

RA
NA

stichting
mathematisch
centrum



REKENAFDELING

MR 134/72

JULY

P.W. HEMKER
PARAMETER ESTIMATION IN
NON-LINEAR DIFFERENTIAL EQUATIONS

RA

2e boerhaavestraat 49 amsterdam

BIBLIOTHEEK MATHEMATISCH CENTRUM
AMSTERDAM

Printed at the Mathematical Centre, 49, 2e Boerhaavestraat, Amsterdam.

The Mathematical Centre, founded the 11-th of February 1946, is a non-profit institution aiming at the promotion of pure mathematics and its applications. It is sponsored by the Netherlands Government through the Netherlands Organization for the Advancement of Pure Research (Z.W.O), by the Municipality of Amsterdam, by the University of Amsterdam, by the Free University at Amsterdam, and by industries.

Contents

Preface

1.	Introduction	3
2.	The method	4
	The dependence of $Y(p)$ on p	4
	Minimizing $S(p)$	6
3.	Statistics	7
4.	Integration of the equations	9
5.	The ALGOL 60 procedure "odeparest"	12
	General remarks, users manual	12
	Procedure text	19
6.	Problems solved	29
	The ESCEP problem	29
	Bellman's problem	61
	Gear's problem	69
	Barnes' problem	75
	Analysing a sum of exponentials	82
	References	91

Preface

This report describes some experiences with the estimation of parameters in nonlinear differential equations. The work was done as part of work in a group on biomathematics and a group on stiff differential equations. The program used is written in ALGOL 60 and has been run on the EL X8 computer of the Mathematical Centre. After an exposition of the method, a detailed description of the procedure is given and a number of solved problems are shown in detail.

1. Introduction

In this report we shall be concerned with a problem which arises from experimental science. In order to predict the behaviour of systems, an experimental scientist not only wants to describe phenomena phenomenologically, but he also wants to construct a model of the process under consideration. Often a mathematical representation of the model will be given by a system of differential equations in which a set of parameters is not known a priori. These parameters have to be determined on the basis of experiments.

Mathematically stated, the problem is this: A set of n differential equations is given *

$$\frac{d}{dt} y = f(t, y, p) \quad (1.1)$$

where p represents an m -vector of parameters. In the process considered, p has the value p^* , but p^* is not known. Some components of the vector y can be measured for different values of t , but these measurements are affected by some random errors. It is assumed that the form of f is known, together with some statistical properties of the measurement errors. The problem is to deduce an estimate \bar{p} of the vector p^* .

With y_i ($1 \leq i \leq N$) we denote the observed value of some component y at time t_i . Thus the index i identifies an observation and also determines what component of y has been observed. So we have a set of observations $\{y_i\}$, a corresponding set $\{t_i\}$ ($t_1 \leq t_2 \leq \dots \leq t_N$) and, for some p , we can compute a set of theoretical values $y(t_i, p)$. The problem now seems to be quite simple: we define the N -vector

$$Y(p) = (y(t_i, p) - y_i) \quad 1 \leq i \leq N \quad (1.2)$$

and we define

*) We use vector notation throughout, so $p \in R^m$,

$y \in R \times R^m \rightarrow R^n$, $f \in R \times R^n \times R^m \rightarrow R^n$ etc..

$$S(p) = || Y(p) ||_2^2 = \sum_{i=1}^N (y(t_i, p) - y_i)^2 \quad (1.3)$$

the sum of the squares of the discrepancies. Using an integration procedure to solve $y(t_i, p)$, we can solve the problem stated by minimizing $S(p)$ using standard techniques. Even when we assume that the minimum is unique and that the function $S(p)$ is the best one to minimize (this can be justified under certain conditions), the question still remains as to how badly conditioned the problem is. I.e. how small a perturbation in some values of y_i will cause how large a variation in the minimizing vector \bar{p} . In relation to this question it is clear that not only an estimate of p^* has to be determined but also an estimate of its reliability.

In this report we will assume that the measurement errors are statistically independent and that they have a Gaussian distribution with zero mean and variance σ^2 . Thus the covariance matrix of the vector of errors η is

$$E(\eta\eta^T) = \sigma^2 I \quad (1.4)$$

and the probability density of η is given by

$$p(\eta) = (2\pi\sigma)^{-N/2} \exp(- ||\eta||^2 / 2\sigma^2).$$

2. The method

2.1. The dependence of $Y(p)$ on p

The solution of the differential equation (1) can be considered to be a function of t as well as a function of p . We consider the difference between two adjacent solutions $y_1(t, p)$ and $y_2(t, p+\delta)$ of equation (1), both starting at $y_1(0, p) = y_2(0, p+\delta) = c$. We compute the perturbation due to this small change in p .

$$\frac{d}{dt} y_1 = f(t, y_1, p) \quad y_1(0) = c \quad (2.1)$$

$$\frac{d}{dt} y_2 = f(t, y_2, p + \delta) \quad y_2(0) = c \quad (2.2)$$

Expanding (2.2) in a Taylorseries and keeping only first order terms in δ , we obtain

$$\frac{d}{dt} y_2 = f(t, y_1, p) + FY(y_2 - y_1) + FP \delta \quad (2.3)$$

where

$$FY = \left(\frac{\partial}{\partial y_1} f(t, y_1, p) \right) \quad (2.4)$$

is an $n \times n$ matrix and

$$FP = \left(\frac{\partial}{\partial p} f(t, y_1, p) \right) \quad (2.5)$$

is an $n \times p$ matrix, both matrices being functions of t, p and y_1 , but not of δ or $y_2 - y_1$.

It would be expedient to know how the computable values $y(t_i, p)$ depend upon small variations δ around p . Since equation (2.3) enables us to construct the differential equation which defines

$$YP = \frac{\partial}{\partial p} y(t, p), \quad (2.6)$$

we use (2.3) and write

$$\frac{\partial}{\partial p} \frac{d}{dt} y(t, p) = FP + FY \cdot \frac{\partial}{\partial p} y(t, p) \quad (2.7)$$

or, in shorthand,

$$\frac{d}{dt} YP = FP + FY \cdot YP. \quad (2.8)$$

This is a system of $n \times m$ differential equations. If we solve this system together with system (1.1), we are able to compute

$$A(p) = \frac{\partial}{\partial p} y(t_i, p), \quad (2.9)$$

an $N \times m$ matrix, giving the dependence of $Y(p)$ (see equation (1.2)) upon variations to p .

2.2. Minimizing $S(p)$

Consider the function $S(p)$ defined by equation (1.3). The value \bar{p} that minimizes $S(p)$ is an estimate of the true value p^* . In equation (1.3) y is a nonlinear function of p . Without some further assumptions the analysis would therefore be too involved to give hope of useful results. This difficulty is dealt with by assuming that p is a reasonably good approximation to \bar{p} . Using a generalized Newton-Raphson technique we linearize the nonlinearity for small departures δp from \bar{p} .

Suppose that p is a trial vector and δp is the required correction ($p + \delta p = \bar{p}$). The residual vector $Y(p)$ is approximated by a linear function of the parameter

$$Y(p) = Y(\bar{p} - \delta p) = Y(\bar{p}) - A \delta p$$

and for the residual function

$$\begin{aligned} S(\bar{p}) = S(p + \delta p) &= || Y(p + \delta p) ||^2 \\ &\approx || Y(p) + A(p) \delta p ||^2 \\ &= || Y ||^2 + 2\delta p^T A^T Y + \delta p^T A^T A \delta p \end{aligned}$$

The approximating function to $S(p)$ has a minimum at the point given by the normal equations

$$A^T(p)A(p)\delta p = - A^T(p) Y(p). \quad (2.10)$$

If the matrix $A^T A$ is nonsingular, this equation determines δp from $Y(p)$.

In the linear theory $p + \delta p$ so determined would be the required solution and the minimum value of S attained there would

be

$$S(\bar{p}) = ||Y(p)||^2 - \delta p^T A^T A \delta p \quad (2.11)$$

In general, $S(p+\delta p)$ will not be the minimal value of S and the whole process is repeated using $p+\delta p$ as an approximation to \bar{p} for the next iteration.

The process we use has the same order of convergence as quasilinearization has (see: Bellman and Kalaba [1965]). The latter process often is called quadratically convergent. In fact, both processes have 2nd order convergence only in the case that the observed values are exact in all decimal places, otherwise they have 1st order convergence (Willems [1972]). So we prefer to speak of first order convergence.

If it appears that $S(p+\delta p) > S(p)$, some other techniques are applied. Firstly the method of steepest descent is used, with p as a point of departure. For this purpose the gradient vector $r = -A^T(p) Y(p)$ is calculated and a new trial step is executed with

$$\delta p = r ||r||^2 / ||Ar||^2$$

If even with this δp it appears that $S(p+\delta p) > S(p)$, the direction of the step is not changed, but a relaxation factor is used, the step δp is multiplied by $S(p)/(S(p)+S(p+\delta p))$ and a new trial step is executed from p .

3. Statistics

Let \bar{p} be the final estimate of p so that $S(p) \geq S(\bar{p})$ for all p : we assume that the linear theory holds in a sufficient large neighbourhood of \bar{p} .

For the perturbations η_i of the observed values y_i we assume an $N(0, \sigma^2)$ distribution and so it follows from equation (2.10) that

the estimated value \bar{p} will also be normally distributed. We define $\delta p = \bar{p} - p^*$, hence the expectation of δp will be zero when $p = \bar{p}$. We are also interested in the covariance matrix of δp , i.e. the expected value of $\delta p \delta p^T$.

$$\begin{aligned} E(\delta p \delta p^T) &= E((A^T A)^{-1} A^T Y Y^T A (A^T A)^{-1}) = \\ &= (A^T A)^{-1} A^T E(Y Y^T) A (A^T A)^{-1} = \sigma^2 (A^T A)^{-1}. \end{aligned}$$

From this covariance matrix we derive r_{ij} , the correlations between the estimates δp_i and δp_j .

$$r_{ij} = \frac{q_{ij}}{\sqrt{q_{ii} q_{jj}}} \quad \text{with } q_{ij} = (A^T A)_{ij} \quad (3.1)$$

By equation (2.10) δp is a linear function of Y . Hence its probability density will be Gaussian and will be given by

$$P(\delta p) = ((2\pi\sigma)^m \det((A^T A)^{-1}))^{-\frac{1}{2}} \exp(-\delta p^T A^T A \delta p / 2\sigma^2)$$

From (2.11) follows immediately

$$||Y(\bar{p} + \delta p)||^2 = S(\bar{p}) + \delta p^T A^T A \delta p.$$

Now it is clear that $||Y||^2/\sigma^2$, $\delta p^T A^T A \delta p/\sigma^2$ and $S(\bar{p})/\sigma^2$ have a χ^2 distribution with N , m and $N-m$ degrees of freedom, respectively. An estimate of σ^2 is given by

$$s^2 = S(\bar{p})/(N-m) = ||Y(\bar{p})||^2/(N-m) \quad (3.2)$$

The confidence region at level α is the ellipsoidal region

$$\delta p^T A^T A \delta p \leq \frac{m}{N-m} S(\bar{p}) F_\alpha(m, N-m), \quad (3.3)$$

where $F_\alpha(n, N-m)$ is the α -point of the F-distribution with m and $N-m$ degrees of freedom.

The principal axes of the ellipsoidal region are given by the eigenvectors of $A^T A$ and the length of the axes is $\lambda_i^{-1/2}$ (λ_i is the eigenvalue of the corresponding eigenvector).

The confidence limits for each estimate, supposing that the other estimates are exact, are

$$\bar{p}_i \pm \delta p_i$$

where

$$\delta p_i = \sqrt{\frac{m}{N-m} S(\bar{p}) F_\alpha / (A^T A)_{ii}} \quad (3.4)$$

Other confidence limits for the individual estimates (independently) are

$$\bar{p}_i \pm \delta p_i^*$$

where

$$\delta p_i^* = \sqrt{\frac{m}{N-m} S(\bar{p}) F_\alpha (A^T A)_{ii}^{-1}} \quad (3.5)$$

The geometrical interpretation is that the tangent planes to the ellipsoid with normals to the direction i are at a distance δp_i^* from the centre of the ellipsoid and that the axis i intercepts the ellipsoid at points δp_i from the centre. Clearly $\delta p_i \leq \delta p_i^*$.

4. Integration of the differential equations

The system of the differential equations which we have to solve in each iteration step of the optimizing process is, in general, a rather large one. In the system we distinguish two parts

1. [see equation (1.1)]

$$\frac{d}{dt} y(t,p) = f(t,y,p) \quad (4.1)$$

a coupled system of n differential equations.

2. [see equation (2.8)]

$$\frac{d}{dt} YP = FP + FY.YP \quad (4.2)$$

This is a set of m systems; each system consists of n differential equations and is coupled with system (4.1).

The structure of the system (4.1-4.2) as a whole can be clarified by writing:

1) the system (4.1 - 4.2) as

$$\begin{aligned} \dot{y} &= f \\ \dot{y}_{p1} &= f_{p1} + f_y y_{p1} \\ &\vdots \\ \dot{y}_{pm} &= f_{pm} + f_y y_{pm} \end{aligned} \quad (4.3)$$

where $y_{pi} = \partial y / \partial p_i$, $f_{pi} = \partial f / \partial p_i$ and

$f_y = \partial f / \partial y$ the Jacobian matrix of the system (4.1).

and by writing

2) the Jacobian matrix of the system (4.1-4.2) as

$$J = \begin{pmatrix} f_y & 0 & \dots & 0 \\ f_{py1} & f_y & & 0 \\ \vdots & & \ddots & \\ f_{pym} & 0 & & f_y \end{pmatrix}, \quad (4.4)$$

where $f_{pyi} = \partial(\partial f / \partial p_i) / \partial y$.

In this Jacobian matrix the one way coupling of the system is clearly demonstrated. Besides we notice that the eigenvalues of J are all the same as the eigenvalues of f_y , and so the stability behaviours of system (4.3) and system (4.4) are similar.

In order to solve the system, linear multistep methods are used. Essentially, the integrating procedure used ("multistep"), is the same as the one described in Hemker [1971]. This procedure uses variable steplength and variable order. In the case of stiff differential equations the procedure switches from Adams-Moulton to stiffly stable methods.

In order to solve (4.3) efficiently, we make use of the particular structure mentioned. In each step of the integrating process, equation (4.1) is solved as a independent system. When this part

of the integration has been successfully completed, the m systems of equations (4.2) can be solved with only a little work. We will show this in more detail.

Since we only use implicit linear multistep methods, the solution of one integration step

$$\dot{y} = f(y)$$

corresponds to the solution of the nonlinear equation

$$y_n = h\beta f(y_n) + \phi_n, \quad (4.4^a)$$

where ϕ_n contains the information about a number of completed steps. After the choice of a suitable starting value ${}_0y_n$, this equation is solved with a modified Newton-Raphson method

$${}_{r+1}y_n = {}_ry_n - (I - h\beta f_y)^{-1}({}_ry_n - \phi_n - h\beta f({}_ry_n)). \quad (4.5)$$

When we solve the system of differential equations

$$\begin{aligned} \dot{y} &= f(y) \\ \dot{w} &= g(y) + f_y w \end{aligned}$$

we make use of the one-way coupling of the system. In each step, we have to solve the nonlinear system

$$y_n = h\beta f(y_n) + \zeta_n \quad (4.6)$$

$$w_n = h\beta g(y_n) + h\beta f_y(y_n) \cdot w_n + \psi_n \quad (4.7)$$

We do not iterate this system simultaneously, but we solve the nonlinear equation (4.6) by the iteration process (4.5), we substitute the computed value of y_n in (4.7), and we solve the linear equation (4.7) directly. For the solution of this linear equation one needs $(I - h\beta f_y(y_n))^{-1}$: the same factor that will be used in (4.5).

The solution of the system (4.3) is obtained in the same way. In

each step of the integration process, the first system of n equations (4.1) is solved by iteration. When this iteration has been completed, each of the m systems of the n equations (4.2) is solved directly. Each one of these m systems needs the L-U-decomposition of one and the same matrix $I-h\beta f_y(y_n)$. Moreover, this L-U-decomposition can be used again in the next modified Newton-Raphson iteration. This implies that each step in the solution of (4.3) only involves:

- i) 1 or more (up to 3) evaluations of f .
- ii) 1 evaluation of f_{p_i} , for $i = 1, a, \dots, m$.
- iii) 1 evaluation of f_y .

Each evaluation of f_y involves an L-U-decomposition of $I-h\beta f_y$ and each evaluation of f or f_{p_i} involves an execution of the second stage of the Gaussian elimination.

When, during an integration step, it appears that the iteration process (4.5) does not converge or that the local error bound is exceeded, the step length is changed and the work mentioned in i) and iii) has to be repeated.

We notice that the possibility of coupling the integration of (4.2) with the integration of (4.1) with this ease, depends crucially on the form of the linear integration formula (4.4^a). It cannot be done, for instance, with Runge-Kutta methods.

We use another feature of the integration method. On an interval containing some meshpoints, the linear multistep methods approximate the solution of the differential equation to a polynomial of a certain degree. As a consequence, there is no need to take the meshpoints of our integrating procedure together with the points $\{t_i\}$ where the solution is wanted. The solution is obtained by interpolating the approximating polynomial.

5. The procedure odeparest

5.1. General remarks, users manual

Although we know that the iteration process has first order convergence, it is evident that in most practical (nonlinear) problems, we cannot say anything about the a priori fitness

of a first estimate. This reason, and others that make parameter estimation an art rather than only a computing technique, lead us to give the output of the procedure in printed form. This prevents the use, without inspection, of the results as a starting point for further calculations.

INPUT

The input of the procedure can be divided into four parts:

1. The system of differential equations which defines the problem, together with its initial values.
2. The observations to which the parameters will be adjusted.
3. A first estimate of the parameters, together with some upper and lower bounds for them.
4. Some actual parameters of the procedure, by which the optimizing and integration processes will be controlled and one actual parameter which specifies the confidence region desired.

Now we shall treat these four items in detail.

1) The system of differential equations defining the problem has to be supplied by the user as a set of sub-procedures for the procedure `odeparest`. Four procedures are needed:

- a) a procedure which identifies the function f (see equation 1.1).

This is a procedure with the heading procedure call `f(r); value r; real r;`.

By this procedure the values of the left hand part of (1.1), multiplied by the real value r , will be assigned to the array elements of `f[1:n]`.

- b) a procedure which identifies the Jacobian matrix of the vector-function f . (I.e. f_y in the equations 4.3 and 4.4).

This is a procedure with the heading procedure call `fy(r); value r; real r;`.

By this procedure the values of the partial derivatives of f_i with respect to y_j multiplied by a real value r , will be assigned to the array element `fy[i,j]`.

- c) a procedure which identifies the partial derivatives of f with respect to p .

This is a procedure with the heading procedure call $fp(r)$; value r ; real r ;

By this procedure the value of $\partial f_i / \partial p_j * r$ will be assigned to the array element $fp[1,j]$.

- d) a procedure by which the initial values of equation (1.1) are supplied.

This is a procedure with the heading procedure call $ystart$;

By this procedure the initial values of y are assigned to the array elements $y[0,i]$ ($1 \leq i \leq n$). However, the procedure has to do another job: some positive values have to be assigned to the array elements $y_{max}[i]$ ($1 \leq i \leq n$). The desired value of $y_{max}[i]$ corresponds to an estimate of the maximal absolute value of y on the integration interval. If no estimate can be given, the value 1 can be assigned. (For a detailed description of the use of y_{max} see the manual for the ALGOL 60. procedure MULTISTEP, Hemker [1971]).

- N.B. 1. Note that the structure of the system is completely determined by f , f_y and f_p can be derived from f . However, by supplying f_y and f_p in an analytic form, we are able to solve our problem efficiently.
- N.B. 2. f , f_y and f_p are functions of t , y and p . These values of t , y and p can be obtained from the identifiers (array elements) x , $y[0,i]$ ($1 \leq i \leq n$) and $par[i]$ ($1 \leq i \leq m$) respectively.
- N.B. 3. The initial values may be functions of the parameters p . In that case the initial values of $\partial y / \partial p$ also have to be supplied; thus it is useful to know that $\partial y_i / \partial p_j$ corresponds with $y[0,n*j+i]$.
- N.B. 4. Since procedure call $ystart$ is only called once during the integration of an interval, and since "call f ", "call f_y " and "call f_p " are used many times, assignments of the constant value zero to an element of f , f_y or f_p will be placed in "call $ystart$ ".

- 2) The observations to be fitted to, and
- 3) the first estimate, upper- and lower-bounds of the parameters, are asked for by means of a call of the procedure 'data' from the formal parameter list of the procedure 'odeparest'.

The actual declaration of this procedure has the heading

```
procedure data (nobs, tobs, cobs, obs, npar, parlbd,  
                par, parubd);
```

```
integer nobs, npar; integer array cobs;
```

```
array tobs, obs, parlbd, par, par ubd;.
```

nobs and npar are inputparameters, indicating the number of parameters, m, respectively. For each observation a value is assigned to

tobs[i], cobs[i] and obs[i] ($1 \leq i \leq \text{nobs}$)

tobs[i] - the time of observation

cobs[i] - the component of y observed ($1 \leq \text{cobs}[i] \leq n$)

obs[i] - the observed value of the component cobs[i] of y at the time tobs[i].

If the time, corresponding to the starting values (given in 'call ystart') does not equal zero, this time has to be provided in tobs[0].

The observations have to be ordered such that tobs[i] \leq tobs[j] if $i \leq j$.

For each parameter in the system (1.1), values are assigned to

parlbd[i], par[i] and parubd[i] ($1 \leq i \leq \text{npar}$)

par[i] - a first estimate of the i-th parameter.

parlbd[i] and parubd[i] - lower- and upper-bounds, respectively, for the parameter value.

N.B. 1. The procedure 'odeparest' only solves the unconstrained optimization problem; parlbd and parubd are provided only to prevent some unwanted effects (e.g. f, fy and fp may be undefined outside the indicated parameter region).

N.B. 2. If the value of 'nobs' is decreased by the procedure 'data', only the first 'nobs' (new value) observations will be used during the calculation.

If the value of 'npar' is decreased by the procedure 'data', only the first 'npar' (new value) parameters will be adjusted.

4) Before we explain the formal procedure parameters of the procedure 'odeparest', by which the process is controlled, we give the heading of the procedure:
procedure odeparest (n, nobs, npar, data, itmax, converge, eps, meshp, stiff, fa);
value n, nobs, npar, itmax, converge, eps, meshp, stiff, fa);
integer n, nobs, npar, itmax, meshp; real converge, eps, fa;
boolean stiff; procedure data;

The actual parameters corresponding to the formal parameters are:

n : < integer expression >;
the number of equations of system (1.1).
nobs : < integer expression >;
the number of observations: N.
npar : < integer expression >;
the number of parameters: m.
data : < procedure >;
this procedure is described in item 2 and 3.
itmax : < integer expression >;
the maximum number of iterations of the optimization process.
converge : < real expression >;
The optimization process is deemed to have converged if the final (estimated) improvement in $S(p)$ (i.e. $|S(p) - S(p + \delta p)|$) is less than

$$\text{converge} * S(p)$$

This test arises from the fact that the difference between $S(\bar{p})$ and $S(p)$, evaluated on the boundary of the confidence region, is

$$\frac{m}{N-m} F_{\alpha}(m, N-m) * S$$

It seems reasonable that some small function fraction of this should be used as convergence criterion.

- eps : < real expression >;
a parameter which controls the relative local error bound during the integration process. During the last iteration step of the optimazing process eps is replaced by eps/10.
- meshp : < integer expression >;
the maximal number of meshpoints that will be used by the integrating procedure, between two different observation times tobs[i] and tobs[i+1].
- stiff : < boolean expression >;
In order to make efficient use of the integrating procedure, 'stiff' can be set true, if the user knows that stiff differential equations will be integrated.
- fa : < real expression >;
 $F_{\alpha}(m, N-m)$, fa is the α -point of the F-distribution with npar and nobsnpar degrees of freedom. The confidence regions at level α will be printed.

OUTPUT.

As we mentioned before, a call of procedure 'odeparest' only results in some printed output.

This printout can be of three kinds.

- 1) Results for each iteration, associated with the fitting of the data.
- 2) Diagnostic printout.
- 3) Final results, which include parameter values, confidence regions, correlation- and covariance-matrices.

We describe the printout in more detail.

- 1) An iteration is called successful, if $S(p_{\text{new}}) < S(p_{\text{old}})$ holds for the new estimate p_{new} of \bar{p} .
 - a) Each successful iteration results in the printout 'iteration number' and the number of the iteration performed. The following additional results will be

'computed residue': $\|Y(p)\|_2^2$ (see equation (1.2))

'computed standard error': $(\|Y(p)\|_2^2/(N-m))^{1/2}$

'estimated residue' : $\|Y(p+\delta p)\|_2^2$

'estimated standard error': $(\|Y(p+\delta p)\|_2^2/(N-m))^{1/2}$

'corrections for parameters': δp_i ($1 \leq i \leq m$)

'parameter value': $(p+\delta p)_i$ ($1 \leq i \leq m$)

These additional results will also be printed after the messages:

b) 'boundary constraints jump':

the calculated new parameter value violates the boundary constraints. Linear interpolation gives the maximal permissible jump in the computed direction.

c) 'plus ultra':

even on the boundaries of the permissible region the minimizing vector \bar{p} seems to be beyond these boundaries.

d) 'steepest descent':

the last iteration step was not successful. The old value of p is maintained and a step according to the method of the steepest descent is executed.

e) 'relation par':

even steepest descent was unsatisfactory; the last jump is repeated with a relaxation factor $S(p)/(S(p)+S(p+\delta p))$.

2) Diagnostic printouts are:

'strong nonlinearity'

The differential equation seems to be a very nonlinear one. This may result in a long computing time, since integration is continued with a smaller steplength than specified by 'meshp'. This diagnostic can be avoided by choosing a larger value for 'meshp'. However, this will not avoid the evil. This diagnostic also can appear when f_y doesn't represent the Jacobian matrix correctly.

'linear dependence in (dy/dp) [i]'

The matrix $A^T A$ seems to be singular. The initial estimate or the set of sample-times $\{tobs[i]/1 \leq i \leq N\}$ are not appropriate to solve the problem. This diagnostic

may also occur if fp is not represented correctly.

'the equation was found to be stiff at t='

This message is only given if the formal parameter stiff \equiv false. If the equation appears to be stiff in the greater part of the integration, it will be efficient to set stiff \equiv true.

'some little problems with stiffness < number >'

This message is given if a stiff differential equation is solved. The < number > indicates the number of times that the relative local error bound eps is exceeded. If it is a large number (\approx meshp) it may be better to choose a larger number for meshp.

- 3) During the last two iterations, information about the confidence region and the linear correlation between the parameters is printed.

This information involves:

- a) the conditional confidence interval:
the values δp_i (see equation 3.4).
- b) the independent confidence interval:
the values δp_i^* (see equation 3.5).
- c) the correlation matrix,
- d) the covariance matrix and
- e) the principal axes of the confidence region.

For detailed information see section 3.

The last iteration is a special one. It computes $y(t_i, p)$ with an accuracy $\text{eps}/10$ and it computes $p+\delta p$ even in the case $S(p+\delta p) \neq S(p)$.

5.2. The procedure text

```
procedure odeparest(n,nobs,npar,data,itmax,converge,eps,meshp,stiff,fa);
value n,nobs,npar,itmax,converge,eps,meshp,stiff,fa;
integer n,nobs,npar,itmax,meshp; real converge,eps,fa; boolean stiff;
begin comment The procedures: call ystart,call f,call fy,call fp
  define the problem supplied by the user.
  The four procedures inserted here only are examples;
  procedure call ystart;
  begin y[0,1]:= ymax[1]:= ymax[2]:= 1; y[0,2]:= 0 end;

  procedure call f(r); value r; real r;
  begin f[1]:= -rx((1-y[0,2])xy[0,1] - par[2]xy[0,2]);
        f[2]:= rxpar[1]x((1-y[0,2])xy[0,1] -
                        (par[2]+par[3])xy[0,2])
  end;

  procedure call fy(r); value r; real r;
  begin fy[1,1]:= -rx(1-y[0,2]);
        fy[1,2]:= rx(par[2]+y[0,1]);
        fy[2,1]:= rxpar[1]x(1-y[0,2]);
        fy[2,2]:= -rxpar[1]x(par[2]+par[3]+y[0,1]);
  end;

  procedure call fp(r); value r; real r;
  begin fp[1,1]:= 0; fp[1,2]:= rxy[0,2]; fp[1,3]:= 0;
        fp[2,1]:= rx((1-y[0,2])xy[0,1] - (par[2]+par[3])xy[0,2]);
        fp[2,2]:= -rxpar[1]xy[0,2];
        fp[2,3]:= -rxpar[1]xy[0,2]
  end last procedure declared by the user;

array y[0:7,1:nx(npar+1)],ymax,f[1:n],fy[1:n,1:n],fp[1:n,1:npar];
proc pr(s); begin nclr; printtext(s) end;
proc fl(r); flot(5,3,r);
proc pf(s,r); begin pr(s); tab; fl(r) end;

proc out(s,r); string s; real r;
begin int i; if linenumber>50 then new page else nclr;
  pr(s); print(r);
  pf({computed residue (stand.dev.)},comp error);
  fl(sqrt(comp error/(nobs-npar)));
  pf({estimated residue (stand.dev.)},est error);
  fl(sqrt(est error/(nobs-npar)));
  pr({corrections for parameter}); tab;
  for i:=1 step 1 until npar do fl(delta par[i]); nclr;
  pr({parameter value}); tab; tab;
  for i:= 1 step 1 until npar do fl(par[i]);
end;

boolean first,adams; integer k,kold,same,fails;
real x,xold,h,ch,hold,tolconv,tolup,tol,toldwn,a0;
array a[0:7],dd[0:7,0:n],last delta[1:n], jac[1:n,1:n],const[1:45],
  tobs[0:nobs],obs[1:nobs],par1,par,paru[1:npar];
int array cobs[1:nobs],pp[1:n];
```

```

procedure multistep(xend,hmin,hmax,eps);
value xend,hmin,hmax,eps; real xend,hmin,hmax,eps;
begin comment This sub-procedure 'multistep' is essentially the same
as the procedure 'MULTISTEP' described in Hemker[1971];

boolean conv; integer i,j,l,knew,np;
real chnew,c,error,dfi; array delta,df,y0[1:n];

procedure method;
begin dd[0,0]:= if adams then -10600 else x; i:= k:= 1;
  if adams then
    begin for const[i]:= 1,1,12,2,1,.5,1,.5,24,12,1,5/12,1,.75,
      1/6,37.89,24,2,.375,1,11/12,1/3,1/24,53.33,37.89,1,
      251/720,1,25/24,35/72,5/48,1/120,70.08,53.33,.3158,
      95/288,1,137/120,.625,17/96,.025,1/720,0,70.08,
      .07407 do i:= i + 1
    end else
    begin for const[i]:= 1,1,3,2,1,2/3,1,1/3,6,4.5,1,6/11,1,
      6/11,1/11,9.167,7.333,0.5,.48,1,.7,.2,.02,12.5,
      10.42,.1667,120/274,1,225/274,85/274,15/274,1/274,
      15.98,13.7,.04167,180/441,1,58/63,5/12,25/252,
      3/252,1/1764,0,17.15,.008333 do i:= i + 1
    end
  end method;

procedure order;
begin j:= (k-1) × (k+8) / 2 + 1;
  for i:= 0 step 1 until k do a[i]:= const[i+j]; a0:= a[0];
  tolup := (eps×const[j+k+1])2;
  tol := (eps×const[j+k+2])2;
  toldwn:= (eps×const[j+k+3])2;
  tolconv:= eps/(2×n×(k+2));
  same:= k+1
end order;

procedure evaluate jacobian;
begin call fy( -a0×h);
  for i:= 1 step 1 until n do
    for j:= 1 step 1 until n do jac[i,j]:= fy[i,j];
  for i:= 1 step 1 until n do jac[i,i]:= jac[i,i] + 1;
  det(jac,n,pp)
end evaluate jacobian;

procedure calculate step and order;
begin real a1,a2,a3; same:= 10;
  a1:= if k<1 then 0 else
    0.75×(toldwn/sum(i,1,n,(y[k,i]/ymax[i])2))(0.5/k);
  a2:= 0.80×(tol /error) (0.5/(k+1));
  a3:= if fails≠0 then 0 else
    0.70×(tolup /sum(i,1,n,((delta[i]-last delta[i])/
      ymax[i])2))(0.5/(k+2));
  if a1>a2 ∧ a1>a3 then begin knew:=k-1; chnew:=a1 end else
  if a2>a3 then begin knew:=k ; chnew:=a2 end else
  begin knew:=k+1; chnew:=a3 end
end calculate step and order;

```

```
procedure reset step;
begin real c;
  if ch < hmin/hold then ch:= hmin/hold else
  if ch > hmax/hold then ch:= hmax/hold;
  x:= xold; h:= hold × ch; c:= 1;
  for j:=0 step 1 until k do
  begin for i:=1 step 1 until n do y[j,i]:= dd[j,i] × c;
  c:= c × ch
  end;
  evaluate jacobian;
  same:= k + 1
end reset step;

procedure begin;
begin hold:= h:= hmin; ch:= 1; call f(h);
  for i:= 1 step 1 until n do
  begin dd[0,i]:= y[0,i]; dd[1,i]:= y[1,i]:= f[i] end;
  fails:= kold:= 0; k:= 1; order; evaluate jacobian
end begin;

if first then
begin first:= false; adams:= 7stiff; method;
  xold:= x; begin; for i:= 1,2,3 do dd[i,0]:= 0
end;

for l:= 0 while x<xend do
begin x:= x+h;

  comment prediction;
  for i:=0 step 1 until k-1 do
  for j:= k-1 step -1 until i do
  elmrow(1,n,j,j+1,y,y,1);
  for i:= 1 step 1 until n do delta[i]:= 0;

  comment correction and estimation local error;
  for l:=1,2,3 do
  begin call f(h);
  for i:=1 step 1 until n do df[i]:= f[i] - y[1,i];
  sol(jac,n,pp,df);

  conv:= true;
  for i:= 1 step 1 until n do
  begin dfi:= df[i];
  y[0,i]:= y[0,i] + a0×dfi;
  y[1,i]:= y[1,i] + dfi;
  delta[i]:= delta[i] +dfi;
  conv:= conv ∧ abs(dfi) < tolconv × ymax[i]
  end;
  if conv then
  begin error:= sum(i,1,n,(delta[i]/ymax[i])2);
  goto convergence
  end
end;
end;
```



```
comment acceptance or rejection;
if  $\neg$ conv then no convergence:
begin if  $h < h_{min} \times 1.0001$  then
    begin pr( $\{$  strong nonlinearity $\}$ );  $h_{min} := h_{min}/4$  end;
     $ch := ch/4$ ; reset step
end else convergence:

if  $error > tol$  then error test not ok:
begin fails := fails + 1;
    if  $h > h_{min} \times 1.0001$  then
    begin if fails  $> 2$  then
        begin  $k := 0$ ; reset step; begin end else
        begin calculate step and order;
            if  $knew \neq k$  then begin  $k := knew$ ; order end;
             $ch := ch \times ch_{new}/fails$ ; reset step
        end
    end else
    if adams then
    begin adams := false; method; order; reset step end else
    if  $k \neq 1$  then
    begin  $k := 1$ ; order; reset step end else
    begin  $dd[2,0] := dd[2,0] + 1$ ; goto error test ok end
end else

error test ok:
begin fails := 0;
    if  $k > 2$  then begin for  $i := 1$  step 1 until n do
        elmcolvec(2,k,i,y,a,delta[i]) end;
    for  $i := 1$  step 1 until n do if  $abs(y[0,i]) > y_{max}[i]$ 
        then  $y_{max}[i] := abs(y[0,i])$ ;
    same := same - 1;
    if same = 1 then begin for  $i := 1$  step 1 until n do
        last delta[i] := delta[i] end else
    if same = 0 then
    begin calculate step and order;
        if  $ch_{new} > 1.1$  then
        begin same := k + 1;
            if  $knew \neq k$  then
            begin if  $knew > k$  then
                begin for  $i := 1$  step 1 until n do
                     $y[knew,i] := delta[i] \times a[k]/knew$ 
                end;
                 $k := knew$ ; order
            end;
            if  $ch_{new} > h_{max}/h$  then  $ch_{new} := h_{max}/h$ ;
             $h := h \times ch_{new}$ ;  $c := 1$ ;
            for  $j := 1$  step 1 until k do
            begin  $c := c \times ch_{new}$ ;
                for  $i := 1$  step 1 until n do
                     $y[j,i] := y[j,i] \times c$ 
                end
            end
        end
    end
end;
end;
end;
```

```
for i:= 1 step 1 until n do
  for j:= 0 step 1 until k do dd[j,i]:= y[j,i];

  if h $\neq$  hold then
  begin ch:= h/hold; c:= 1;
    for j:= 1 step 1 until kold do
      begin c:= cxch;
        for i:= n+1 step 1 until nmp do
          y[j,i]:= y[j,i]xc;
        end; hold:= h;
      end;
    if k>kold then
      for i:= n+1 step 1 until nmp do y[k,i]:= 0;
      kold:= k; xold:= x; ch:= 1;

    evaluate jacobian; call fp(h);

    for i:= 0 step 1 until k-1 do
      for j:=k-1 step -1 until i do
        elmrow(n+1,nmp,j,j+1,y,y,1);

    for j:= 1 step 1 until npar do
      begin np:= jxn;
        for i:=1 step 1 until n do y0[i]:= y[0,np+i];
        for i:=1 step 1 until n do df[i]:=
          fp[i,j] - matvec(1,n,i,fy,y0)/a0 - y[1,np+i];
        sol(jac,n,pp,df);
        for i:=1 step 1 until n do
          elmcolvec(0,k,np+i,y,a,df[i]);
        end;
      end
    end step
  end multistep;

  integer i,j,l,cobi,iteration,nmp; bool further;
  real old comp error,comp error,est error,tobsdif,bound,b,r;
  array aux[0:2],em[0:5],delta par,aid,val[1:npar], delta obs[1:nobs],
  aa[1:nobs,1:npar],ata,q[1:npar,1:npar]; int array ci,ich[1:npar];

  aux[0]:= 10-10; em[0]:= 10-11; em[2]:= 10-8; em[4]:= 5xnpar;
  old comp error:= 10600; further:= true; tobs[0]:= 0;
  data(nobs,tobs,cobs,obs,npar,parl,par,paru);
  nmp:= n + nxnpar; b:= faxnpar/(nobs-npar);
```

```
for iteration:= 1, iteration+1 while further, iteration do
begin if  $\neg$ further then eps:= eps/10;

comment integration of the differential equations;
for i:= n+1 step 1 until nmp do y[0,i]:= 0; x:= tobs[0];
call ystart; first:= true;
for i:= 1 step 1 until nobobs do
begin tobsdif:= tobs[i] - tobs[i-1]; if tobsdif>0 then
multistep(tobs[i], tobsdif/meshp, tobsdif, eps);
tobsdif:= (tobs[i] - x)/h; cobi:= cobs[i];
delta obs[i]:= obs[i] - sum(1,0,k,y[1,cobi]xtobsdifl);
for j:= 1 step 1 until npar do
aa[i,j]:= sum(1,0,k,y[1,nxj+cobi]xtobsdifl);
end;

comment diagnostic printout;
if further then else
for i:= 1 step 1 until nobobs do obs[i]:= delta obs[i];
if  $\neg$ stiff  $\wedge$  dd[0,0]  $\neq$  600 then
pf( $\{$ the equation was found to be stiff at x =  $\}$ , dd[0,0]);
if dd[2,0]  $\neq$  0 then
begin pf( $\{$ some little problems with stiffness $\}$ , dd[2,0]); nlcrend;

comment minimization;
comp error:= sum(i,1,nobobs,delta obs[i]2);
old comp error:= old comp error*(1+eps);
if  $\neg$ further  $\vee$  comp error<old comp error then
begin comment least squares;
if npar  $\neq$  lsqdec(aa,nobobs,npar,aux,aid,ci) then
begin pr( $\{$ linear dependence in (dy/dp)[i] $\}$ );
further:= false; goto end iteration
end;
lsqsol(aa,nobobs,npar,aid,ci,delta obs);
for i:= 1 step 1 until npar do
begin delta par[i]:= delta obs[i];
par[i]:= par[i] + delta par[i]
end;
est error:= sum(i,npar+1,nobobs,delta obs[i]2);
out( $\{$ iteration number $\}$ , iteration);
end else if est error  $\neq$  0 then
begin comment steepest descent;
for i:= 1 step 1 until npar do
begin ata[i,i]:= tammat(1,i-1,i,i,aa,aa)+aid[i]2;
par[i]:= par[i]-deltapar[i];
for j:= i+1 step 1 until npar do ata[i,j]:=
ata[j,i]:= tammat(1,i-1,i,j,aa,aa)+aa[i,j]xaid[i];
end;
for i:= npar step -1 until 1 do if ci[i]  $\neq$  i then
begin ichcol(1,npar,i,ci[i],ata);
ichrow(1,npar,i,ci[i],ata)
end;
end;
```

```
for i:= 1 step 1 until npar do
    val[i]:= matvec(1,npar,i,ata,deltapar);
for i:= 1 step 1 until npar do
    aid[i]:= matvec(1,npar,i,ata,val);
r:= vecvec(1,npar,0,val,val)/vecvec(1,npar,0,val,aid);
for i:= 1 step 1 until npar do
    begin deltapar[i]:= bound:= r × val[i];
        par[i]:= par[i] + bound
    end; est error:= 0;
out(⟨steepest descent⟩,r)
end else
begin r:= comp error/(old comp error + comp error);
    if r > .99 then r:= .99;
    for i:= 1 step 1 until npar do
        begin par[i]:= par[i] - r×deltapar[i];
            delta par[i]:= deltapar[i]×(1-r)
        end; iteration:= iteration + 1;
    eps:= eps/2; further:= iteration < itmax;
    out(⟨relaxation par⟩,1-r);
    goto end iteration
end;

comment constraints; r:= 1;
for i:= 1 step 1 until npar do
    begin if par[i]<parl[i] then bound:=parl[i]-par[i] else
        if par[i]>paru[i] then bound:=paru[i]-par[i] else
            goto through; bound:= 1+bound/deltapar[i];
        if bound<r then r:= bound; through:
    end;
    if 0 < r ∧ r < 1 then
        begin for i:= 1 step 1 until npar do
            begin par[i]:= par[i] + (r-1)× delta par[i];
                deltapar[i]:= deltapar[i]×r
            end;
            est error:= est error + r×r×(comp error - est error);
            out(⟨boundary constraints. jump⟩,r);
        end else if r<0 then
            begin for i:= 1 step 1 until npar do
                if par[i]<parl[i] then par[i]:= parl[i] else
                    if par[i]>paru[i] then par[i]:= paru[i];
                out(⟨plus ultra⟩,r);
            end;

further:= further ∧ iteration < itmax-1 ∧
    comp error - est error > converge × est error;
```

```
comment statistics;
if 7 further then
begin for i:= 1 step 1 until npar do
  begin ata[i,i]:= q[i,i]:=
    tammat(1,i-1,i,i,aa,aa) + aid[i]xaid[i];
    for j:= i+1 step 1 until npar do
      ata[i,j]:= ata[j,i]:= q[i,j]:=
        tammat(1,i-1,i,j,aa,aa) + aa[i,j]xaid[i];
    end;
  if qrisym(q,npar,val,em)≠0 then
    pr({qrisym doesnot converge});
  for i:= npar step -1 until 1 do if ci[i]≠i then
  begin ichcol(1,npar,i,ci[i],ata);
    ichrow(1,npar,i,ci[i],ata);
    ichrow(1,npar,i,ci[i],q)
  end;

  comment output;
  pr({confidence interval (cond.)}); tab;
  for i:= 1 step 1 until npar do
  fl(sqrt(bxest error/ata[i,i]));
  detinv(ata,npar);
  pr({confidence interval (indept.)}); tab;
  for i:= 1 step 1 until npar do
  fl(sqrt(bxest errorxata[i,i]));
  if linenumber + 2xnpar>53 then new page else nlc;
  pr({relationships between parameters});
  pr({correlation matrix}); space(22);
  printtext({covariance matrix});
  for i:= 1 step 1 until npar do
  begin nlc; for j:=1 step 1 until npar do
    begin if i=j then space(40); fl(if i>j then
      ata[i,j]/sqrt(ata[i,i]xata[j,j]) else ata[i,j])
    end;
  end; nlc;
pr({principal axes (direction cos and conf interval along each axis)});
  for i:= 1 step 1 until npar do
  begin nlc; for j:= 1 step 1 until npar do fl(q[j,i]);
    space(5); fl(sqrt(bxest error/val[i]))
  end; new page;

  end;
  old comp error:= comp error; end iteration:
end iteration;
```

```
tobsdif:= tobs[0];  
pr(residuals, specified for each observation,});  
for i:= 1 step 1 until nobs do  
begin r:= tobs[i]; if r>tobsdif then nlcr else tab;  
tobsdif:= r; absfixt(3,0,i); space(3); fl(obs[i])  
end  
end odeparest;
```

comment

Procedures used

In the body of procedure 'odeparest' a number of procedures are not declared. These procedures (library routines of the EL X8 system of the Mathematical Centre) are:

matvec, tamm~~at~~, elmrow, elmcolvec, ichrow, ichcol,
det, sol, detinv, lsqdec, lsqsol, qrisym
(see: Dekker [1968] and Dekker and Hoffmann [1968])

and:
nlcr, tab, space, print, printtext, absfixt, flot,
new page, linenum~~ber~~, sum
(see: Grune[1972]).

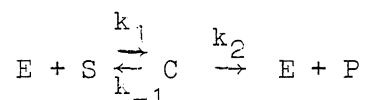
;

6 Problems solved

6.1. The ESCEP problem

Our first example originates from biochemistry.

A set of couples chemical reactions



is given : a catalyst E combines with a reactant S at one stage and is regenerated in a subsequent stage of the reaction. The problem is to find the rate constants k_1 , k_{-1} and k_2 from observations on the overall reaction rate (i.e. velocity of generation of the product P).

Rescaling the problem in some convenient way (see Heineken et al.[1967]), we obtain a description of the system as an initial value problem:

$$\begin{aligned} ds/dt &= -(1-c)s + qc \\ dc/dt &= M((1-c)s - (p+q)c) \\ s(0) &= 1 \quad , \quad c(0) = 0. \end{aligned}$$

Observations on $s(t)$ and $c(t)$ can be made and the unknown (positive) parameters M , p and q have to be determined.

In order to test our algorithm we generated some experimental values $s(t_i)$ and $c(t_i)$ ($i=1,2,\dots,23$) using the parameter values

$$\begin{aligned} M &= 1000 \quad , \\ p &= 0.99 \quad , \\ q &= 0.01 \quad . \end{aligned}$$

These parameter values require that we are dealing with a stiff system of differential equations.

We can distinguish a short initial period in which $c(t)$ increases rapidly and a period in which the steady state hypothesis holds. This represents a common type of enzymatic reaction in biochemistry : after a rapid generation of the complex C there is a period in which the Michaelis - Menten approximation holds.

We made five different tests:

- 1) we used 23 observations on each of the two components of the system, $s(t)$ and $c(t)$.

The observations were taken from the initial period as well as from the pseudo-steady state period.

- 2) Only the 23 observations on the component $c(t)$ were taken.
- 3) 12 observations were taken on the component $c(t)$ (every 2nd observation of test (2) was left out).
- 4) Only the 12 last observations from test (2) were used. All observations are in the pseudo-steady state region.
- 5) Only the 12 first observations from test (2) were used. Most observations were taken from the initial period.

We note that in tests 1), 2) and 3) our algorithm works highly accurate, since the quality of the observations was perfect : (a) four digits are correct (b) the observations contain information from the initial and from the pseudo-steady state period. In test 4) the parameter M is only approximately correct (1239 in stead of 1000) since this parameter, which is responsible for the initial period, is badly defined by the experimental observations.

In test 5) the parameter M is approximately correct but the other parameters are not determined at all since not enough information is available from the pseudo-steady state region.

NOTE : A component of the correlation matrix which approximately equals one, means that the algorithm cannot fix the parameter vector in some linear subspace of the parameter space.

B13681.138,PHEMKER,T150

```

1  BEGIN COMMENT THE ESCEP PROBLEM;
2
3  EQQC ODEPAREST(N,NOBS,NPAR,DATA,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
4  VAL N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA;
5  INT N,NOBS,NPAR,ITMAX,MESHP; BEAL CONVERGE,EPS,FA; BQQL STIFF;
6  BEGIN COMMENT THE PROCEDURES: CALL YSTART,CALL F,CALL FY,CALL FP
7  DEFINE THE PROBLEM SUPPLIED BY THE USER;
8
9  EQQC CALL YSTART;
10 BEGIN Y(0,1):= YMAX[1]; YMAX[2]:= 1; Y(0,2):= 0; OUTC
11 END;
12 EQQC CALL F(R); VAL R; BEAL R;
13 BEGIN CF:= CF+1;
14 F[1]:= -R*((1-Y(0,2))*Y(0,1) - PAR[2]*Y(0,2));
15 F[2]:= R*PAR[1]*((1-Y(0,2))*Y(0,1) - (PAR[2]+PAR[3])*Y(0,2))
16 END;
17 EQQC CALL FY(R); VAL R; BEAL R;
18 BEGIN FY[1,1]:= -R*(1-Y(0,2)); FY[1,2]:= R*(PAR[2]+Y(0,1));
19 FY[2,1]:= R*PAR[1]*(1-Y(0,2)); FY[2,2]:=-R*PAR[1]*(PAR[2]+PAR[3]+Y(0,1));
20 CFY:= CFY+1;
21 END;
22 EQQC CALL FP(R); VAL R; BEAL R;
23 BEGIN FP[1,1]:= 0; FP[1,2]:= R*Y(0,2); FP[1,3]:= 0;
24 FP[2,1]:= R*((1-Y(0,2))*Y(0,1) - (PAR[2]+PAR[3])*Y(0,2)); FP[2,2]:= -R*PAR[1]*Y(0,2);
25 FP[2,3]:=-R*PAR[1]*Y(0,2); CFP:= CFP+1
26 END;
27
28 ABBAY Y(0:7,1:N*(NPAR+1)),YMAX,F(1:N),FY(1:N,1:N),FP(1:N,1:NPAR);
29 EQQC PR(S); BEGIN NLCR; PRINTTEXT(S) END;
30 EQQC FL(R); FLOT(5,3,R);
31 EQQC PF(S,R); BEGIN PR(S) TAB; FL(R) END;
32
33 EQQC OUT(S,R); SIBING S; BEAL R;
34 BEGIN INT I; IF LINENUMBER>50 THEN NEW PAGE ELSE NLCR;
35 PR(S); PRINT(R);
36 PF(⟨COMPUTED RESIDUE (STAND.DEV.)⟩,COMP ERROR);
37 FL(SQRT(COMP ERROR/(NOBS-NPAR)));
38 PF(⟨ESTIMATED RESIDUE (STAND.DEV.)⟩,EST ERROR);
39 FL(SQRT(EST ERROR/(NOBS-NPAR)));
40 PR(⟨CORRECTIONS FOR PARAMETER⟩); TAB;
41 EQB I:=1 STEP 1 UNIL NPARG QO FL(DELTA PAR[I]); NLCR;
42 PR(⟨PARAMETER VALUE⟩); TAB; TAB;
43 EQB I:= 1 STEP 1 UNIL NPARG QO FL(PAR[I]);
44 END;
45
46 BQQL FIRST,ADAMS; INTEGER K,KOLD,SAME,FAILS;
47 BEAL X,XOLD,H,CH,HOLD,TOLCONV,TOLUP,TOL,TOLDWN,A0;
48 ABBAY A(0:7),DD(0:7,0:N),LAST DELTA(1:N), JAC(1:N,1:N),CONST[1:45],
49 TOBS(0:NOBS),OBS[1:NOBS],PARL,PAR,PARU(1:NPAR);
50 INT ABBAY COBS(1:NOBS),PP(1:N);
51
52 EQQC MULTISTEP(XEND,HMIN,HMAX,EPS);
53 VALUE XEND,HMIN,HMAX,EPS; BEAL XEND,HMIN,HMAX,EPS;
54
55 BEGIN BOOLEAN CONV; INTEGERS I,J,L,KNEW,NP;
56 BEAL CHNEW,C,ERROR,DF; ABBAY DELTA,DF,Y0(1:N);

```

```

357 TAMMAT(1,1-1,1,1,AA,AA) + AID(1)*AID(1);
358 EQB J:= 1+1 STEP 1 UNTIL NPAR DO
359 ATA(1,J):= ATA(J,1):= Q(1,J):=
360 TAMMAT(1,1-1,1,J,AA,AA) + AA(1,J)*AID(1);
361 END;
362 IE QR(SYM(Q\NPAR,VAL,EM)#0 THEN
363 PR(†QR(SYM DOESNOT CONVERGE†));
364 EQB I:= NPAR STEP -1 UNTIL 1 DO IE C(I)≠1 THEN
365 BEGIN ICHCOL(1,NPAR,1,C(I),ATA); ICHROW(1,NPAR,1,C(I),ATA);
366 ICHROW(1,NPAR,1,C(I),Q)
367 END;
368
369 COMMENT OUTPUT;
370 PR(†CONFIDENCE INTERVAL (COND,†)); TAB;
371 EQB I:= 1 STEP 1 UNTIL NPAR DO FL(SQRT(B*EST ERROR/ATA(1,I)));
372 DETINV(ATA,NPAR); PR(†CONFIDENCE INTERVAL (INDEPT,†)); TAB;
373 EQB I:= 1 STEP 1 UNTIL NPAR DO FL(SQRT(B*EST ERROR*ATA(1,I)));
374 IE LINENUMBER + 2*NPAR>53 THEN NEW PAGE ELSE NLCR;
375 PR(†RELATIONSHIPS BETWEEN PARAMETERS†);
376 PR(†CORRELATION MATRIX†); SPACE(22); PRINTTEXT(†COVARIANCE MATRIX†);
377 EQB I:= 1 STEP 1 UNTIL NPAR DO
378 BEGIN NLCR; EQB J:=1 STEP 1 UNTIL NPAR DO
379 BEGIN IE I=J THEN SPACE(40); FL(IE I>J THEN
380 ATA(1,J)/SQRT(ATA(1,I)*ATA(J,J)) ELSE ATA(1,J))
381 END;
382 END; NLCR;
383 PR(†PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS†));
384 EQB I:= 1 STEP 1 UNTIL NPAR DO
385 BEGIN NLCR; EQB J:= 1 STEP 1 UNTIL NPAR DO FL(Q(J,I));
386 SPACE(5); FL(SQRT(B*EST ERROR/VAL(1)))
387 END; NEW PAGE;
388 END;
389 OLD COMP ERROR:= COMP ERROR; END ITERATION;
390 END ITERATION;
391
392 TOBSDIF:= TOBS(0); PR(†RESIDUALS, SPECIFIED FOR EACH OBSERVATION,1);
393 EQB I:= 1 STEP 1 UNTIL NOBS DO
394 BEGIN R:= TOBS(I); IE R>TOBSDIF THEN NLCR ELSE TAB; TOBSDIF:= R;
395 ABSFIXT(3,0,1); SPACE(3); FL(OBS(I))
396 END
397 END ODEPAREST;
398
399 EBQC READ OBS AND PAR(NOBS,TOBS,COBS,OBS,NPAR,PARL,PAR,PARU);
400 BEGIN I=1; REAL R,S; NLCR; PR(†THE OBSERVATIONS WERE:†); PR(† I TOBS(I) COBS(I) OBS(I)†);
401 TOBS(0):= S:= READ; NLCR; ABSFIXT(3,0,0); SPACE(3); FL(TOBS(0));
402 EQB I:= 1 STEP 1 UNTIL NOBS DO
403 BEGIN TOBS(I):= R:= READ; COBS(I):= READ; OBS(I):= READ; IE R>S THEN NLCR ELSE TAB; S:= R;
404 ABSFIXT(3,0,1); SPACE(3); FL(R); FIXT(3,0,COBS(I)); SPACE(2); FL(OBS(I));
405 END; NLCR; NLCR; PR(†THE PARAMETER ESTIMATES WERE:†);
406 PR(† I PARLWB(I) PAR(I) PARUPB(I)†);
407 EQB I:= 1 STEP 1 UNTIL NPAR DO
408 BEGIN PARL(I):= READ; PAR(I):= READ; PARU(I):= READ; NLCR;
409 ABSFIXT(3,0,1); EQB R:= PARL(I),PAR(I),PARU(I) DO BEGIN FL(R); SPACE(2) END;
410 END; NEW PAGE;
411 END;
412
413 EBQC PR(S); BEGIN NLCR; PRINTTEXT(S) END;
414 EBQC P(S,R); BEGIN PR(S); TAB; PRINT(R) END;
415 EBQC FL(R); FLOT(5,3,R);
416 EBQC PF(S,R); BEGIN PR(S); TAB; FL(R) END;

```

```

417
418      INT CF,CFY,CFP;
419      ERQC OUTC;
420      BEGIN INI R; NLCR; SPACE(100); IE CF=0 THEN
421          BEGIN SPACE(6); PRINTTEXT(⟨EVALUATIONS OF⟨⟩); NLCR; SPACE(106);PRINTTEXT(⟨F      FY      FP⟩) END ELSE
422          EQB R:= CF,CFY,CFP DD ABSFIXT(6,0,R);
423          CF:= CFY:= CFP:= 0;
424      END;
425
426      ERQC JOB(N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
427      VAL N,NOBS,NPAR,ITMAX,CONVERGE,MESHP,STIFF,FA;
428      INI N,NOBS,NPAR,ITMAX,MESHP; REAL CONVERGE,EPS,FA; BQQL STIFF;
429      BEGIN REAL TIM;
430          PR(⟨PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:⟨⟩);
431          P(⟨N      =⟨⟩,N); P(⟨NPAR =⟨⟩,NPAR); P(⟨NOBS =⟨⟩,NOBS); P(⟨ITMAX=⟨⟩,ITMAX);
432          P(⟨CONVERGE =⟨⟩,CONVERGE); P(⟨EPS      =⟨⟩,EPS); P(⟨MESHP=⟨⟩,MESHP);
433          PR(⟨STIFF= ⟨⟩); TAB; IE STIFF THEN PRINTTEXT(⟨ IBUE⟨⟩) ELSE PRINTTEXT(⟨ EALSE⟨⟩);
434          P(⟨FA      =  ⟨⟩,FA); PR(⟨THE CONFIDENCE REGION AT LEVEL A IS PRINTED⟨⟩);
435          PR(⟨FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM⟨⟩);
436          NLCR; CF:= CFY:= CFP:= 0; TIM:= TIME;
437          ODEPAREST(N,NOBS,NPAR,READ OBS AND PAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
438          TIM:= TIME-TIM; OUTC; NLCR;NLCR; NLCR;
439          PR(⟨THE ENTIRE CALCULATION CONSUMED⟨⟩); ABSFIXT(3,2,TIM); PRINTTEXT(⟨SEC. ON THE EL X8.⟨⟩);
440      END JOB;
441
442          JOB(2,READ,3,16,0.01,=4,100,EALSE,4.28);
443          COMMENT 4.28=F(0.01)(3,43);
444      END
445

```

PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +46
 ITMAX = +16
 CONVERGE = +.1000000000001E- 1
 EPS = +.9999999999999E- 4
 MESH = +100
 STIFF = FALSE
 FA = +.4279999999999E+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	T OBS[I]	COBS[I]	OBS[I]						
0	+0.0000E- 0	0							
1	+2.0000E- 3	+1	+99980E- 0	2	+2.0000E- 3	+2	+16480E- 0		
3	+4.0000E- 3	+1	+99970E- 0	4	+4.0000E- 3	+2	+27530E- 0		
5	+6.0000E- 3	+1	+99960E- 0	6	+6.0000E- 3	+2	+34930E- 0		
7	+8.0000E- 3	+1	+99960E- 0	8	+8.0000E- 3	+2	+39900E- 0		
9	+1.0000E- 2	+1	+99960E- 0	10	+1.0000E- 2	+2	+43220E- 0		
11	+1.2000E- 2	+1	+99950E- 0	12	+1.2000E- 2	+2	+45450E- 0		
13	+1.4000E- 2	+1	+99950E- 0	14	+1.4000E- 2	+2	+46950E- 0		
15	+1.6000E- 2	+1	+99950E- 0	16	+1.6000E- 2	+2	+47950E- 0		
17	+1.8000E- 2	+1	+99950E- 0	18	+1.8000E- 2	+2	+48620E- 0		
19	+2.0000E- 2	+1	+99950E- 0	20	+2.0000E- 2	+2	+49070E- 0		
21	+2.2000E- 2	+1	+99940E- 0	22	+2.0000E- 1	+2	+49990E- 0		
23	+4.0000E- 1	+1	+99930E- 0	24	+4.0000E- 1	+2	+49980E- 0		
25	+6.0000E- 1	+1	+99920E- 0	26	+6.0000E- 1	+2	+49980E- 0		
27	+8.0000E- 1	+1	+99910E- 0	28	+8.0000E- 1	+2	+49980E- 0		
29	+1.0000E- 0	+1	+99900E- 0	30	+1.0000E- 0	+2	+49980E- 0		
31	+1.0000E+ 1	+1	+99450E- 0	32	+1.0000E+ 1	+2	+49860E- 0		
33	+2.0000E+ 1	+1	+98950E- 0	34	+2.0000E+ 1	+2	+49730E- 0		
35	+5.0000E+ 1	+1	+97470E- 0	36	+5.0000E+ 1	+2	+49360E- 0		
37	+1.0000E+ 2	+1	+95020E- 0	38	+1.0000E+ 2	+2	+48720E- 0		
39	+1.0000E+ 2	+1	+92600E- 0	40	+1.5000E+ 2	+2	+48080E- 0		
41	+2.0000E+ 2	+1	+90210E- 0	42	+2.0000E+ 2	+2	+47430E- 0		
43	+2.0000E+ 2	+1	+87860E- 0	44	+2.5000E+ 2	+2	+46770E- 0		
45	+3.0000E+ 2	+1	+85530E- 0	46	+3.0000E+ 2	+2	+46100E- 0		

THE PARAMETER ESTIMATES WERE:

I	PARLWB[I]	PAR[I]	PARUPB[I]
1	+0.0000E- 0	+1.6000E+ 4	+25000E+ 4
2	+0.0000E- 0	+8.0000E- 0	+20000E+ 1
3	+0.0000E- 0	+1.2000E+ 1	+20000E+ 1

EVALUATIONS OF
F PY PP

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11572_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +1
COMPUTED RESIDUE (STAND.DEV.) +.71050_m+ 1 +.40649_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.56079_m+ 1 +.36113_m- 0
CORRECTIONS FOR PARAMETER -.13012_m+ 4 +.11222_m+ 1 -.23527_m+ 1
PARAMETER VALUE +.29883_m+ 3 +.19222_m+ 1 -.11527_m+ 1

BOUNDARY CONSTRAINTS, JUMP+.5100630429897_m- 0
COMPUTED RESIDUE (STAND.DEV.) +.71050_m+ 1 +.40649_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.59974_m+ 1 +.37346_m- 0
CORRECTIONS FOR PARAMETER -.66368_m+ 3 +.57238_m- 0 -.12000_m+ 1
PARAMETER VALUE +.93632_m+ 3 +.13724_m+ 1 -.00000_m- 0

328 162 149

THE EQUATION WAS FOUND TO BE STIFF AT X = +.16794_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +2
COMPUTED RESIDUE (STAND.DEV.) +.14767_m- 0 +.58602_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.27718_m- 3 +.25389_m- 2
CORRECTIONS FOR PARAMETER +.38729_m+ 2 -.44803_m- 0 +.93545_m- 2
PARAMETER VALUE +.97505_m+ 3 +.92434_m- 0 +.93545_m- 2

189 102 94

THE EQUATION WAS FOUND TO BE STIFF AT X = +.18076_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +3
COMPUTED RESIDUE (STAND.DEV.) +.48038_m- 2 +.10570_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.10903_m- 5 +.15924_m- 3
CORRECTIONS FOR PARAMETER +.23473_m+ 2 +.63419_m- 1 +.56804_m- 3
PARAMETER VALUE +.99852_m+ 3 +.98776_m- 0 +.99196_m- 2

189 99 92

THE EQUATION WAS FOUND TO BE STIFF AT X = +.13005_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +4
COMPUTED RESIDUE (STAND.DEV.) +.87965_m- 5 +.45229_m- 3
ESTIMATED RESIDUE (STAND.DEV.) +.97692_m- 7 +.47664_m- 4
CORRECTIONS FOR PARAMETER +.16552_m+ 1 +.21989_m- 2 +.67811_m- 4
PARAMETER VALUE +.10002_m+ 4 +.98996_m- 0 +.99874_m- 2

162 85 78

THE EQUATION WAS FOUND TO BE STIFF AT X = +.12673_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +5

COMPUTED RESIDUE (STAND.DEV.) +.17284_m- 6 +.63399_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.78876_m- 7 +.42829_m- 4
 CORRECTIONS FOR PARAMETER +.71049_m- 1 +.59385_m- 5 +.10685_m- 4

PARAMETER VALUE +.10002_m+ 4 +.98997_m- 0 +.99981_m- 2

160 84 77

THE EQUATION WAS FOUND TO BE STIFF AT X = +.12673_m- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +6

COMPUTED RESIDUE (STAND.DEV.) +.80423_m- 7 +.43247_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.77181_m- 7 +.42366_m- 4
 CORRECTIONS FOR PARAMETER +.68692_m- 2 -.42558_m- 6 +.19919_m- 5

PARAMETER VALUE +.10003_m+ 4 +.98997_m- 0 +.10000_m- 1

160 84 77

THE EQUATION WAS FOUND TO BE STIFF AT X = +.12672_m- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +7

COMPUTED RESIDUE (STAND.DEV.) +.77027_m- 7 +.42324_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.76914_m- 7 +.42293_m- 4
 CORRECTIONS FOR PARAMETER +.74688_m- 3 -.11067_m- 6 +.37276_m- 6

PARAMETER VALUE +.10003_m+ 4 +.98997_m- 0 +.10000_m- 1
 CONFIDENCE INTERVAL (COND.) +.35182_m- 0 +.14758_m- 3 +.53040_m- 5
 CONFIDENCE INTERVAL (INDEPT.) +.37275_m- 0 +.15651_m- 3 +.53096_m- 5

RELATIONSHIPS BETWEEN PARAMETERS
CORRELATION MATRIX

+ .33004_m- 0
 -.30686_m- 3 -.43414_m- 1

COVARIANCE MATRIX

+√60497_m+ 7 +.83833_m+ 3 -.26443_m- 1
 +.10665_m+ 1 -.15708_m- 2
 +.12275_m- 2

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.22444_m- 6 +.16512_m- 2 +.10000_m+ 1 +.53040_m- 5
 +.13857_m- 5 -.10000_m+ 1 +.16512_m- 2 +.14774_m- 3
 +.10000_m+ 1 +.13857_m- 3 -.43711_m- 8 +.37275_m- 0

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11394_u 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_u 1

ITERATION NUMBER +8
COMPUTED RESIDUE (STAND.DEV.) +.57579_u 7 +.36593_u 4
ESTIMATED RESIDUE (STAND.DEV.) +.39239_u 7 +.30208_u 4
CORRECTIONS FOR PARAMETER -.28749_u 0 +.30690_u 4 =.38921_u 6

PARAMETER VALUE +.99997_u 3 +.99000_u 0 +.10000_u 1
CONFIDENCE INTERVAL (COND.) +.25607_u 0 +.10540_u 3 +.37908_u 5
CONFIDENCE INTERVAL (INDEPT.) +.27126_u 0 +.11175_u 3 +.37948_u 5

RELATIONSHIPS BETWEEN PARAMETERS
CORRELATION MATRIX

COVARIANCE MATRIX
+.62801_u 7 +.85279_u 3 -.28560_u 1
+.10659_u 1 -.15691_u 2
+.12290_u 2

+.32962_u 0
-.32508_u 3 -.43352_u 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
-.21946_u 6 +.16496_u 2 +.10000_u 1 +.37908_u 5
+.13579_u 5 -.10000_u 1 +.16496_u 2 +.10531_u 3
+.10000_u 1 +.13579_u 3 -.45477_u 8 +.27126_u 0

RESIDUALS, SPECIFIED FOR EACH OBSERVATION,

1	-.32018 _m - 4	2	-.48515 _m - 4
3	-.24118 _m - 4	4	-.28407 _m - 4
5	-.49451 _m - 4	6	-.84650 _m - 4
7	+.91730 _m - 6	8	-.14189 _m - 4
9	+.32006 _m - 4	10	-.77490 _m - 4
11	-.41823 _m - 4	12	-.66609 _m - 4
13	-.22959 _m - 4	14	-.85430 _m - 5
15	-.14997 _m - 4	16	-.23427 _m - 4
17	-.72200 _m - 5	18	-.36063 _m - 4
19	-.18458 _m - 5	20	-.34154 _m - 4
21	-.27884 _m - 5	22	+.40917 _m - 4
23	-.28382 _m - 5	24	-.35671 _m - 4
25	-.28931 _m - 5	26	-.12226 _m - 4
27	-.29617 _m - 5	28	+.20054 _m - 4
29	-.30339 _m - 5	30	+.50819 _m - 4
31	-.19363 _m - 4	32	-.32695 _m - 4
33	-.40349 _m - 4	34	-.80809 _m - 4
35	+.21362 _m - 4	36	+.32362 _m - 5
37	+.37013 _m - 4	38	-.30868 _m - 4
39	+.30840 _m - 4	40	+.10424 _m - 4
41	+.33316 _m - 7	42	+.26133 _m - 4
43	+.41227 _m - 4	44	+.14388 _m - 4
45	-.49611 _m - 4	46	-.26659 _m - 4

155

79

74

THE ENTIRE CALCULATION CONSUMED 131.72 SEC. ON THE EL X8.

PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +23
 ITMAX = +16
 CONVERGE = +.1000000000001₁₆ = 1
 EPS = +.9999999999999₁₆ = 4
 MESH = +100
 STIFF = FALSE
 FA = +.4940000000002₁₆ = 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TUBS(I)	COBS(I)	OBS(I)
0	+0J000 ₁₆ = 0		
1	+2J000 ₁₆ = 3	+2	+16480 ₁₆ = 0
2	+4J000 ₁₆ = 3	+2	+27530 ₁₆ = 0
3	+6J000 ₁₆ = 3	+2	+34930 ₁₆ = 0
4	+8J000 ₁₆ = 3	+2	+39900 ₁₆ = 0
5	+1J000 ₁₆ = 2	+2	+43220 ₁₆ = 0
6	+12000 ₁₆ = 2	+2	+45450 ₁₆ = 0
7	+14000 ₁₆ = 2	+2	+46950 ₁₆ = 0
8	+16000 ₁₆ = 2	+2	+47950 ₁₆ = 0
9	+18000 ₁₆ = 2	+2	+48620 ₁₆ = 0
10	+20000 ₁₆ = 2	+2	+49070 ₁₆ = 0
11	+2J000 ₁₆ = 1	+2	+49990 ₁₆ = 0
12	+4J000 ₁₆ = 1	+2	+49980 ₁₆ = 0
13	+6J000 ₁₆ = 1	+2	+49980 ₁₆ = 0
14	+8J000 ₁₆ = 1	+2	+49980 ₁₆ = 0
15	+10000 ₁₆ = 0	+2	+49980 ₁₆ = 0
16	+1J000 ₁₆ = 1	+2	+49860 ₁₆ = 0
17	+2J000 ₁₆ = 1	+2	+49730 ₁₆ = 0
18	+50000 ₁₆ = 1	+2	+49360 ₁₆ = 0
19	+1J000 ₁₆ = 2	+2	+48720 ₁₆ = 0
20	+12000 ₁₆ = 2	+2	+48080 ₁₆ = 0
21	+20000 ₁₆ = 2	+2	+47430 ₁₆ = 0
22	+22000 ₁₆ = 2	+2	+46770 ₁₆ = 0
23	+30000 ₁₆ = 2	+2	+46100 ₁₆ = 0

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUPB(I)
1	+0.0000 ₁₆ = 0	+16000 ₁₆ = 4	+25000 ₁₆ = 4
2	+0.0000 ₁₆ = 0	+80000 ₁₆ = 0	+20000 ₁₆ = 1
3	+0.0000 ₁₆ = 0	+12000 ₁₆ = 1	+20000 ₁₆ = 1

EVALUATIONS OF
F FY FP

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11572_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +1
COMPUTED RESIDUE (STAND.DEV.) +.17718_m+ 1 +.29764_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.11735_m+ 1 +.24223_m- 0
CORRECTIONS FOR PARAMETER -.12620_m+ 4 +.18566_m+ 1 =.30514_m+ 1
PARAMETER VALUE +.33798_m+ 3 +.26566_m+ 1 -.18514_m+ 1

BOUNDARY CONSTRAINTS, JUMP+.3932632438264_m- 0
COMPUTED RESIDUE (STAND.DEV.) +.17718_m+ 1 +.29764_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.12660_m+ 1 +.25160_m- 0
CORRECTIONS FOR PARAMETER -.49631_m+ 3 +.73015_m- 0 =.12000_m+ 1
PARAMETER VALUE +.11037_m+ 4 +.15301_m+ 1 +.18190_m- 11

328 162 149

THE EQUATION WAS FOUND TO BE STIFF AT X = +.46713_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +2
COMPUTED RESIDUE (STAND.DEV.) +.16227_m- 0 +.90075_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.48594_m- 3 +.49292_m- 2
CORRECTIONS FOR PARAMETER -.19588_m+ 3 -.66029_m- 0 +.96919_m- 2
PARAMETER VALUE +.90782_m+ 3 +.86986_m- 0 +.96919_m- 2

189 101 93

THE EQUATION WAS FOUND TO BE STIFF AT X = +.69112_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +3
COMPUTED RESIDUE (STAND.DEV.) +.14980_m- 1 +.27368_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.44831_m- 5 +.47345_m- 3
CORRECTIONS FOR PARAMETER +.73926_m+ 2 +.11379_m- 0 +.25278_m- 3
PARAMETER VALUE +.98174_m+ 3 +.98365_m- 0 +.99447_m- 2

470 239 232

THE EQUATION WAS FOUND TO BE STIFF AT X = +.14132_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +4
COMPUTED RESIDUE (STAND.DEV.) +.67976_m- 4 +.18436_m- 2
ESTIMATED RESIDUE (STAND.DEV.) +.21267_m- 6 +.10312_m- 3
CORRECTIONS FOR PARAMETER +.16735_m+ 2 +.62029_m- 2 +.58868_m- 4
PARAMETER VALUE +.99848_m+ 3 +.98985_m- 0 +.10004_m- 1

168 88 81

THE EQUATION WAS FOUND TO BE STIFF AT X = +.12996_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.50229_μ- 6 +.15848_μ- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.56618_μ- 7 +.53206_μ- 4
 CORRECTIONS FOR PARAMETER +.16031_μ+ 1 +.89647_μ- 4 +.27540_μ- 6
 PARAMETER VALUE +.10001_μ+ 4 +.98994_μ- 0 +.10004_μ- 1
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.12674_μ- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_μ+ 1

162 85 78

ITERATION NUMBER +6
 COMPUTED RESIDUE (STAND.DEV.) +.63747_μ- 7 +.56456_μ- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.59899_μ- 7 +.54726_μ- 4
 CORRECTIONS FOR PARAMETER +.15156_μ- 0 +.12546_μ- 4 -.85614_μ- 6
 PARAMETER VALUE +.10002_μ+ 4 +.98996_μ- 0 +.10003_μ- 1
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.12673_μ- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_μ+ 1

160 84 77

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.60422_μ- 7 +.54964_μ- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.60387_μ- 7 +.54949_μ- 4
 CORRECTIONS FOR PARAMETER +.13889_μ- 1 +.11800_μ- 5 -.23603_μ- 6
 PARAMETER VALUE +.10002_μ+ 4 +.98996_μ- 0 +.10003_μ- 1
 CONFIDENCE INTERVAL (COND.) +.49107_μ- 0 +.20799_μ- 3 +.25462_μ- 4
 CONFIDENCE INTERVAL (INDEPT.) +.53434_μ- 0 +.28756_μ- 3 +.33211_μ- 4

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX
 +.63807_μ+ 7 +.13472_μ+ 4 -.88117_μ+ 2
 +.18479_μ+ 1 -.13685_μ- 0
 +.24649_μ- 1
 +.39232_μ- 0
 -.22219_μ- 0 - .64123_μ- 0

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
 -.23001_μ- 5 +.76114_μ- 1 +.99710_μ- 0 +.25389_μ- 4
 +.21157_μ- 3 -.99710_μ- 0 +.76114_μ- 1 +.26526_μ- 3
 +.10000_μ+ 1 +.21113_μ- 3 -.13810_μ- 4 +.53434_μ- 0

170772- 9

B 13681.138 PHEMKER

12

00

160

84

77

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11393_m- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

ITERATION NUMBER +8
COMPUTED RESIDUE (STAND.DEV.) +.40737_m- 7 +.45131_m- 4
ESTIMATED RESIDUE (STAND.DEV.) +.22182_m- 7 +.33303_m- 4
CORRECTIONS FOR PARAMETER -.27407_m- 0 +.49294_m- 4 -.37172_m- 5

PARAMETER VALUE +.99997_m+ 3 +.99001_m- 0 +.99990_m- 2
CONFIDENCE INTERVAL (COND.) +.30329_m- 0 +.12604_m- 3 +.15439_m- 4
CONFIDENCE INTERVAL (INDEPT.) +.32990_m- 0 +.17410_m- 3 +.20122_m- 4

RELATIONSHIPS BETWEEN PARAMETERS
CORRELATION MATRIX

COVARIANCE MATRIX

+ .39160_m- 1
-.22146_m- 1 -.64056_m- 0
+.66216_m+ 7 +.13684_m+ 4 -.89446_m+ 2
+.18440_m+ 1 -.13653_m- 0
+.24635_m- 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.22557_m- 5 +.76091_m- 1 +.99710_m- 0 +.15394_m- 4
+.20706_m- 3 -.99710_m- 0 +.76091_m- 1 +.16065_m- 3
+.10000_m+ 1 +.20665_m- 3 -.13508_m- 4 +.32990_m- 0

RESIDUALS, SPECIFIED FOR EACH OBSERVATION:

1	-.47636 ₁₀ -	4
2	-.27446 ₁₀ -	4
3	-.83974 ₁₀ -	4
4	-.13932 ₁₀ -	4
5	-.77666 ₁₀ -	4
6	-.67177 ₁₀ -	4
7	-.94434 ₁₀ -	5
8	-.24595 ₁₀ -	4
9	-.37443 ₁₀ -	4
10	-.35695 ₁₀ -	4
11	+ .38925 ₁₀ -	4
12	-.37656 ₁₀ -	4
13	-.14209 ₁₀ -	4
14	+ .18067 ₁₀ -	4
15	+ .48861 ₁₀ -	4
16	-.34399 ₁₀ -	4
17	-.82217 ₁₀ -	4
18	+ .27244 ₁₀ -	5
19	-.29857 ₁₀ -	4
20	+ .12995 ₁₀ -	4
21	+ .37298 ₁₀ -	4
22	+ .27180 ₁₀ -	4
23	-.19205 ₁₀ -	4

155

79

74

THE ENTIRE CALCULATION CONSUMED 151.97 SEC. ON THE EL X8.

PROCEDURE ODEPART WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +12
 ITMAX = +16
 CONVERGE = +.1000000000001_u- 1
 EPS = +.99999999999999_u- 4
 MESH = +100
 STIFF = FALSE
 FA = +.3860000000001_u+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TUBS(I)	COBS(I)	OBS(I)
0	+0.0000 _u -	0	
1	+0.2000 _u -	3	+0.16480 _u - 0
2	+0.6000 _u -	3	+0.34930 _u - 0
3	+0.1000 _u -	2	+0.43220 _u - 0
4	+0.1400 _u -	2	+0.46950 _u - 0
5	+0.1800 _u -	2	+0.48620 _u - 0
6	+0.2000 _u -	1	+0.49990 _u - 0
7	+0.6000 _u -	1	+0.49980 _u - 0
8	+0.1000 _u -	0	+0.49980 _u - 0
9	+0.2000 _u +	1	+0.49730 _u - 0
10	+0.1000 _u +	2	+0.48720 _u - 0
11	+0.2000 _u +	2	+0.47430 _u - 0
12	+0.3000 _u +	2	+0.46100 _u - 0

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUPB(I)
1	+0.0000 _u - 0	+0.16000 _u + 4	+0.25000 _u + 4
2	+0.0000 _u - 0	+0.80000 _u - 0	+0.20000 _u + 1
3	+0.0000 _u - 0	+0.12000 _u + 1	+0.20000 _u + 1

EVALUATIONS OF
P FY FP

THE EQUATION WAS FOUND TO BE STIFF AT X = +.10969e- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000e+ 1

ITERATION NUMBER +1
COMPUTED RESIDUE (STAND.DEV.) +.92495e- 0 +.32058e- 0
ESTIMATED RESIDUE (STAND.DEV.) +.65942e- 0 +.27068e- 0
CORRECTIONS FOR PARAMETER -.11607e+ 4 +.14314e+ 1 -.27008e+ 1
PARAMETER VALUE +.43934e+ 3 +.22314e+ 1 -.15008e+ 1

BOUNDARY CONSTRAINTS, JUMP+.4443101165480e- 0
COMPUTED RESIDUE (STAND.DEV.) +.92495e- 0 +.32058e- 0
ESTIMATED RESIDUE (STAND.DEV.) +.71184e- 0 +.28124e- 0
CORRECTIONS FOR PARAMETER -.51569e+ 3 +.63897e- 0 -.12000e+ 1
PARAMETER VALUE +.10843e+ 4 +.14360e+ 1 -.18190e- 11

316 157 144

THE EQUATION WAS FOUND TO BE STIFF AT X = +.10e20e- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000e+ 1

ITERATION NUMBER +2
COMPUTED RESIDUE (STAND.DEV.) +.58275e- 1 +.80467e- 1
ESTIMATED RESIDUE (STAND.DEV.) +.18511e- 3 +.45352e- 2
CORRECTIONS FOR PARAMETER -.14259e+ 3 -.52644e- 0 +.83665e- 2
PARAMETER VALUE +.94172e+ 3 +.90953e- 0 +.83665e- 2

127 68 60

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11552e- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000e+ 1

ITERATION NUMBER +3
COMPUTED RESIDUE (STAND.DEV.) +.40825e- 2 +.21298e- 1
ESTIMATED RESIDUE (STAND.DEV.) +.21711e- 5 +.49115e- 3
CORRECTIONS FOR PARAMETER +.48692e+ 2 +.76334e- 1 +.12889e- 2
PARAMETER VALUE +.99041e+ 3 +.98587e- 0 +.96554e- 2

115 60 57

THE EQUATION WAS FOUND TO BE STIFF AT X = +.10938e- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000e+ 1

ITERATION NUMBER +4
COMPUTED RESIDUE (STAND.DEV.) +.21798e- 4 +.15563e- 2
ESTIMATED RESIDUE (STAND.DEV.) +.47063e- 7 +.72313e- 4
CORRECTIONS FOR PARAMETER +.87943e+ 1 +.40871e- 2 +.26612e- 3
PARAMETER VALUE +.99921e+ 3 +.98995e- 0 +.99215e- 2

131 68 61

THE EQUATION WAS FOUND TO BE STIFF AT X = +.10926e- 0
SOME LITTLE PROBLEMS WITH STIFFNESS +.10000e+ 1

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.30026_m- 6 +.18265_m- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.12146_m- 7 +.36737_m- 4
 CORRECTIONS FOR PARAMETER +.93699_m- 0 +.10383_m- 3 +.58812_m- 4
 PARAMETER VALUE +.10001_m+ 4 +.99006_m- 0 +.99803_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.10920_m- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

131 68 61

ITERATION NUMBER +6
 COMPUTED RESIDUE (STAND.DEV.) +.24964_m- 7 +.52667_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.12413_m- 7 +.37139_m- 4
 CORRECTIONS FOR PARAMETER +.10410_m- 0 +.63844_m- 5 +.14649_m- 4
 PARAMETER VALUE +.10002_m+ 4 +.99006_m- 0 +.99949_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.10920_m- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

131 68 61

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.13175_m- 7 +.38260_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.12430_m- 7 +.37163_m- 4
 CORRECTIONS FOR PARAMETER +.12096_m- 1 -.49038_m- 6 +.37842_m- 5
 PARAMETER VALUE +.10003_m+ 4 +.99006_m- 0 +.99987_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.10919_m- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000_m+ 1

131 68 61

ITERATION NUMBER +8
 COMPUTED RESIDUE (STAND.DEV.) +.12465_m- 7 +.37216_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.12416_m- 7 +.37142_m- 4
 CORRECTIONS FOR PARAMETER +.15564_m- 2 -.36539_m- 6 +.99306_m- 6
 PARAMETER VALUE +.10003_m+ 4 +.99806_m- 0 +.99997_m- 2
 CONFIDENCE INTERVAL (COND.) +.40706_m- 0 +.17383_m- 3 +.17489_m- 4
 CONFIDENCE INTERVAL (INDEPT.) +.43723_m- 0 +.23291_m- 3 +.22285_m- 4

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX

+v11967_m+ 8 +.23191_m+ 4 -.12316_m+ 3
 +.36381_m- 0 +.33957_m+ 1 -.20121_m- 0
 -.20192_m- 0 -.61929_m- 0 +.31088_m- 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.14473_m- 5 +.60476_m- 1 +.99817_m- 0 +.17457_m- 4
 +.19407_m- 3 -.99817_m- 0 +.60476_m- 1 +.21734_m- 3
 +.10000_m+ 1 +.19380_m- 3 -.10292_m- 4 +.43723_m- 0

THE EQUATION WAS FOUND TO BE STIFF AT X = +.11763₁₀- 0
 SOME LITTLE PROBLEMS WITH STIFFNESS +.10000₁₀+ 1

ITERATION NUMBER +9
 COMPUTED RESIDUE (STAND.DEV.) +.27909₁₀- 7 +.55687₁₀- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.14187₁₀- 7 +.39703₁₀- 4
 CORRECTIONS FOR PARAMETER -.40836₁₀- 0 -.92822₁₀- 4 +.36651₁₀- 5

PARAMETER VALUE +.99985₁₀+ 3 +.98997₁₀- 0 +.10003₁₀- 1
 CONFIDENCE INTERVAL (COND.) +.44179₁₀- 0 +.18544₁₀- 3 +.20321₁₀- 4
 CONFIDENCE INTERVAL (INDEPT.) +.47480₁₀- 0 +.25066₁₀- 3 +.26121₁₀- 4

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX
 +.12350₁₀+ 8 +.23794₁₀+ 4 -.13852₁₀+ 3
 +.34419₁₀+ 1 -.22516₁₀- 0
 +.37379₁₀- 1
 +.30495₁₀- J
 -.20387₁₀- U -.62774₁₀- 0

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
 -.16944₁₀- 5 +.66880₁₀- 1 +.99776₁₀- 0 +.20276₁₀- 4
 +.19298₁₀- 3 -.99776₁₀- 0 +.66880₁₀- 1 +.23389₁₀- 3
 +.10000₁₀+ 1 +.19266₁₀- 3 -.11216₁₀- 4 +.47480₁₀- 0

RESIDUALS, SPECIFIED FOR EACH OBSERVATION,

1	-.48093 ₁₀	- 4
2	-.78147 ₁₀	- 4
3	-.64658 ₁₀	- 4
4	+.87488 ₁₀	- 5
5	-.16034 ₁₀	- 4
6	+.63975 ₁₀	- 4
7	+.18068 ₁₀	- 4
8	+.71642 ₁₀	- 4
9	-.57228 ₁₀	- 4
10	-.19386 ₁₀	- 4
11	+.42301 ₁₀	- 4
12	-.74947 ₁₀	- 5

147 75 72

THE ENTIRE CALCULATION CONSUMED 115.92 SEC. ON THE EL X8.

PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +12
 ITMAX = +16
 CONVERGE = +.1000000000001₁₀ = 1
 EPS = +.999999999999999₁₀ = 4
 MESH = +100
 STIFF = FALSE
 FA = +.386000000000001₁₀ = 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TOBS(I)	COBS(I)	OBS(I)
0	+.00000 ₁₀ = 0		
1	+.40000 ₁₀ = 1	+2	+.49980 ₁₀ = 0
2	+.60000 ₁₀ = 1	+2	+.49980 ₁₀ = 0
3	+.80000 ₁₀ = 1	+2	+.49980 ₁₀ = 0
4	+.10000 ₁₀ = 0	+2	+.49980 ₁₀ = 0
5	+.10000 ₁₀ = 1	+2	+.49860 ₁₀ = 0
6	+.20000 ₁₀ = 1	+2	+.49730 ₁₀ = 0
7	+.50000 ₁₀ = 1	+2	+.49360 ₁₀ = 0
8	+.10000 ₁₀ = 2	+2	+.48720 ₁₀ = 0
9	+.10000 ₁₀ = 2	+2	+.48080 ₁₀ = 0
10	+.20000 ₁₀ = 2	+2	+.47430 ₁₀ = 0
11	+.20000 ₁₀ = 2	+2	+.46770 ₁₀ = 0
12	+.30000 ₁₀ = 2	+2	+.46100 ₁₀ = 0

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUP(I)
1	+.00000 ₁₀ = 0	+.10000 ₁₀ = 2	+.20000 ₁₀ = 4
2	+.00000 ₁₀ = 0	+.50000 ₁₀ = 0	+.20000 ₁₀ = 1
3	+.00000 ₁₀ = 0	+.50000 ₁₀ = 0	+.20000 ₁₀ = 1

EVALUATIONS OF
P FY FP

ITERATION NUMBER +1
COMPUTED RESIDUE (STAND.DEV.) +.13332_m+ 1 +.38488_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.93934_m- 0 +.32307_m- 0
CORRECTIONS FOR PARAMETER +.10240_m+ 2 +.10058_m+ 1 -.63001_m- 0

PARAMETER VALUE +.20240_m+ 2 +.15058_m+ 1 -.13001_m- 0

BOUNDARY CONSTRAINTS, JUMP+.7936380460351_m- 0
COMPUTED RESIDUE (STAND.DEV.) +.13332_m+ 1 +.38488_m- 0
ESTIMATED RESIDUE (STAND.DEV.) +.11874_m+ 1 +.36323_m- 0
CORRECTIONS FOR PARAMETER +.81267_m+ 1 +.79823_m- 0 -.50000_m- 0

PARAMETER VALUE +.18127_m+ 2 +.12982_m+ 1 -.22737_m- 12

185 89 84

ITERATION NUMBER +2
COMPUTED RESIDUE (STAND.DEV.) +.71146_m- 1 +.88911_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.36949_m- 3 +.64074_m- 2
CORRECTIONS FOR PARAMETER +.13619_m+ 2 -.34389_m- 0 +.10731_m- 1

PARAMETER VALUE +.31746_m+ 2 +.95434_m- 0 +.10731_m- 1

477 239 234

THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
SOME LITTLE PROBLEMS WITH STIFFNESS +.20000_m+ 1

ITERATION NUMBER +3
COMPUTED RESIDUE (STAND.DEV.) +.14864_m- 2 +.12851_m- 1
ESTIMATED RESIDUE (STAND.DEV.) +.20890_m- 4 +.15235_m- 2
CORRECTIONS FOR PARAMETER +.11780_m+ 2 +.31567_m- 1 -.92586_m- 3

PARAMETER VALUE +.43526_m+ 2 +.98590_m- 0 +.98050_m- 2

154 79 76

THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
SOME LITTLE PROBLEMS WITH STIFFNESS +.20000_m+ 1

ITERATION NUMBER +4
COMPUTED RESIDUE (STAND.DEV.) +.32891_m- 3 +.60453_m- 2
ESTIMATED RESIDUE (STAND.DEV.) +.70040_m- 6 +.27897_m- 3
CORRECTIONS FOR PARAMETER +.13151_m+ 2 +.19592_m- 2 +.62856_m- 4

PARAMETER VALUE +.56677_m+ 2 +.98394_m- 0 +.98678_m- 2

144 75 73

THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
SOME LITTLE PROBLEMS WITH STIFFNESS +.20000_m+ 1

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.37965_m- 4 +.20539_m- 2
 ESTIMATED RESIDUE (STAND.DEV.) +.45848_m- 7 +.71374_m- 4
 CORRECTIONS FOR PARAMETER +.13034_m+ 2 +.26511_m- 3 +.68927_m- 4
 PARAMETER VALUE +.69711_m+ 2 +.98421_m- 0 +.99368_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.12000_m+ 2

148 77 73

ITERATION NUMBER +6
 COMPUTED RESIDUE (STAND.DEV.) +.47230_m- 5 +.72442_m- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.15631_m- 7 +.41674_m- 4
 CORRECTIONS FOR PARAMETER +.15652_m+ 2 +.91192_m- 3 +.28762_m- 4
 PARAMETER VALUE +.85363_m+ 2 +.98512_m- 0 +.99655_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.12000_m+ 2

140 72 70

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.48319_m- 6 +.23171_m- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.10383_m- 7 +.33966_m- 4
 CORRECTIONS FOR PARAMETER +.15148_m+ 2 +.68799_m- 3 +.75665_m- 5
 PARAMETER VALUE +.10051_m+ 3 +.98581_m- 0 +.99731_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.22000_m+ 2

169 87 79

ITERATION NUMBER +8
 COMPUTED RESIDUE (STAND.DEV.) +.64722_m- 7 +.84801_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.15466_m- 7 +.41454_m- 4
 CORRECTIONS FOR PARAMETER +.10587_m+ 2 +.32942_m- 3 +.39064_m- 5
 PARAMETER VALUE +.11110_m+ 3 +.98614_m- 0 +.99770_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.22000_m+ 2

198 81 76

ITERATION NUMBER +9
 COMPUTED RESIDUE (STAND.DEV.) +.18350_m- 7 +.45155_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.14919_m- 7 +.40715_m- 4
 CORRECTIONS FOR PARAMETER +.55563_m+ 1 +.16825_m- 3 +.10748_m- 5
 PARAMETER VALUE +.11665_m+ 3 +.98631_m- 0 +.99781_m- 2
 THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.22000_m+ 2

155 80 76

ITERATION NUMBER +10
 COMPUTED RESIDUE (STAND. DEV.) +.14573_m- 7 +.40240_m- 4
 ESTIMATED RESIDUE (STAND. DEV.) +.14462_m- 7 +.40086_m- 4
 CORRECTIONS FOR PARAMETER -.11656_m- 0 -.18476_m- 4 +.22602_m- 6

PARAMETER VALUE +.11654_m+ 3 +.98629_m- 0 +.99783_m- 2
 CONFIDENCE INTERVAL (COND.) +.42130_m+ 1 +.16229_m- 3 +.16557_m- 4
 CONFIDENCE INTERVAL (INDEPT.) +.54661_m+ 2 +.21016_m- 2 +.23138_m- 4

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX
 +.99418_m- 0
 +.62182_m- 1 -.13115_m- 1
 +.16057_m+ 12 +.61377_m+ 7 +.42263_m+ 4
 +.23737_m+ 3 -.34272_m- 1
 +.28770_m- 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
 -.27524_m- 5 +.71319_m- 1 +.99745_m- 0 +.16515_m- 4
 +.38126_m- 4 -.99745_m- 0 +.71319_m- 1 +.22693_m- 3
 +.10000_m+ 1 +.38225_m- 4 +.26321_m- 7 +.54661_m+ 2

THE EQUATION WAS FOUND TO BE STIFF AT X = +.40000_m- 3
 SOME LITTLE PROBLEMS WITH STIFFNESS +.52000_m+ 2

ITERATION NUMBER +11
 COMPUTED RESIDUE (STAND.DEV.) +.12301_m- 7 +.36970_m- 4
 ESTIMATED RESIDUE (STAND.DEV.) +.11350_m- 7 +.35513_m- 4
 CORRECTIONS FOR PARAMETER +.73885_m+ 1 +.25030_m- 3 +.22481_m- 5

PARAMETER VALUE +.12393_m+ 3 +.98654_m- 0 +.99806_m- 2
 CONFIDENCE INTERVAL (COND.) +.37436_m+ 1 +.14387_m- 3 +.14446_m- 4
 CONFIDENCE INTERVAL (INDEPT.) +.38757_m+ 2 +.15053_m- 2 +.20256_m- 4

RELATIONSHIPS BETWEEN PARAMETERS

CORRELATION MATRIX

COVARIANCE MATRIX

+10285_m+ 12 +.39590_m+ 7 -.35743_m+ 4
 +.99102_m- 0 +.15516_m+ 3 -.33241_m- 0
 -.66491_m- 1 -.15921_m- 0 +.28096_m- 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.26757_m- 5 +.70414_m- 1 +.99752_m- 0 +.14410_m- 4
 +.38399_m- 4 -.99752_m- 0 +.70414_m- 1 +.20178_m- 3
 +.10000_m+ 1 +.38492_m- 4 -.34752_m- 7 +.38757_m+ 2

RESIDUALS, SPECIFIED FOR EACH OBSERVATION

1	+.29508 ₁₀ -	4
2	+.38775 ₁₀ -	5
3	+.28449 ₁₀ -	4
4	+.53371 ₁₀ -	4
5	-.25235 ₁₀ -	4
6	-.66102 ₁₀ -	4
7	+.15118 ₁₀ -	4
8	-.21777 ₁₀ -	4
9	+.16383 ₁₀ -	4
10	+.28219 ₁₀ -	4
11	+.14223 ₁₀ -	4
12	-.32582 ₁₀ -	4

211 110 105

THE ENTIRE CALCULATION CONSUMED 171.93 SEC. ON THE EL X8.

PROCEDURE ODEPART WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +12
 ITMAX = +9
 CONVERGE = +.1000000000001_u- 1
 EPS = +.9999999999999_u- 4
 MESH = +100
 STIFF = FALSE
 FA = +.3860000000001_u+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TOBS(I)	COBS(I)	OBS(I)
0	+.0000 _u - 0		
1	+.2000 _u - 3	+2	+.16480 _u - 0
2	+.4000 _u - 3	+2	+.27530 _u - 0
3	+.6000 _u - 3	+2	+.34930 _u - 0
4	+.8000 _u - 3	+2	+.39900 _u - 0
5	+.1000 _u - 2	+2	+.43220 _u - 0
6	+.1200 _u - 2	+2	+.45450 _u - 0
7	+.1400 _u - 2	+2	+.46950 _u - 0
8	+.1600 _u - 2	+2	+.47950 _u - 0
9	+.1800 _u - 2	+2	+.48620 _u - 0
10	+.2000 _u - 2	+2	+.49070 _u - 0
11	+.2000 _u - 1	+2	+.49990 _u - 0
12	+.4000 _u - 1	+2	+.49980 _u - 0

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUPB(I)
1	+.0000 _u - 0	+.1000 _u + 2	+.2000 _u + 4
2	+.0000 _u - 0	+.5000 _u - 0	+.2000 _u + 1
3	+.0000 _u - 0	+.5000 _u - 0	+.2000 _u + 1

EVALUATIONS OF
F FY FP

ITERATION NUMBER +1
 COMPUTED RESIDUE (STAND.DEV.) +.17749_u+ 1 +.44409_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.55124_u- 1 +.78261_u- 1
 CORRECTIONS FOR PARAMETER +.31497_u+ 3 +.20610_u+ 5 -.20182_u+ 5
 PARAMETER VALUE +.32497_u+ 3 +.20611_u+ 5 -.20181_u+ 5

BOUNDARY CONSTRAINTS, JUMP+.2477474026819_u- 4
 COMPUTED RESIDUE (STAND.DEV.) +.17749_u+ 1 +.44409_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.55124_u- 1 +.78261_u- 1
 CORRECTIONS FOR PARAMETER +.78033_u- 2 +.51061_u- 0 -.50000_u- 0
 PARAMETER VALUE +.10008_u+ 2 +.10106_u+ 1 -.00000_u- 0

33 24 23

ITERATION NUMBER +2
 COMPUTED RESIDUE (STAND.DEV.) +.17749_u+ 1 +.44409_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.55107_u- 1 +.78250_u- 1
 CORRECTIONS FOR PARAMETER +.31500_u+ 3 +.20596_u+ 5 -.20168_u+ 5
 PARAMETER VALUE +.32501_u+ 3 +.20597_u+ 5 -.20168_u+ 5

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.17749_u+ 1 +.44409_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.55107_u- 1 +.78250_u- 1
 CORRECTIONS FOR PARAMETER +.31500_u+ 3 +.20596_u+ 5 -.20168_u+ 5
 PARAMETER VALUE +.32501_u+ 3 +.20000_u+ 1 +.00000_u- 0

33 24 23

ITERATION NUMBER +3
 COMPUTED RESIDUE (STAND.DEV.) +.46667_u- 0 +.22771_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.67799_u- 3 +.86794_u- 2
 CORRECTIONS FOR PARAMETER +.43920_u+ 3 +.81988_u+ 1 -.93965_u+ 1
 PARAMETER VALUE +.76421_u+ 3 +.10199_u+ 2 -.93965_u+ 1

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.46667_u- 0 +.22771_u- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.67799_u- 3 +.86794_u- 2
 CORRECTIONS FOR PARAMETER +.43920_u+ 3 +.81988_u+ 1 -.93965_u+ 1
 PARAMETER VALUE +.76421_u+ 3 +.20000_u+ 1 +.00000_u- 0

70 37 36

ITERATION NUMBER +4
 COMPUTED RESIDUE (STAND.DEV.) +.22241_u- 0 +.15720_u+ 0
 ESTIMATED RESIDUE (STAND.DEV.) +.12114_u- 4 +.11602_u- 2
 CORRECTIONS FOR PARAMETER +.17156_u+ 3 -.12622_u+ 1 -.23002_u- 0
 PARAMETER VALUE +.93577_u+ 3 +.73783_u- 0 -.23002_u- 0

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.22241_m- 0 +.15729_m- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.12114_m- 4 +.11602_m- 2
 CORRECTIONS FOR PARAMETER +.17156_m+ 3 -.12622_m+ 1 -.23002_m- 0
 PARAMETER VALUE +.93577_m+ 3 +.73783_m- 0 +.00000_m- 0

71 37 36

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.26571_m- 1 +.54336_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.83682_m- 5 +.96426_m- 3
 CORRECTIONS FOR PARAMETER +.52095_m+ 2 +.81563_m- 0 -.57725_m- 0
 PARAMETER VALUE +.98786_m+ 3 +.15535_m+ 1 -.57725_m- 0

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.26571_m- 1 +.54336_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.83682_m- 5 +.96426_m- 3
 CORRECTIONS FOR PARAMETER +.52095_m+ 2 +.81563_m- 0 -.57725_m- 0
 PARAMETER VALUE +.98786_m+ 3 +.15535_m+ 1 +.00000_m- 0

83 43 42

STEEPEST DESCENT+.1724278651036_m+ 1
 COMPUTED RESIDUE (STAND.DEV.) +.78790_m- 1 +.93565_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_m- 0 +.00000_m- 0
 CORRECTIONS FOR PARAMETER +.22507_m- 0 +.32972_m- 2 -.15959_m+ 1
 PARAMETER VALUE +.93599_m+ 3 +.74113_m- 0 -.10187_m+ 1

BOUNDARY CONSTRAINTS JUMP+.3617034401022_m- 0
 COMPUTED RESIDUE (STAND.DEV.) +.78790_m- 1 +.93565_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.10308_m- 1 +.33843_m- 1
 CORRECTIONS FOR PARAMETER +.81409_m- 1 +.11926_m- 2 -.57725_m- 0
 PARAMETER VALUE +.93585_m+ 3 +.73902_m- 0 -.00000_m- 0

107 54 51

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.26290_m- 1 +.54048_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.82542_m- 5 +.95767_m- 3
 CORRECTIONS FOR PARAMETER +.52066_m+ 2 +.80885_m- 0 -.57145_m- 0
 PARAMETER VALUE +.98791_m+ 3 +.15479_m+ 1 -.57145_m- 0

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.26290_m- 1 +.54048_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.82542_m- 5 +.95767_m- 3
 CORRECTIONS FOR PARAMETER +.52066_m+ 2 +.80885_m- 0 -.57145_m- 0
 PARAMETER VALUE +.98791_m+ 3 +.15479_m+ 1 +.00000_m- 0

83 43 42

STEEPEST DESCENT+.1728280197774_m+ 1
 COMPUTED RESIDUE (STAND.DEV.) +.77513_m- 1 +.92804_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_m- 0 +.00000_m- 0
 CORRECTIONS FOR PARAMETER +.22614_m- 0 +.31859_m- 2 -.15917_m+ 1:

PARAMETER VALUE +.93607_m+ 3 +.74221_m- 0 -.10202_m+ 1

BOUNDARY CONSTRAINTS, JUMP+.3590277575213_m- 0
 COMPUTED RESIDUE (STAND.DEV.) +.77513_m- 1 +.92804_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.99915_m- 2 +.33319_m- 1
 CORRECTIONS FOR PARAMETER +.81189_m- 1 +.11438_m- 2 -.57145_m- 0

PARAMETER VALUE +.93593_m+ 3 +.74017_m- 0 -.00000_m- 0
 CONFIDENCE INTERVAL (COND.) +.20830_m- 0 +.64131_m+ 1 +.10787_m+ 2
 CONFIDENCE INTERVAL (INDEPT.) +.20915_m- 0 +.11173_m+ 2 +.18793_m+ 2

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX

+ .85885_m- 1
 +.85504_m- 1 +.81871_m- 0
 +.34026_m+ 1 +.15611_m+ 2 +.26143_m+ 2
 +.97104_m+ 4 +.13372_m+ 5
 +.27473_m+ 5

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

+ .55306_m- 3 +.88127_m- 0 -.47262_m- 0 +.57131_m+ 1
 +.87805_m- 3 +.47262_m- 0 +.88127_m- 0 +.21104_m+ 2
 +.00000_m+ 1 -.90237_m- 3 -.51241_m- 3 +.20830_m- 0

ITERATION NUMBER +9
 COMPUTED RESIDUE (STAND.DEV.) +.26038_μ- 1 +.53788_μ- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.50102_μ- 5 +.74612_μ- 3
 CORRECTIONS FOR PARAMETER +.50012_μ+ 2 +.73464_μ- 0 -.50023_μ- 0
 PARAMETER VALUE +.98594_μ+ 3 +.14748_μ+ 1 -.50023_μ- 0

PLUS ULTRA -0
 COMPUTED RESIDUE (STAND.DEV.) +.26038_μ- 1 +.53788_μ- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.50102_μ- 5 +.74612_μ- 3
 CORRECTIONS FOR PARAMETER +.50012_μ+ 2 +.73464_μ- 0 -.50023_μ- 0

PARAMETER VALUE +.98594_μ+ 3 +.14748_μ+ 1 +.00000_μ- 0
 CONFIDENCE INTERVAL (COND.) +.44407_μ+ 1 +.33383_μ- 2 +.33192_μ- 2
 CONFIDENCE INTERVAL (INDEPT.) +.62234_μ+ 1 +.51518_μ- 0 +.51090_μ- 0

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX
 +.60081_μ+ 7 +.24877_μ+ 6 -.24479_μ+ 6
 +.41171_μ+ 5 -.40828_μ+ 5
 +.40490_μ+ 5
 +.50019_μ- U
 -.49631_μ- J -.99997_μ- 0

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
 -.30110_μ- J +.70507_μ- 0 +.70914_μ- 0 +.23538_μ- 2
 +.58788_μ- I -.70790_μ- 0 +.70386_μ- 0 +.62800_μ- 0
 +.99827_μ- U +.41901_μ- 1 -.41236_μ- 1 +.62340_μ+ 1

RESIDUALS, SPECIFIED FOR EACH OBSERVATION

1	+.50671 ₁₀	2
2	+.22413 ₁₀	3
3	-.90022 ₁₀	2
4	-.19413 ₁₀	1
5	-.29608 ₁₀	1
6	-.38639 ₁₀	1
7	-.46255 ₁₀	1
8	-.54587 ₁₀	1
9	-.57679 ₁₀	1
10	-.61692 ₁₀	1
11	-.74608 ₁₀	1
12	-.74706 ₁₀	1

107

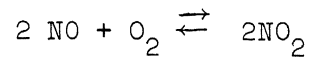
54

53

THE ENTIRE CALCULATION CONSUMED 63.87 SEC. ON THE EL X8.

6.2. Bellman's problem

This test problem is taken from an example given in an article by Bellman c.s. [1967]. It originates from a chemical experiment on the reaction



reported by Bodonstein [1922].
The differential equation reads

$$dy/dt = p(126.2-y) (91.9-y)^2 - q y^2 .$$

The parameters p and q have to be determined from 14 given observations.

Bellman reports as parameter values and computed residue (apart from a printing error in his article)

$$\begin{aligned} p &= .4577_{10} - 5 \\ q &= .2793_{10} - 5 \\ s &= 22.7 \end{aligned}$$

We note that the 1% confidence regions are

$$\delta p = .31_{10} - 6 \quad \text{and} \quad \delta q = .48_{10} - 3 .$$

Our algorithm finds respectively

$$\begin{aligned} p &= .44_{10} - 5 & \delta p &= .30_{10} - 6 \\ q &= .23_{10} - 3 & \delta q &= .43_{10} - 3 \\ s &= 25.12 \end{aligned}$$

The computed residue is slightly greater but the difference is by no means important.

B13681.138,PHEMKER,T150

```

1  BEGIN COMMENT BELLMAN'S PROBLEM, SEE: MATH.B.OSC. 1(67)71 ;
2
3  PROC ODEPAREST(N,NOBS,NPAR,DATA,ITMAX,CONVERGE,EPS,MESH,STIFF,FA);
4  VAL N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESH,STIFF,FA;
5  INT N,NOBS,NPAR,ITMAX,MESH; REAL CONVERGE,EPS,FA; BOOL STIFF;
6  BEGIN COMMENT THE PROCEDURES: CALL YSTART,CALL F,CALL FY,CALL FP
7  DEFINE THE PROBLEM SUPPLIED BY THE USER;
8
9  PROC CALL YSTART;
10 BEGIN Y(0,1):= 0; YMAX(1):= 50; OUTC
11 END;
12 PROC CALL F(R); VAL R; REAL R;
13 BEGIN CF:= CF+1; F(1):= R*(PAR(1)*(126.2-Y(0,1)) * (91.9-Y(0,1))+2
14 =PAR(2)*Y(0,1)+2 )
15 END;
16 PROC CALL FY(R); VAL R; REAL R;
17 BEGIN FY(1,1):= R*(
18 -PAR(1)*(-91.9+344.3 + 620.0*Y(0,1) -3*Y(0,1)+2)
19 -PAR(2)*Y(0,1)+2 )
20 CFY:= CFY+1;
21 END;
22 PROC CALL FP(R); VAL R; REAL R;
23 BEGIN FP(1,1):= R*(126.2-Y(0,1))*(91.1-Y(0,1))+2 ;
24 FP(1,2):=-R*Y(0,1)+2; CFP:= CFP+1
25 END;
26
27 ABBAY Y(0:7,1:N*(NPAR+1)),YMAX,F(1:N),FY(1:N,1:N),FP(1:N,1:NPAR);
28 PROC PR(S); BEGIN NLCR; PRINTTEXT(S) END;
29 PROC FL(R); FLOT(5,3,R);
30 PROC PF(S,R); BEGIN PR(S); TAB; FL(R) END;
31
32 PROC OUT(S,R); SIRING S; REAL R;
33 BEGIN INT I) IF LINENUMBER>50 THEN NEW PAGE ELSE NLCR;
34 PR(S); PRINT(R);
35 PF(↓COMPUTED RESIDUE (STAND.DEV.)↓,COMP ERROR);
36 FL(SQRT(COMP ERROR/(NOBS-NPAR)));
37 PF(↓ESTIMATED RESIDUE (STAND.DEV.)↓,EST ERROR);
38 FL(SQRT(EST ERROR/(NOBS-NPAR)));
39 PR(↓CORRECTIONS FOR PARAMETER↓); TAB;
40 EQB I:=1 STEP 1 UNTIL NPAR DO FL(DELTA PAR(I)); NLCR;
41 PR(↓PARAMETER VALUE↓); TAB; TAB;
42 EQB I:= 1 STEP 1 UNTIL NPAR UQ FL(PAR(I));
43 END;
44
45 BOOL FIRST,ADAMS; INTEGER K,KOLD,SAME,FAILS;
46 REAL X,XOLD,H,CH,HOLD,TOLCONV,TOLUP,TOL,TOLDOWN,A0;
47 ABBAY A(0:7),DD(0:7,0:N),LAST DELTA(1:N),JAC(1:N,1:N),CONST(1:45),
48 TOBS(0:NOBS),OBS(1:NOBS),PARL,PAR,PARU(1:NPAR);
49 INT ARRAY COBS(1:NOBS),PP(1:N);
50
51 PROC MULTISTEP(XEND,HMIN,HMAX,EPS);
52 VALUE XEND,HMIN,HMAX,EPS; REAL XEND,HMIN,HMAX,EPS;
53
54 BEGIN BOOLEAN CONV; INTEGER I,J,L,KNEW,NP;
55 REAL CHNEW,C,ERROR,DFI; ABBAY DELTA,DF,Y0(1:N);
56

```


EVALUATIONS OF
F FY FP

ITERATION NUMBER +1
 COMPUTED RESIDUE (STAND.DEV.) +.40843_μ+ 4 +.18449_μ+ 2
 ESTIMATED RESIDUE (STAND.DEV.) +.13275_μ+ 3 +.33261_μ+ 1
 CORRECTIONS FOR PARAMETER +.14831_μ- 5 +.18734_μ- 2
 PARAMETER VALUE +.24831_μ- 5 +.19734_μ- 2

43 24 23

ITERATION NUMBER +2
 COMPUTED RESIDUE (STAND.DEV.) +.21964_μ+ 4 +.13529_μ+ 2
 ESTIMATED RESIDUE (STAND.DEV.) +.10301_μ+ 3 +.29299_μ+ 1
 CORRECTIONS FOR PARAMETER -.69354_μ- 7 -.30568_μ- 1
 PARAMETER VALUE +.24138_μ- 5 -.28595_μ- 1

BOUNDARY CONSTRAINTS, JUMP+.6455684411230_μ- 1
 COMPUTED RESIDUE (STAND.DEV.) +.21964_μ+ 4 +.13529_μ+ 2
 ESTIMATED RESIDUE (STAND.DEV.) +.11174_μ+ 3 +.30515_μ+ 1
 CORRECTIONS FOR PARAMETER -.44773_μ- 8 -.19734_μ- 2
 PARAMETER VALUE +.24786_μ- 5 -.00000_μ- 0

133 78 64

ITERATION NUMBER +3
 COMPUTED RESIDUE (STAND.DEV.) +.70601_μ+ 3 +.76704_μ+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.60001_μ+ 2 +.22361_μ+ 1
 CORRECTIONS FOR PARAMETER +.70689_μ- 6 +.70937_μ- 3
 PARAMETER VALUE +.31855_μ- 5 +.70937_μ- 3

68 30 29

ITERATION NUMBER +4
 COMPUTED RESIDUE (STAND.DEV.) +.65954_μ+ 3 +.74136_μ+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.17928_μ+ 2 +.12223_μ+ 1
 CORRECTIONS FOR PARAMETER +.21550_μ- 6 -.60068_μ- 2
 PARAMETER VALUE +.34010_μ- 5 -.52974_μ- 2

BOUNDARY CONSTRAINTS, JUMP+.1180947078510_μ- 0
 COMPUTED RESIDUE (STAND.DEV.) +.65954_μ+ 3 +.74136_μ+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.26876_μ+ 2 +.14966_μ+ 1
 CORRECTIONS FOR PARAMETER +.25450_μ- 7 -.70937_μ- 3
 PARAMETER VALUE +.32110_μ- 5 -.00000_μ- 0

100 53 48

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.22422_μ+ 3 +.43226_μ+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.32133_μ+ 2 +.16364_μ+ 1
 CORRECTIONS FOR PARAMETER +.41967_μ- 6 +.37065_μ- 3
 PARAMETER VALUE +.36307_μ- 5 +.37065_μ- 3

76 31 30

ITERATION NUMBER +6
 COMPUTED RESIDUE (STAND.DEV.) +.20569_u+ 3 +.41401_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.12692_u+ 2 +.10284_u+ 1
 CORRECTIONS FOR PARAMETER +.25951_u- 6 -.15412_u- 2

PARAMETER VALUE +.38902_u- 5 -.11705_u- 2

BOUNDARY CONSTRAINTS, JUMP+.2404997579242_u- 0
 COMPUTED RESIDUE (STAND.DEV.) +.20569_u+ 3 +.41401_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.23855_u+ 2 +.14099_u+ 1
 CORRECTIONS FOR PARAMETER +.62412_u- 7 -.37065_u- 3

PARAMETER VALUE +.36931_u- 5 -.00000_u- 0

105 57 50

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.10666_u+ 3 +.29813_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.21888_u+ 2 +.13506_u+ 1
 CORRECTIONS FOR PARAMETER +.25365_u- 6 +.23346_u- 3

PARAMETER VALUE +.39467_u- 5 +.23346_u- 3

82 32 31

ITERATION NUMBER +8
 COMPUTED RESIDUE (STAND.DEV.) +.67884_u+ 2 +.23785_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.18095_u+ 2 +.12280_u+ 1
 CORRECTIONS FOR PARAMETER +.23093_u- 6 -.33316_u- 3

PARAMETER VALUE +.41776_u- 5 -.99699_u- 4

BOUNDARY CONSTRAINTS, JUMP+.7007490319338_u- 0
 COMPUTED RESIDUE (STAND.DEV.) +.67884_u+ 2 +.23785_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.42544_u+ 2 +.18829_u+ 1
 CORRECTIONS FOR PARAMETER +.16183_u- 6 -.23346_u- 3

PARAMETER VALUE +.41085_u- 5 +.11102_u- 15

98 48 44

STEEPEST DESCENT+.2868668658626_u- 14
 COMPUTED RESIDUE (STAND.DEV.) +.93932_u+ 2 +.27978_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_u- 0 +.00000_u- 0
 CORRECTIONS FOR PARAMETER +.16175_u- 6 -.64924_u- 10

PARAMETER VALUE +.41085_u- 5 +.23346_u- 3

84 33 32

ITERATION NUMBER +10
 COMPUTED RESIDUE (STAND.DEV.) +.44502_u+ 2 +.19257_u+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.19447_u+ 2 +.12730_u+ 1
 CORRECTIONS FOR PARAMETER +.16612_u- 6 -.23518_u- 3

PARAMETER VALUE +.42746_u- 5 -.17164_u- 5

BOUNDARY CONSTRAINTS, JUMP+.9927016284564_m- 0
 COMPUTED RESIDUE (STAND.DEV.) +.44502_m+ 2 +.19257_m+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.44138_m+ 2 +.19178_m+ 1
 CORRECTIONS FOR PARAMETER +.16491_m- 6 -.23346_m- 3

PARAMETER VALUE +.42734_m- 5 +.71124_m- 16

93 41 38

STEEPEST DESCENT+.3050702941380_m- 14
 COMPUTED RESIDUE (STAND.DEV.) +.10711_m+ 3 +.29876_m+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_m- 0 +.00000_m- 0
 CORRECTIONS FOR PARAMETER +.16482_m- 6 -.71060_m- 10

PARAMETER VALUE +.42733_m- 5 +.23346_m- 3

84 33 32

ITERATION NUMBER +12
 COMPUTED RESIDUE (STAND.DEV.) +.29872_m+ 2 +.15778_m+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.21001_m+ 2 +.13229_m+ 1
 CORRECTIONS FOR PARAMETER +.10159_m- 6 -.13714_m- 3

PARAMETER VALUE +.43749_m- 5 +.96321_m- 4

94 42 39

STEEPEST DESCENT+.3166938513554_m- 14
 COMPUTED RESIDUE (STAND.DEV.) +.53079_m+ 2 +.21032_m+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_m- 0 +.00000_m- 0
 CORRECTIONS FOR PARAMETER +.10154_m- 6 -.44067_m- 10

PARAMETER VALUE +.43748_m- 5 +.23346_m- 3
 CONFIDENCE INTERVAL (COND.) +.00000_m- 0 +.00000_m- 0
 CONFIDENCE INTERVAL (INDEPT.) +.00000_m- 0 +.00000_m- 0

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX

+.7558_m- 14

+.97565_m- 44 +.42403_m- 52
 +.59778_m- 31

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

+.00000_m+ 1 +.00000_m- 0 +.00000_m- 0
 +.00000_m- 1 +.10000_m+ 1 +.00000_m- 0

ITERATION NUMBER +14
 COMPUTED RESIDUE (STAND.DEV.) +.25124_μ+ 2 +.14469_μ+ 1
 ESTIMATED RESIDUE (STAND.DEV.) +.21983_μ+ 2 +.13535_μ+ 1
 CORRECTIONS FOR PARAMETER +.68717_μ- 7 -.72843_μ- 4

PARAMETER VALUE +.44435_μ- 5 +.16062_μ- 3
 CONFIDENCE INTERVAL (COND.) +.29635_μ- 6 +.43013_μ- 3
 CONFIDENCE INTERVAL (INDEPT.) +.34822_μ- 6 +.50541_μ- 3

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX

+ .52508_μ- 1
 +.47757_μ- 14 +.36396_μ- 11
 +.10060_μ- 7

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

+ .0000_μ+ 1 -.36177_μ- 3 +.29635_μ- 6
 +.36177_μ- 3 +.10000_μ+ 1 +.50541_μ- 3

RESIDUALS, SPECIFIED FOR EACH OBSERVATION.

1	-.29614 _u +	1
2	-.18947 _u +	1
3	-.11908 _u +	1
4	-.42015 _u -	0
5	+.26207 _u -	0
6	+.16116 _u +	1
7	+.99253 _u -	0
8	+.11359 _u +	1
9	+.13101 _u +	1
10	+.13794 _u +	1
11	+.96308 _u -	0
12	+.41278 _u -	0
13	-.67007 _u -	1
14	-.12272 _u +	1

138

64

58

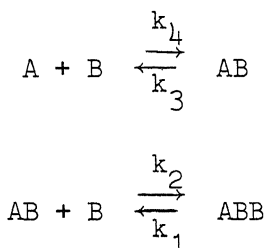
THE ENTIRE CALCULATION CONSUMED 65.05 SEC. ON THE EL X8.

6.3. Gear's problem

This test originates from a problem in Gear [1971, p.229-230].
The system of differential equations is

$$\begin{aligned} \frac{dy}{dt} &= -k_1 y + k_2 z (b-z-2y) \\ \frac{dz}{dt} &= -k_3 z + k_4 (b-z-2y) (a-z-y) - \frac{dy}{dt} \\ y(0) &= 0.25 \quad , \quad z(0) = 0.5 \end{aligned}$$

Apparently this system originates from the chemical reactions



with $z = [AB]$ and $y = [ABB]$.

No solution was given for this problem.

At any rate, the solution found by our algorithm is a sufficient one since the residuals for each observation are less than the experimental error (3 digit accuracy) .

B13681.138,PHEMKER,T150

```

1  BEGIN COMMENT GEAR'S PROBLEM , SEE: GEAR[1971]P.230 ;
2
3  BRQC ODEPAREST(N,NOBS,NPAR,DATA,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
4  VAL N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA;
5  INI N,NOBS,NPAR,ITMAX,MESHP; REAL CONVERGE,EPS,FA; BOOL STIFF;
6  BEGIN COMMENT THE PROCEDURES: CALL YSTART,CALL F,CALL FY,CALL FP
7  DEFINE THE PROBLEM SUPPLIED BY THE USER;
8
9  BRQC CALL YSTART;
10 BEGIN
11     Y(0,2):= YMAX[1]:= YMAX[2]:= 0.5; Y(0,1):= 0.25;
12     FP[1,3]:= FP[1,4]:= U; OUTC
13 END;
14 BRQC CALL F(R); VAL R; REAL R;
15 BEGIN REAL Q,Z,W; COMMENT ; CFI= CF+1;
16     COMMENT A=1, B= 2;
17     Q:= Y(0,1); Z:= Y(0,2); W:= 2-Q-Q-Z;
18     F[1]:= R*(-PAR[1]*Q + PAR[2]*W*Z);
19     F[2]:= R*(-PAR[3]*Z + PAR[4]*W*(1-Q-Z)) - F[1];
20 END;
21 BRQC CALL FY(R); VAL R; REAL R;
22 BEGIN REAL Q,Z,W,V,F1,F2;
23     Q:= Y(0,1); Z:= Y(0,2); W:= 2-Q-Q-Z; V:= 1-Q-Z;
24     FY[1,1]:= F1:= R*(-PAR[1] - 2*PAR[2]*Z);
25     FY[1,2]:= F2:= R*( PAR[2]*(W-Z));
26     FY[2,1]:= R*(-PAR[4]*(V+V+W)) - F1;
27     FY[2,2]:= R*(-PAR[3] - PAR[4]*(V+W)) - F2;
28     CFY:= CFY+1;
29 END;
30 BRQC CALL FP(R); VAL R; REAL R;
31 BEGIN REAL Q,Z,W,F1,F2;
32     Q:= Y(0,1); Z:= Y(0,2); W:= 2-Q-Q-Z;
33     F1:= FP[1,1]:= -Q*R; F2:= FP[1,2]:= W*Z*R;
34     FP[2,1]:= -F1; FP[2,2]:= -F2;
35     FP[2,3]:= -Z*R; FP[2,4]:= W*(1-Q-Z)*R;
36     CFP:= CFP + 1;
37 END;
38
39 ARRAY Y(0:7,1:N*(NPAR+1)),YMAX,F(1:N),FY(1:N,1:N),FP(1:N,1:NPAR);
40 BRQC PR(S); BEGIN NLCR; PRINTTEXT(S) END;
41 BRQC FL(R); FLOT(5,3,R);
42 BRQC PF(S,R); BEGIN PR(S); TAB; FL(R) END;
43
44 BRQC OUT(S,R); SIBING S; REAL R;
45 BEGIN INT I; IF LINENUMBER>50 THEN NEW PAGE ELSE NLCR;
46     PR(S); PRINT(R);
47     PF({COMPUTED RESIDUE (STAND.DEV.)},COMP ERROR);
48     FL(SQRT(COMP ERROR/(NOBS-NPAR)));
49     PF({ESTIMATED RESIDUE (STAND.DEV.)},EST ERROR);
50     FL(SQRT(EST ERROR/(NOBS-NPAR)));
51     PR({CORRECTIONS FOR PARAMETER}); TAB;
52     FOR I:=1 STEP 1 UNIL NPAR DO FL(Delta PAR[I]); NLCR;
53     PR({PARAMETER VALUE}); TAB; TAB;
54     FOR I:= 1 STEP 1 UNIL NPAR DO FL(PAR[I]);
55 END;
56

```


PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +4
 NOBS = +8
 ITMAX = +24
 CONVERGE = +.1000000000001₁₀- 1
 EPS = +.9999999999999₁₀- 4
 MESH = +100
 STIFF = FALSE
 FA = +.6680000000000₁₀+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TUBS(I)	COBS(I)	OBS(I)						
0	+.01000 ₁₀ - 0								
1	+.33300 ₁₀ - 0	+1	+.30100 ₁₀ - 0	2	+.33300 ₁₀ - 0	+2	+.40300 ₁₀ - 0		
3	+.67200 ₁₀ - 0	+1	+.32400 ₁₀ - 0	4	+.67200 ₁₀ - 0	+2	+.36200 ₁₀ - 0		
5	+.11120 ₁₀ + 1	+1	+.33500 ₁₀ - 0	6	+.10120 ₁₀ + 1	+2	+.34500 ₁₀ - 0		
7	+.11000 ₁₀ + 3	+1	+.34500 ₁₀ - 0	8	+.10000 ₁₀ + 3	+2	+.33200 ₁₀ - 0		

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUPB(I)
1	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.10000 ₁₀ + 2
2	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.10000 ₁₀ + 2
3	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.10000 ₁₀ + 2
4	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.10000 ₁₀ + 2

280772-169

B 13681.138 PHEMKER

10

00

EVALUATIONS OF
F FY FP

ITERATION NUMBER +1
 COMPUTED RESIDUE (STAND.DEV.) +.29886_m- 3 +.86438_m- 2
 ESTIMATED RESIDUE (STAND.DEV.) +.29652_m- 5 +.86098_m- 3
 CORRECTIONS FOR PARAMETER -.24647_m- 0 -.18866_m- 0 -.76952_m- 1 -.23282_m- 1

PARAMETER VALUE +.75353_m- 0 +.81134_m- 0 +.92305_m- 0 +.97672_m- 0

145 73 65

ITERATION NUMBER +2
 COMPUTED RESIDUE (STAND.DEV.) +.74640_m- 5 +.13660_m- 2
 ESTIMATED RESIDUE (STAND.DEV.) +.24398_m- 6 +.24697_m- 3
 CORRECTIONS FOR PARAMETER +.38606_m- 1 +.30865_m- 1 -.27768_m- 1 -.33981_m- 1

PARAMETER VALUE +.79213_m- 0 +.84220_m- 0 +.89528_m- 0 +.94274_m- 0

90 45 42

ITERATION NUMBER +3
 COMPUTED RESIDUE (STAND.DEV.) +.25409_m- 6 +.25204_m- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.21613_m- 6 +.23245_m- 3
 CORRECTIONS FOR PARAMETER +.33519_m- 2 +.29445_m- 2 -.16623_m- 2 -.17801_m- 2

PARAMETER VALUE +.79549_m- 0 +.84515_m- 0 +.89362_m- 0 +.94096_m- 0

117 59 52

ITERATION NUMBER +4
 COMPUTED RESIDUE (STAND.DEV.) +.23171_m- 6 +.24068_m- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.23049_m- 6 +.24005_m- 3
 CORRECTIONS FOR PARAMETER -.14616_m- 3 -.66329_m- 4 -.50710_m- 3 -.64300_m- 3

PARAMETER VALUE +.79534_m- 0 +.84568_m- 0 +.89311_m- 0 +.94031_m- 0
 CONFIDENCE INTERVAL (COND.) +.33666_m- 2 +.29626_m- 2 +.48223_m- 2 +.59231_m- 2
 CONFIDENCE INTERVAL (INDEPT.) +.21905_m- 1 +.19434_m- 1 +.39016_m- 1 +.47636_m- 1

RELATIONSHIPS BETWEEN PARAMETERS
CORRELATION MATRIX

COVARIANCE MATRIX

+431163_m+ 3 +.27263_m+ 3 -.20151_m+ 3 -.23865_m+ 3
 +.98606_m-) +.24530_m+ 3 -.18052_m+ 3 -.20853_m+ 3
 -.36304_m-) -.36657_m- 0 +.98869_m+ 3 +.11959_m+ 4
 -.35215_m-) -.34682_m- 0 +.99074_m- 0 +.14738_m+ 4

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

+.62649_m-) -.71559_m- 0 -.23960_m- 0 +.19502_m- 0 +.21513_m- 2
 +.21834_m-) -.21937_m- 0 +.73818_m- 0 -.59941_m- 0 +.42281_m- 2
 +.73223_m-) +.64910_m- 0 +.11517_m- 0 +.17101_m- 0 +.26782_m- 1
 +.15387_m-) +.13594_m- 0 -.62001_m- 0 -.75725_m- 0 +.62523_m- 1

THE EQUATION WAS FOUND TO BE STIFF AT X = +.33300₁₀- 2
 SOME LITTLE PROBLEMS WITH STIFFNESS +.20000₁₀+ 1

ITERATION NUMBER +5
 COMPUTED RESIDUE (STAND.DEV.) +.22630₁₀- 6 +.23785₁₀- 3
 ESTIMATED RESIDUE (STAND.DEV.) +.22372₁₀- 6 +.23649₁₀- 3
 CORRECTIONS FOR PARAMETER -.26061₁₀- 3 -.30077₁₀- 3 -.27050₁₀- 3 -.20842₁₀- 3
 PARAMETER VALUE +.79508₁₀- 0 +.84478₁₀- 0 +.89284₁₀- 0 +.94011₁₀- 0
 CONFIDENCE INTERVAL (COND.) +.33630₁₀- 2 +.29853₁₀- 2 +.48538₁₀- 2 +.59251₁₀- 2
 CONFIDENCE INTERVAL (INDEPT.) +.22231₁₀- 1 +.19927₁₀- 1 +.39679₁₀- 1 +.48069₁₀- 1

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX
 +.33071₁₀+ 3 +.29242₁₀+ 3 -.22553₁₀+ 3 -.26467₁₀+ 3
 +.98649₁₀- J +.26570₁₀+ 3 -.20503₁₀+ 3 -.23516₁₀+ 3
 -.38209₁₀- J -.38753₁₀- 0 +.10535₁₀+ 4 +.12646₁₀+ 4
 -.37013₁₀- J -.36690₁₀- 0 +.99088₁₀- 0 +.15461₁₀+ 4

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)
 +.62932₁₀- J -.71268₁₀- 0 -.24003₁₀- 0 +.19606₁₀- 0 +.21588₁₀- 2
 +.22108₁₀- J -.21815₁₀- 0 +.73575₁₀- 0 -.60184₁₀- 0 +.42503₁₀- 2
 +.72729₁₀- J +.65077₁₀- 0 +.12218₁₀- 0 +.18064₁₀- 0 +.27026₁₀- 1
 +.6167₁₀- J +.14495₁₀- 0 -.62139₁₀- 0 -.75281₁₀- 0 +.63429₁₀- 1

280772-169

B 13681.138 PHEMKE

12

00

RESIDUALS, SPECIFIED FOR EACH OBSERVATION:

1	+ .28751 _μ	4	2	- .13850 _μ	3
3	- .17981 _μ	3	4	+ .89109 _μ	4
5	+ .19571 _μ	3	6	+ .29093 _μ	3
7	- .79138 _μ	4	8	- .19186 _μ	3

135

70

67

THE ENTIRE CALCULATION CONSUMED 57.28 SEC. ON THE EL X8.

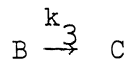
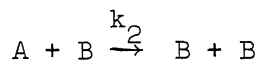
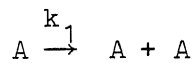
6.4. Barnes' problem

This problem was suggested during the FEBS summerschool on computing techniques in biochemistry (Edinburgh 1968). The system of differential equations

$$dx/dt = k_1x - k_2xy$$

$$dy/dt = k_2xy - k_3y$$

originates from the chemical reactions



This is an oscillating system of the Lotka-Volterra type (see Lotka [1956], Volterra [1931]), which also has many applications in theoretical biology.

As approximate results for a set of given observations, it is known that

$$k_1 = 0.861 \pm 0.14$$

$$k_2 = 2.080 \pm 0.39$$

$$k_3 = 1.816 \pm 0.42$$

confidence interval 1%.

These values agree fairly well with our results.

•

B13681.138,PHEMKER,T150

```

1  BEGIN COMMENT BARNES' PROBLEM;
2
3  PROQ ODEPARREST(N,NOBS,NPAR,DATA,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
4  VAL N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA;
5  INI N,NOBS,NPAR,ITMAX,MESHP; BEAL CONVERGE,EPS,FA; BQOL STIFF;
6  BEGIN COMMENT THE PROCEDURES: CALL YSTART,CALL F,CALL FY,CALL FP
7  DEFINE THE PROBLEM SUPPLIED BY THE USER;
8
9  PROQ CALL YSTART;
10 BEGIN Y(0,1):= YMAX[1]:= 1; Y(0,2):= 0.3; YMAX[2]:= 0.5;
11     FP(1,3):= FP(2,1):= 0; OUTC
12
13 END;
14 PROQ CALL F(R); VAL R; BEAL R;
15 BEGIN CF:= CF+1;
16     F[1]:= R*Y(0,1)*(PAR[1]-PAR[2]*Y(0,2));
17     F[2]:= -R*Y(0,2)*(PAR[3]-PAR[2]*Y(0,1));
18
19 END;
20 PROQ CALL FY(R); VAL R; BEAL R;
21 BEGIN REAL F12; CFY:= CFY+1;
22     FY(1,1):= R*(PAR[1]-PAR[2]*Y(0,2));
23     FY(1,2):= F12:= -R*PAR[2]*Y(0,2); FY(2,1):= -F12;
24     FY(2,2):= R*(PAR[2]*Y(0,1)-PAR[3]);
25
26 END;
27 PROQ CALL FP(R); VAL R; BEAL R;
28 BEGIN REAL F12; CFP:= CFP+1;
29     FP(1,1):= Y(0,1)*R;
30     F12:= FP(1,2):= -Y(0,1)*Y(0,2)*R;
31     FP(2,2):= -F12;
32     FP(2,3):= -Y(0,2)*R;
33
34 END;
35
36 ARRAY Y(0:7,1:N*(NPAR+1)),YMAX,F(1:N),FY(1:N,1:N),FP(1:N,1:NPAR);
37 PROQ PR(S); BEGIN NLCR; PRINTTEXT(S) END;
38 PROQ FL(R); FLOT(5,3,R);
39 PROQ PF(S,R); BEGIN PR(S); TAB; FL(R) END;
40
41 PROQ OUT(S,R); STRING S; REAL R;
42 BEGIN INI I; IE LINENUMBER>50 THEN NEW PAGE ELSE NLCR;
43     PR(S); PRINT(R);
44     PF(ESTIMATED RESIDUE (STAND.DEV.)*,COMP ERROR);
45     FL(SQRT(COMP ERROR/(NOBS-NPAR)));
46     PF(ESTIMATED RESIDUE (STAND.DEV.)*,EST ERROR);
47     FL(SQRT(EST ERROR/(NOBS-NPAR)));
48     PR(CORRECTIONS FOR PARAMETER); TAB;
49     FOR I:=1 STEP 1 UNILL NPAR DO FL(DELTA PAR[I]); NLCR;
50     PR(PARAMETER VALUE); TAB; TAB;
51     FOR I:= 1 STEP 1 UNILL NPAR DO FL(PAR[I]);
52
53 END;
54
55 BQOL FIRST,ADAMS; INIEGEB K,KOLD,SAME,FAILS;
56 REAL X,XOLD,H,CH,HOLD,TOLCONV,TOLUP,TOL.TOLDWN,A0;
57 ARRAY A(0:7),DD(0:7,0:N),LAST DELTA(1:N), JAC(1:N,1:N),CONST(1:45),
58     TOBS(0:NOBS),OBS(1:NOBS),PARL,PAR,PARU(1:NPAR);
59 INI ARRAY COBS(1:NOBS),PP(1:N);
60
61 PROQ MULTISTEP(XEND,HMIN,HMAX,EPS);

```

PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +3
 NOBS = +20
 ITMAX = +24
 CONVERGE = +.1000000000001₁₀- 1
 EPS = +.9999999999999₁₀- 4
 MESH = +100
 STIFF = FALSE
 FA = +.5180000000000₁₀+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE OBSERVATIONS WERE:

I	TOBS(I)	COBS(I)	OBS(I)						
0	+.01000 ₁₀ - 0								
1	+.51000 ₁₀ - 0	+1	+.11000 ₁₀ + 1	2	+.50000 ₁₀ - 0	+2	+.35000 ₁₀ - 0		
3	+.11000 ₁₀ + 1	+1	+.13000 ₁₀ + 1	4	+.10000 ₁₀ + 1	+2	+.40000 ₁₀ - 0		
5	+.15000 ₁₀ + 1	+1	+.11000 ₁₀ + 1	6	+.15000 ₁₀ + 1	+2	+.50000 ₁₀ - 0		
7	+.21000 ₁₀ + 1	+1	+.90000 ₁₀ - 0	8	+.20000 ₁₀ + 1	+2	+.50000 ₁₀ - 0		
9	+.25000 ₁₀ + 1	+1	+.70000 ₁₀ - 0	10	+.25000 ₁₀ + 1	+2	+.40000 ₁₀ - 0		
11	+.31000 ₁₀ + 1	+1	+.50000 ₁₀ - 0	12	+.30000 ₁₀ + 1	+2	+.30000 ₁₀ - 0		
13	+.35000 ₁₀ + 1	+1	+.60000 ₁₀ - 0	14	+.35000 ₁₀ + 1	+2	+.25000 ₁₀ - 0		
15	+.41000 ₁₀ + 1	+1	+.70000 ₁₀ - 0	16	+.40000 ₁₀ + 1	+2	+.25000 ₁₀ - 0		
17	+.45000 ₁₀ + 1	+1	+.80000 ₁₀ - 0	18	+.45000 ₁₀ + 1	+2	+.30000 ₁₀ - 0		
19	+.51000 ₁₀ + 1	+1	+.10000 ₁₀ + 1	20	+.50000 ₁₀ + 1	+2	+.35000 ₁₀ - 0		

THE PARAMETER ESTIMATES WERE:

I	PARLWB(I)	PAR(I)	PARUPB(I)
1	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.30000 ₁₀ + 1
2	+.0000 ₁₀ - 0	+.10000 ₁₀ + 1	+.30000 ₁₀ + 1
3	+.0000 ₁₀ - 0	+.13000 ₁₀ + 1	+.30000 ₁₀ + 1

					EVALUATIONS OF		
					F	FY	FP
ITERATION NUMBER +1							
COMPUTED RESIDUE (STAND.DEV.)	+ .20345 _m +	2	+ .10940 _m +	1			
ESTIMATED RESIDUE (STAND.DEV.)	+ .50795 _m +	1	+ .54662 _m -	0			
CORRECTIONS FOR PARAMETER	- .63413 _m -	1	+ .45862 _m -	0	+ .29026 _m -	0	
PARAMETER VALUE	+ .93659 _m -	0	+ .14586 _m +	1	+ .15903 _m +	1	117 45 43
ITERATION NUMBER +2							
COMPUTED RESIDUE (STAND.DEV.)	+ .31463 _m +	1	+ .43020 _m -	0			
ESTIMATED RESIDUE (STAND.DEV.)	+ .37049 _m -	0	+ .14763 _m -	0			
CORRECTIONS FOR PARAMETER	- .26418 _m -	1	+ .38646 _m -	0	+ .13818 _m -	0	
PARAMETER VALUE	+ .91017 _m -	0	+ .18451 _m +	1	+ .17284 _m +	1	127 49 43
ITERATION NUMBER +3							
COMPUTED RESIDUE (STAND.DEV.)	+ .43549 _m -	0	+ .16005 _m -	0			
ESTIMATED RESIDUE (STAND.DEV.)	+ .13641 _m -	0	+ .89579 _m -	1			
CORRECTIONS FOR PARAMETER	- .60317 _m -	2	+ .22838 _m -	0	+ .12969 _m -	0	
PARAMETER VALUE	+ .90414 _m -	0	+ .20735 _m +	1	+ .18581 _m +	1	111 41 37
ITERATION NUMBER +4							
COMPUTED RESIDUE (STAND.DEV.)	+ .18044 _m -	0	+ .10303 _m -	0			
ESTIMATED RESIDUE (STAND.DEV.)	+ .15356 _m -	0	+ .95042 _m -	1			
CORRECTIONS FOR PARAMETER	- .14002 _m -	1	+ .57262 _m -	1	+ .87401 _m -	2	
PARAMETER VALUE	+ .89014 _m -	0	+ .21367 _m +	1	+ .18669 _m +	1	97 38 35
ITERATION NUMBER +5							
COMPUTED RESIDUE (STAND.DEV.)	+ .16852 _m -	0	+ .99565 _m -	1			
ESTIMATED RESIDUE (STAND.DEV.)	+ .16509 _m -	0	+ .98545 _m -	1			
CORRECTIONS FOR PARAMETER	- .12529 _m -	1	- .23028 _m -	3	- .20624 _m -	1	
PARAMETER VALUE	+ .87761 _m -	0	+ .21364 _m +	1	+ .18463 _m +	1	91 36 33
STEEPEST DESCENT +.6783314817062 _m - 1							
COMPUTED RESIDUE (STAND.DEV.)	+ .16865 _m -	0	+ .99602 _m -	1			
ESTIMATED RESIDUE (STAND.DEV.)	+ .00000 _m -	0	+ .00000 _m -	0			
CORRECTIONS FOR PARAMETER	- .12279 _m -	1	- .17576 _m -	2	- .10166 _m -	2	
PARAMETER VALUE	+ .87786 _m -	0	+ .21289 _m +	1	+ .18659 _m +	1	93 37 33

ITERATION NUMBER +7
 COMPUTED RESIDUE (STAND.DEV.) +.16779_m- 0 +.99349_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.16507_m- 0 +.98539_m- 1
 CORRECTIONS FOR PARAMETER -.80093_m- 3 +.14125_m- 1 -.55416_m- 2
 PARAMETER VALUE +.87705_m- 0 +.21430_m+ 1 +.18603_m+ 1

93 37 33

STEEPEST DESCENT+.1364513087151_m- 0
 COMPUTED RESIDUE (STAND.DEV.) +.17039_m- 0 +.10012_m- 0
 ESTIMATED RESIDUE (STAND.DEV.) +.00000_m- 0 +.00000_m- 0
 CORRECTIONS FOR PARAMETER +.44054_m- 3 +.13373_m- 1 +.51776_m- 3
 PARAMETER VALUE +.87830_m- 0 +.21423_m+ 1 +.18664_m+ 1

94 37 34

ITERATION NUMBER +9
 COMPUTED RESIDUE (STAND.DEV.) +.16984_m- 0 +.99954_m- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.16845_m- 0 +.99542_m- 1
 CORRECTIONS FOR PARAMETER -.68080_m- 2 -.89510_m- 2 -.22265_m- 1
 PARAMETER VALUE +.87149_m- 0 +.21333_m+ 1 +.18441_m+ 1
 CONFIDENCE INTERVAL (COND.) +.10461_m- 0 +.14431_m- 0 +.13694_m- 0
 CONFIDENCE INTERVAL (INDEPT.) +.23298_m- 0 +.47408_m- 0 +.47495_m- 0

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

COVARIANCE MATRIX

+135250_m- 0 +.62722_m- 0 +.63825_m- 0
 +.87443_m- 1 +.14596_m+ 1 +.13895_m+ 1
 +.88817_m- 1 +.95023_m- 0 +.14650_m+ 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.30574_m- 1 -.67210_m- 0 -.67439_m- 0 +.69525_m- 0
 -.47602_m- 1 +.72133_m- 0 -.50308_m- 0 +.10859_m- 0
 -.82458_m- 1 -.16722_m- 0 +.54047_m- 0 +.97191_m- 1

ITERATION NUMBER +10
 COMPUTED RESIDUE (STAND.DEV.) +.16984_μ- 0 +.99953_μ- 1
 ESTIMATED RESIDUE (STAND.DEV.) +.16967_μ- 0 +.99903_μ- 1
 CORRECTIONS FOR PARAMETER +.74720_μ- 3 +.29422_μ- 2 -.19381_μ- 2
 PARAMETER VALUE +.87224_μ- 0 +.21363_μ+ 1 +.18422_μ+ 1
 CONFIDENCE INTERVAL (COND.) +.10956_μ- 0 +.14536_μ- 0 +.13861_μ- 0
 CONFIDENCE INTERVAL (INDEPT.) +.24304_μ- 0 +.48772_μ- 0 +.47880_μ- 0

RELATIONSHIPS BETWEEN PARAMETERS
 CORRELATION MATRIX

+ .87775_μ-)
 + .88512_μ-) +.95148_μ- 0

COVARIANCE MATRIX

+ .38085_μ- 0 +.67084_μ- 0 +.66409_μ- 0
 +.15337_μ+ 1 +.14326_μ+ 1
 +.14781_μ+ 1

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)

-.31258_μ-) -.67786_μ- 0 -.66544_μ- 0 +.70991_μ- 0
 +.77151_μ-) +.22750_μ- 0 -.59416_μ- 0 +.10212_μ- 0
 +.55414_μ-) -.69911_μ- 0 +.45186_μ- 0 +.10859_μ- 0

RESIDUALS, SPECIFIED FOR EACH OBSERVATION,

1	+.1570 _u - 1	2	-.15551 _u - 1
3	+.20867 _u - 0	4	-.67389 _u - 1
5	+.13641 _u - 0	6	-.57497 _u - 1
7	+.91303 _u - 1	8	-.70121 _u - 1
9	-.22814 _u - 2	10	-.10476 _u - 0
11	-.16528 _u - 0	12	-.11376 _u - 0
13	-.91623 _u - 1	14	-.87445 _u - 1
15	-.65997 _u - 1	16	-.40703 _u - 1
17	-.77560 _u - 1	18	+.22896 _u - 1
19	-.73487 _u - 3	20	+.49724 _u - 1

132

51

47

THE ENTIRE CALCULATION CONSUMED 78.20 SEC. ON THE EL X8.

6.5. Analyzing a sum of exponentials

As another example of parameter estimation we report some experiences with linear differential equations. Analysing a sum of exponentials can be considered as the estimation of parameters in a linear initial value problem. Here the parameters appear as well in the differential equations as in the initial values. Since the parameters appear in a nonlinear way, our estimation problem is a nonlinear one. However, the linearity of the differential equation causes a rather efficient use of the integration method.

We consider the sum of exponentials

$$y(t) = a + be^{\lambda t} + ce^{\mu t} .$$

To this function $y(t)$ we associate a system of linear differential equations

$$\dot{y}(t) = z$$

$$\dot{z}(t) = -\lambda\mu y + (\lambda+\mu)z + \lambda\mu a .$$

This system has the general solution

$$\begin{pmatrix} y \\ z \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ \lambda \end{pmatrix} e^{\lambda t} + c_2 \begin{pmatrix} 1 \\ \mu \end{pmatrix} e^{\mu t} + \begin{pmatrix} a \\ 0 \end{pmatrix} .$$

With initial conditions

$$y(0) = a + b + c$$

$$z(0) = \lambda b + \mu c$$

this system has the particular solution

$$y(t) = a + be^{\lambda t} + ce^{\mu t}$$

$$z(t) = \lambda be^{\lambda t} + \mu ce^{\mu t}$$

It appears from the general solution that it will be difficult to determine the parameters in the case that $\lambda \approx \mu$. In order to be able to determine the complete set of parameters, it is evident that the observations should contain information about both exponentials: some observations have to represent $e^{\lambda t}$ (sample times t , with the order of magnitude $1/\lambda$) and some observations have to represent $e^{\mu t}$. The example shown below satisfies these conditions.

In order to make intelligible the details of the example we give the initial values and functions as they are used in the program.

Notation $y1 = y(t)$; $y2 = z(t)$; $f1 = \dot{y}(t)$; $f2 = \dot{z}(t)$.

Initial values ($t=0$):

$$\begin{array}{ll} y1 & = a + b + c & y2 & = \lambda b + \mu c \\ \partial f1/\partial a & = 1 & \partial f2/\partial a & = 0 \\ \partial f1/\partial b & = 1 & \partial f2/\partial b & = \lambda \\ \partial f1/\partial c & = 1 & \partial f2/\partial c & = \mu \\ \partial f1/\partial \lambda & = 0 & \partial f2/\partial \lambda & = b \\ \partial f1/\partial \mu & = 0 & \partial f2/\partial \mu & = c \end{array}$$

Functions :

$$\begin{array}{l} f1 = y2 \\ f2 = (\lambda + \mu) y2 + \lambda \mu (a - y1) \\ \\ \partial f1/\partial y1 = 0 & \partial f1/\partial y2 = 1 \\ \partial f2/\partial y1 = -\lambda \mu & \partial f2/\partial y2 = \lambda + \mu \\ \\ \partial f1/\partial a = \partial f1/\partial b = \partial f1/\partial c = \partial f1/\partial \lambda = \partial f1/\partial \mu = 0 \\ \partial f2/\partial b = \partial f2/\partial c = 0 \\ \partial f2/\partial a = \lambda \mu \\ \partial f2/\partial \lambda = y2 + \mu(a - y1) \\ \partial f2/\partial \mu = y2 + \lambda(a - y1) \end{array}$$

B13681.138,PHEMKER,T150

```

1  BEGIN COMMENT ANALIZING A SUM OF EXPONENTIALS;
2
3  BBQC ODEPAREST(N,NOBS,NPAR,DATA,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
4  VAL N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA;
5  INI N,NOBS,NPAR,ITMAX,MESHP; REAL CONVERGE,EPS,FA; BQQL STIFF; BBQC DATA;
6  BEGIN COMMENT Y(U, 1 2
7  PAR[1]= C 3 4
8  PAR[2]= MU 5 6
9  PAR[3]= B 7 8
10 PAR[4]= LAMBDA 9 10
11 PAR[5]= A 11 12 );
12
13 BBQC CALL YSTART;
14 BEGIN YMAX[1]:= SUM(1,0,2,ABS(PAR[1+I+I]));
15 YMAX[2]:= ABS(PAR[1]*PAR[2]) + ABS(PAR[3]*PAR[4]);
16 Y(0,1):= SUM(1,0,2,PAR[1+I+I]);
17 Y(0,2):= PAR[1]*PAR[2] + PAR[3]*PAR[4];
18 Y(0,3):= Y(0,7):= Y(0,11):= 1;
19 Y(0,4):= PAR[2]; Y(0,6):= PAR[1];
20 Y(0,8):= PAR[4]; Y(0,10):= PAR[3];
21 EQB 1:= 1;2,3,4,5 DQ FP(1,1):= 0;
22 FP(2,1):= FP(2,3):= FY(1,1):= 0) OUTC
23 END;
24
25 BBQC CALL F(R); VAL R; REAL R;
26 BEGIN F(1):= R*Y(0,2); CF1:= CF + 1;
27 F(2):= R*((PAR[2]+PAR[4])*Y(0,2)
28 + PAR[2]*PAR[4]*(PAR[5]-Y(0,1)));
29 END;
30
31 BBQC CALL FY(R); VAL R; REAL R;
32 BEGIN FY(1,2):= R; CFY1:= CFY + 1;
33 FY(2,1):= -R*PAR[2]*PAR[4];
34 FY(2,2):= R*(PAR[2]+PAR[4]);
35 END;
36
37 BBQC CALL FP(R); VAL R; REAL R;
38 BEGIN FP(2,5):= R*PAR[2]*PAR[4]; CFP1:= CFP + 1;
39 FP(2,2):= R*(Y(0,2) + PAR[4]*(PAR[5]-Y(0,1)));
40 FP(2,4):= R*(Y(0,2) + PAR[2]*(PAR[5]-Y(0,1)));
41 END;
42
43 ARRAY Y(0:7,1:N*(NPAR+1)),YMAX,F(1:N),FY(1:N,1:N),FP(1:N,1:NPAR);
44 BBQC PR(S); BEGIN NLCR; PRINTTEXT(S) ENQ;
45 BBQC FL(R); FLOT(5,3,R);
46 BBQC PF(S,R); BEGIN PR(S); TAB; FL(R) END;
47
48 BBQC OUT(S,R); SIBING S; REAL R;
49 BEGIN INI 1; IF LINENUMBER>50 THEN NEW PAGE ELSE NLCR;
50 PR(S); PRINT(R);
51 PF(1,COMPUTED RESIDUE (STAND.DEV.)},COMP ERROR);
52 FL(SQRT(COMP ERROR/(NOBS-NPAR)));
53 PF(1,ESTIMATED RESIDUE (STAND.DEV.)},EST ERROR);
54 FL(SQRT(EST ERROR/(NOBS-NPAR)));
55 PR(1,CORRECTIONS FOR PARAMETER}); TAB;
56 EQB 1:=1 SIER 1 UNILL NPAR DQ FL(DELTA PAR(1)); NLCR;

```

```

417      ERQC PF(S,R); BEGIN PR(S); TAB; FL(R) END;
418
419      INI CF,CFY,CFP;
420      ERQC OUTC;
421      BEGIN INI R; NLCR; SPACE(100); IE CF=0 THEN
422          BEGIN SPACE(6); PRINTTEXT({EVALUATIONS OF}); NLCR; SPACE(106);PRINTTEXT({F      FY      FP}) END ELSE
423          EQB R:= CF,CFY,CFP DO ABSFIXT(6,0,R);
424          CF:= CFY:= CFP:= 0;
425      END;
426
427      ERQC EXP DATA(N,T,CT,O,NP,PL,P,PU);
428      BEGIN REAL A,B,C,L,M,TOBS,TT; INI I,NOBS,NPAR;
429          TT:= TIME;
430          A:= P[5]:= READ; B:= P[3]:= READ; C:= P[1]:= READ; L:= P[4]:= READ; M:= P[2]:= READ;
431          NLCR; NLCR; PRINTTEXT({THE PROGRAM TRIES TO FIT THE SUM OF EXPONENTIALS});
432          NLCR;FIXT(3,2,C); PRINTTEXT({ * EXP( }); FIXT(3,2,M); PRINTTEXT({ * T });
433          FIXT(3,2,B); PRINTTEXT({ * EXP( }); FIXT(3,2,L); PRINTTEXT({ * T }); FIXT(3,2,A); NLCR; NLCR;
434          NLCR; NLCR;TOBS:= T[0]:= 0; N:= NOBS:= READ;
435          PRINTTEXT({THE FUNCTION WAS SAMPLED AT T=}); NLCR;
436          EQB I:= 1 STEP 1 UNTIL NOBS DO
437              BEGIN TOBS:= T[I]:= READ; CT[I]:= 1; FL(TOBS);
438                  O[I]:= A + B*EXP(L*TOBS) + C*EXP(TOBS*M);
439                  IE PRINTPOS>70 THEN NLCR ELSE TAB;
440              END; NLCR;
441          NP:= NPAR:= READ; NLCR; PRINTTEXT({THE PARAMETER ESTIMATES WERE:});
442          PR({ I PARLWB(I) PAR(I) PARUPB(I)});
443          EQB I:= 1 STEP 1 UNTIL NPAR DO
444              BEGIN NLCR; ABSFIXT(3,0,I); A:=PL[I]:= READ; FL(A); A:= P[I]:= READ; FL(A); A:= PU[I]:= READ; FL(A) END;
445          NEW PAGE; TIM:= TIM + TT - TIME
446      END;
447      REAL TIM;
448
449      ERQC EXP JOB(N,NOBS,NPAR,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
450      VAL N,NOBS,NPAR,ITMAX,CONVERGE,MESHP,STIFF,FA;
451      INI N,NOBS,NPAR,ITMAX,MESHP; REAL CONVERGE,EPS,FA; BQQI STIFF;
452      BEGIN PR({PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:});
453          P({N =,N}); P({NPAR =,NPAR}); P({NOBS =,NOBS}); P({ITMAX=,ITMAX});
454          P({CONVERGE =,CONVERGE}); P({EPS =,EPS}); P({MESHP=,MESHP});
455          PR({STIFF= }); TAB; IE STIFF THEN PRINTTEXT({ TRUE}) ELSE PRINTTEXT({ FALSE});
456          P({FA = ,FA}); PR({THE CONFIDENCE REGION AT LEVEL A IS PRINTED});
457          PR({FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM});
458          NLCR; CF:= CFY:= CFP:= 0; TIM:= TIME;
459          ODEPAREST(N,NOBS,NPAR,EXP DATA,ITMAX,CONVERGE,EPS,MESHP,STIFF,FA);
460          TIM:= TIME-TIM; OUTC; NLCR;NLCR; NLCR;
461          PR({THE ENTIRE CALCULATION CONSUMED}); ABSFIXT(3,2,TIM); PRINTTEXT({SEC. ON THE EL X8,});
462      END JOB;
463
464      EXP JOB(2,READ,5,16,0.01,,=4.100,IRUE,5.06);
465      COMMENT 5.06= F(0.01)(5,12);
466
467      END

```

PROCEDURE ODEPAREST WAS CALLED WITH THE PARAMETERS:

N = +2
 NPAR = +5
 NOBS = +17
 ITMAX = +16
 CONVERGE = +.10000000000001₁₆- 1
 EPS = +.999999999999999₁₆- 4
 MESH = +100
 STIFF = TRUE
 FA = +.50599999999998₁₆+ 1

THE CONFIDENCE REGION AT LEVEL A IS PRINTED

FA IS THE A-POINT OF THE F-DISTRIBUTION WITH NPAR AND NOBS-NPAR DEGREES OF FREEDOM

THE PROGRAM TRIES TO FIT THE SUM OF EXPONENTIALS

-3.00 * EXP(-20.00 * T) + 2.00 * EXP(-1.00 * T) + 1.00

THE FUNCTION WAS SAMPLED AT T=

+ .20000 ₁₆ - 1	+ .40000 ₁₆ - 1	+ .60000 ₁₆ - 1	+ .80000 ₁₆ - 1	+ .10000 ₁₆ - 0
+ .20000 ₁₆ -)	+ .40000 ₁₆ - 0	+ .60000 ₁₆ - 0	+ .80000 ₁₆ - 0	+ .10000 ₁₆ + 1
+ .20000 ₁₆ + 1	+ .30000 ₁₆ + 1	+ .40000 ₁₆ + 1	+ .50000 ₁₆ + 1	+ .10000 ₁₆ + 2
+ .15000 ₁₆ + 2	+ .20000 ₁₆ + 2			

THE PARAMETER ESTIMATES WERE:

I	PARLWB[I]	PAR[I]	PARUPB[I]
1	-.1000 ₁₆ + 2	-.50000 ₁₆ + 1	+.10000 ₁₆ + 2
2	-.4000 ₁₆ + 2	-.10000 ₁₆ + 2	-.10000 ₁₆ - 1
3	-.5000 ₁₆ + 1	+.50000 ₁₆ + 1	+.50000 ₁₆ + 1
4	-.5000 ₁₆ + 1	-.50000 ₁₆ - 0	-.10000 ₁₆ - 0
5	-.5000 ₁₆ + 1	+.50000 ₁₆ - 0	+.50000 ₁₆ + 1

										EVALUATIONS OF			
										P	PY	FP	
ITERATION NUMBER +1													
COMPUTED RESIDUE (STAND.DEV.)	+ .23845 _u +	2	+ .14097 _u +	1									
ESTIMATED RESIDUE (STAND.DEV.)	+ .16545 _u -	1	+ .37132 _u -	1									
CORRECTIONS FOR PARAMETER	+ .22491 _u +	1	- .42683 _u +	1	- .30728 _u +	1	- .10424 _u -	0	+ .51105 _u -	0			
PARAMETER VALUE	- .27509 _u +	1	- .14268 _u +	2	+ .19272 _u +	1	- .60424 _u -	0	+ .10111 _u +	1	165	84	82
ITERATION NUMBER +2													
COMPUTED RESIDUE (STAND.DEV.)	+ .75052 _u -	0	+ .25009 _u -	0									
ESTIMATED RESIDUE (STAND.DEV.)	+ .23014 _u -	2	+ .13849 _u -	1									
CORRECTIONS FOR PARAMETER	- .25946 _u -	0	- .50296 _u +	1	+ .63934 _u -	1	- .24332 _u -	0	+ .10982 _u -	2			
PARAMETER VALUE	- .30104 _u +	1	- .19298 _u +	2	+ .19911 _u +	1	- .84756 _u -	0	+ .10122 _u +	1	152	78	76
ITERATION NUMBER +3													
COMPUTED RESIDUE (STAND.DEV.)	+ .76284 _u -	1	+ .79731 _u -	1									
ESTIMATED RESIDUE (STAND.DEV.)	+ .22978 _u -	4	+ .13838 _u -	2									
CORRECTIONS FOR PARAMETER	- .59071 _u -	2	- .69262 _u -	0	+ .15834 _u -	1	- .13000 _u -	0	- .10842 _u -	1			
PARAMETER VALUE	- .30163 _u +	1	- .19991 _u +	2	+ .20070 _u +	1	- .97756 _u -	0	+ .10013 _u +	1	159	81	79
ITERATION NUMBER +4													
COMPUTED RESIDUE (STAND.DEV.)	+ .22891 _u -	2	+ .13812 _u -	1									
ESTIMATED RESIDUE (STAND.DEV.)	+ .12321 _u -	5	+ .32042 _u -	3									
CORRECTIONS FOR PARAMETER	+ .16256 _u -	1	- .59411 _u -	2	- .57463 _u -	2	- .22140 _u -	1	- .13863 _u -	2			
PARAMETER VALUE	- .30001 _u +	1	- .19996 _u +	2	+ .20012 _u +	1	- .99970 _u -	0	+ .99992 _u -	0	162	82	80
ITERATION NUMBER +5													
COMPUTED RESIDUE (STAND.DEV.)	+ .80985 _u -	5	+ .82151 _u -	3									
ESTIMATED RESIDUE (STAND.DEV.)	+ .23709 _u -	6	+ .14056 _u -	3									
CORRECTIONS FOR PARAMETER	+ .12845 _u -	3	+ .27472 _u -	2	- .97612 _u -	3	- .66138 _u -	3	+ .12205 _u -	3			
PARAMETER VALUE	- .29999 _u +	1	- .19994 _u +	2	+ .20002 _u +	1	- .10004 _u +	1	+ .10000 _u +	1	162	82	80
ITERATION NUMBER +6													
COMPUTED RESIDUE (STAND.DEV.)	+ .23464 _u -	6	+ .13983 _u -	3									
ESTIMATED RESIDUE (STAND.DEV.)	+ .22232 _u -	6	+ .13611 _u -	3									
CORRECTIONS FOR PARAMETER	- .67500 _u -	4	- .58372 _u -	4	+ .15898 _u -	4	+ .51143 _u -	4	+ .32551 _u -	5			
PARAMETER VALUE	- .30000 _u +	1	- .19994 _u +	2	+ .20003 _u +	1	- .10003 _u +	1	+ .10000 _u +	1	162	82	80

ITERATION NUMBER	+7							
COMPUTED RESIDUE (STAND.DEV.)	+ .22367 _μ -	6	+ .13653 _μ -	3				
ESTIMATED RESIDUE (STAND.DEV.)	+ .22362 _μ -	6	+ .13651 _μ -	3				
CORRECTIONS FOR PARAMETER	+ .19926 _μ -	5	- .28885 _μ -	4	+ .16144 _μ -	5 + .46270 _μ - 6 - .39176 _μ - 6		
PARAMETER VALUE	- .30000 _μ +	1	- .19994 _μ +	2	+ .20003 _μ +	1 - .10003 _μ +	1 + .10000 _μ +	1
CONFIDENCE INTERVAL (COND.)	+ .84794 _μ -	3	+ .68985 _μ -	2	+ .28098 _μ -	3 + .42610 _μ -	3 + .16653 _μ -	3
CONFIDENCE INTERVAL (INDEPT.)	+ .18685 _μ -	2	+ .18846 _μ -	1	+ .78593 _μ -	3 + .93961 _μ -	3 + .30832 _μ -	3

RELATIONSHIPS BETWEEN PARAMETERS
CORRELATION MATRIX

		COVARIANCE MATRIX									
		+ .74056 _μ +	1	+ .39859 _μ +	2	- .68451 _μ -	0	+ .12606 _μ -	0	- .30724 _μ -	1
				+ .75334 _μ +	3	+ .17964 _μ +	2	- .23259 _μ +	2	+ .22636 _μ +	1
+ .53365 _μ -	J					+ .13102 _μ +	1	- .99803 _μ -	0	- .59142 _μ -	1
- .21975 _μ -	K	+ .57179 _μ -	0					+ .18726 _μ +	1	- .32541 _μ -	0
+ .33872 _μ -	L	- .61924 _μ -	0	- .63718 _μ -	0					+ .20162 _μ -	0
- .25144 _μ -	M	+ .18367 _μ -	0	- .11507 _μ -	0	- .52958 _μ -	0				

PRINCIPAL AXES (DIRECTION COSINES AND CONFIDENCE INTERVAL ALONG EACH AXIS)											
+ .93584 _μ -	L	- .99677 _μ -	2	+ .43473 _μ -	0	+ .25681 _μ -	0	+ .85802 _μ -	0	+ .14504 _μ -	3
+ .33243 _μ -	J	- .43710 _μ -	1	+ .82575 _μ -	0	- .24470 _μ -	0	- .38190 _μ -	0	+ .43795 _μ -	3
- .21247 _μ -	K	+ .35278 _μ -	1	+ .19399 _μ -	0	+ .89379 _μ -	0	- .34222 _μ -	0	+ .62653 _μ -	3
- .91256 _μ -	L	+ .32859 _μ -	1	+ .30160 _μ -	0	- .27269 _μ -	0	+ .28725 _μ -	1	+ .17145 _μ -	2
+ .53060 _μ -	M	+ .99783 _μ -	0	+ .23724 _μ -	1	- .30773 _μ -	1	+ .29953 _μ -	2	+ .18887 _μ -	1

RESIDUALS, SPECIFIED FOR EACH OBSERVATION,

1	-.44339 ₁₀	5
2	+.11727 ₁₀	3
3	+.81554 ₁₀	4
4	+.51513 ₁₀	4
5	+.14461 ₁₀	4
6	-.66740 ₁₀	4
7	-.48047 ₁₀	4
8	+.16470 ₁₀	4
9	+.61385 ₁₀	4
10	+.96188 ₁₀	4
11	+.94246 ₁₀	4
12	+.69905 ₁₀	4
13	+.97097 ₁₀	5
14	-.29693 ₁₀	4
15	-.56893 ₁₀	4
16	-.43462 ₁₀	4
17	-.65404 ₁₀	4

225

114

109

THE ENTIRE CALCULATION CONSUMED 153.13 SEC. ON THE EL 28.

References

- Bellman R., Jacquez J., Kalaba R. and Schwimmer S.
Quasilinearization and the estimation of chemical rate constants
from raw kinetic data.
Math. Biosc. 1(1967) 71-76.
- Bellman R. and Kalaba R.
Quasilinearization and nonlinear boundary value problems.
American Elsevier, New York, 1965.
- Dekker T.J. and Hoffmann W.
ALGOL 60 procedures in numerical algebra. Part 1 and 2.
Mathematical Centre Tracts 22, 23 (1968).
- Grüne D.
Handleiding voor het MILLI systeem voor de EL X8.
LR 1.1., Mathematisch Centrum, Amsterdam (1972).
- Heineken F.G., Tsuchiya H.M. and Aris R.
On the mathematical status of the pseudo steady state hypothesis
of biochemical kinetics.
Math. Biosc. 1(1967) 95-113.
- Hemker P.W.
An ALGOL 60 procedure for the solution of stiff differential
equations.
MR 128, Mathematisch Centrum, Amsterdam (1971).
- Lotka A.J.
Elements of mathematical biology.
Dover, New York, 1956 (1st ed. 1924).
- Volterra V.
Leçons sur la théorie mathématique de la lutte pour la vie.
Gauthier-Vilars, Paris, 1931.
- Willems G.
Parameter bepaling in de biomathematics.
In: Colloquium stijve differentiaalvergelijkingen.
MC Syllabus, Mathematisch Centrum, Amsterdam (to appear).