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## 1. INTRODUCTION

Let P be an N×N Markov matrix whose (i,j) element is  $p_{ij}$  (i,j=1,...,N), i.e.,  $p_{ij} \ge 0$  and  $\sum_{j} p_{ij}$ =1. Let T be an N component column vector whose ith element is  $T_i$  where  $T_i > 0$  for i=1,...,N, and let q be an N component column vector whose ith element is  $q_i$  (i=1,...,N). The triple (P,T,q) can be thought of as a semi-Markov reward process with transition probabilities  $p_{ij}$ , expected transition times  $T_i$  and one-transition rewards  $q_i$ . It is assumed that the Markov matrix P has a single recurrent chain. Let state N be a recurrent state of the Markov matrix P.

In each iteration of Howard's [2] well known policy-iteration algorithm a set of linear simultaneous equations must be solved. For the single chain case this set of equations is of the following type:

$$gT + v = q + Pv , \qquad (1)$$

where g is an unknown scalar and v is an unknown N component column vector whose ith element is  $v_i$  (i=1,...,N). It is important to have an efficient method for solving (1). For the case where P is an aperiodic Markov matrix Morton [4] has given a simple iterative scheme to solve (1).

The purpose of this note is to demonstrate that a solution of (1) can be found by solving two sets of linear simultaneous equations which are more easy to tackle than (1). In our approach we need not require that P is aperiodic. Despite the fact that our approach is implied in the paper of Derman and Veinott[1], the theorem below seems to have passed unnoticed.

## 2. RESULTS

We first introduce some notation. Let  $T^*$  be the N-1 component column vector whose ith element is  $T_i$ , let  $q^*$  be the N-1 component column vector whose ith element is  $q_i$ , and let R be the N-1 component row vector whose ith element is  $p_{Ni}$  (i=1,...,N-1). Denote by Q the (N-1)×(N-1) matrix whose (i,j) element is  $p_{ij}$  (i,j=1,...,N-1). Observe that  $Q^n \rightarrow 0$  as  $n \rightarrow \infty$ , since N is a recurrent state of the Markov matrix P.

We have the following theorem (cf. Derman and Veinott [1] and Theorem 1 of Morton [4])

THEOREM. Let the column vector  $x=(x_1,\ldots,x_{N-1})$  be the unique solution to

$$x = q^* + Qx , \qquad (2)$$

and let the column vector  $y=(y_1,\ldots,y_{N-1})$  be the unique solution to

$$y = T^* + Qy . \tag{3}$$

Define the scalar g by

$$g=(q_{\rm N}+Rx)/(T_{\rm N}+Ry) , \qquad (4)$$

and define the N component column vector  $v=(v_1,\ldots,v_N)$  by

$$v_i = x_i - gy_i \text{ for } i=1,...,N-1, v_N = 0.$$
 (5)

Then g, v satisfy equation (1).

*Proof.* Let us first observe that both (2) and (3) have a unique solution, since  $Q^n \rightarrow 0$  as  $n \rightarrow \infty$ . Denote by  $v^*$  the N-1 component column vector whose

ith element is  $v_i$  (i=1,...,N-1). From (2), (3) and (5),

$$gT^* + v^* = gT^* + q^* + Qx - g(T^* + Qy) = q^* + Q(x - gy) = q^* + Qv^*$$
,

while from (4) and (5) it follows that

$$gT_{N} + v_{N} = q_{N} + Rx - gRy = q_{N} + R(x-gy) = q_{N} + Rv^{*}$$
.

Using  $v_N = 0$  the theorem now follows.

Observe that g in (4) can be interpreted as the ratio of the expected return earned during a cycle and the expected length of a cycle, where a cycle is defined as the time interval between two successive visits to the recurrent state N. It is well-known that this ratio equals the long-run average return.

Remark. Suppose that  $p_{iN}=1-\alpha_i > 0$  for  $i=1,\ldots,N-1$ . Let  $z_0$  be an arbitrary N-1 component column vector, and for  $n\geq 1$  define  $z_n$  by  $z_n = b + Qz_{n-1}$ , where b is a given N-1 component column vector. Let z be the unique solution to z=b+Qz. Define for any n>1,

$$u'_{n}(i)=z_{n}(i)+(1-\alpha_{i})^{-1} \min_{j}\{z_{n}(j)-z_{n-1}(j)\}$$
 for i=1,...,N-1,

and

$$u''_{n}(i) = z_{n}(i) + (1-\alpha_{i})^{-1} \max_{j} \{z_{n}(j) - z_{n-1}(j)\}$$
 for  $i = 1, ..., N-1$ .

Then, for any  $n \ge 1$ ,  $u'_n(i) \le z(i) \le u'_n(i)$  for  $i=1,\ldots,N-1$ , where  $u'_n(i)$  is nondecreasing in n to z(i) and  $u''_n(i)$  is nonincreasing in n to z(i) for all i. The proof of this assertion is a slight modification of proofs given by Macqueen [3] and is based on the following fact: If Tu<Tw then  $u \le w$ , where the transformation T is defined by Tu=u-(b+Qu) for any N-1 component column vector u. Remark. It is straightforward to extend the analysis above to the case of a general Markov matrix P; in this case the set of simultaneous equations g=Pg and gT+v=q+Pv has to be solved where g and v are unknown N component column vectors.

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