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ON THE EXISTENCE OF G-COMPACTIFICATIONS

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On the existence of G -compactifications ^{*})

by

J. de Vries

ABSTRACT

The main result of this paper is that every Tychonoff G -space has a G -compactification provided the topological group G is locally compact. As an application we improve an embedding theorem of CARLSON.

KEY WORDS & PHRASES: G -space, equivariant embedding, compactification.

^{*}) This paper is not for review; it is meant for publication elsewhere.

1. INTRODUCTION

In this paper we contribute to the solution of the following problem: *Can every topological transformation group $\langle G, X, \pi \rangle$ with X a Tychonoff space equivariantly be embedded in a topological transformation group $\langle G, Y, \sigma \rangle$ with Y a compact Hausdorff space? If so, how "small" can Y be chosen?* Several authors have worked earlier on this problem. For the case of discrete groups (where only the second part of the problem is non-trivial) we refer to [6], [2] (section 3.4), and [1]. For the case $G = \mathbb{R}$ we mention [4], and for more general groups, [3], [11] and [13]. For a categorical motivation of this question, see [11] or [12], the final remarks in 4.3.13. Our result improves all earlier results by showing that the answer is affirmative for every locally compact group G , no matter what the Tychonoff space X and the action π look like, and that one can choose the compact Hausdorff space Y such that $w(Y) \leq \max\{w(G), w(X)\}$. Here $w(Z)$ denotes the weight of the topological space Z .

As a typical application of our result we mention the following. In [5], Theorem 1, CARLSON describes a dynamical system (τ, C_V^∞) which is universal for the class of all dynamical systems (π, X) on separable metrizable spaces X such that the action π is, what he calls, *bounded* (in the sequel, we shall call his notion of boundedness: *metrical* boundedness). A consequence of the main result of our paper is that the condition of being bounded is superfluous in CARLSON's theorem: any dynamical system with a separable metrizable phase space is metrically bounded (cf. 4.1 below). No reparametrization is needed, as was suggested at the end of [5].

2. PRELIMINARIES

Notation will be as in [12], but for convenience we recall here some definitions and terminology. A *topological transformation group* (ttg) or a G -space is a triple $\langle G, X, \pi \rangle$ where G is a topological group, X is a topological space, and π is a (left) *action* of G on X , that is, $\pi : G \times X \rightarrow X$ is a continuous function, $\pi(e, x) = x$ and $\pi(t, \pi(s, x)) = \pi(ts, x)$ for every $x \in X$ and $s, t \in G$ (e denotes the identity of G). The *transitions* $\pi^t : X \rightarrow X$

and the motions $\pi_x : G \rightarrow X$ are defined by $\pi_x^t := \pi(t, x) = : \pi_x t$ for $(t, x) \in G \times X$. If $\langle G, X, \pi \rangle$ and $\langle G, Y, \sigma \rangle$ are G -spaces, then a function $f : X \rightarrow Y$ is called *equivariant* whenever $f \circ \pi^t = \sigma^t \circ f$ for every $t \in G$. If f is an equivariant dense topological embedding of X into Y , and Y is a compact Hausdorff space, then we call $\langle G, Y, \sigma \rangle$ a *G -compactification of $\langle G, X, \pi \rangle$* . A necessary condition for $\langle G, X, \pi \rangle$ to have a G -compactification is that X is a Tychonoff space and from now on we assume that X is such a space. Recall that X admits a uniformity which is compatible with the topology of X (shortly: a uniformity for X). We shall call a ttg $\langle G, X, \pi \rangle$ *U -bounded* or *bounded w.r.t. U* whenever U is a uniformity for X and

$$\forall \alpha \in U, \exists U \in V_e : (\pi_x^t, x) \in \alpha \quad \text{for all } t \in U, x \in X$$

(here V_e denotes the neighbourhood filter of e in G). In this case we shall also call the action π of G on X bounded w.r.t. U or U -bounded. The relevance of the notion of boundedness for the problem of the existence of G -compactifications is immediate from the following result, which generalizes Theorem 3.1(1) of [3]:

2.1. THEOREM. *Let $\langle G, X, \pi \rangle$ be a ttg with X a Tychonoff space. The following conditions are equivalent:*

(i) *There exists a G -compactification $\langle G, Y, \sigma \rangle$ of $\langle G, X, \pi \rangle$.*

(ii) *The action π of G on X is bounded w.r.t. some uniformity U for X .*

If these conditions are fulfilled, then $\langle G, X, \pi \rangle$ has a G -compactification $\langle G, Y_0, \sigma_0 \rangle$ such that

$$(*) \quad w(Y_0) \leq \max\{w(G), w(X)\}.$$

PROOF. Cf. [12], Proposition 7.3.12. \square

2.2. REMARK. The proof of (i) \Rightarrow (ii) is easy. A quick proof of the converse implication (ii) \Rightarrow (i), using Theorem 3.1 of [3], is included in [13]; the difference between the result in [3] and ours is, that in [3] condition (ii) is replaced by the stronger condition

(ii)' *The action π is bounded w.r.t. some uniformity U for X and each π^t ($t \in G$) is a unimorphism w.r.t. U .*

In addition, [3] and [13] contain no proof of the inequality (*).

3. MAIN RESULT

Throughout this section $\langle G, X, \pi \rangle$ shall denote a ttg with G an arbitrary locally compact Hausdorff group and X a Tychonoff space. The basic result is:

3.1. PROPOSITION. *There exists a uniformity U for X such that the action π of G on X is U -bounded.*

PROOF. It is sufficient to prove that there exists a set $\{g_i : i \in I\}$ of continuous, $[0,1]$ -valued functions on X satisfying the conditions

- (1) $\{g_i : i \in I\}$ separates points and closed subsets of X , i.e. for any closed subset A of X and $x \in X \setminus A$ there exists $i \in I$ with $g_i(x) \notin \text{cl } g_i[A]$.
- (2) $\forall i \in I : \{g_i \circ \pi_x : x \in X\}$ is equicontinuous at e .

Indeed, if we have such a family, let U denote the weakest uniformity on X making every $g_i : X \rightarrow [0,1]$ uniformly continuous. Then the topology generated by U coincides with the weakest topology on X , making every g_i continuous. By (1), this topology is just the original topology of X , hence U is a uniformity for X . In addition, π is U -bounded. For if $\alpha \in U$, then there are a finite subset I_α of I and a real number $\varepsilon > 0$ such that for all $(x,y) \in \alpha$:

$$|g_i(x) - g_i(y)| < \varepsilon \quad \text{for all } i \in I_\alpha \quad \Rightarrow \quad (x,y) \in \alpha.$$

In view of (2), there is for every $i \in I$ a neighbourhood U_i of e in G such that $|g_i(\pi(t,x)) - g_i(x)| < \varepsilon$ for every $t \in U_i$ and $x \in X$. Hence $(\pi(t,x), x) \in \alpha$ for all $t \in \bigcap \{U_i : i \in I_\alpha\}$ and $x \in X$, as desired.

We shall demonstrate now that a family $\{g_i : i \in I\}$ with properties (1) and (2) exists. The proof will be interrupted by several lemmas.

3.2. LEMMA. *There exists a set Φ of left uniformly continuous, real valued functions on G such that*

- (3) $\forall \varphi \in \Phi : \varphi(e) = 0 \text{ \& } \varphi(t) \geq 0 \text{ (} t \in G \text{)} ;$
- (4) $\forall t \in G [t \neq e \Rightarrow \exists \varphi \in \Phi : \varphi(t) > 0] ;$
- (5) $\forall \varphi \in \Phi : \text{the set } A_{\varphi} := \{t \in G : \varphi(t) \leq 2\} \text{ is a compact subset of } G.$

PROOF. Since G is a locally compact Hausdorff group, there exists a local base \mathcal{B} at e such that $\text{cl } U$ is compact for every $U \in \mathcal{B}$. Choose for every $U \in \mathcal{B}$ a continuous function $\varphi_U : G \rightarrow [0,3]$ such that $\varphi_U(e) = 0$ and $\varphi_U(t) = 3$ if $t \in G \sim U$. Now take $\Phi := \{\varphi_U : U \in \mathcal{B}\}$. Since for each $U \in \mathcal{B}$, φ_U is constant outside a compact set (viz. $\text{cl } U$) it is clear that φ_U is left uniformly continuous. \square

3.3. If Φ is as above and if for $(n,\varphi) \in \mathbb{N} \times \Phi$ we define

$$U_{n,\varphi} := \{t \in G : \varphi(t) \leq 1/n\},$$

then $U_{n,\varphi}$ is a compact neighbourhood of e in G , and

$$\bigcap \{U_{n,\varphi} : (n,\varphi) \in \mathbb{N} \times \Phi\} = \{e\}.$$

It follows easily that $\{U_{n,\varphi} : (n,\varphi) \in \mathbb{N} \times \Phi\}$ is a local base at e (see e.g.[8], the proof of 8.5, which can easily be adapted to the present situation). In particular, if Φ is countable, then G is metrizable (cf.[8],8.3). Conversely, if G is metrizable, one can choose Φ such that it contains only one element: set $\varphi(t) := d(e,t)$ ($t \in G$) where d is a left invariant metric for G such that $\{t \in G : d(e,t) \leq 2\}$ is compact.

3.4. Fix a set Φ as indicated in 3.2. For every $f \in C(X,[0,1])$ and $\varphi \in \Phi$, a real-valued function \tilde{f}_{φ} on X can be defined by

$$(6) \quad \tilde{f}_{\varphi}(x) := \inf_{t \in G} \{\varphi(t) + f(\pi^t x)\}$$

for $x \in X$. Incidentally, this definition and the lemmas 3.5 and 3.7 below are motivated by Lemma 7 in [7].

3.5. LEMMA. The functions \tilde{f}_φ ($f \in C(X, [0, 1])$ and $\varphi \in \Phi$) map X continuously into the interval $[0, 1]$.

PROOF. Clearly, $0 \leq \tilde{f}_\varphi(x) \leq \varphi(e) + f(x) = f(x) \leq 1$ for every $x \in X$. So we need only to prove continuity of \tilde{f}_φ . In order to do so, first observe that for every $t \in G$ with $\varphi(t) \geq 2$ we have $\varphi(t) + f(\pi^t x) \geq 2 > 1 \geq \tilde{f}_\varphi(x)$. Consequently, with A_φ as defined in (5), we have

$$(7) \quad \tilde{f}_\varphi(x) = \inf_{t \in A_\varphi} \{\varphi(t) + f(\pi^t x)\}.$$

However, the function $t \mapsto \varphi(t) + f(\pi^t x) : A_\varphi \rightarrow \mathbb{R}$ is continuous and A_φ is compact. Hence the infimum in (7) is not only actually attained at some point $t_x \in A_\varphi$ but it follows also that \tilde{f}_φ is continuous, as is well-known and easy to prove. \square

3.6. LEMMA. If $f(x) = 0$ then $\tilde{f}_\varphi(x) = 0$ for every $\varphi \in \Phi$. If $f(x) > 0$ then there exists $\varphi \in \Phi$ such that $\tilde{f}_\varphi(x) > 0$.

PROOF. If $f(x) = 0$, then the inequalities $0 \leq \tilde{f}_\varphi(x) \leq f(x)$ (cf. the proof of 3.5) imply that $\tilde{f}_\varphi(x) = 0$. If $f(x) > 0$, then there is $U \in \mathcal{V}_e$ such that $f(\pi^t x) > \frac{1}{2}f(x)$ for all $t \in U$. By 3.3, there exists $\varphi \in \Phi$ and $n \in \mathbb{N}$ such that $U_{n, \varphi} \subseteq U$. We may and shall assume that $1/n \leq \frac{1}{2}f(x)$. Then we have for every $t \in G$, $\varphi(t) + f(\pi^t x) > 1/n$, whence $\tilde{f}_\varphi(x) \geq 1/n > 0$. \square

3.7. LEMMA. For every $f \in C(X, [0, 1])$ and $\varphi \in \Phi$, the family $\{\tilde{f}_\varphi \circ \pi_x : x \in X\}$ is equicontinuous at e .

PROOF. Fix f and φ as indicated. For every $(t, x) \in G \times X$ we have

$$\begin{aligned} \tilde{f}_\varphi(\pi(t, x)) &= \inf_{s \in G} \{\varphi(s) + f(\pi(st, x))\} \\ &= \inf_{u \in G} \{\varphi(ut^{-1}) - \varphi(u) + \varphi(u) + f(\pi^u x)\} \\ &\geq \inf_{u \in G} \{\varphi(ut^{-1}) - \varphi(u)\} + \tilde{f}_\varphi(x) \end{aligned}$$

Since φ is left uniformly continuous on G , there is for every $\varepsilon > 0$ a neighbourhood U_ε of e in G such that $|\varphi(ut^{-1}) - \varphi(u)| < \varepsilon$ for all $t \in U_\varepsilon$ and $u \in G$.

Consequently, $\tilde{f}_\varphi(\pi(t,x)) \geq \tilde{f}_\varphi(x) - \varepsilon$ for all $t \in U_\varepsilon$ and all $x \in X$. Similarly, there is $V_\varepsilon \in \mathcal{V}_e$ such that $\tilde{f}_\varphi(x) \geq \tilde{f}_\varphi(\pi(t,x)) - \varepsilon$ for all $t \in V_\varepsilon$ and all $x \in X$. Hence

$$(8) \quad |\tilde{f}_\varphi(\pi(t,x)) - \tilde{f}_\varphi(x)| < \varepsilon$$

for every $t \in U_\varepsilon \cap V_\varepsilon$ and every $x \in X$. \square

3.8. In the preceding proof we have shown a little bit more than was actually needed; namely, if $t \in U_\varepsilon \cap V_\varepsilon$ then (8) holds not only uniformly in $x \in X$, but also uniformly in $f \in C(X, [0,1])$. Hence $\{\tilde{f}_\varphi \circ \pi_x : x \in X \text{ \& } f \in C(X, [0,1])\}$ is equicontinuous at e . However, the statement of lemma 3.7 is sufficient for our purposes.

3.9. PROOF OF 3.1 (continued). Consider the family $\{\tilde{f}_\varphi : (\varphi, f) \in \Phi \times C(X, [0,1])\}$. By 3.5, this is a set of continuous, $[0,1]$ -valued functions, and it is easy to see that it satisfies condition (1) (use lemma 3.6 and the fact that for any closed set $A \subseteq X$ and any point $x \in X \sim A$ there is $f \in C(X, [0,1])$ with $f(x) = 1$ and $f[A] = \{0\}$). In addition, our family fulfills condition (2): this is exactly lemma 3.7. \square

3.10 THEOREM. Any $ttg \langle G, X, \pi \rangle$ with G a locally compact Hausdorff group and X a Tychonoff space has a G -compactification $\langle G, Y, \sigma \rangle$. Moreover, one may assume that

$$w(Y) \leq \max\{w(G), w(X)\}.$$

PROOF. Combine 2.1 and 3.1. \square

3.11. The restriction that G is Hausdorff can be omitted from 3.1 and 3.10. This can be seen as follows. Suppose we are given a $ttg \langle H, X, \pi' \rangle$ with H locally compact but not Hausdorff, and X a Tychonoff space. Then the stability subgroup $H_0 := \{t \in H : \pi'(t,x) = x \text{ for every } x \in X\}$ is a closed normal subgroup of H , hence $G := H/H_0$ is a locally compact Hausdorff topological group. Let π denote the naturally induced action of G on X . Then theorem 3.10 can be applied to $\langle G, X, \pi \rangle$ so as to produce a G -compactification

$\langle G, Y, \sigma \rangle$ of $\langle G, X, \pi \rangle$. If $\psi: H \rightarrow G$ is the quotient mapping, then an action σ^ψ of H on Y can be defined by $\sigma^\psi(t, y) := \sigma(\psi(t), y)$ for $(t, y) \in H \times Y$. It is plain that now $\langle H, Y, \sigma^\psi \rangle$ is the desired H -compactification of $\langle H, X, \pi' \rangle$.

4. AN APPLICATION

In [5], a dynamical system (that is, an \mathbb{R} -space in our terminology) is described, which is defined by a Cauchy problem for an autonomous partial differential equation and which has the following property: every "bounded" dynamical system on a separable metrizable space can equivariantly be embedded in this "universal" system. However, the notion of boundedness which occurs in [5] differs slightly from ours, and we shall call it therefore *metrical* boundedness. Here is the definition: a ttg $\langle G, X, \pi \rangle$ with X a metrizable space is called *metrically bounded w.r.t. a metric d* provided it is bounded w.r.t. the uniformity U_d which corresponds with d . Here the situation is somewhat subtle: a bounded action on a metrizable space X (w.r.t. some uniformity U for X) may be *not* metrically bounded w.r.t. any metric d for X , even if the acting group is a separable locally compact group (cf. [10], p.110, where an example is given with a σ -compact locally compact Hausdorff group G ; if we take in that example for the index set A a set with the cardinality of the continuum, we obtain a separable group: a product of continuously many separable spaces is still separable). However, if G is a σ -compact locally compact Hausdorff group (in particular, if $G = \mathbb{R}$) and X is a *separable* metrizable space, then boundedness of $\langle G, X, \pi \rangle$ w.r.t. some uniformity U implies metric boundedness of $\langle G, X, \pi \rangle$ w.r.t. some metric d .

For a proof of this fact in its full generality, we refer to [10], Corollary 4.11, or to [12], 7.3.14. For the special case of $G = \mathbb{R}$ we present here a quick proof:

4.1. PROPOSITION. *Every ttg $\langle \mathbb{R}, X, \pi \rangle$ with X a separable metrizable space is metrically bounded w.r.t. some metric d for X .*

PROOF. According to 3.10, the ttg $\langle \mathbb{R}, X, \pi \rangle$ has an \mathbb{R} -compactification $\langle \mathbb{R}, Y, \sigma \rangle$ with $w(Y) \leq \max\{w(\mathbb{R}), w(X)\} = \aleph_0$. Hence Y is metrizable. Clearly, the action of σ of \mathbb{R} on Y is bounded w.r.t. any metric d for Y , hence the

action π of \mathbb{R} on X is bounded w.r.t. the restriction of d to X . \square

4.2. COROLLARY. *Every ttg $\langle \mathbb{R}, X, \pi \rangle$ with X a separable metrizable space can equivariantly be embedded in CARLSON's universal system $\langle \mathbb{R}, C_V^\infty, \tau \rangle$.*

PROOF. Use proposition 4.1 above and [5], Theorem 1. \square

4.3. REMARK. In [5], boundedness is used only in order to prove that the equivariant embedding mapping F constructed there is actually a relatively open mapping: for injectivity and continuity of F no boundedness condition is needed. Hence a different proof of 4.2 can be given as follows: if $\langle \mathbb{R}, X, \pi \rangle$ is a ttg with X a separable metrizable space, then there is an \mathbb{R} -compactification $\langle \mathbb{R}, Y, \sigma \rangle$ with Y compact metrizable and also separable (cf. the proof of 4.1). Apply CARLSON's proof to $\langle \mathbb{R}, Y, \sigma \rangle$; note that a continuous injection F of Y into C_V^∞ is automatically a topological embedding (Y is compact and C_V^∞ is Hausdorff). Hence the restriction of F to X is a topological embedding of X in C_V^∞ .

A similar application of theorem 3.10 to another embedding problem is the following one: Let G be an infinite σ -compact, locally compact Hausdorff group. In [9] we constructed a linear action π of G on the Hilbert space $L^2(G \times G)$ such that every bounded ttg $\langle G, X, \sigma \rangle$ with X a separable metrizable space can equivariantly be embedded in $\langle G, L^2(G \times G), \pi \rangle$. By 3.10, we can remove here the boundedness condition as well, provided G is second countable, i.e. separable and metrizable. For such groups G we infer that every separable metrizable G -space can equivariantly be embedded in the Hilbert G -space $\langle G, L^2(G \times G), \pi \rangle$.

Further applications of 3.10 will be published in the future.

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