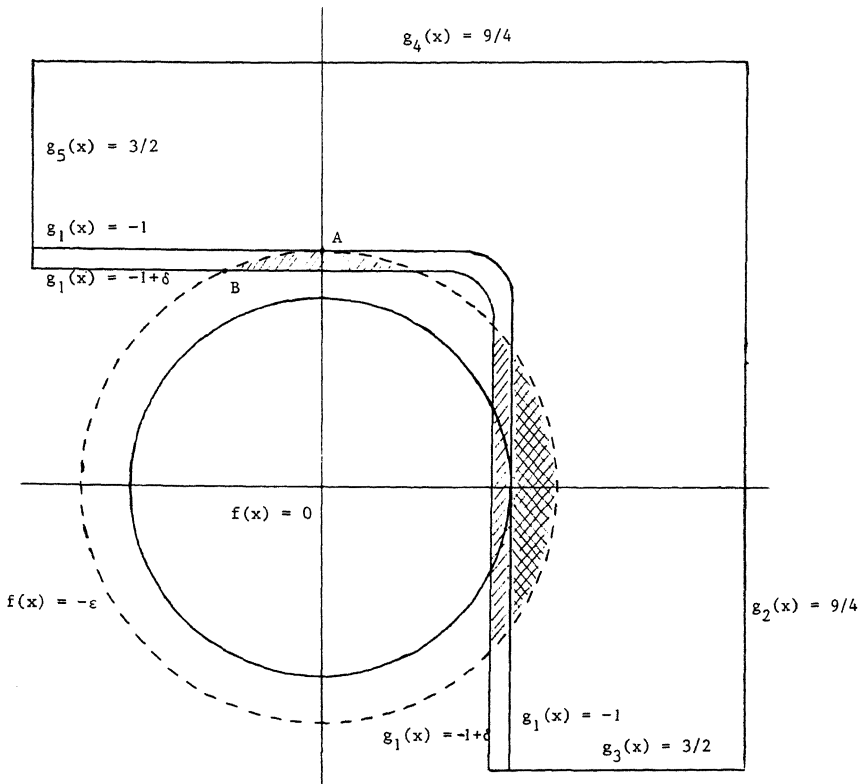


Figure 1

*Example 4.2.* By repeating infinitely often the trick by which the function  $g_1$  of example 3 was constructed, one can construct an example with the following properties: 1)  $-f$  is a convex differentiable function; 2)  $g_1$  is a continuous differentiable function; 3)  $g_2, \dots, g_5$  are linear functions; 4)  $S_b$  is uniformly linearly continuous for  $b$  in a suitable hypercube  $B$ ; and 5) for every  $b(0)$  in the 4-dimensional subcube of  $B$  where  $b_1 = -1$  there is an infinite sequence  $\{\epsilon(n)\}_n, \epsilon(n) > 0$  such that  $S_{b,\epsilon(n)}^*$  is not linearly upper semicontinuous in  $b$  at  $b(0)$  for all  $n \in \mathcal{N}$ . Moreover,  $\lim_{n \rightarrow \infty} \epsilon(n) = 0$  and  $S_{b,0}^*$  is not linearly upper semicontinuous in  $b$  at  $b(0)$ .

In this example  $f, g_2, \dots, g_5$  are as in example 3. The function  $g_1$  is constructed as follows. We first define the level curve  $g_1(x) = -1$ . Draw rays  $l_n$  from the origin in  $\mathbb{R}^2$  at an angle of  $2^{-n-1}\pi$  with the positive  $X_1$ -axis. Let  $A_n$  be the point on  $l_n$  at distance  $1+a_n$  from the origin. In the points  $A_n$

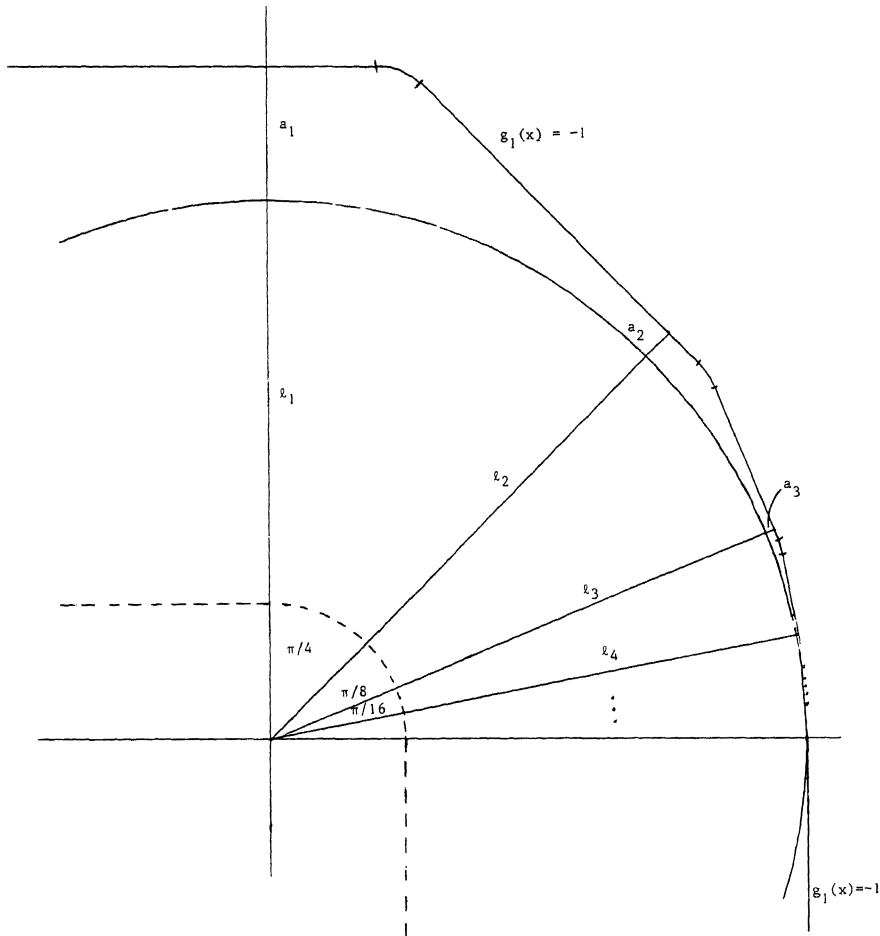


Figure 2

draw lines  $m_n$  perpendicular to  $l_n$ . If one takes, e.g.,  $a_n = 4^{-n-1}\pi^2/2$ , then the intersection point of  $m_n$  and  $m_{n+1}$  is in the angle formed by  $l_n$  and  $l_{n+1}$ . Now join suitable segments of the  $m_n$  by "smoothing the corners in the intersection points." This can be done by means of circle arcs of radius  $1/8$ . The resulting curve  $C$  is differentiable and has the property that it is a straight line near every intersection point  $C \cap l_n = A_n, n \in \mathcal{N}$ .

Let  $E \subset \mathbb{R}^2$  be the region

$$E = \{x \in \mathbb{R}^2 \mid x_1 \geq \frac{1}{4}\} \cup \{x \in \mathbb{R}^2 \mid x_2 \geq \frac{1}{4}\} \cup \{x \in \mathbb{R}^2 \mid x_1 \geq 0, x_2 \geq 0, \|x\| \geq \frac{1}{4}\}.$$

The boundary of  $E$  is the dashed line in Figure 2. For each  $x \in E$  let  $l_x$  be the ray from the origin passing through  $x$ ,  $B_x$  be the intersection point  $l_x \cap C$ , and  $r_x$  be the distance of  $B_x$  to the origin. We now define  $g_1(x) = -\|x\|r_x^{-1}$ . This defines a differentiable function  $g_1 : E \rightarrow \mathbb{R}$ , which by the familiar tools of differential topology can be extended to a suitable, continuously differentiable function  $g_1 : \mathbb{R}^2 \rightarrow \mathbb{R}$ , such that  $g_1(x) \geq -\frac{1}{2}$  for all  $x \in \mathbb{R}^2 \setminus E$  (see [1]).

A suitable hypercube such that property 4 holds is, e.g., defined by the inequalities  $-\frac{3}{4} \geq b_1 \geq -2$ ,  $3 \leq b_2 \leq 4$ ,  $3 \leq b_3 \leq 4$ ,  $4 \leq b_4 \leq 5$ ,  $2 \leq b_5 \leq 3$ . In the example as described (see Figure 2) property 5 holds for all  $b(0)$  in this cube for which  $b_1 = -1$ . For example,  $S_{b,0}^*$  grows nonlinearly at  $b = (-1, b_2, b_3, b_4, b_5)$  as  $b_1$  becomes greater than  $-1$ . Nonlinear growth in the  $S_{b,\epsilon_n}^*$  for  $\epsilon_n = a_n^2$  at  $b = (-1, b_2, b_3, b_4, b_5)$  as  $b_1$  becomes greater than  $-1$  is caused by the straight-line sections in the curve  $g_1(x) = -1$  at the points  $A_n$ .

The functions  $f$  and  $g_1$  of examples 2, 3, and 4.2 are continuously differentiable but not twice continuously differentiable. There are similar examples with  $f$  and  $g_1$  of class  $C^\infty$ , i.e.,  $n$  times continuously differentiable for all  $n$ . This is done by smoothing the functions  $g_1$  suitably, using techniques as in [1]. To obtain suitable functions  $f$  one needs only a  $C^\infty$  function  $h$  of one variable  $r$  that is convex,  $\geq 0$  everywhere and such that  $h(r) = 0 \Leftrightarrow 0 \leq r \leq 1$ . Such functions  $h$  exist, e.g.,  $h(r) = (r-1)^6 \exp(-(r-1)^{-2})$  if  $r \geq 1$ ,  $h(r) = 0$  if  $0 \leq r \leq 1$ .

REFERENCES

1. J. MUNKRES, *Elementary Differential Topology*, Princeton University Press, Princeton, N. J., 1963.
2. M. H. STERN AND D. M. TOPKIS, "Rates of Stability in Nonlinear Programming," *Opns. Res.* **24**, 462-476 (1976).