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MATHEMATISCH CENTRUM

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Supplement to report ZW 1959-010, Solution of the Laplace inversion problem for a special function

by

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In report ZW 1959-010 the problem was how to find a function $h(t)$, such that the given function

$$(1) \quad f(p) = \int_0^{\infty} \frac{e^{-z\sqrt{x^2+a^2}} p^2 J_0(\rho x) x \, dx}{c\sqrt{x^2+a^2} p^2 + d\sqrt{x^2+b^2} p^2} \quad (p > 0),$$

is the Laplace transform

$$(2) \quad f(p) = p \int_0^{\infty} e^{-pt} h(t) dt$$

of $h(t)$. In this report a different method for solving this problem will be given.

We again assume that ρ, z, a, b, c, d are positive constants and that $a \neq b$. We also put $\sqrt{\rho^2 + z^2} = R$. Substituting $y = p^{-1} \sqrt{x^2 + a^2} p^2$, we deduce from (1)

$$(3) \quad f(p) = p \int_a^{\infty} \frac{e^{-zyp} J_0(\rho p \sqrt{y^2 - a^2}) y \, dy}{cy + d\sqrt{y^2 + b^2 - a^2}}.$$

By the well-known formula

$$(4) \quad J_0(x) = \frac{1}{\pi} \int_{-1}^1 \frac{e^{ixs}}{\sqrt{1-s^2}} ds,$$

we then have

$$(5) \quad f(p) = p \int_a^{\infty} \frac{e^{-zyp} y \, dy}{cy + d\sqrt{y^2 + b^2 - a^2}} \frac{1}{\pi} \int_{-1}^1 \frac{e^{isp\rho\sqrt{y^2 - a^2}}}{\sqrt{1-s^2}} ds.$$

Replacing s by the new variable t

$$(6) \quad t = zy - i\rho s\sqrt{y^2 - a^2},$$

we obtain

$$(7) \quad f(p) = \int_a^\infty dy \int_L \varphi(y,t) dt,$$

where $\varphi(y,t)$ is defined by

$$(8) \quad \varphi(y,t) = \frac{p}{\pi i} \frac{y e^{-pt}}{\sqrt{\rho^2(y^2 - a^2) + (zy - t)^2 (cy + d \sqrt{y^2 + b^2 - a^2})}}.$$

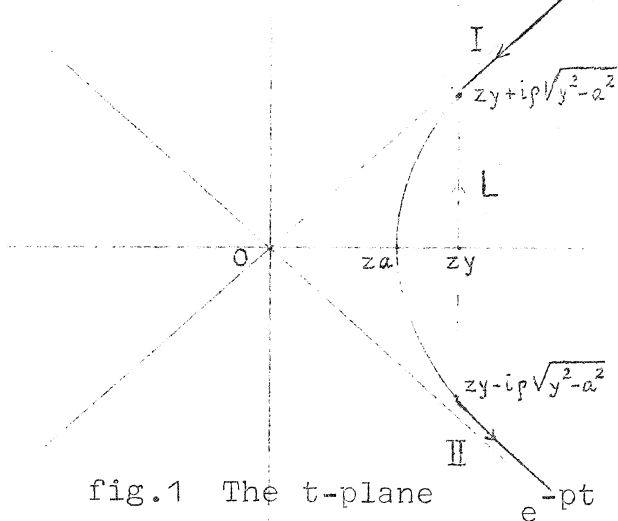


fig.1 The t-plane

The t-integration contour in (7) is a line segment L connecting $zy - i\rho\sqrt{y^2 - a^2}$ and $zy + i\rho\sqrt{y^2 - a^2}$ (fig.1). If y varies from a to ∞ , the points $zy - i\rho\sqrt{y^2 - a^2}$ and $zy + i\rho\sqrt{y^2 - a^2}$ describe a branch H of a hyperbola in the complex t-plane. If y is fixed, the function

$$\sqrt{\rho^2(y^2 - a^2) + (zy - t)^2}$$

of t has no singularities in the region G to the right of H, and is $O(e^{-pt})$ if $t \rightarrow \infty$. We therefore have

$$(9) \quad \int_L \varphi(y,t) dt = \int_I \varphi(y,t) dt + \int_{II} \varphi(y,t) dt,$$

where the sign of $\sqrt{\rho^2(y^2 - a^2) + (zy - t)^2}$ has to be chosen in such a way that the square root is asymptotically equal to t if $t \rightarrow \infty$, $t \in G$. The contours I and II are parts of H as is shown in fig.1, and have parametric representations

$$(10) \quad \begin{aligned} I &: t = t_1(u) = zu + i\rho\sqrt{u^2 - a^2}, \quad u \geq a; \\ II &: t = t_2(v) = zv - i\rho\sqrt{v^2 - a^2}, \quad v \geq a. \end{aligned}$$

From (7), (9) and (10) we deduce

$$(11) \quad \begin{aligned} f(p) &= \int_a^\infty dy \int_I \varphi(y,t) dt + \int_a^\infty dy \int_{II} \varphi(y,t) dt = \\ &= \int_a^\infty dy \int_a^y \varphi(y, t_1(u)) t_1'(u) du + \int_a^\infty dy \int_y^\infty \varphi(y, t_2(v)) t_2'(v) dv = \\ &= - \int_a^\infty t_1'(u) du \int_a^u \varphi(y, t_1(u)) dy + \int_a^\infty t_2'(v) dv \int_a^v \varphi(y, t_2(v)) dy. \end{aligned}$$

The integrations can be interchanged, as is justified in the following way. If $t_1 \in I$ we have

$$(12) \quad \left| \rho^2(y^2 - a^2) + (zy - t_1)^2 \right| = \left| t_1 - (zy + i\rho \sqrt{y^2 - a^2}) \right| \left| t_1 - (zy - i\rho \sqrt{y^2 - a^2}) \right| \geq \left| zu - zy \right| \left| 2\rho \sqrt{y^2 - a^2} \right| .$$

We also have

$$(13) \quad \left| t_1'(u) \right| = \left| z + \frac{i\rho u}{\sqrt{u^2 - a^2}} \right| \leq z + \frac{\rho y}{\sqrt{y^2 - a^2}} .$$

From (12) and (13) it follows that

$$\begin{aligned} \psi(y) &= \int_y^\infty \left| \varphi(y, t_1(u)) \right| \left| t_1'(u) \right| du \leq \left| \frac{\rho}{\pi} \frac{y}{cy + d\sqrt{y^2 + b^2 - a^2}} \right| \frac{1}{\sqrt{2\rho z \sqrt{y^2 - a^2}}} \cdot \\ &\quad \cdot \left(z + \frac{\rho y}{\sqrt{y^2 - a^2}} \right) \int_y^\infty \frac{e^{-pzu}}{\sqrt{u-y}} du . \end{aligned}$$

So there is a constant C (independent of y) with

$$\psi(y) \leq C \frac{y^2 e^{-pzy}}{(cy + d\sqrt{y^2 + b^2 - a^2})(y^2 - a^2)^{3/4}} ,$$

As $cy + d\sqrt{y^2 + b^2 - a^2} \geq db > 0$ if $y \geq a$, and since $a \neq 0$, $p > 0$, $z > 0$, we have

$$\int_a^\infty \psi(y) dy < \infty .$$

The integral over II can be handled with in the same way.

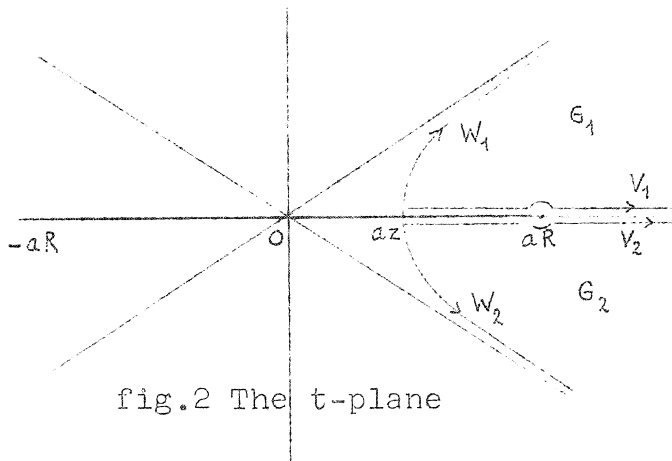


fig.2 The t-plane

If u ranges from a to ∞ , $t_1(u)$ describes a contour W_1 , which is the part of H above the real axis (fig.2). If $t \in W_1$, the corresponding value of u will be given by

$$(14) \quad u(t) = \frac{tz - i\rho \sqrt{t^2 - a^2 R^2}}{R^2}.$$

From now on we cut the t -plane along the real axis from $-aR$ to aR , taking $\sqrt{t^2 - a^2 R^2}$ positive if $t > aR$. Similarly, if v ranges from a to ∞ , $t_2(v)$ describes a contour W_2 , the part of H under the real axis, and now

$$(15) \quad v(t) = \frac{tz + i\rho \sqrt{t^2 - a^2 R^2}}{R^2} \quad (t \in W_2).$$

Hence (11) can be written

$$(16) \quad f(p) = - \int_{W_1} dt \int_a^{u(t)} \varphi(y, t) dy + \int_{W_2} dt \int_a^{v(t)} \varphi(y, t) dy.$$

From now on y will also assume complex values. Let G_1 be the region bounded by W_1 and the part of the positive real axis from az to ∞ . Let

$$(17) \quad g(t) = \int_{W(t)} \varphi(y, t) dy,$$

first be defined as follows for $t \in G_1$.

G_1 is conformally mapped onto a region G'_1 of the y -plane by $y = u(t)$ ((14)). G'_1 is also bounded by the positive real axis, and a hyperbolic arc, which is the image of the part of the real axis $t > aR$ (fig.3).

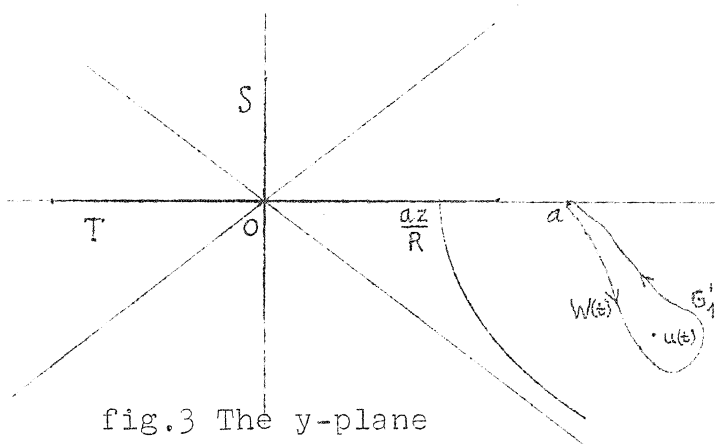


fig.3 The y -plane

$\sqrt{y^2 + b^2 - a^2}$ is defined in the following way.

I. If $a < b$, we cut the y -plane along the interval

$$S : [-i\sqrt{b^2 - a^2}, i\sqrt{b^2 - a^2}]$$

on the imaginary axis.

II. If $a > b$, the real axis is cut along the interval

$$T : [-\sqrt{a^2 - b^2}, \sqrt{a^2 - b^2}].$$

In both cases the square root is positive for large positive values of y . $W(t)$ is a simple curve in the y -plane. Starting in a , $W(t)$ encircles $u(t)$ in positive direction, ending in a again without leaving G'_1 . Evidently, if t is fixed in G_1 , only the root $u(t)$ of $\rho^2(y^2 - a^2) + (zy - t)^2 = 0$ is in G'_1 .

On $W(t)$ we define the function $\sqrt{\rho^2(y^2 - a^2) + (zy - t)^2}$ by analytic continuation, taking the value $t - za$ at the starting-point $y = a$ of $W(t)$. If $W(t)$ satisfies the above conditions, the integral on the right of (17) is independent of $W(t)$, and $g(t)$ is uniquely defined on G_1 . One can easily prove that $g(t)$ is analytic on G_1 . In fact, $g(t)$ can be analytically continued to the boundary of G_1 , the point $t = Ra$ being excluded. If t is fixed and $t \neq Ra$, the conformal mapping $y = u(t)$ can be extended across the cut $(-aR, aR)$, and the roots of $\rho^2(y^2 - a^2) + (zy - t)^2 = 0$ are separated. If $u(t)$ is on the boundary of G_1 , we can take a contour $W(t)$, which leaves G_1 only in a small neighbourhood of $u(t)$, but for the rest satisfies the above conditions. In case II it may occur that $u(t) \in T$; $\sqrt{y^2 + b^2 - a^2}$ then has to be continued analytically along $W(t)$ across the cut T .

Finally we need an estimate of $|g(t)|$ if $t \in G_1$ and $t \rightarrow \infty$. It is not difficult to see that there exists a constant $k > 0$ so that

$$(18) \quad \left| \frac{y}{cy + d \sqrt{y^2 + b^2 - a^2}} \right| \leq k \quad (y \in G_1').$$

We can deform $W(t)$ into the line-segment

$$(19) \quad y = a + (u(t) - a)s \quad (0 \leq s \leq 1).$$

Then, (17), (18) and (19),

$$(20) \quad |g(t)| \leq \frac{2pk}{\pi} e^{-p\text{Re}t} \int_0^1 \frac{|u(t) - a| ds}{\sqrt{|a - u(t)| |1 - s| \left| a(1 - s) + u(t)(1 + s) - \frac{2tz}{R} \right|}} \leq \frac{2p1}{\pi} e^{-p\text{Re}t} \sqrt{\frac{2|t|}{R} + a},$$

if $|t|$ is sufficiently large (1 is independent of t).

If $u(t)$ is on the real axis and $> a$

$$g(t) = 2 \int_a^{u(t)} \varphi(y, t) dy,$$

which integral occurs in (16). This can be proved by deforming $W(t)$ into the interval $[a, u(t)]$. We therefore have

$$(21) \quad \int_{W_1} dt \int_a^{u(t)} \varphi(y,t) dt = \frac{1}{2} \int_{W_1} g(t) dt.$$

Now, by (20) and since $g(t)$ is analytic in G_1 we can replace W_1 on the right of (21) by the contour V_1 of fig.2.

Hence

$$(22) \quad \int_{W_1} dt \int_a^{u(t)} \varphi(y,t) dt = \int_{V_1} dt \int_a^{u(t)} \varphi(y,t) dt.$$

The second term on the right of (16) can be transformed in exactly the same way. Hence

$$(23) \quad f(p) = -\frac{1}{2} \int_{V_1} dt \int_a^{u(t)} \varphi(y,t) dy + \frac{1}{2} \int_{V_2} dt \int_a^{v(t)} \varphi(y,t) dy.$$

Adding the contours in the y -plane, we either obtain

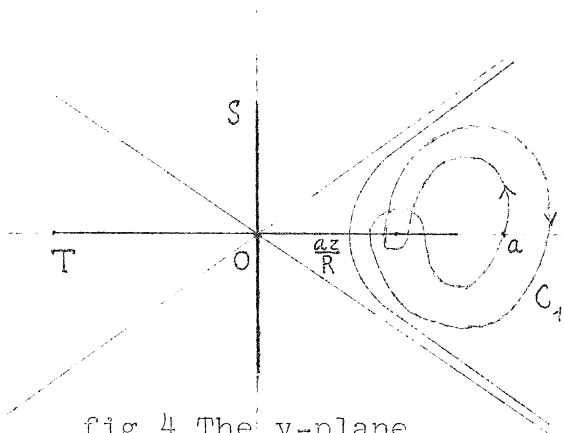


fig.4 The y -plane

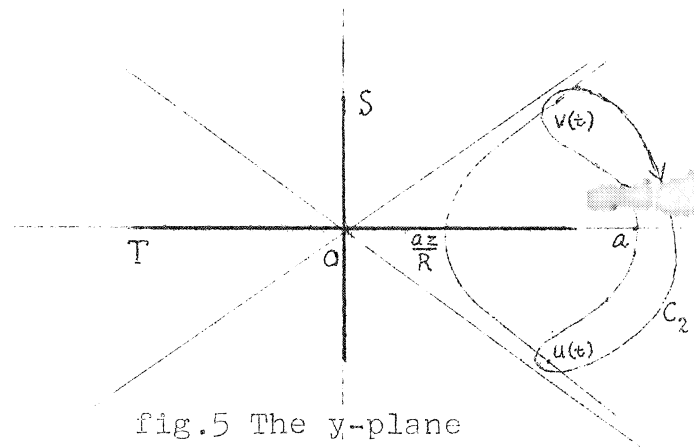


fig.5 The y -plane

a contour C_1 (fig.4) if $az < t < aR$, or a contour C_2 (fig.5) if $t > aR$. From (23) it is clear, that the function

$$(24) \quad h(t) = \frac{1}{2\pi i} \int_{C_i} \frac{y dy}{(cy+d\sqrt{y^2+b^2-a^2}) \sqrt{\rho^2(y^2-a^2)+(zy-t)^2}},$$

where $i=1$ if $az < t < aR$, $i=2$ if $t > aR$, satisfies (2). (Both roots in the denominator of the integral are > 0 if $y=a$). A further discussion of the function $h(t)$ can be found in § 5 of report ZW 1959-010, and need not be repeated here.