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On Interpolating Random Fields using a Finite Number of Observations

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Abstract

The best in the mean square sense linear interpolator for a zero mean weakly stationary random field is expressed in terms of orthonormal polynomials associated with the spectral distribution function of this field.

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1 Introduction

In this report we present formulas for interpolating a zero mean weakly stationary random field $\{X_u\}_{u \in \mathbb{Z}^d}$ under the assumption that the second order characteristics of the random field are known. Let $\{X_{\omega_m}\}_{m \in W}$ be a finite set of random variables, with $W = \{0, \dots, N\}$. Fix subsets $\{X_{\omega_s}\}_{s \in S}$ and $\{X_{\omega_t}\}_{t \in W \setminus S}$ with S a non-empty proper subset of W , and suppose that only observations from the last set of random variables are available. Our aim is now to find the best (in the least squares sense) linear interpolators $\{\hat{X}_{\omega_s}\}_{s \in S}$ based on the observations available. It is well known that the interpolators \hat{X}_{ω_s} can be determined by solving a $(|W| - |S|) \times (|W| - |S|)$ linear system of equations, no matter whether the random field is stationary or not.

In this report we exploit the fact that the random field is stationary: by the stationarity assumption we can recurrently construct orthonormal polynomials $\{\phi_{\omega,n}\}_{n=0}^N$ as described in [Dzhaparidze and Janssen]. The coefficients of the linear interpolators $\{\hat{X}_{\omega_s}\}_{s \in S}$ can now be expressed in terms of the coefficients of the orthonormal polynomials (cf. Theorem 1). Notice that the procedure described here requires the inversion of a $|S| \times |S|$ matrix.

This report is organized as follows: in Chapter 2 basic notions are presented and the (least squares) minimization problem is formulated. In Chapter 3 the minimization problem is solved in terms of orthonormal polynomials. In Chapter 4 the results of Chapter 3 are applied to a zero mean real Gaussian random field.

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2 Interpolation

2.1 Basic Notions

In this subsection some basic notions are introduced; see [Dzhaparidze and Janssen] for more details.

By using the usual multi-index notations, z to the power η for $z = (z_1, z_2, \dots, z_d) \in \mathbb{C}^d$ and $\eta = (\eta_1, \eta_2, \dots, \eta_d) \in \mathbb{Z}^d$ is defined by

$$z^\eta := \prod_{k=1}^d z_k^{\eta_k} \in \mathbb{C},$$

so that

$$z^\eta \cdot z^\nu = z^{\eta+\nu}$$

for all $\eta, \nu \in \mathbb{Z}^d$. Once powers of the variable z are known, monomials can be defined. A monomial is then a function $\mathbb{C}^d \rightarrow \mathbb{C}$ such that

$$z \mapsto z^\eta$$

for some $\eta \in \mathbb{Z}^d$. This mapping will be denoted by e_η . Notice that

$$e_\eta \cdot e_\nu = e_{\eta+\nu}$$

for all $\eta, \nu \in \mathbb{Z}^d$. Finally a polynomial is a finite linear combination of monomials.

The ρ^{th} - derivative of the polynomial p in z with $\rho = (\rho_1, \dots, \rho_d) \in \mathbb{N}^d$ is defined by

$$\frac{d^\rho}{dz^\rho} p(z) := \frac{\partial^{\rho_1}}{\partial z_1^{\rho_1}} \cdots \frac{\partial^{\rho_d}}{\partial z_d^{\rho_d}} p(z).$$

So we have

$$\frac{d^\rho}{dz^\rho} e_\rho(z) = \rho!$$

with

$$\rho! := \prod_{k=1}^d \rho_k!$$

Using the notation

$$0_d := (0, \dots, 0) \in \mathbb{N}^d,$$

we get for all $\eta \in \mathbb{N}^d$ that if $\eta \neq \rho$, then

$$\frac{d^\rho}{dz^\rho} e_\eta(z) \Big|_{z=0_d} = 0.$$

Let (P^d, \mathbb{C}) denote the complex vector space consisting of the polynomials. On this vector space, an inner product will be defined. Let $F : \Lambda \rightarrow \mathbb{R}$ be a spectral distribution

function, where $\Lambda = (-\pi, \pi]^d$. Then *it is assumed that* the mapping $\langle \cdot; \cdot \rangle: \mathbb{P}^d \times \mathbb{P}^d \rightarrow \mathbb{C}$ given by

$$\langle f; g \rangle := \int_{\Lambda} f(e^{i\lambda}) \overline{g(e^{i\lambda})} dF(\lambda)$$

is an inner product, where the numbers $e^{i\lambda}$ for $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_d) \in \mathbb{R}^d$ are defined by

$$e^{i\lambda} := (e^{i\lambda_1}, e^{i\lambda_2}, \dots, e^{i\lambda_d}) \in \mathbb{C}^d.$$

The norm $\|\cdot\|: \mathbb{P}^d \rightarrow \mathbb{R}$ induced by the inner product is given by

$$\|\cdot\| = \langle \cdot; \cdot \rangle^{\frac{1}{2}}.$$

We can now introduce systems of orthonormal polynomials: let

$$e_{\omega_0}, e_{\omega_1}, \dots, e_{\omega_N}$$

be an ordered system of monomials, with $\omega = (\omega_0, \omega_1, \dots, \omega_N) \in \mathbb{Z}^d \times \mathbb{Z}^d \times \dots \times \mathbb{Z}^d$ and $\omega_i \neq \omega_j$ for all $i \neq j$. Then a unique system of polynomials $\{\phi_{\omega,n}\}_{n=0}^N$ exists such that

- $\phi_{\omega,n}$ is a linear combination of the monomials $e_{\omega_0}, \dots, e_{\omega_n}$.
- the coefficient of e_{ω_n} in $\phi_{\omega,n}$ is a positive real number.
- the polynomials $\{\phi_{\omega,n}\}_{n=0}^N$ are orthonormal, i.e.

$$\langle \phi_{\omega,n}; \phi_{\omega,m} \rangle = \delta_{n,m} = \begin{cases} 1 & \text{if } n = m \\ 0 & \text{if } n \neq m \end{cases}$$

cf. [Grenander and Szegö]. In this report the sequences ω belong either to the set

$$\Omega_N = \{(\omega_0, \omega_1, \dots, \omega_N) \mid \omega_i \in \mathbb{Z}^d, \omega_0 = 0_d, \forall i, j \in \{0, \dots, N\} : (i \neq j) \Rightarrow (\omega_i \neq \omega_j)\} \quad (1)$$

or to the set

$$\Omega_N^+ = \{(\omega_0, \omega_1, \dots, \omega_N) \mid \omega_i \in \mathbb{N}^d, \omega_0 = 0_d, \forall i, j \in \{0, \dots, N\} : (i \neq j) \Rightarrow (\omega_i \neq \omega_j)\}.$$

Notice that for each component ω_i from $\omega = (\omega_0, \omega_1, \dots, \omega_N) \in \Omega_N^+$, we can take the ω_i^{th} -derivative of an arbitrary polynomial.

Fix now $\omega \in \Omega_N$. For a fixed $a \in \mathbb{C}^d$, define the kernel polynomial $s_{\omega}(a, \cdot): \mathbb{C}^d \rightarrow \mathbb{C}$ by

$$s_{\omega}(a, \cdot) = \sum_{k=0}^N \overline{\phi_{\omega,k}(a)} \phi_{\omega,k}(\cdot)$$

Notice that this polynomial can also be represented as

$$s_\omega(a, \cdot) = \overline{(e_{\omega_0}(a), \dots, e_{\omega_N}(a))} (\mathbf{H}_\omega)^{-1} \begin{pmatrix} e_{\omega_0}(\cdot) \\ \vdots \\ e_{\omega_N}(\cdot) \end{pmatrix},$$

with

$$\mathbf{H}_\omega = \begin{pmatrix} \langle e_{\omega_0}; e_{\omega_0} \rangle & \langle e_{\omega_0}; e_{\omega_1} \rangle & \dots & \langle e_{\omega_0}; e_{\omega_N} \rangle \\ \langle e_{\omega_1}; e_{\omega_0} \rangle & \langle e_{\omega_1}; e_{\omega_1} \rangle & \dots & \langle e_{\omega_1}; e_{\omega_N} \rangle \\ \dots & \dots & \dots & \dots \\ \langle e_{\omega_N}; e_{\omega_0} \rangle & \langle e_{\omega_N}; e_{\omega_1} \rangle & \dots & \langle e_{\omega_N}; e_{\omega_N} \rangle \end{pmatrix}.$$

cf. [Dzhaparidze and Janssen].

2.2 Minimization problem

Let $\{X_t\}_{t \in \mathbb{Z}^d}$ be a complex valued zero mean weakly stationary random field with given covariances, i.e.

- $\forall t \in \mathbb{Z}^d \quad \mathbb{E}(X_t) = 0$ and $\mathbb{E}(|X_t|^2) < \infty$.
- $\forall s, t \in \mathbb{Z}^d$

$$\text{Cov}(X_s, X_t) = \mathbb{E}(X_s \overline{X_t})$$

depends only on $s - t$.

Due to stationarity, there exists a spectral distribution function $F : \Lambda \rightarrow \mathbb{R}$ with $\Lambda = (-\pi, \pi]^d$ such that for all $s, t \in \mathbb{Z}^d$

$$\mathbb{E}(X_s \overline{X_t}) = \int_{\Lambda} (e^{i\lambda})^{s-t} dF(\lambda) = \langle e_s; e_t \rangle.$$

From now on we fix $N+1$ random variables in ‘a window’. This window $\omega = (\omega_0, \dots, \omega_N)$ of indices of the random variables belongs to the set Ω_N . For $\omega \in \Omega_N$ the covariance matrix of $X_{\omega_0}, \dots, X_{\omega_N}$ is given by

$$\Gamma_\omega = \mathbb{E} \begin{pmatrix} X_{\omega_0} \\ \vdots \\ X_{\omega_N} \end{pmatrix} \overline{(X_{\omega_0}, \dots, X_{\omega_N})} = \mathbf{H}_\omega.$$

Assume that we miss observations on $X_{\omega_{s_0}}, \dots, X_{\omega_{s_q}}$ with $s_0 < \dots < s_q$. Surely the set of indices $S = \{s_0, \dots, s_q\}$ belongs to $W = \{0, \dots, N\}$. For a fixed $s \in S$, the best *linear* interpolator for X_{ω_s} , based on $\{X_{\omega_t} | t \in W \setminus S\}$, is given by

$$\hat{X}_{\omega_s} = \sum_{t \in W \setminus S} c_t^{(s)} X_{\omega_t},$$

where the numbers $c_t^{(s)} \in \mathbb{C}$ are chosen so that the mean squared error

$$\mathbb{E}|X_{\omega_s} - \hat{X}_{\omega_s}|^2$$

is minimized. Using the notation $W \setminus S = \{t_0, \dots, t_{N-q-1}\}$ with $t_0 < \dots < t_{N-q-1}$, we can write

$$\hat{X}_{\omega_s} = \sum_{n=0}^{N-q-1} c_{t_n}^{(s)} X_{\omega_{t_n}}. \quad (2)$$

It is well known that the coefficients $c_{t_n}^{(s)}$ minimizing the mean squared error, satisfy the system

$$(c_{t_0}^{(s)}, \dots, c_{t_{N-q-1}}^{(s)}) \Gamma_{W \setminus S} = (\mathbb{E}(X_{\omega_s} \bar{X}_{\omega_{t_0}}), \dots, \mathbb{E}(X_{\omega_s} \bar{X}_{\omega_{t_{N-q-1}}})) , \quad (3)$$

in which

$$\Gamma_{W \setminus S} = \mathbb{E} \left(\begin{array}{c} X_{\omega_{t_0}} \\ \vdots \\ X_{\omega_{t_{N-q-1}}} \end{array} \right) \overline{(X_{\omega_{t_0}}, \dots, X_{\omega_{t_{N-q-1}}})}. \quad (4)$$

In view of stationarity the mean squared error can be written in the following form:

$$\mathbb{E}|X_{\omega_s} - \hat{X}_{\omega_s}|^2 = \int_{\Lambda} |(e^{i\lambda})^{\omega_s} - \sum_{t \in W \setminus S} c_t^{(s)} (e^{i\lambda})^{\omega_t}|^2 dF(\lambda).$$

If the polynomial

$$\pi_{\omega}^{(s)} = e_{\omega_s} + \sum_{t \in W \setminus S} a_t^{(s)} e_{\omega_t}$$

minimizes $\|\cdot\|$ over $\text{span}(e_{\omega_t} | t \in (W \setminus S) \cup \{s\})$ under the restriction that the coefficient of e_{ω_s} equals one, then the numbers $c_t^{(s)}$ are given by

$$c_t^{(s)} = -a_t^{(s)}.$$

In the next section we will construct the polynomials $\pi_{\omega}^{(s)}$ for $s \in S$.

3 Interpolation Polynomials

To find the coefficients of the interpolator \hat{X}_{ω_s} , we have to solve the system (3), i.e. we have to invert the $(N-q) \times (N-q)$ matrix $\Gamma_{W \setminus S}$. Alternatively, we can proceed as follows: by the stationarity assumption we can recurrently construct the orthonormal polynomials $\{\phi_{\omega,n}\}_{n=0}^N$ as described in [Dzhaparidze and Janssen]. Coefficients of these polynomials will then be used to construct matrices A_S and Φ_S given by (5) and (8). Finally, the interpolation polynomials $\pi_{\omega}^{(s)}$ for $s \in S$ are constructed by using (11) and (12) (at this step we have to invert the $(q+1) \times (q+1)$ matrix Φ_S). The coefficients of $\pi_{\omega}^{(s)}$ determine the coefficients of the best linear interpolator \hat{X}_{ω_s} , as was already noted at the end of the previous section.

Fix $N \in \mathbb{N}$ and $\omega = (\omega_0, \dots, \omega_N) \in \Omega_N$. Along with $W = \{0, \dots, N\}$ and $S = \{s_0, \dots, s_q\} \subset W$ where $s_0 < \dots < s_q$, we use the notation $Q = \{0, \dots, q\}$. For a fixed $r \in Q$ we denote by $\pi_{\omega}^{(s_r)}$ the polynomial that minimizes $\|\cdot\|$ over $\text{span}(e_{\omega_t} | t \in (W \setminus S) \cup \{s_r\})$ under the restriction that the coefficient of $e_{\omega_{s_r}}$ equals one.

Theorem 1 shows how the polynomial $\pi_{\omega}^{(s_r)}$ can be constructed by using the matrices A_S and Φ_S , which are defined as follows: let the orthonormal polynomials $\{\phi_{\omega,n}\}_{n=0}^N$ be given by

$$\phi_{\omega,n} = \sum_{m=0}^n \varphi_{n,m} e_{\omega_m},$$

in which $\varphi_{n,n} = k_n \in \mathbb{R}^+$ (cf. [Dzhaparidze and Janssen]). We set $\varphi_{n,m} = 0$ when $m > n$. Then the matrix $[(A_S)_{\mu,\nu} | 0 \leq \mu \leq N - s_0, 0 \leq \nu \leq q]$ is given by

$$(A_S)_{\mu,\nu} = \varphi_{s_0+\mu, s_\nu}.$$

So

$$A_S = \begin{pmatrix} \varphi_{s_0, s_0} & 0 & \vdots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ \varphi_{s_1-1, s_0} & 0 & \vdots & 0 \\ \varphi_{s_1, s_0} & \varphi_{s_1, s_1} & \vdots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & 0 \\ \varphi_{s_q, s_0} & \varphi_{s_q, s_1} & \vdots & \varphi_{s_q, s_q} \\ \vdots & \vdots & \vdots & \vdots \\ \varphi_{N, s_0} & \varphi_{N, s_1} & \vdots & \varphi_{N, s_q} \end{pmatrix} \quad (5)$$

If $\omega \in \Omega_N^+$, then

$$(A_S)_{\mu,\nu} = \frac{1}{\omega_{s_\nu}!} \frac{d^{\omega_{s_\nu}}}{dz^{\omega_{s_\nu}}} \phi_{\omega, s_0+\mu}(z) \Big|_{z=0_d}. \quad (6)$$

The $(q+1) \times (q+1)$ matrix $[(\Phi_S)_{u,v} | 0 \leq u, v \leq q]$ is given by

$$(\Phi_S)_{u,v} := \sum_{k=s_0}^N \bar{\varphi}_{k,s_u} \varphi_{k,s_v} = \sum_{k=0}^N \bar{\varphi}_{k,s_u} \varphi_{k,s_v}. \quad (7)$$

Hence

$$\Phi_S = A_S^* A_S, \quad (8)$$

where A_S^* is the conjugate transpose of A_S . The matrix Φ_S is invertible, since the columns of the matrix A_S are linearly independent ($\varphi_{s,s} \in \mathbb{R}^+$ for all $s \in S$).

If $\omega \in \Omega_N^+$, then

$$\begin{aligned} (\Phi_S)_{u,v} &= \sum_{k=0}^N \bar{\varphi}_{k,s_u} \varphi_{k,s_v} \\ &= \sum_{k=0}^N \left[\frac{1}{\omega_{s_u}!} \frac{d^{\omega_{s_u}}}{da^{\omega_{s_u}}} \phi_{\omega,k}(a) \Big|_{a=0_d} \right] \left[\frac{1}{\omega_{s_v}!} \frac{d^{\omega_{s_v}}}{dz^{\omega_{s_v}}} \phi_{\omega,k}(z) \Big|_{z=0_d} \right] \\ &= \frac{1}{\omega_{s_u}!} \frac{\partial^{\omega_{s_u}}}{\partial a^{\omega_{s_u}}} \frac{1}{\omega_{s_v}!} \frac{\partial^{\omega_{s_v}}}{\partial z^{\omega_{s_v}}} s_\omega(a, z) \Big|_{a=z=0_d} \end{aligned}$$

Using the notation

$$\nabla_{S,z} = \left(\frac{1}{\omega_{s_0}!} \frac{\partial^{\omega_{s_0}}}{\partial z^{\omega_{s_0}}}, \dots, \frac{1}{\omega_{s_q}!} \frac{\partial^{\omega_{s_q}}}{\partial z^{\omega_{s_q}}} \right),$$

we can rewrite the last identity as follows:

$$\Phi_S = \nabla_{S,a}^* \nabla_{S,z} s_\omega(a, z) \Big|_{a=z=0_d}. \quad (9)$$

For $\omega \in \Omega_N$ we can also write

$$\begin{aligned} (\Phi_S)_{u,v} &= \sum_{k=0}^N \bar{\varphi}_{k,s_u} \varphi_{k,s_v} \\ &= \sum_{k=0}^N \left[\frac{1}{(2\pi)^d} \int_{\Lambda} (e^{i\lambda})^{\omega_{s_u}} \bar{\phi}_k(e^{i\lambda}) d\lambda \right] \left[\frac{1}{(2\pi)^d} \int_{\Lambda} (e^{-i\mu})^{\omega_{s_v}} \phi_k(e^{i\mu}) d\mu \right] \\ &= \frac{1}{(2\pi)^{2d}} \int_{\Lambda} \int_{\Lambda} (e^{i\lambda})^{\omega_{s_u}} (e^{-i\mu})^{\omega_{s_v}} s_\omega(e^{i\lambda}, e^{i\mu}) d\lambda d\mu, \end{aligned}$$

which yields

$$\Phi_S = \frac{1}{(2\pi)^{2d}} \int_{\Lambda} \int_{\Lambda} \begin{pmatrix} (e^{i\lambda})^{\omega_{s_0}} \\ \vdots \\ (e^{i\lambda})^{\omega_{s_q}} \end{pmatrix} \overline{((e^{i\mu})^{\omega_{s_0}}, \dots, (e^{i\mu})^{\omega_{s_q}})} s_\omega(e^{i\lambda}, e^{i\mu}) d\lambda d\mu. \quad (10)$$

Theorem 1 Fix $r \in Q$. Let $\pi_\omega^{(s_r)}$ be the unique polynomial that minimizes $\|\cdot\|$ over $\text{span}(e_{\omega_t} | t \in (W \setminus S) \cup \{s_r\})$ under the restriction that the coefficient of $e_{\omega_{s_r}}$ equals one. Then

$$\pi_\omega^{(s_r)} = \sum_{n=s_0}^N v_n^{(s_r)} \phi_{\omega,n}, \quad (11)$$

where $v^{(s_r)} = (v_{s_0}^{(s_r)}, \dots, v_N^{(s_r)})$ is given by

$$v^{(s_r)} = \chi_{q,r}^T \Phi_S^{-1} A_S^*. \quad (12)$$

The minimum itself equals $(\Phi_S^{-1})_{r,r}$. Here $\chi_{q,r}$ is the unit vector of length $q+1$ with 1 at the $(r+1)^{\text{th}}$ place. Therefore formula (12) is equivalent to

$$\begin{pmatrix} v_{s_0}^{(s_r)} & \dots & v_N^{(s_r)} \\ \dots & \dots & \dots \\ v_{s_0}^{(s_q)} & \dots & v_N^{(s_q)} \end{pmatrix} = \Phi_S^{-1} A_S^*.$$

Proof: Let $g_\omega^{(s_r)}$ be an element of $\text{span}(e_{\omega_t} | t \in (W \setminus S) \cup \{s_r\})$, with the coefficient of $e_{\omega_{s_r}}$ equal to one, i.e.

$$g_\omega^{(s_r)} = \sum_{n=0}^N b_n^{(s_r)} \phi_{\omega,n},$$

with the constraint that for all $\nu \in Q$

$$\sum_{n=0}^N b_n^{(s_r)} \varphi_{n,s_\nu} = \delta_{\nu,r} = \begin{cases} 1 & \text{if } \nu = r \\ 0 & \text{if } \nu \neq r \end{cases} \quad (13)$$

Since $\varphi_{n,m} = 0$ for $m > n$, formula (13) reduces to

$$\sum_{n=s_0}^N b_n^{(s_r)} \varphi_{n,s_\nu} = \delta_{\nu,r} \quad (14)$$

for all $\nu \in Q$, or in vector notation

$$(b_{s_0}^{(s_r)}, \dots, b_N^{(s_r)}) A_S = \chi_{q,r}^T. \quad (15)$$

Notice that (15) does not depend on $b_n^{(s_r)}$ for $n < s_0$. So when minimizing

$$\|g_\omega^{(s_r)}\|^2 = \sum_{n=0}^N |b_n^{(s_r)}|^2 = \sum_{n=0}^{s_0-1} |b_n^{(s_r)}|^2 + \sum_{n=s_0}^N |b_n^{(s_r)}|^2,$$

under the constraint (15), we have to take $b_n^{(s_r)} = 0$ for $n < s_0$. This means that

$$\pi_\omega^{(s_r)} = \sum_{n=s_0}^N v_n^{(s_r)} \phi_{\omega,n},$$

where $v^{(s_r)} = (v_{s_0}^{(s_r)}, \dots, v_N^{(s_r)})$ is the particular solution of (15) with

$$\sum_{n=s_0}^N |v_n^{(s_r)}|^2$$

as small as possible. Thus $[v^{(s_r)}]^T$ has to satisfy

$$A_S^T [v^{(s_r)}]^T = \chi_{q,r}$$

(cf. (15)) and $[v^{(s_r)}]^T$ has to belong to the column space of $(A_S^T)^*$. This yields

$$v^{(s_r)} = \chi_{q,r}^T (A_S^* A_S)^{-1} A_S^* = \chi_{q,r}^T \Phi_S^{-1} A_S^*.$$

The minimum itself equals

$$v^{(s_r)} [v^{(s_r)}]^* = \chi_{q,r}^T \Phi_S^{-1} [\chi_{q,r}^T]^* = (\Phi_S^{-1})_{r,r}.$$

□

Remark: If $\omega \in \Omega_N^+$, then (6), (9), (11) and (12) yield

$$\pi_\omega^{(s_r)}(\cdot) = \chi_{q,r}^T (\nabla_{S,a}^* \nabla_{S,z} s_\omega(a, z)|_{a=z=0_d})^{-1} \nabla_{S,a}^* s_\omega(a, \cdot)|_{a=0_d}$$

Corollary 1 *If S contains only one element, i.e. $q = 0$ and $S = \{s_0\}$, then the polynomial $\pi_\omega^{(s_0)}$ is given by*

$$\pi_\omega^{(s_0)} = \frac{\sum_{n=s_0}^N \bar{\varphi}_{n,s_0} \phi_{\omega,n}}{\sum_{n=s_0}^N \bar{\varphi}_{n,s_0} \varphi_{n,s_0}}.$$

This polynomial is called a ‘one-point interpolation polynomial’. If moreover $s_0 = 0$, then

$$\pi_\omega^{(0)} = \frac{\sum_{n=0}^N \bar{l}_n \phi_{\omega,n}}{\sum_{n=0}^N |l_n|^2},$$

where $l_n = \varphi_{n,0}$. If $\omega \in \Omega_N^+$, then the polynomial $\pi_\omega^{(s_0)}$ is given by

$$\pi_\omega^{(s_0)}(\cdot) = \frac{\frac{\partial^{\omega s_0}}{\partial a^{\omega s_0}} s_\omega(a, \cdot)|_{a=0_d}}{\frac{1}{\omega_{s_0}!} \frac{\partial^{\omega s_0}}{\partial a^{\omega s_0}} \frac{\partial^{\omega s_0}}{\partial z^{\omega s_0}} s_\omega(a, z)|_{a=z=0_d}}$$

□

Remark: Notice that the adapted Gram-Schmidt orthogonalization procedure defined in [Dzhaparidze and Janssen] by

$$e_{\omega_N}, \dots, e_{\omega_0} \xrightarrow{GS} u_{\omega,N},$$

leads to the identity

$$u_{\omega,N} = \pi_{\omega}^{(0)},$$

with $\pi_{\omega}^{(0)}$ defined in Corollary 1. Hence, using again the notations from [Dzhaparidze and Janssen] we have

$$\frac{\phi_{V_N(\omega),N}^*}{k_{V_N(\omega),N}} = \frac{\sum_{n=0}^N \bar{l}_n \phi_{\omega,n}}{\sum_{n=0}^N |l_n|^2}. \quad (16)$$

The next theorem shows that the interpolation polynomials $\pi_{\omega}^{(s)}$ can be expressed in terms of the one-point interpolation polynomials as defined in Corollary 1.

Theorem 2 For $u \in Q$ define

$$\hat{\pi}_{\omega}^{(s_u)} = \frac{\sum_{n=s_u}^N \bar{\varphi}_{n,s_u} \phi_{\omega,n}}{\sum_{n=s_u}^N \bar{\varphi}_{n,s_u} \varphi_{n,s_u}}$$

(cf. Corollary 1). Define the $(q+1) \times (q+1)$ matrix $[(\hat{\Phi}_S)_{\alpha,\beta} | 0 \leq \alpha, \beta \leq q]$ by

$$(\hat{\Phi}_S)_{\alpha,\beta} = (\Phi_S)_{\alpha,\beta} \delta_{\alpha,\beta}, \quad (17)$$

in which the matrix Φ_S is given by (8). Then

$$\Phi_S \begin{pmatrix} \pi_{\omega}^{(s_0)} \\ \vdots \\ \pi_{\omega}^{(s_q)} \end{pmatrix} = \hat{\Phi}_S \begin{pmatrix} \hat{\pi}_{\omega}^{(s_0)} \\ \vdots \\ \hat{\pi}_{\omega}^{(s_q)} \end{pmatrix} \quad (18)$$

Proof: Fix $r \in Q$ and let $d^{(s_r)} = (d_0^{(s_r)}, \dots, d_q^{(s_r)})$ be given by

$$d^{(s_r)} = \chi_{q,r}^T \Phi_S^{-1} \hat{\Phi}_S. \quad (19)$$

Then (7), (11) and (12) yield

$$\begin{aligned} \pi_{\omega}^{(s_r)} &= \chi_{q,r}^T \Phi_S^{-1} A_S^* (\phi_{\omega,s_0}, \dots, \phi_{\omega,N})^T \\ &= \chi_{q,r}^T \Phi_S^{-1} \hat{\Phi}_S \hat{\Phi}_S^{-1} A_S^* (\phi_{\omega,s_0}, \dots, \phi_{\omega,N})^T \\ &= d^{(s_r)} (\hat{\pi}_{\omega}^{(s_0)}, \dots, \hat{\pi}_{\omega}^{(s_q)})^T. \end{aligned}$$

So

$$\pi_{\omega}^{(s_r)} = \sum_{u=0}^q d_u^{(s_r)} \hat{\pi}_{\omega}^{(s_u)}.$$

This yields (18). □

4 Gaussian Random Fields

In conclusion, we present the following application of results to a zero mean Gaussian random field.

Theorem 3 *Assume that $\{X_t\}_{t \in \mathbb{Z}^d}$ is a real zero mean Gaussian random field. Then the conditional probability density function of $X_{\omega_{s_r}}, r \in Q$ given $X_{\omega_t} = x_{\omega_t}, t \in W \setminus S$ is*

$$p(x_{\omega_{s_0}}, \dots, x_{\omega_{s_q}} | x_{\omega_t}, t \in W \setminus S) = \frac{1}{(\sqrt{2\pi})^{q+1} \sqrt{\det(\Phi_S^{-1})}} e^{-\frac{1}{2} \mathbf{x}^T \Phi_S \mathbf{x}}, \quad (20)$$

where

$$\mathbf{x}^T = ([x_{\omega_{s_0}} + \sum_{t \in W \setminus S} a_t^{(s_0)} x_{\omega_t}], \dots, [x_{\omega_{s_q}} + \sum_{t \in W \setminus S} a_t^{(s_q)} x_{\omega_t}]),$$

with the coefficients satisfying the following identities:

$$\pi_{\omega}^{(s_r)} = e_{\omega_{s_r}} + \sum_{t \in W \setminus S} a_t^{(s_r)} e_{\omega_t}$$

for all $r \in Q$.

Proof: Recall that for a real Gaussian random field $\{X_t\}_{t \in \mathbb{Z}^d}$, the best linear interpolator for X_{ω_s} ($s \in S$) based on $\{X_{\omega_t} | t \in W \setminus S\}$, is the conditional expectation

$$\hat{X}_{\omega_s} = \mathbb{E}[X_{\omega_s} | X_{\omega_t}, t \in W \setminus S] \text{ almost surely.}$$

This determines the form of the vector \mathbf{x} in (20). It remains therefore to verify that for $k, l \in Q$

$$\mathbb{E}[X_{\omega_{s_k}} - \hat{X}_{\omega_{s_k}}] \overline{[X_{\omega_{s_l}} - \hat{X}_{\omega_{s_l}}]} = (\Phi_S^{-1})_{k,l}.$$

This is indeed true, because by using (12) we have

$$\begin{aligned} \mathbb{E}[X_{\omega_{s_k}} - \hat{X}_{\omega_{s_k}}] \overline{[X_{\omega_{s_l}} - \hat{X}_{\omega_{s_l}}]} &= \langle \pi_{\omega}^{(s_k)}; \pi_{\omega}^{(s_l)} \rangle \\ &= v^{(s_k)} [v^{(s_l)}]^* \\ &= \chi_{q,k}^T \Phi_S^{-1} A_S^* A_S \Phi_S^{-1} \chi_{q,l} \\ &= (\Phi_S^{-1})_{k,l}. \end{aligned}$$

□

Remark: If $X_{\omega_t} = x_{\omega_t} = 0$ for all $t \in W \setminus S$, then by (10) the quadratic form $\mathbf{x}^T \Phi_S \mathbf{x}$ in (20) can be expressed as follows:

$$\mathbf{x}^T \Phi_S \mathbf{x} = \frac{1}{(2\pi)^{2d}} \int_{\Lambda} \int_{\Lambda} \overline{\left(\sum_{u=0}^q x_{\omega_{s_u}} (e^{-i\lambda})^{\omega_{s_u}} \right)} \left(\sum_{v=0}^q x_{\omega_{s_v}} (e^{-i\mu})^{\omega_{s_v}} \right) s_{\omega}(e^{i\lambda}, e^{i\mu}) d\lambda d\mu. \quad (21)$$

It is perhaps worthwhile to compare the result of Theorem 3 with the following assertion:

Theorem 4 [Dobrushin] *Suppose*

$$\frac{dF(\lambda)}{d\lambda} = f(\lambda)$$

exists and

$$\int_{\Lambda} \frac{1}{f(\lambda)} d\lambda < \infty,$$

(notice that $f \geq 0$). Define the matrix $T(\frac{1}{(2\pi)^{2d}f})$ by

$$T\left(\frac{1}{(2\pi)^{2d}f}\right) = \int_{\Lambda} \begin{pmatrix} (e^{i\lambda})^{\omega_{s_0}} \\ \vdots \\ (e^{i\lambda})^{\omega_{s_q}} \end{pmatrix} \frac{1}{((e^{i\lambda})^{\omega_{s_0}}, \dots, (e^{i\lambda})^{\omega_{s_q}})} \frac{1}{(2\pi)^{2d}f(\lambda)} d\lambda. \quad (22)$$

Then the conditional probability density function of $X_{\omega_{s_r}}, r \in Q$ given $X_m = 0, m \notin \{\omega_{s_r} \mid r \in Q\}$ is

$$p(x_{\omega_{s_0}}, \dots, x_{\omega_{s_q}}) = \frac{1}{(\sqrt{2\pi})^{q+1} \sqrt{\det(T(\frac{1}{(2\pi)^{2d}f})^{-1})}} e^{-\frac{1}{2} \mathbf{x}^T T(\frac{1}{(2\pi)^{2d}f}) \mathbf{x}}, \quad (23)$$

with

$$\mathbf{x}^T T\left(\frac{1}{(2\pi)^{2d}f}\right) \mathbf{x} = \frac{1}{(2\pi)^{2d}} \int_{\Lambda} \frac{|\sum_{u=0}^q x_{\omega_{s_u}} (e^{-i\lambda})^{\omega_{s_u}}|^2}{f(\lambda)} d\lambda. \quad (24)$$

□

Notice that (21) and (24) yield

$$0 \leq \mathbf{x}^T T\left(\frac{1}{(2\pi)^{2d}f}\right) \mathbf{x} - \mathbf{x}^T \Phi_S \mathbf{x} = \frac{1}{(2\pi)^{2d}} \int_{\Lambda} \int_{\Lambda} \frac{\left(\sum_{u=0}^q x_{\omega_{s_u}} (e^{-i\lambda})^{\omega_{s_u}}\right) \overline{\left(\sum_{v=0}^q x_{\omega_{s_v}} (e^{-i\mu})^{\omega_{s_v}}\right)}}{f(\lambda)f(\mu)} \zeta_{\omega}(\lambda, \mu) dF(\lambda) dF(\mu) \quad (25)$$

in which the function ζ_{ω} is determined by the relation

$$\int_{\Lambda} p(e^{i\lambda}) \zeta_{\omega}(\lambda, \mu) dF(\lambda) = \begin{cases} 0 & \text{if } p \in \text{span}\{e_{\omega_0}, \dots, e_{\omega_N}\} \\ p(e^{i\mu}) & \text{if } p \in \text{span}\{e_{\omega_0}, \dots, e_{\omega_N}\}^{\perp} \end{cases}$$

Loosely speaking, we can say that

$$\zeta_{\omega}(\lambda, \mu) = \frac{\delta(\lambda - \mu)}{f(\lambda)} - \overline{s_{\omega}(e^{i\mu}, e^{i\lambda})}.$$

References

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