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Report TW 78

Distributions on Surfaces

by

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March 1962

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§ 0. This topic has not yet, so far as we know, received a very thorough treatment in the literature, but it shows promise of becoming a useful tool. The classical solution of the wave equation by Hadamard (for uneven space dimensions) can be given in such terms; and they are used (if somewhat loosely) to describe the solutions of the Klein-Gordon equation  $\sum \partial^2 u / \partial x_i^2 - \partial^2 u / \partial t^2 - m^2 u = 0$  desired in quantum field theory.

This report contains a cleaned-up version of pp. 200-227 of Verallgemeinerte Funktionen I, by Gelfand and Shilov, with a few additions.

The principal difference is in the definition of the distributions in question,  $\mathcal{J}^{(k)}(P)$ . The present definition leads to much simpler proofs of existence and uniqueness of the  $\mathcal{J}^{(k)}(P)$ , as well as of the relevant formulas. The only differential geometry required is Gauss' theorem in  $R_n$ .

§ 1. We consider distributions concentrated on a surface in  $R_n$  of dimension  $n-1$  given by an equation  $P(x)=0$ , where  $x=(x_1, \dots, x_n)$ ,  $P$  is a  $C^\infty$  function, and  $\nabla P$  never vanishes on  $\{P=0\}$ .

The simplest case is  $n=1$ ,  $P(x)=x$ ; the distributions concentrated on  $\{x=0\}$  are linear combinations of  $\mathcal{J}(x)$ ,  $\mathcal{J}'(x)$ , etc. These are all derivatives of the regular distribution  $\theta(x)$ :  $(\theta(x), \varphi) = \int_{x \geq 0} \varphi(x) dx$ . If we now let  $P$  be a more general  $C^\infty$  function with no double zeros, then  $\theta(P)$  is easy to define:  $(\theta(P), \varphi) = \int_{P(x) \geq 0} \varphi(x) dx$ .  $\mathcal{J}(P)$  should in some sense be the derivative of  $\theta$ , in fact it is  $d\theta(P)/dP = d\theta(P)/dx \cdot dx/dP$ . Thus  $(\mathcal{J}(P), \varphi) = \sum_{x=z_n} \varphi(x) / |P'(x)|$ , where  $z_n$  are the zeros of  $P$ . Similarly  $\mathcal{J}^{(k)}(P) = d^{k+1} \theta(P) / dP^{k+1}$ .

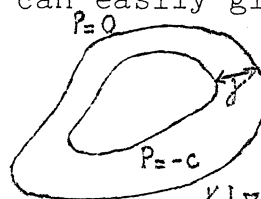
§ 2. Leaving the case  $n=1$ , we find that  $\theta(P)$  is still easy to define by  $(\theta(P), \varphi) = \int_{P \geq 0} \varphi$ .  $\mathcal{J}(P)$  should be in some sense the derivative of  $\theta(P)$  with respect to  $P$ . The most

naive interpretation of this turns out to serve very well.

Definition. If  $P$  is a  $C^\infty$  function with  $\nabla P$  never zero on  $\{P=0\}$ , then  $\mathcal{J}(P) = \lim_{c \rightarrow 0} \frac{1}{c} [\mathcal{J}(P+c) - \mathcal{J}(P)]$ , and

$$\mathcal{J}^{(k+1)}(P) = \lim_{c \rightarrow 0} \frac{1}{c} [\mathcal{J}^{(k)}(P+c) - \mathcal{J}^{(k)}(P)].$$

It is not immediately clear that any of these distributions exist, but we can easily give an interpretation of  $\mathcal{J}(P)$ . Let  $d\sigma$  be the surface measure on  $\{P=0\}$ .



Then we have  $(\mathcal{J}(P), \varphi) =$

$$\lim_{c \rightarrow 0^+} \frac{1}{c} \int_{-c \leq P \leq 0} \varphi dx \approx \lim_{c \rightarrow 0} \frac{1}{c} \int_{P=0} \varphi c \frac{d\sigma}{|\nabla P|} = \int_{P=0} \varphi \frac{d\sigma}{|\nabla P|}.$$

This agrees with the case  $n=1$  considered above.

§ 3. We establish the existence of  $\mathcal{J}^{(k)}(P)$  by giving it a concrete representation in terms of suitably chosen local coordinates. In some neighbourhood  $V$  of any point on  $\{P=0\}$  we can introduce new coordinates  $u=u(x)$  such that  $u_1=P$ , the Jacobean  $\frac{\partial u}{\partial x} \neq 0$ , and the  $x$  can also be written uniquely as a function  $x(u)$  of  $u$ . If  $\partial P / \partial x_1$  is not zero in  $V$ , for instance, we can choose  $u_1=P$ ,  $u_2=x_2, \dots, u_n=x_n$ ; and since one of the  $\partial P / \partial x_j$  is non-zero in a sufficiently small neighbourhood of any point on  $\{P=0\}$ , some such system is always available. For a test function  $\varphi$  with support in  $V$  we have

$$\begin{aligned} (\mathcal{J}(P), \varphi) &= \int_{P \geq 0} \varphi dx = \int_{u_1 \geq 0} \varphi \left| \frac{\partial x}{\partial u} \right| du, \text{ and} \\ \lim_{c \rightarrow 0} \frac{1}{c} (\mathcal{J}(P+c) - \mathcal{J}(P), \varphi) &= \lim_{c \rightarrow 0} \frac{1}{c} \int_{-c \leq u_1 \leq 0} \varphi \left| \frac{\partial x}{\partial u} \right| du_1 \dots du_n = \\ &= \int \left[ \varphi \left| \frac{\partial x}{\partial u} \right| \right]_{u_1=0} du_2 \dots du_n. \text{ Further } (\mathcal{J}^{(1)}(P), \varphi) = \\ \lim_{c \rightarrow 0} \int \frac{\left[ \varphi \left| \frac{\partial x}{\partial u} \right| \right]_{u_1=-c} - \left[ \varphi \left| \frac{\partial x}{\partial u} \right| \right]_{u_1=0}}{c} du_2 \dots du_n \end{aligned}$$

$$= - \int_{u_1=0} \left[ \partial(\varphi) \left| \frac{\partial x}{\partial u} \right| \right] / \partial u_1 \Big|_{u_1=0} du_2 \dots du_n, \text{ and}$$

generally

$$(\mathcal{J}^{(k)}(P), \varphi) = (-1)^k \int \left[ \partial^{(k)}(\varphi) \left| \frac{\partial x}{\partial u} \right| \right] / \partial u_1^k \Big|_{u_1=0} du_2 \dots du_n.$$

Thus  $\mathcal{J}(P)$  is a simple layer, and  $\mathcal{J}^{(k)}(P)$  a  $(k+1)$ -fold layer, roughly speaking. The expression for  $\mathcal{J}(P)$  gives a strict justification of the formula obtained in (§ 2).

#### § 4. Examples

$$i) P(x_1, \dots, x_n) = x_1. \quad \mathcal{J}^{(k)}(x_1) = \int \left[ \partial^k \varphi / \partial x_1^k \right]_{x_1=0} dx_2 \dots dx_n,$$

$$ii) P(x_1, \dots, x_n) = r - c, \quad r^2 = \sum_{j=1}^n x_j^2. \text{ Since } |\nabla P| = 1,$$

we have  $(\mathcal{J}(r-c), \varphi) = \int_{r=c} \varphi d\sigma$ , with  $d\sigma$  the surface area on

$r = c$ , i.e.  $d\sigma = c^{n-1} d\Omega$ , where  $d\Omega$  is the surface area on the unit sphere  $\Omega$ . Let  $x = r\omega$  with  $|\omega| = 1$ . Then finally

$$(\mathcal{J}(P), \varphi) = \int_{\Omega} \varphi(c\omega) c^{n-1} d\Omega. \text{ Using the definition in (§ 2),}$$

$$(\mathcal{J}'(P), \varphi) = \lim_{\varepsilon \rightarrow 0} \int_{\Omega} \frac{1}{\varepsilon} [\varphi((c-\varepsilon)\omega)(c-\varepsilon)^{n-1} - \varphi(c\omega)c^{n-1}] d\Omega$$

$$= - \int_{\Omega} \left[ \partial \varphi(r\omega) r^{n-1} / \partial r \right]_{r=c} d\Omega,$$

and generally

$$(\mathcal{J}^{(k)}(P), \varphi) = (-1)^k \int_{\Omega} \left[ \partial^k \varphi(r\omega) r^{n-1} / \partial r^k \right]_{r=c} d\Omega.$$

$$iii) P = r^2 - c^2. \text{ Proceeding as in (ii),}$$

$$(\mathcal{J}(P), \varphi) = \frac{1}{2} \int_{\Omega} \varphi(c\omega) c^{n-2} d\Omega,$$

$$(\mathcal{J}'(P), \varphi) = \lim \frac{1}{2} \int_{\Omega} \frac{1}{\varepsilon} [\varphi(\omega \sqrt{c^2 - \varepsilon})(c^2 - \varepsilon)^{n-2} - \varphi(c\omega) c^{n-2}] d\Omega$$

$$= \frac{1}{2} \int_{\Omega} \left[ \frac{1}{2r} \partial \varphi(r\omega) r^{n-2} / \partial r \right]_{r=c} d\Omega, \text{ and generally}$$

$$(\mathcal{J}^{(k)}(P), \varphi) = \frac{1}{2} \int_{\Omega} \left[ \left( \frac{1}{2r} \frac{\partial}{\partial r} \right)^k \varphi(r\omega) r^{n-2} \right]_{r=c} d\Omega.$$

iv)  $P = x_1^2 - \sum_{j=2}^n x_j^2 - c^2$ .  $\{P=0\}$  is a hyperboloid, on each sheet of which we can set  $u_1=P$ ,  $u_2=x_2, \dots, u_n=x_n$ , and apply the formula of (§ 3). We have for the Jacobian  $\partial u / \partial x = 2x_1$ , and

$$\frac{\partial}{\partial u_1} = \sum_{j=2}^n \frac{\partial x_j}{\partial u_1} \frac{\partial}{\partial x_j} = \frac{1}{2x_1} \frac{\partial}{\partial x_1}. \text{ Thus}$$

$$\begin{aligned} (\mathcal{J}^{(k)}(P), \varphi) &= \\ &= (-1)^k \int_{-\infty}^{\infty} \int \left[ \left( \frac{\partial}{2x_1 \partial x_1} \right)^k (\varphi(x_1, \dots, x_n) / 2|x_1|) \right]_{x_1 = \sqrt{\sum_{j=2}^n x_j^2 + c^2}} \\ &\quad + \left[ \left( \frac{\partial}{2x_1 \partial x_1} \right)^k (\varphi(x_1, \dots, x_n) / 2|x_1|) \right]_{x_1 = -\sqrt{\sum_{j=2}^n x_j^2 + c^2}} dx_2 \dots dx_n \\ &= (-1)^k \int_{-\infty}^{\infty} \int \left( \frac{1}{2x_1} \frac{\partial}{\partial x_1} \right)^k (\varphi(x) / 2x_1) \Big|_{x_1 = -\sqrt{\sum_{j=2}^n x_j^2 + c^2}}^{x_1 = \sqrt{\sum_{j=2}^n x_j^2 + c^2}} dx_2 \dots dx_n. \end{aligned}$$

This could also be written as

$$\begin{aligned} (\mathcal{J}^{(k)}(P), \varphi) &= (-1)^k \int_{|x_1| < \sqrt{\sum_{j=2}^n x_j^2 + c^2}} \left( \frac{\partial}{\partial x_1} \frac{1}{2x_1} \right)^{k+1} \varphi(x) dx_2 \dots dx_n \\ &= -(\theta(-P), \left( -\frac{\partial}{\partial x_1} \frac{1}{2x_1} \right)^{k+1} \varphi), \text{ which gives a} \\ &\text{regularization of } \mathcal{J}^{(k)}(x_1^2 - \sum_{j=2}^n x_j^2 - c^2). \end{aligned}$$

## § 5. Chain rules for $\mathcal{J}^{(k)}(P)$ .

The significance of  $\mathcal{J}^{(k)}(P)$  lies primarily in the chain rule  $\partial \mathcal{J}^{(k)}(P) / \partial x_j = \mathcal{J}^{(k+1)}(P) \partial P / \partial x_j$ . Except for this, it would have little advantage over the standard "layers" defined on a surface  $S$  independently of its representation, i.e.  $(L^{(k)}(S), \varphi) = (-1)^k \int_S \partial^k \varphi / \partial v^k d\sigma$ , with  $\partial / \partial v$  the normal derivative.

We establish the chain rule inductively, starting with  $\theta(P) = \mathcal{J}^{(-1)}(P)$ . Let  $\vec{\varphi}_j = (0, \dots, \varphi, \dots, 0)$ , with the non-zero entry in place  $j$ . Then

$$(\partial \theta(P) / \partial x_j, \varphi) = - \int_{P \geq 0} \partial \varphi / \partial x_j dx = - \int_{P \geq 0} \nabla \cdot \vec{\varphi}_j dx = - \int_{P=0} \vec{\varphi}_j \cdot \vec{n} d\sigma,$$

with  $\vec{n} = -\nabla P / |\nabla P|$  the outer normal to the boundary of

$P \geq 0$ . Thus  $(\partial \theta(P)/\partial x_j, \varphi) = \int_{P=0} P_j \varphi \frac{d\sigma}{|\nabla P|} = (P_j \delta(P), \varphi)$ , as

desired. In general, by induction,

$$\begin{aligned} (\partial \theta^{(k)}(P)/\partial x_j, \varphi) &= -\lim_{c \rightarrow 0} \frac{1}{c} (\delta^{(k-1)}(P+c) - \delta^{(k-1)}(P), \partial \varphi / \partial x_j) \\ &= \lim_{c \rightarrow 0} \frac{1}{c} (\delta^{(k)}(P+c) - \delta^{(k)}(P), P_j \varphi) = (P_j \delta^{(k+1)}(P), \varphi). \end{aligned}$$

## § 6. Another formula

We have  $(P \delta(P), \varphi) = \int_{P=0} \frac{P \varphi}{|\nabla P|} d\sigma = 0$ . Differentiating,

$P_j \delta(P) + P_j P \delta'(P) = 0$ , so  $|\nabla P|^2 [\delta(P) + P \delta'(P)] = 0$ , and  $\delta(P) + P \delta'(P) = 0$ . By further differentiating we find

$$\underline{P \delta^{(k)}(P) = -k \delta^{(k-1)}(P)}.$$

§ 7. Before we can apply the  $\delta^{(k)}$  to solving the wave equation, we need a rule for differentiating  $\delta(P)$  with respect to a parameter.

Consider a function  $P(x, t) = P_t(x)$ . Suppose that for  $a < t < b$ ,  $P(x, t)$  is  $C^\infty$  in its  $n+1$  variables, and

$|P|^2 + \sum_1^n |\partial P / \partial x_j|^2 > 0$ . Then we can introduce local

coordinates in  $n+1$  space by  $u_1 = P(x, t)$ ,  $u_2 = u_2(x, t), \dots, u_n = u_n(x, t)$ ,  $t = t$ . This is permissible, since

$\frac{\partial(u, t)}{\partial(x, t)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \dots & \frac{\partial u}{\partial t} \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{vmatrix} = \frac{\partial u}{\partial x} \neq 0$ . Now let  $\varphi(x)$  be a test function

with support in the domain where the  $u$ -coordinates are

valid, and set  $A(t) = (\delta^{(k)}(P_t), \varphi) = (-1)^k \int \delta^k(\varphi \frac{\partial x}{\partial u}) / \partial u_1^k \Big|_{u_1=0} du_2 \dots du_n$  where the right-hand

side is calculated separately for each  $t$ . The question is, what is  $A'(t)$ . To calculate this, consider  $A(t)$  as a distribution on  $a < t < b$ . If  $\psi(t)$  is a  $C^\infty$  function vanishing outside  $a < t < b$ , then

$$\begin{aligned} (A'(t), \psi) &= - \int_a^b A(t) \psi'(t) dt = \\ &= (-1)^{k+1} \int_a^b \psi'(t) \int \partial^k (\varphi | \frac{x}{u} |) / \partial u_1^k \Big|_{u_1=0} du_2 \dots du_n dt \\ &= (-1)^{k+1} \int_a^b \partial^k (\frac{\partial \varphi \psi}{\partial t} | \frac{\partial(x, t)}{\partial(u, t)} |) / \partial u_1^k \Big|_{u_1=0} du_2 \dots du_n dt \\ &= - (\delta^{(k)}(P(x, t)), \partial \varphi \psi / \partial t) = (\delta^{(k+1)}(P(x, t)) \partial P / \partial t, \varphi \psi) \\ &= (-1)^{k+1} \int_a^b \partial^{k+1} (\varphi \psi \frac{\partial P}{\partial t} | \frac{\partial(x, t)}{\partial(u, t)} |) / \partial u_1^k \Big|_{u_1=0} du_2 \dots du_n dt \\ &= \int_a^b (\delta^{(k+1)}(P_t) \partial P / \partial t, \varphi) \psi(t) dt. \end{aligned}$$

Thus

$$\underline{\partial \delta^{(k)}(P_t) / \partial t = \delta^{(k+1)}(P_t) \partial P_t / \partial t},$$

the same formula as before, but with a slightly different meaning.

§ 8. Solution of Cauchy's problem for the wave equation in odd spatial dimensions.

Let  $r^2 = \sum_{j=1}^n x_j^2$ , and consider  $t$  a parameter.

By virtue of (§ 5) and (§ 7), we have

$$\partial^2 \delta^{(k)}(r^2 - t^2) / \partial x_j^2 = 2 \delta^{(k+1)}(r^2 - t^2) + 4 x_j^2 \delta^{(k+2)}(r^2 - t^2), \text{ and}$$

$$\partial^2 \delta^{(k)}(r^2 - t^2) / \partial t^2 = -2 \delta^{(k+1)}(r^2 - t^2) + 4 t^2 \delta^{(k+2)}(r^2 - t^2).$$

Thus

$$\begin{aligned} \sum_{j=1}^n \partial^2 \delta^{(k)}(r^2 - t^2) / \partial x_j^2 - \partial^2 \delta^{(k)}(r^2 - t^2) / \partial t^2 = \\ 2(n+1) \delta^{(k+1)}(r^2 - t^2) \\ + 4(r^2 - t^2) \delta^{(k+2)}(r^2 - t^2). \end{aligned}$$

By (§ 6), this can be rewritten

$\square \mathcal{J}^{(k)}(r^2-t^2)=2 [n-2k-3] \mathcal{J}^{(k+1)}(r^2-t^2)$ , with  $\square$  the wave operator. Hence if  $k=\frac{n-3}{2}$ ,  $\square \mathcal{J}^{(k)}(r^2-t^2)=0$  for  $t>0$  and for  $t<0$ . We investigate next its initial values  $\lim_{t \rightarrow 0} \mathcal{J}^{(k)}(r^2-t^2)$  and  $\lim_{t \rightarrow 0} \partial \mathcal{J}^{(k)}(r^2-t^2)/\partial t$ . We have from (4,iii)

$$(\mathcal{J}^{(k)}(r^2-t^2), \varphi) = (-1)^k \frac{1}{2} \int_{\Omega} \left( \frac{1}{2r} \frac{\partial}{\partial r} \right)^k (\varphi r^{n-2}) \Big|_{r=t} d\Omega.$$

Since  $k=\frac{n-3}{2}$ ,  $k$  operations by  $\frac{1}{2r} \frac{\partial}{\partial r}$  reduce the power of  $r$  in  $\varphi r^{n-2}$  by  $2k=n-3$ . Thus

$$\left( \frac{1}{2r} \frac{\partial}{\partial r} \right)^k (\varphi r^{n-2}) \Big|_{r=t} = o(t), \text{ and } \lim_{t \rightarrow 0} (\mathcal{J}^{(k)}(r^2-t^2), \varphi) = 0.$$

For the first derivative, expand

$$\begin{aligned} \varphi(r\omega) &= \varphi(0) + r \varphi_1(\omega) + r^2 \varphi_2(\omega) + \dots, \text{ which leads to} \\ \left( \frac{1}{2r} \frac{\partial}{\partial r} \right)^{k+1} (r^{n-2} \varphi(r\omega)) &= 2^{-k-1} \varphi(0) \frac{(n-2) \dots (n-2k-2)}{r} \\ &\quad + c_1 \varphi_1(\omega) + c_2 r \varphi_2(\omega) + \dots \end{aligned}$$

Thus

$$\begin{aligned} \lim_{t \rightarrow 0} \frac{\partial}{\partial t} (\mathcal{J}^{(k)}(r^2-t^2), \varphi) &= \lim_{t \rightarrow 0} (-2t) (\mathcal{J}^{(k+1)}(r^2-t^2), \varphi) \\ &= \lim_{t \rightarrow 0} (-1)^k t \int_{\Omega} \left( \frac{1}{2r} \frac{\partial}{\partial r} \right)^{k+1} (\varphi r^{n-2}) \Big|_{r=t} d\Omega = \\ &\quad (-1)^k |\Omega| \frac{(n-2)!}{\left(\frac{n-3}{2}\right)!} \varphi(0) \\ &= (-1)^k 2\pi^{k+1} (\mathcal{J}(x), \varphi), \text{ or} \end{aligned}$$

$$\lim_{t \rightarrow 0} \partial \mathcal{J}^{(k)}(r^2-t^2)/\partial t = (-1)^k 2\pi^{k+1} \mathcal{J}(x).$$

This solves the Cauchy problem for a unit pulse in the time derivative at  $t=x=0$ . To solve  $\Delta v - v_{tt}=0$  with more normal initial values, e.g.  $v(x,0)=0$ ,  $v_t(x,0)=\varphi$ , we can set

$$v(x_0, t) = \frac{(-1)^k}{2} \pi^{-k-1} (\mathcal{J}^{(k)}(r^2-t^2), \varphi(x_0+x)) =$$

$$\frac{(-1)^k}{2} \pi^{-k-1} \mathcal{J}^{(k)}(r^2-t^2) * \varphi.$$



§ 8'. Extension of the solution to even spatial dimensions.

The previous solution leads easily to the case of even

dimensions by Hadamard's method of descent. To solve the

equation  $\square v=0$ ,  $v=0$  if  $t=0$ ,  $v_t=\varphi(x_1, \dots, x_n)$  if  $t=0$ , with  $n$

even, define first a function  $\tilde{\varphi}(x_1, \dots, x_{n+1}) = \varphi(x_1, \dots, x_n)$ ,

let  $k = \frac{n+4}{2}$ , and set  $v(x_1, \dots, x_{n+1}) = \frac{(-1)^k}{2} \pi^{-k-1} \delta^{(k)}(\rho^2 - t^2) * \tilde{\varphi}$ ,

with  $\rho^2 = \sum_{j=1}^{n+1} x_j^2$ . Then  $\partial v / \partial x_{n+1} = \delta^{(k)}(\rho^2 - t^2) * \partial \tilde{\varphi} / \partial x_{n+1} = 0$ ,

so  $\sum_{j=1}^n \partial^2 v / \partial x_j^2 - \partial^2 v / \partial t^2 = \sum_{j=1}^{n+1} \partial^2 v / \partial x_j^2 - \partial^2 v / \partial t^2 = 0$ . Also

$\lim_{t \rightarrow 0} v = 0$ , and  $\lim_{t \rightarrow 0} \partial v / \partial t = \varphi$ . Thus  $v$  solves the wave

equation in  $n$  dimensions.

For an explicit form of the solution, let  $\omega = (\omega_1, \dots, \omega_{n+1})$  be on the unit sphere  $\Omega_{n+1}$  in  $R^{n+1}$ , and  $\omega' = (\omega_1, \dots, \omega_n, 0)$ . Then

$$v(x_1, \dots, x_n, t) = (-1)^k \frac{1}{2} \int_{\Omega_{n+1}} \left( \frac{1}{2\rho} \frac{\partial}{\partial \rho} \right)^k (\varphi(x + \omega' \rho) \rho^{n-1}) \Big|_{\rho=t} d\Omega_{n+1}.$$

If  $\xi = (\xi_1, \dots, \xi_n)$  is a variable point in  $R^n$ , this becomes

$$v = (-1)^k \int_{|\xi| \leq 1} \left( \frac{1}{2\rho} \frac{\partial}{\partial \rho} \right)^k (\varphi(x + \rho \xi) \rho^{n-1}) \Big|_{\rho=t} \frac{d\xi}{\sqrt{1 - |\xi|^2}}. \text{ Since}$$

$v$  depends on all values of  $\varphi$  inside (not just on) the light cone, the "strong Huygens' principle" is lacking.

# § 9. Further formulas

i) For distributions  $f$  we have, for a change of coordinates  $u(x)$ , that  $\partial f / \partial u_i = \sum \partial f / \partial x_j \partial x_j / \partial u_i$ . Thus  $\partial \delta^{(k)}(P) / \partial u_j = \delta^{(k+1)}(P) \partial P / \partial u_j$ ,  $k = -1, 0, 1, \dots$ .

For example in spherical coordinates with  $r > 0$  we have, for  $t \neq 0$ ,  $\theta(r^2 - t^2) = \theta(r - t) - \theta(-r - t)$ , so that  $2r\delta(r^2 - t^2) = \delta(r - t) + \delta(-r - t) = \delta(r - t) + \delta(r + t)$ , or  $\delta(r^2 - t^2) = (2r)^{-1} [\delta(r - t) + \delta(r + t)]$ . Clearly one of  $\delta(r - t)$  and  $\delta(r + t)$  is zero, according as  $t < 0$  or  $t > 0$ .

ii) If  $P$  and  $Q$  have no common zeroes,

$$(\delta(PQ), \varphi) = \int_{PQ=0} \frac{\varphi}{|\nabla PQ|} d\sigma = \int_{P=0} \frac{\varphi}{|Q| |\nabla P|} d\sigma + \int_{Q=0} \frac{\varphi}{|P| |\nabla Q|} d\sigma =$$

$\left( \frac{\delta(P)}{|Q|} + \frac{\delta(Q)}{|P|}, \varphi \right)$ . If  $Q$  has no zeros at all, and  $Q > 0$ , then  $\delta(PQ) = Q^{-1} \delta(P)$ . We can apply this to  $r^2 - t^2 = (r - t)(r + t)$  for  $t > 0$ , finding  $\delta(r^2 - t^2) = \frac{\delta(r - t)}{r + t} = \frac{\delta(r - t)}{2r}$ .

iii) The above formula can be taken further by differentiation, but the results are not neat. If  $Q > 0$  everywhere, however, it works nicely. Differentiating  $Q\delta(PQ) = \delta(P)$ , we have

$$Q_j \delta(PQ) + Q \delta'(PQ) P_{Q_j} + Q^2 \delta'(PQ) P_j = \delta'(P) P_j.$$

By (§ 6), the first two terms cancel, and the same process as in (§ 6) justifies cancelling  $P_j$  from the resulting equation, so

$$Q^2 \delta'(PQ) = \delta'(P).$$

Proceeding by induction,

$$Q^{k+1} \delta^{(k)}(PQ) = \delta^{(k)}(P),$$

if  $Q > 0$  everywhere.

Thus e.g.  $\delta^{(k)}(r^2 - c^2) = (r + c)^{-k-1} \delta^{(k)}(r - c)$ , for  $c > 0$ .

## § 10. Other generalizations of $\delta(x)$ .

There is another sort of  $\delta$ -function that generalizes the 1-dimensional  $\delta(x)$ , and that provides a convenient notation frequently used in applied mathematics. Originally we interpreted  $(\delta(x), \varphi(x)) = \varphi(0)$  as the (0-dimensional) integral of  $\varphi(x)$  over the set  $x=0$ , which led to the interpretation of  $(\delta(x_1), \varphi(x_1, x_2))$  as the 1-dimensional integral  $\int_{-\infty}^{\infty} \varphi(0, x_2) dx_2$  over the set  $x_1=0$ , and thence to the  $\delta(P)$  of § 2. However  $\delta(x)$  could just as well be viewed as a restriction map, transforming functions on the line to functions on the point  $x=0$ . From this point of view, the generalization to two dimensions would require  $\delta(x_1) \cdot \varphi(x_1, x_2) = \varphi(0, x_2)$ . To avoid confusion, we denote this operation by a different symbol,  $\delta_0(x_1)$ . Thus  $\delta(x_1)$  is a distribution, but  $\delta_0(x_1)$  is a mapping from test functions of  $n$  variables to test functions of  $n-1$  variables, defined by  $\delta_0(x_1) \varphi(x_1, \dots, x_n) = \varphi(0, x_2, \dots, x_n)$ . Such a mapping might be called a partial distribution. If the test functions are topologized in any of the standard ways, e.g. as  $K(M_p)$ , then  $\delta_0(x_1)$  is clearly continuous, and of course linear.

The adjoint of  $\delta_0(x_1)$ , which we denote by  $\delta^0(x_1)$ , is then a continuous map from distributions on  $R_{n-1}$  to distributions on  $R_n$ . If  $g$  is a distribution on  $R_{n-1}$ , then  $\delta^0(x_1)g$  is defined by  $(\delta^0(x_1)g, \varphi) = (g, \delta_0(x_1)\varphi)$ . In terms of this new concept we can write in a well-defined way  $\delta(x_1, \dots, x_n) = \delta^0(x_1) \dots \delta^0(x_{n-1})\delta(x_n)$ ; the usual expression written, i.e.  $\delta(x_1, \dots, x_n) = \delta(x_1) \dots \delta(x_n)$  does not allow one to interpret  $\delta(x_j)$  in the same sense as the general  $\delta(P)$  defined in § 2.

The connection between  $\delta^0(x_1)$  and  $\delta(x_1)$  can be expressed by  $\delta(x_1) = \delta^0(x_1) \{1\}$ , where  $\{1\}$  is the distribution on  $R_{n-1}$  given by  $(\{1\}, \varphi) = \int \varphi(x_2, \dots, x_n) dx_2 \dots dx_n$ .

Similarly  $\delta^k(x_1)\varphi$  is the restriction to  $x_1=0$  of  $(-\frac{\partial}{\partial x_1})^k \varphi$ . Thus  $\delta^k(x_1) \{1\} = \delta^{(k)}(x_1)$ . It is also easy to see that  $x_1 \delta^k(x_1) = -k \delta^{k-1}(x_1)$ . However it is apparently

impossible to make any analogy with the formula

$\partial \delta^{(k)}(P)/\partial x_j = \partial P/\partial x_j \delta^{(k+1)}(P)$ ; there seems to be no reasonable way of defining  $\partial(\delta^k(x_1))/\partial x_2$  so that  $\partial \delta^k(x_1)/\partial x_2 = 0 = \delta^{k+1}(x_1) \partial x_1/\partial x_2$ . The trouble is that the formula for  $\delta^{(k)}$  depends on an integration by parts, and in  $\delta^k$  there is no integration.

In § 11 we define a  $\delta_k(P)$  that generalizes  $\delta_k(x_1)$ , and satisfies  $P \delta_k(P) = -k \delta_{k-1}(P)$ . It follows from this that for any distributions  $g_0, \dots, g_N$  on  $\{P=0\}$ ,  $f = \sum_0^N \delta^k(P) g_k$  satisfies  $P^{N+1} f = 0$ . Proposition 1 of § 11 shows that conversely every solution of  $P^{N+1} f = 0$  has the form  $f = \sum_0^N \delta^k(P) g_k$ . Thus any distribution  $f$  such that  $x_1^{N+1} f = 0$  can be obtained by applying to  $f$  and its first  $N$  normal derivatives  $N+1$  distributions in the plane  $x_1=0$ .

# § 11 $\delta^k(P)$ .

Let  $P$  be a  $C^\infty$  function such that  $|P|^2 + |\nabla P|^2 > 0$ . Then the set  $\{P=0\}$  is a  $C^\infty$  Riemannian manifold, and distributions on  $\{P=0\}$  can be defined as continuous functionals on  $K(P=0)$ , the space of all  $C^\infty$  functions of compact support defined on  $\{P=0\}$ . Each such test function is the restriction to  $\{P=0\}$  of a test function in  $K(R_n)$ . The topology of  $K(P=0)$  can be given in terms of a particular way of extending functions on  $\{P=0\}$  to functions on  $R_n$  (which we shall indicate in § 13), and requiring this to be a homeomorphism. Another way is to define a sequence of norms in  $K(P=0)$  by  $\|\phi\|_k = \inf \|\psi\|_k$ , where  $\psi$  is a  $C^\infty$  function of compact support on  $R_n$  with  $\psi = \phi$  on  $\{P=0\}$ , and the inf is taken over all such  $\psi$ .

The "partial distribution"  $\delta_k(P)$  is then a continuous map from  $K(R_n)$  to  $K(P=0)$  obtained as follows. For  $\phi$  in  $K(R_n)$  let  $L\phi = \frac{\nabla P \cdot \nabla \phi}{|\nabla P|^2}$ , defined in a neighbourhood of  $\{P=0\}$ ; in a sense to be made precise in § 12,  $L\phi = -\partial\phi/\partial P$ . This suggests an identity that can easily be proved from the actual definition of  $L$ ,

$$1) \quad L^k P \varphi = -k L^{k-1} \varphi + P L^k \varphi .$$

Then we make the definition

$$2) \quad \mathcal{J}_k(P) \varphi = L^k \varphi \text{ restricted to } \{P=0\} .$$

From (1) follows immediately

$$3) \quad \mathcal{J}_k(P) P \varphi = -k \mathcal{J}_{k-1}(P) \varphi ,$$

which corresponds to the formula of § 6. As we have seen, the more precise formula of § 5 cannot be expected to apply to  $\mathcal{J}_k(P)$ .

If  $g$  is a distribution on  $\{P=0\}$ , then  $\mathcal{J}^k(P)g$  is the distribution on  $R_n$  defined by

$$4) \quad (\mathcal{J}^k(P)g, \varphi) = (g, \mathcal{J}_k(P)\varphi) .$$

Thus  $\mathcal{J}^k(P)$  is the adjoint of  $\mathcal{J}_k(P)$ .

From (3) it follows that for an arbitrary distribution  $g$  on  $\{P=0\}$

$$5) \quad P \mathcal{J}^k(P)g = -k \mathcal{J}^{k-1}(P)g .$$

Thus  $P^N \mathcal{J}^k(P)g = 0$  for  $k < N$ :  $(P^N \mathcal{J}^k(P)g, \varphi) =$

$$(g, \mathcal{J}_k(P) P^N \varphi) = (g, (-1)^k k! \mathcal{J}_0(P) P^{N-k} \varphi) = (g, 0) = 0 .$$

Conversely, the following result holds.

Proposition 1. If  $f$  is a distribution on  $R_n$  such that  $P^{N+1}f=0$ , then there are unique distributions  $g_0, \dots, g_N$  on  $\{P=0\}$  such that  $f = \sum_{k=0}^N \mathcal{J}^k(P)g_k$ .

The proof will be indicated in § 13.

Examples.

$$i) \quad P=r-c, \quad |\nabla P|=1, \quad L\varphi = -\frac{\partial \varphi}{\partial r},$$

$$\mathcal{J}_k(r-c)\varphi = \left( -\frac{\partial}{\partial r} \right)^k \varphi \Big|_{r=c} .$$

$$ii) \quad P=r^2-c^2, \quad |\nabla P|=2r, \quad L\varphi = -\frac{1}{2r} \frac{\partial \varphi}{\partial r},$$

$$\mathcal{J}_k(r^2-c^2)\varphi = \left( -\frac{1}{2r} \frac{\partial}{\partial r} \right)^k \varphi \Big|_{r=c} .$$

$$\text{iii)} \quad P = x_1^2 - \sum_{j=2}^n x_j^2 - m^2 = \sum g_{jj} x_j^2 - m^2, \quad (\nabla P)_j = 2g_{jj} x_j,$$

$$\frac{\nabla P \cdot \nabla \varphi}{|\nabla P|^2} = \frac{1}{2} |x|^{-2} \sum g_{jj} x_j \partial \varphi / \partial x_j,$$

$$\mathfrak{J}_0(P) \varphi = \varphi \Big|_{P=0}, \quad \mathfrak{J}_1(P) \varphi = -\frac{1}{2} |x|^{-2} \sum g_{jj} x_j \partial \varphi / \partial x_j \Big|_{P=0},$$

but formulas for  $\mathfrak{J}_k, \dots$  become messy. According to Proposition 1, every solution of

$$6) \quad \left( \sum g_{jj} x_j^2 - m^2 \right) f = 0$$

is of the form  $f = \mathfrak{J}^0(P)g$ , with  $g$  a distribution on  $\{P=0\}$ . Equation (6) is the Fourier transform of the Klein-Gordon equation  $\left[ -(\partial/\partial y_1)^2 + \sum_{j=2}^n (\partial/\partial y_j)^2 - m^2 \right] \tilde{f} = 0$ , important in quantum field theory. Some properties of  $g$  can be deduced from corresponding properties of  $\tilde{f}$ ; e.g. if  $\tilde{f}$  leads to a continuous energy tensor, then  $g$  is a locally square integrable function on  $\{P=0\}$ .

Remark. The  $\mathfrak{J}_k(P)$  defined above is clearly not the only generalization of  $\mathfrak{J}_k(x_1)$ ; for example the restriction of  $L^k(\varphi/|\nabla \varphi|)$  to  $\{P=0\}$  would be another candidate, and would lead to an obvious connection between  $\mathfrak{J}_0(P)$  and  $\mathfrak{J}(P)$ , i.e.  $(\mathfrak{J}(P), \varphi) = \int_{P=0} \mathfrak{J}_0(P) \varphi \, d\sigma$ . Definition (2) has been chosen as the simplest expression for which (3) holds. In § 12 we show that a partial distribution  $\mathfrak{J}^k(P)$  can be defined so that for each  $k$   $(\mathfrak{J}^{(k)}(P), \varphi) = \int_{P=0} \mathfrak{J}^k(P) \varphi \, d\sigma$ ; but it is practically impossible to calculate  $\mathfrak{J}^1(P)$  explicitly for the  $P$  of example (iii) above.

## § 12. Canonical coordinates

Here we introduce in a neighbourhood  $U$  of  $\{P=0\}$  new coordinates  $(\xi, t)$  ( $\xi$  in  $\{P=0\}$ ,  $t$  real) such that  $t=P$  and the curves  $\xi = \text{constant}$  are orthogonal to all the surfaces  $P = \text{constant}$ . The existence of such a system rests on

ordinary differential equations, as follows.

Through each point  $x_0$  in  $\{|\nabla P| > 0\}$  there is a unique solution  $a(x_0, t)$  of  $da/dt = \nabla P / |\nabla P|^2$  with the initial values  $a(x_0, P(x_0)) = x_0$ . There is a neighbourhood  $U(x_0)$  and a number  $\epsilon(x_0)$  such that the solution  $a(x, t)$  is defined for all  $x$  in  $U(x_0)$  and all  $|t - P(x_0)| < \epsilon$ , and is a  $C^\infty$  function  $(x, t)$  there. Since  $P(a(x, P(x))) = P(x)$  and  $dP(a(x, t))/dt = \nabla P \cdot da/dt = 1$ , it follows that  $P(a(x, t)) = t$ .

Thus for fixed  $x$  the curve  $a(x, t)$  is orthogonal to  $P = \text{constant}$ , and the parameter  $t$  is  $P$ . Now there is an open set  $U$  containing  $\{P=0\}$  such that for each  $x$  in  $U$   $a(x, t)$  is defined for  $|t| \leq 2|P(x)|$ . In  $U$  is defined the function  $a(x, 0)$ , which is thus a  $C^\infty$  map of  $U$  onto  $\{P=0\}$ .

We call the pair  $(a(x, 0), P(x))$  canonical coordinates of the point  $x$  in  $U$ ; the coordinates are actually a map onto an open subset  $V$  of the Cartesian product of  $\{P=0\}$  by the real line. If  $\xi$  represents an arbitrary point on  $\{P=0\}$  and  $t$  is a real number, then for all  $(\xi, t)$  in  $V$  the map  $(\xi, t) \rightarrow a(\xi, t)$  is the inverse of  $x \rightarrow (a(x, 0), P(x))$ . Since  $P=t$  in this correspondence, it makes sense for  $C^\infty$  functions  $\varphi$  defined in  $U$  to let  $\partial\varphi/\partial P = d\varphi(a(\xi, t))/dt = \nabla\varphi \cdot da/dt = \nabla\varphi \cdot \nabla P / |\nabla P|^2$ . This is the interpretation of  $L\varphi$  mentioned in § 11.

We can further define a partial distribution  $\mathcal{J}_k(P)$  (probably of no practical importance) such that

$\int_{P=0} \mathcal{J}_k(P) \varphi \, d\sigma = (\mathcal{J}^{(k)}(P), \varphi)$ . To this end let  $v(y)$  be the function such that for each continuous  $\varphi$  with compact support,  $\int_{P=t} \varphi(y) d\sigma_t = \int_{P=0} \varphi(a(y, t)) v(a(y, t)) d\sigma$ , where

$d\sigma_t$  is the surface element on  $\{P=t\}$  and  $d\sigma = d\sigma_0$ . It is easy to check that such a  $v$  exists, is  $C^\infty$ , and is unique. Clearly  $v(y)=1$  if  $y$  is on  $\{P=0\}$ .

We now define

$$7) \mathcal{J}_k(P) \varphi = \left( - \frac{\partial}{\partial P} \right)^k \left( \varphi v / |\nabla P| \right) \Big|_{P=0}.$$

It is trivial to prove by induction that

$$(\mathcal{J}^{(k)}(P+s), \varphi) = \int_{P=0} (d/dt)^k \left( \frac{\varphi v}{|\nabla P|} (a(\xi, -t)) \right) \Big|_{t=0}^{t=s} d\sigma,$$

and consequently that

$$8) (\mathcal{J}^{(k)}(P), \varphi) = \int_{P=0} \mathcal{J}_k(P) \varphi d\sigma.$$

This  $\mathcal{J}_k(P)$  is relatively easy to calculate if  $v(y)$  is easy to calculate (e.g. if the surfaces  $P=\text{constant}$  are spheres, cylinders, or planes), but otherwise quite difficult.

### § 13. Characterization of the solutions of $P^N f=0$

Before proving Proposition 1, we give a way of extending functions in  $K(P=0)$  to functions in  $K(R_n)$ , in terms of the canonical coordinates of § 12. Define a  $C^\infty$  "cut-off function"  $\chi(x)$  such that  $\chi \equiv 1$  in a neighbourhood of  $\{P=0\}$ ,  $\chi(x)=0$  if the distance from  $x$  to  $\{P=0\}$  is  $\geq 1$ , and the support of  $\chi$  is contained in the neighbourhood  $U$  where the canonical coordinates are defined. Such a  $\chi$  can be obtained by defining it successively in the spheres  $|x| \leq n$ . Then if  $\psi$  is in  $K(P=0)$   $\tilde{\psi}(x) = \chi(x) \psi(a(x, 0))$  is in  $K(R_n)$ ; and on  $\{P=0\}$ ,  $\psi = \tilde{\psi}$ . Here  $a(x, t)$  is the function of § 12.

Proposition 1 is proved by induction. If  $f$  is a distribution on  $R_n$  such that  $Pf=0$ , then a distribution  $g_0$  on  $\{P=0\}$  must be found such that  $f = \mathcal{J}^0(P)g_0$ . If  $\psi$  is in  $K(P=0)$ , let  $\tilde{\psi}$  be the extension indicated above, and define  $(g_0, \psi) = (f, \tilde{\psi})$ . To show that  $f = \mathcal{J}^0(P)g_0$ , note that  $(f, \varphi) = (f, \chi \varphi)$ , so that  $(f, \varphi) - (\mathcal{J}^0(P)g_0, \varphi) = (f, \chi(x) \varphi(x)) -$

$(f, \chi(x) \varphi(a(x, 0))) = (Pf, \chi(x) \frac{\varphi(x) - \varphi(a(x, 0))}{P(x)})$ . Since  $Pf=0$ , this expression is zero if

$\chi(x) \frac{\varphi(x) - \varphi(a(x, 0))}{P(x)}$  is a test function. The fact that it

has compact support follows from the properties of  $\chi$ , so the only question is its differentiability. In canonical

coordinates  $(\xi, t)$  let  $\varphi(x) = \varphi_1(\xi, t)$ , where

$(\xi, t) = (a(x, 0), P(x))$ ; and  $\varphi_2(\xi, t) = d\varphi_1(\xi, t)/dt$ . Then  $\varphi_1$



and  $\varphi_2$  are in  $C^\infty$  on the support of  $\chi$ , and

$$\frac{\varphi(x) - \varphi(a(x, 0))}{P(x)} = \frac{\varphi_1(\xi, t) - \varphi_1(\xi, 0)}{t} = \frac{1}{t} \int_0^1 \frac{d}{ds} \varphi_1(\xi, ts) ds$$

$$= \int_0^1 \varphi_2(\xi, ts) ds, \text{ which is in } C^\infty \text{ on the support of } \chi.$$

This establishes Proposition 1 for  $N=0$ . Suppose for all  $N < M$  the solution of  $P^{N+1}f=0$  can be represented as

$\sum_0^N \delta^k(P)g_k$ , and let now  $P^{M+1}f=0$ . Then there is a  $g_M$  such that  $P^M f = (-1)^M M! \delta^0(P)g_M$ . In view of formula (5) of § 11,  $P^M(f - \delta^M(P)g_M) = P^M f - (-1)^M M! \delta^0(P)g_M = 0$ , so that by the induction assumption there are  $g_1, \dots, g_{M-1}$  such that  $f - \delta^M(P)g_M = \sum_0^{M-1} \delta^k(P)g_k$ .

The uniqueness is easy to check for  $M=0$ , and is then extended to other  $M$  by formula (5).