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Newton's Problem of the Body of Minimal Resistance in the Class of Convex Developable Functions

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ABSTRACT

We investigate the minimization of Newton's functional for the problem of the body of minimal resistance with maximal height M>0 [4] in the class of convex developable functions defined in a disc. This class is a natural candidate to find a (non-radial) minimizer in accordance with the results of [9].

We prove that the minimizer in this class has a minimal set in the form of a regular polygon with n sides centered in the disc, and numerical experiments indicate that the natural number $n \geq 2$ is a non-decreasing function of M. The corresponding functions all achieve a lower value of the functional than the optimal radially symmetric function with the same height M.

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1. Introduction

There has been a recent revival of interest in Newton's problem of the body of minimal resistance. In modern terms this problem can be formulated as the minimization problem

$$\inf_{U \in \mathcal{C}} \mathcal{F}(U), \quad \text{with} \quad \mathcal{F}(U) = \int_{\Omega} \frac{dx}{1 + |\nabla U|^2}. \tag{1.1}$$

Here Ω is a smooth subset of \mathbb{R}^2 ; the graph of the function U represents the form of a three-dimensional body, and the functional \mathcal{F} models the resistance experienced by this body as it moves through a cloud of gas particles. We refer to [4] for a detailed discussion of the model and the history of this problem.

The form of \mathcal{F} favours functions U with rapid oscillations. Because of this fact, the choice of the class \mathcal{C} of admissible functions is a delicate issue. A number of different choices have been explored in the literature [4, 5, 6, 7, 2], but the most interesting one, from a mathematical viewpoint, seems to be

$$C = \{U : \Omega \to [0, M] : U \text{ is convex } \}.$$

We shall adopt this definition of C throughout the further discussion. The scalar constant M > 0 is a parameter whose role will become clear below.

When Ω is a ball in \mathbb{R}^2 —which we shall assume from now on—the function \mathcal{F} and the set \mathcal{C} are rotationally invariant. Newton exhibited a function U [8] that is radially symmetric and minimizes the functional \mathcal{F} among all radially symmetric members of \mathcal{C} . This function is smooth and strictly convex (see Figure 1, the rightmost shape). For a long time it was implicitly assumed that the minimizer of \mathcal{F} among the whole of \mathcal{C} is necessarily radially symmetric, and therefore coincides with the function found by Newton. However, the symmetry of the general minimizer was never proved, and in 1996 the converse was demonstrated by Brock, Ferone, and Kawohl [3]: when Ω is a ball,

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the minimizer of \mathcal{F} over \mathcal{C} is necessarily non-radially symmetric. The proof consisted of remarking that the second derivative of \mathcal{F} , calculated at Newton's function, had a negative direction that was admissible. Therefore the functional was not minimal.

This result naturally opened the hunt on the true form of the minimizer. In [9] we proved a first step in this direction:

Theorem 1 Let U achieve (1.1), and let $\omega \subset \Omega$ be an open set. Then U is not strictly convex on ω .

The class of non-strictly convex functions on Ω is still relatively large. In this paper we jump the gun, and investigate the functional \mathcal{F} on a much smaller set of functions \mathcal{C}_d . The set \mathcal{C}_d is defined to contain all functions $U \in \mathcal{C}$ such that the graph of U is the convex envelope in \mathbb{R}^3 of the sets $\partial \Omega \times \{M\}$ and $N_0 \times \{0\}$, where

$$N_0 = \{ x \in \Omega : U(x) = 0 \}.$$

Alternatively (and equivalently): U belongs to \mathcal{C}_d whenever U is convex, takes values between 0 and M, satisfies $U(\partial\Omega)=M$, and has no extremal points in $\Omega\setminus\overline{N_0}$. Figure 2 shows the contour lines of a typical function U. Note that for elements of \mathcal{C}_d the convex set N_0 completely characterizes the function.

The reason for considering this set of admissible functions is the following conjecture:

Conjecture 2 Let U solve (1.1). Then $U \in \mathcal{C}_d$.

As supporting evidence for this conjecture we mention of course Theorem 1. Indeed, if we know that U is of class C^2 in $\Omega \setminus \overline{N_0}$, then the conjecture follows from a well-known geometrical property: any regular convex surface with zero Gaussian curvature is indeed a so-called *developable surface*, and can be extended up to a singular line called *line of striction*. Unfortunately, no similar result seems to be known for convex surfaces without any a priori additional regularity; moreover, if ∇U has discontinuities in $\Omega \setminus \overline{N_0}$, then U is only a piecewise developable function. This is why the conjecture is still an open question.

In this paper we thus investigate the problem

$$\inf_{U \in \mathcal{C}_d} \mathcal{F}(U). \tag{1.2}$$

We obtain the following result:

Theorem 3 Let M > 0 be given. If U solves (1.2), then the set N_0 is a regular polygon centered in Ω .

This theorem is proved in two steps. In Section 4 we show that N_0 is necessarily a polygon. In Section 5 we show in addition that this polygon must be regular and centered.

We have computed the value of the functional F for the different regular polygons (m=2, 3, 4, etc.) with an explicit formula (see Appendix A). It turns out, from numerical experiments, that there exists a decreasing sequence $(M_n) \subset \mathbb{N}, n=2,3,\ldots$, with $M_2=\infty$, with the following property: If $M_{n+1} < M < M_n$, and if U solves (1.2), then the set N_0 is a regular polygon with n sides.

This can be seen in Figure 1, where the analytic curves formed by the value of F for n-sided regular polygons are plotted; the optimal curve is a piecewise combination of these. We have also shown in this graph the value of the functional for the radial minimizer given by Newton.

The critical values M_n are given in Table 1

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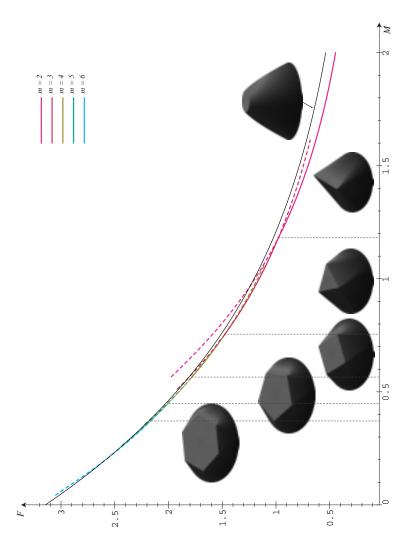


Figure 1: Value of the functional F for optimal regular functions; the thinner line up shows the value for the Newton's radial minimizer.

Table 1: Critical values of M for regular polygons.

M_3	1.179535875
${M}_4$	0.754344515
M_5	0.561232469
M_6	0.447571675
M_7	0.372163842
M_8	0.318383452
M_9	0.278081912

2. The problem in \mathcal{C}_d

2. The problem in C_d

The members of C_d are completely characterized by their set N_0 , and using the convexity of this set we introduce a more convenient representation. Consider the function U of which the contour lines are drawn in Figure 2.

We assume that Ω is the unit ball, and we denote by s the arclength coordinate along $\partial\Omega=S^1$, in the positive direction; x(s) is the point at s, and let $\ell(s)$ be the tangent of N_0 parallel to x'(s), as shown in the figure. We define u(s) to be the signed distance of $\ell(s)$ to the origin, i.e. $u(s)=d(\ell(s),0)$ if ℓ separates 0 from x(s), and $u(s)=-d(\ell(s),0)$ otherwise. Then $u(\cdot)$ completely characterizes N_0 , and to every convex set $N_0\subset\Omega$ there corresponds a function $u:S^1\to [-1,1]$.

We now express the convexity condition and the functional \mathcal{F} in terms of u. If $\ell(s)$ intersects N_0 in one point, then we define y(s) to be this intersection point. If $\ell(s)$ has multiple intersections with N_0 , then y(s) is not well-defined, and the function y is discontinuous at such a point. Denoting the radial and tangent unit vectors at x(s) by $e_r(s)$ and $e_s(s)$, we have

$$u(s) = y(s) \cdot e_r(s)$$
.

Hence $u'(s) = y(s) \cdot e_s(s)$ since $y'(s) \cdot e_r(s) = 0$; and

$$u''(s) = y'(s) \cdot e_s(s) - y(s) \cdot e_r(s) = |y'(s)| - u(s)$$

implying

$$u + u''(s) = |y'(s)| > 0.$$

This is an important result: the condition $u + u'' \ge 0$ (in the sense of distributions on S^1) is equivalent to the statement that the corresponding set N_0 is convex. In the following we shall always assume that u satisfies this condition.

While discussing this point, note that since u + u'' = |y'(s)|, the distribution u + u'' is in fact a Radon measure. The support of the singular part of this measure coincides with the values of s at which y is not continuous, or equivalently, at which $\ell(s)$ intersects N_0 in a line segment of non-zero length. The value of the singular part of u + u'' at such a point is equal to the jump in y, which in turn equals the length of the line segment. At all other points s the singular part of u + u'' is zero, and y is continuous.

On the straight line segment [x, y] the gradient of U is constant, and its length equals $M/((x-y) \cdot e_r) = M/(1-u)$. Hence, using the notation $f(t) = 1/(1+|t|^2)$, we find

$$\begin{split} \mathcal{F}(U) &= \int_{\Omega} f(\nabla U) \, dx = \frac{1}{2} \int_{S^1} f(0) \, y(s) \wedge y'(s) \, ds \, + \\ &\quad + \frac{1}{2} \int_{S^1} f\left(\frac{M}{1 - u(s)}\right) \, (x - y) \wedge (x' + y')(s) \, ds \\ &= \frac{1}{2} f(0) \int_{S^1} u(u + u'') + \frac{1}{2} \int_{S^1} f\left(\frac{M}{1 - u}\right) (1 - u)(1 + u + u'') \end{split}$$

Hence since f(0) = 1, we have to minimize:

$$F(u) = \frac{1}{2} \int_{S^1} u(u + u'') + \frac{M}{2} \int_{S^1} \Phi\left(\frac{1 - u}{M}\right) (1 + u + u'')$$
(2.1)

where

$$\Phi(x) := xf(1/x) = \frac{x^3}{1+x^2} \tag{2.2}$$

2. The problem in \mathcal{C}_d

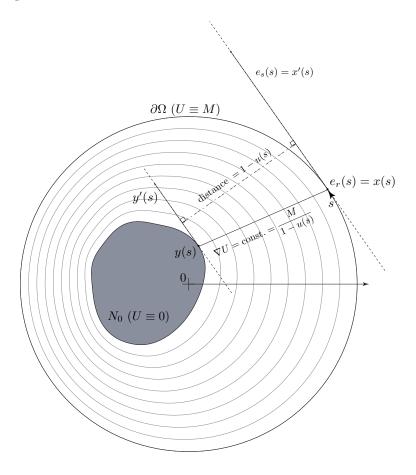


Figure 2: Parametrization of N_0 .

in the set X(-1,1), where we define

$$X(a,b) := \left\{ u \in W^{1,\infty}(S^1) \; ; \; a \le u \le b, \; u + u'' \ge 0 \right\}. \tag{2.3}$$

Note that (2.1) is meaningful, as integrals of a product of a continuous function and a Radon measure. It is sometimes convenient to write F in the form:

$$2F(u) = \int \Psi(u)(1 + u + u'') - \int u \tag{2.4}$$

where

$$\Psi(t) = t + M \Phi\left(\frac{1-t}{M}\right) = \frac{tM^2 + (1-t)^2}{M^2 + (1-t)^2}.$$

Integrating by parts, this can also be written in the form:

$$F(u) = \frac{1}{2} \int_{S^1} \eta(u) - u'^2 \Psi'(u)$$
 (2.5)

3. An estimate of ∇U

where

$$\eta(t) := -t + (1+t)\Psi(t) = \frac{M^2t^2 + (1-t)^2}{M^2 + (1-t)^2}$$

$$\Psi'(t) = M^2 \frac{M^2 - (1-t)^2}{(M^2 + (1-t)^2)^2}.$$

We shall also use

$$\Psi_1(t) := \Psi(t) - 1.$$

3. An estimate of ∇U

In [4] it was proved that if U achieves (1.1), then $|\nabla U| \notin (0,1)$. This fact is related to the concaveness of $f(t) = 1/(1+|t|^2)$ near zero. The radially symmetric minimizer U_N presented by Newton satisfies this condition, and in fact achieves the limit case: close to N_0 , $|\nabla U|$ approaches the value 1.

The bound on u of Lemma 4 below is a reformulation of this result: since $|\nabla U| = M/(1-u)$, the inequality $|\nabla U| \ge 1$ is equivalent to

$$u \ge 1 - M. \tag{3.1}$$

If Conjecture 2 were proved, then (3.1) would follow directly from [4]. Since we have no proof for the conjecture, we state here an independent proof.

Lemma 4 Let u solve problem (4.1). Then $u \ge 1 - M$.

Proof. To force a contradiction we assume that $u(s_0) < 1 - M$, and without loss of generality we also assume that s_0 is a local minimum of u. There are two possibilities: either u' jumps at $s = s_0$, or u' is continuous. We first consider the former case.

Note that u < 1 - M is equivalent to $\Psi'(u) < 0$. For small $\eta > 0$, to be chosen later, we define \tilde{u} to be continuous on S^1 , and to satisfy in addition

$$\tilde{u} \equiv u$$
 on $S^1 \setminus (s_0 - \eta, s_0 + \eta)$ and $\tilde{u} + \tilde{u}'' = 0$ on $(s_0 - \eta, s_0 + \eta)$.

The geometrical interpretation of \tilde{u} is that of a polygon similar to that of u, but where the side corresponding to s_0 is split into two sides, which are then slightly dented outwards.

We set $v = \tilde{u} - u$, and require η to be small enough to ensure that $\Psi'(u) < 0$ on the support of v. On the basis of (2.4) the derivative of $\varepsilon \mapsto 2F(u + \varepsilon v)$ at $\varepsilon = 0$ is given by

$$2F'(u) \cdot v = \int \Psi(u)v'' + \int \Psi'(u)v(1 + u + u'') + \int (\Psi(u) - 1)v.$$
(3.2)

Note that since $v \geq 0$ and $\Psi(\cdot) - 1 \leq 0$, the last two terms are negative; in order to obtain a contradiction we only need to show that the same is true for the first.

The function v'' is a Radon measure with zero integral, i.e. $\int v'' = 0$. The positive part $(v'')_+$ is concentrated at $s = s_0 \pm \eta$. Noting the sign of Ψ' we have $\Psi(u(s)) \geq \Psi(u(s_0 + \eta))$ for $s_0 - \eta \leq s \leq s_0 + \eta$. Therefore

$$\int \Psi(u)v'' = \int [\Psi(u) - \Psi(u(s_0 + \eta))]v'' < 0.$$

This proves the Lemma for the first case.

We next turn to the second possibility, and assume that u' is continuous at $s = s_0$. We choose $\eta > 0$ and define $v(s) = [u(s_0 + \eta) - u(s)]_+$. Repeating the argument, we again have $v \ge 0$, so that the last two terms in (3.2) are negative. By a similar reasoning it follows that

$$\int \Psi(u)v'' = \int [\Psi(u) - \Psi(u(s_0 + \eta))]v'' < 0.$$

This concludes the proof.

4. N_0 is a polygon 7

With this estimate we can derive a simple but useful convexity property. Remark that translating the set N_0 results in adding to u functions of the form $v(s) := a \cos s + b \sin s$. Writing the functional in the form (see (2.1))

$$2F(u) = \int_{S^1} u(u+u'') + M \int_{S^1} \Phi\left(\frac{1-u}{M}\right) (1+u+u''),$$

and differentiating this twice in the direction v we find

$$2d^{2}F(u) \cdot v \cdot v = \frac{1}{M} \int_{S^{1}} \Phi'' \left(\frac{1-u}{M} \right) (1+u+u'') v^{2}.$$

Since $\Phi''((1-u)/M) \ge 0$ whenever $1-M \le u \le 1$, with a strict inequality if u < 1, we find that F is strictly convex with respect to translations of the set N_0 . This proves the following corollary:

Corollary 5 If the set N_0 has an axis of symmetry, then this set is centered in Ω with respect to this symmetry.

4. N_0 is a polygon

In order to prove that N_0 is a polygon we prove the following, more general, theorem. Consider two numbers a < b, and the problem

$$\inf_{u \in X(a,b)} F(u), \quad \text{where } F(u) := \int_{S^1} \left[g(u(s)) - u'^2(s) h(u(s)) \right] ds \tag{4.1}$$

where X(a,b) is defined in (2.3). We assume that $g,h \in C^2(\mathbb{R})$, and

$$h(t) > 0, \ \forall t \in (a, b], \quad h(a) = 0, \quad g'(a) > 0.$$
 (4.2)

Theorem 6 Let u be a minimizer of (4.1). Then the support of u + u'' is a finite subset of S^1 .

This theorem applies directly in our case by setting a=1-M, b=1, $g=\eta$, $h=\Psi'$.

Proof. We assume, to force a contradiction, that there exist sequences $(\alpha_n) \subset (0, \infty)$, $(s_n) \in S^1$ such that $\lim \alpha_n = 0$ and the intersection of the support of $\mu := u + u''$ and $(s_n, s_n + \alpha_n)$ is non-empty. Since S^1 is compact, the support of μ has an accumulation point in S^1 ; we choose this point to be the origin of S^1 .

Let us first assume that u(0) > a; hence $\{u > a\}$ is a neighbourhood of 0, and there exists a constant c > 0 such that h(u) > c in this neighbourhood.

For each $\varepsilon > 0$, there exists $0 < \varepsilon_1 < \varepsilon_2 < \varepsilon$ such that

$$\mu(J_i) > 0, \qquad i = 1, 2, 3,$$

$$(4.3)$$

for each of the intervals $J_1 := (0, \varepsilon_1), J_2 := [\varepsilon_1, \varepsilon_2), J_3 := [\varepsilon_2, \varepsilon)$. For $i = 1, \ldots, 3$ and $\varepsilon > 0$ given, let w_i be the unique solution of the problem

$$w_i(s) + w_i''(s) = \mu(s)\chi_{J_i} \quad \forall s \in (0, \varepsilon), \text{ and } w_i(0) = w_i(\varepsilon) = 0.$$

Then there exist $(\lambda_i)_{i=1,...,3}$ such that $v_{\varepsilon} := \sum_{i=1}^3 \lambda_i w_i$ satisfies

$$0 = v'_{\varepsilon}(0) = \sum_{i=1}^{3} \lambda_i w'_i(0) \quad \text{and} \quad 0 = v'_{\varepsilon}(\varepsilon) = \sum_{i=1}^{3} \lambda_i w'_i(\varepsilon)$$

$$(4.4)$$

4. N_0 is a polygon 8

We extend this function by zero outside $(0, \varepsilon)$, such that v'_{ε} is continuous at 0 and ε . Hence there exists $\eta_0 > 0$ such that $u + \eta v_{\varepsilon} \in X$ for all $\eta \in [-\eta_0, \eta_0]$. Since u solves (4.1), it follows that $F''(u)v_{\varepsilon} \cdot v_{\varepsilon} \geq 0$, that is

$$0 \leq \int_{S^{1}} g''(u)v_{\varepsilon}^{2} - 2h(u){v_{\varepsilon}'}^{2} - 4u'h'(u)v_{\varepsilon}'v_{\varepsilon} - {u'}^{2}h''(u)v_{\varepsilon}^{2}$$

$$\leq \int_{S^{1}} [g''(u) + {u'}^{2}h''(u) + 2u''h'(u)]v_{\varepsilon}^{2} - 2h(u){v_{\varepsilon}'}^{2}.$$

Let us note

$$c_1 := \left\| g''(u) + u'^2 h''(u) + 2u'' h'(u) \right\|_{\text{RM}(S^1)}$$

such that

$$2c\int_0^\varepsilon v_\varepsilon'^2 \le c_1 \|v_\varepsilon\|_{L^\infty(S^1)}^2 \tag{4.5}$$

Since by the Sobolev embedding

$$||v_{\varepsilon}||_{L^{\infty}(S^1)}^2 \le c_0 \varepsilon \int_0^{\varepsilon} {v_{\varepsilon}'}^2,$$

where c_0 does not depend on ε , this contradicts (4.5) for small enough ε .

Hence we have u(0)=a. Moreover, from the previous argument we know that the support of u+u'' is finite in any compact subset of $\{s\in S^1: u(s)>a\}$. Since 0 is not an interior point of the set $\{u=a\}$ we can assume for instance that u(s)>a in a right neighbourhood of 0, say $(0,s_0)$. Then there exists an infinite decreasing sequence (t_n) with limit 0 and a summable sequence $(\alpha_n)\subset (0,\infty)$, such that the restriction of u+u'' to $(0,s_0)$ equals $\sum_n \alpha_n \delta_{t_n}$.

For any given $n \in \mathbb{N}$, n > 2, let us define the function v_n as follows:

$$v_n(s) = \begin{cases} \sin(s - t_{n+1}) \sin(t_{n-1} - t_n) & \text{if } s \in (t_{n+1}, t_n) \\ \sin(t_{n-1} - s) \sin(t_n - t_{n+1}) & \text{if } s \in (t_n, t_{n-1}) \\ 0 & \text{otherwise} \end{cases}$$

One can easily check that v_n is continuous and that the support of $v_n + v_n''$ is the set $\{t_{n+1}, t_n, t_{n-1}\}$. Therefore $u \pm \varepsilon v_n$ is admissible for ε small enough: this implies $F'(u) \cdot v_n = 0$:

$$0 = F'(u) \cdot v_n = \int [g'(u) - (u')^2 h'(u)] v_n - 2u'h(u)v'_n$$

$$= \int [g'(u) + (u')^2 h'(u) + 2u''h(u)] v_n$$

$$= \int [g'(u) + (u')^2 h'(u) - 2uh(u)] v_n + 2 \int (u + u'')h(u)v_n.$$

Taking into account that $u + u'' = \sum_{n} \alpha_n \delta_{t_n}$, and $v_n(t_p) = 0$ if $p \neq n$, we find

$$-g'(a) - (u'(0+))^{2}h'(a) = \frac{2\alpha_{n}h(u(t_{n}))v_{n}(t_{n})}{\int v_{n}} + \frac{\int \chi v_{n}}{\int v_{n}}$$

where

$$\chi(s) := g'(u) - g'(a) + (u')^2 h'(u) - u'(0+)^2 h'(a) + 2uh(u).$$

Note that χ has limit 0 in 0 since u'(t+) is right continuous everywhere; hence as n goes to infinity, $\int \chi v_n / \int v_n$ goes to zero. We also have $\int v_n / v_n(t_n) = \frac{1}{2}(t_{n+1} - t_{n-1}) + o(t_n)$. On the other hand, $h(u(t_n)) = \int_0^{t_n} h'(u(t))u'(t) dt \sim h'(a)u'(0+)t_n$ for n large. Hence if we assume that $g'(a) + u'(0+)^2h'(a) \neq 0$ we see that there exists c > 0 such that

$$\alpha_n > c \, \frac{\tau_n + \tau_{n-1}}{\sum\limits_{j=n}^{\infty} \tau_j}$$

where $\tau_j := t_{j-1} - t_j$.

However it is known that if (τ_n) is a positive summable sequence, then $\tau_n / \sum_{j \geq n} \tau_j$ is not summable. (This comes by considering the step function k such that $k([n, n+1)) = \tau_n$; then define $K(x) := \int_x^\infty k$. The sum $\sum \left(\tau_n / \sum_{j \geq n} \tau_j\right)$ is equivalent to $\int_n^\infty k / K = [\log(-K)]_n^\infty = \infty$.) We deduce that α_n is not summable, a contradiction.

So we must have

$$g'(a) + u'(0+)^2h'(a) = 0.$$

Since we assumed g'(a) < 0, we find that h'(a) > 0 and $u'(0+) \neq 0$. Passing now to the second order derivative, we get, again writing $\tau_j := t_{j-1} - t_j$:

$$\begin{split} 0 &\leq F''(u) \cdot v_n \cdot v_n \\ &= \int [g''(u) + (u')^2 h''(u) - 2uh'(u)] v_n^2 + \\ &\quad + 2 \int (u + u'') h'(u) v_n^2 - 2 \int h(u) (v_n')^2 \\ &= O((\tau_n + \tau_{n+1})^5) + 2\alpha_n h'(u(t_n)) v_n(t_n)^2 - 2 \int h(u) (v_n')^2 \\ &= o((\tau_n + \tau_{n+1})^4) - 2 \int h(u) (v_n')^2 \end{split}$$

taking into account that $v_n(t_n) = \sin \tau_n \sin \tau_{n+1}$ and $\lim \alpha_n = 0$. We recall that $h(u(s)) \sim h'(a)u'(0+)s$ as s goes to zero; hence

$$o((\tau_n + \tau_{n+1})^4) \ge \int h(u)(v_n')^2 \sim h'(a)u'(0+) t_n \int_{t_{n+1}}^{t_{n-1}} (v_n')^2$$
$$\sim h'(a)u'(0+) t_n \tau_n \tau_{n+1} (\tau_n + \tau_{n+1})$$

Since h'(a) > 0, we conclude that u'(0+) < 0, and therefore u is not minimal at 0, a contradiction.

5. POLYGONAL FUNCTIONS AND SYMMETRY We will now prove the following result:

Theorem 7 Among all functions whose minimal sets N_0 are polygons, only the regular ones centered in Ω (i.e. N_0 is a regular polygon with center 0) are stable critical points for the functional F.

We shall say that a function $u: S^1 \to \mathbb{R}$ is polygonal of order $m \ (m \ge 1 \text{ integer})$ if it satisfies:

$$u + u'' = \sum_{k=1}^{m} \alpha_k \delta_{s_k} \tag{5.1}$$

in the distributional sense, for some numbers $\alpha_k > 0$, and different $s_k \in S^1$ (δ_{s_k} is the Dirac measure at s_k). In the following, the numbers s_k are assumed to be ordered in S^1 , for instance $-\pi \leq s_1 < s_2 < \cdots < s_m < \pi$. It is convenient to uses indices modulo m, so that for instance $s_0 := s_m$, and $s_{m+1} := s_1$.

Equation (5.1) implies the compatibility condition

$$\sum_{k=1}^{m} \alpha_k e^{is_k} = 0. ag{5.2}$$

This can be proved by integrating u + u'' against cosine or sine functions. Note that, since u is continuous and satisfies (5.1), we have

$$u_k(s_k) = u_{k-1}(s_k)$$
 and $u'_k(s_k) = \alpha_k + u_{k-1}(s_k)$. (5.3)

We then have:

$$2F(u) = \sum_{k=1}^{m} \alpha_k \Psi(u(s_k)) + \sum_{k=1}^{m} \int_{s_k}^{s_{k+1}} \Phi_M(u_k(s)) ds,$$

where
$$\Phi_M(x) := M \Phi\left(\frac{1-x}{M}\right) = \Psi(x) - x$$
.

The proof of Theorem 7 is given in the rest of the paper. Note that the case m=2 can be easily achieved right now. This corresponds to a line segment for N_0 ; by Corollary 5 it is centered in Ω as claimed. The corresponding function u has the form $u(s) = \mu |\cos(s - s_1)|$ for some $s_1 \in S^1$.

5.1 Alternative parameters

We give some alternative sets of parameters that are useful for new expressions of the functional. Each function u_k satisfies $u_k + u_k'' = 0$ in (s_k, s_{k+1}) . Hence we can express it in the form

$$u_k(s) = \mu_k \cos(s - \theta_k)$$

with $\mu_k \geq 0$ and $\theta_k \in (s_k - \pi, s_k + \pi]$. Let us define $a_k := \theta_k - s_k$ and $b_k := s_{k+1} - \theta_k$. We have by assumption

$$0 < \alpha_k = u_k'(s_k) - u_{k-1}'(s_k) = \mu_k \sin a_k + \mu_{k-1} \sin b_{k-1}$$

$$(5.4)$$

For the value of the functional we get:

$$2F(u) = \sum_{k=1}^{m} (\mu_k \sin a_k + \mu_{k-1} \sin b_{k-1}) \Psi(u(s_k)) + \sum_{k=1}^{m} \int_{-a_k}^{b_k} \Phi_M(\mu_k \cos t) dt$$

$$= \sum_{k=1}^{m} \mu_k \sin a_k \Psi(u(s_k)) + \sum_{k=1}^{m} \mu_k \sin b_k \Psi(u(s_{k+1})) + \sum_{k=1}^{m} \int_{-a_k}^{b_k} \Phi_M(\mu_k \cos t) dt.$$

From their definitions we have

$$u_k(s_k) = \mu_k \cos a_k = u_{k-1}(s_k) = \mu_{k-1} \cos b_{k-1} \tag{5.5}$$

hence

$$2F(u) = 2\pi + \sum_{k=1}^{m} K(\mu_k, a_k) + K(\mu_k, b_k)$$
(5.6)

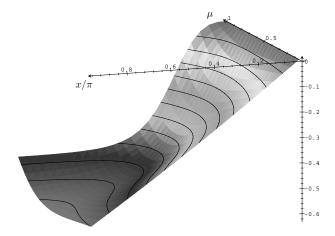


Figure 3: Value of $K(x, \mu)$, for M = 1/2.

where (recall that $\Phi_M(x) = \Psi(x) - x$):

$$K(\mu, x) := \mu \sin x \left(\Psi(\mu \cos x) - 1 \right) + \int_0^x \Psi(\mu \cos t) dt - x.$$

$$= \mu \sin x \ \Psi_1(\mu \cos x) + \int_0^x \Psi_1(\mu \cos t) dt$$
(5.7)

where we used the shortcut notation $\Psi_1 := \Psi - 1$. The additional term -x is permitted since we add 2π in F and take into account that $2\pi = \sum (s_{k+1} - s_k)$, that is

$$2\pi = \sum_{k=1}^{m} b_k + a_k. \tag{5.8}$$

The previous expression can be used to compute the value of the functional, since the integral can be expressed analytically with respect to M, μ , and x, through a complicated expression given in the Appendix. Figure 3 pictures this function for M=1/2; for other values, the picture is similar.

5.2 Bounds on the s_k

While the formulation of the function u above in terms of the functions u_k allows a relative freedom in choosing the values of s_k , there are limits to this freedom. This is the content of the next Lemma.

Lemma 8 Let u be an admissible polygonal function, described by (5.1). For every k, $s_k - s_{k-1} \le \pi$. If $s_k - s_{k-1} = \pi$ for some k, then m = 2, and N_0 is a segment.

Proof. Suppose that $m \geq 2$, and that $s_1 - s_0 > \pi$, so that $(s_0 + 2\pi) - s_1 < \pi$. The operator Au = -u - u'' satisfies the maximum principle on intervals of length less than π . Considering the interval $[s_1, s_0 + 2\pi]$, we note that u_1 solves $Au_1 = 0$, and u satisfies $Au \leq 0$, and the two are equal on the boundary. It follows that $u_1 \geq u$, and therefore $u'(s_1 -) = u'_1(s_1) \geq u'(s_1 +)$, with a strict inequality if $u \not\equiv u_1$. This contradicts the positivity of u + u''.

We might note that one could also use a geometrical argument: the section (s_{k-1}, s_k) corresponds to a vertex of the polygon N_0 (see Figure 2). The values of s_{k-1} and s_k correspond to the directions of the sides of the polygon on either side of the vertex, and the corner formed by the two sides has an internal angle of $\pi - (s_k - s_{k-1})$. If $s_k - s_{k-1} > \pi$, then this angle is negative, and therefore u does not correspond to a well-formed set N_0 .

If $s_1 - s_0 = \pi$, then $u(s_1) = u(s_0) = 0$. Applying a similar argument to the interval $[s_0 + 2\pi, s_1]$, we find that $u = \mu' \sin(s - s_1)$ on $[s_0 + 2\pi, s_1]$ for some $\mu' \in \mathbb{R}$. It follows that m = 2 and that N_0 is a segment.

5.3 Derivative jumps are symmetric

From now on, we assume that u is a minimizer of F.

Lemma 9 Suppose that $m \geq 3$. Then for each k we have

$$u'(s_k+) = -u'(s_k-).$$

Proof. We prove the result for k=1. In order to shorten notation, we write $z_k:=u(s_k)$, and $y_1^+:=u_1'(s_1)=u'(s_1+),\ y_1^-:=u_0'(s_1)=u'(s_1-)$. Note that since $m\geq 3$, by the previous Lemma, $s_2-s_1<\pi$ and $s_1-s_0<\pi$.

Let $\varepsilon \neq 0$ be given. We define $d_{\varepsilon} := (u_1(s_1 + \varepsilon) - u_0(s_1 + \varepsilon))/\varepsilon$ and $d_0 := (y_1^+ - y_1^-)$; one easily checks that $d_{\varepsilon} = d_0 + o(1)$ for small ε since $u_1(s_1) = z_1 = u_0(s_1)$.

Let us consider the function v_0 such that $v_0 + v_0'' = 0$, $v_0(s_2) = 0$ and $v_0(s_1) = d_0$. For $\varepsilon \neq 0$ we also define v_{ε} by $v_{\varepsilon} + v_{\varepsilon}'' = 0$, $v_{\varepsilon}(s_2) = 0$ and $v_{\varepsilon}(s_1 + \varepsilon) = d_{\varepsilon}$. Here again, we see that $v_{\varepsilon} \equiv v_0 + o(1)$ for ε small enough.

We consider the function u^{ε} defined as follows:

$$u^{\varepsilon}(s) = \begin{cases} u_0(s) & \text{if } s \in (s_0, s_1 + \varepsilon) \\ u_1(s) - \varepsilon v_{\varepsilon}(s) & \text{if } s \in (s_1 + \varepsilon, s_2) \\ u(s) & \text{otherwise.} \end{cases}$$

(Observe that u^{ε} is continuous by the definition of v_{ε} .) We note that u^{ε} is admissible for any small enough ε . Hence $F(u^{\varepsilon}) \geq F(u)$ since u is a minimizer. We note that by (2.4)

$$2F(u^{\varepsilon}) = \int_{s_0}^{s_1+\varepsilon} (\Psi - id)(u_0) + \int_{s_1+\varepsilon}^{s_2} (\Psi - id)(u_1 - \varepsilon v_{\varepsilon}) + \int_{s_2+0}^{s_0+2\pi} [\Psi(u)(1 + u + u'') - u] + \\ + \Psi(u^{\varepsilon}(s_1 + \varepsilon)) [u'_1(s_1 + \varepsilon) - \varepsilon v'_{\varepsilon}(s_1 + \varepsilon) - u'_0(s_1 + \varepsilon)] + \\ + \Psi(u(s_2)) [u'_2(s_2) - u'_1(s_2) + \varepsilon v'_{\varepsilon}(s_2)].$$

We recall that $u_0(s_1) = z_1 = u_1(s_1)$; hence $\int_{s_1}^{s_1+\varepsilon} \Psi(u_0) - \Psi(u_1) = o(\varepsilon)$. Moreover, since $u_i + u_i'' = 0$, we have $u_1'(s_1 + \varepsilon) - u_0'(s_1 + \varepsilon) = y_1^+ - y_1^- + O(\varepsilon^2)$. We also have:

$$\Psi(u^{\varepsilon}(s_1+\varepsilon)) = \Psi(u_0(s_1+\varepsilon)) = \Psi(z_1) + \varepsilon \Psi'(z_1) y_1^- + o(\varepsilon).$$

This yields

$$0 \le F(u^{\varepsilon}) - F(u)$$

$$\le o(\varepsilon) - \varepsilon \int_{s_1}^{s_2} [\Psi'(u_1) - 1] v_0 + \varepsilon \Psi'(z_1) y_1^- (y_1^+ - y_1^-) - \varepsilon \Psi(z_1) v_0'(s_1) + \varepsilon \Psi(z_2) v_0'(s_2).$$

Since this holds for any ε small enough (positive or negative), we get

$$\Psi'(z_1)y_1^-(y_1^- - y_1^+) = \int_{s_1}^{s_2} [\Psi'(u_1) - 1]v_0 - \Psi(z_1)v_0'(s_1) + \Psi(z_2)v_0'(s_2).$$
 (5.9)

We briefly consider the possibility that $\Psi'(z_1) = 0$. The integral in (5.9) is negative, so that we then find

$$-\Psi(z_1)v_0'(s_1) + \Psi(z_2)v_0'(s_2) > 0.$$

A simple argument using the concaveness of v_0 and the monotonicity of Ψ shows that this inequality is not satisfied. This proves the Lemma if $\Psi'(z_1) = 0$.

We continue with the case $\Psi'(z_1) > 0$, and consider the variation which is analogous to the one above, but with s_2 replaced by s_0 . Beginning with the function w_0 such that $w_0 + w_0'' = 0$, $w_0(s_0) = 0$, $w_0(s_1) = d_0$, and operating exactly the same way in the interval (s_0, s_1) we get similarly:

$$\Psi'(z_1)y_1^+(y_1^- - y_1^+) = \int_{s_1}^{s_0} [\Psi'(u_0) - 1]w_0 - \Psi(z_1)w_0'(s_1) + \Psi(z_0)w_0'(s_0).$$
(5.10)

Finally let us consider the function

$$\tilde{u}(s) := \begin{cases} u_0 - \varepsilon w_0(s) & \text{if } s \in (s_0, s_1) \\ u_1 - \varepsilon v_0(s) & \text{if } s \in (s_1, s_2) \\ u(s) & \text{otherwise.} \end{cases}$$

Here we also have an admissible function, since $v_0(z_1) = w_0(z_1)$. Applying a first order variation argument again, we find that the right hand side of (5.9) and (5.10) are just opposite. This yields

$$\Psi'(z_1)[(y_1^+)^2 - (y_1^-)^2] = 0.$$

Since $y_1^- \neq y_1^+$ by assumption (u' is not continuous at s_1), and $\Psi'(z_1) > 0$, the proof is complete. \square

5.4 Proof of Theorem 7

From Lemma 9 we have for each k, $\mu_k \sin a_k = \mu_{k-1} \sin b_{k-1}$. Combining with (5.5) we get

$$\mu_k = \mu_{k-1} \qquad \text{and} \qquad a_k = b_{k-1}$$

in that case. Hence the functional can be expressed with respect to the unique parameter μ (the common value of all μ_k) and to the a_k , subject to the condition

$$\sum_{k=1}^{m} a_k = \pi.$$

The derivative jump at s_k is given by $\mu_k \sin a_k + \mu_{k-1} \sin b_{k-1} = 2\mu \sin a_k$, and the convexity condition $u + u'' \ge 0$ therefore implies that $a_k \in [0, \pi]$. The functional itself is just $\sum K(\mu, a_k)$, hence for the minimizer there exists a Lagrange multiplier γ such that

$$\frac{\partial F}{\partial a_k} = K_x'(\mu, a_k) = \gamma \tag{5.11}$$

for all k. On the other hand we have from (5.7):

$$K_x'(\mu, x) = (1 + \mu \cos x)\Psi_1(\mu \cos x) - \mu^2 \sin^2 x \Psi'(\mu \cos x)$$
(5.12)

We now have to prove that all a_k are equal. We first prove an intermediate result:

$$K'_{r}(\mu, a_{k}) = \gamma < K'_{r}(\mu, 0).$$
 (5.13)

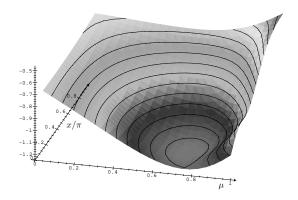


Figure 4: Value of $(m-1)K(\mu, x) + K(\mu, \pi - x(m-1))$ for M = 1/2, m = 4.

Indeed, consider a small number $\varepsilon > 0$, and a function u^{ε} characterized by (m+1) sides with parameters $a_k^{\varepsilon} = b_{k-1}^{\varepsilon} = a_k + \delta a_k$, for $k = 1, \ldots, m$, and $a_{m+1}^{\varepsilon} = b_m^{\varepsilon} = \varepsilon$; $\mu_k^{\varepsilon} = \mu$ for $k = 1, \ldots, (m+1)$. This function satisfies the constraints if we assume that $\sum \delta a_k = -\varepsilon$. We then have

$$F(u^{\varepsilon}) - F(u) = \sum_{k=1}^{m} [K(\mu, a_k^{\varepsilon}) - K(\mu, a_k)] + K(\mu, \varepsilon)$$
$$= \sum_{k=1}^{m} K'_x(\mu, a_k) \, \delta a_k + \varepsilon K'(\mu, 0) + o(\varepsilon).$$

We already know from (5.11) that $K'_x(\mu, a_k) = \gamma$ for all k. Since we have $F(u^{\varepsilon}) \geq F(u)$ for all $\varepsilon > 0$, we get (5.13).

The function $x \mapsto K'_x(\mu, x)$ is explicitly given by (5.12). We can normalize the function K by subtracting $xK'_x(\mu, 0)$: note that this adds a constant to F, so that this does not change the nature of the problem; for this normalized function, still noted K, we have $K'_x(\mu, 0) = 0$. From (5.13), the only values of interest in the following are those such that $K'_x \leq 0$; this corresponds to an interval $[0, \bar{x}]$. One can easily check the following properties: if μ is small, then K'_x is an increasing function on $(0, \pi]$; if μ is larger than a critical value (depending on M), then on $(0, \pi]$ this function is strictly decreasing, then increasing. (This last property is proved in Appendix B.)

From (5.13) we see that μ must be larger than the critical value indicated before. In that case, the function $K'_x(\mu, \cdot)$ attains a strict minimum $x_0 \in (0, \pi)$ and the equation $K'_x(\mu, x) = \gamma_1 \leq K'_x(\mu, 0)$ has two solutions x_1, x_2 satisfying

$$0 \le x_1 < x_0 < x_2 < \pi$$
 and $K_{xx}''(\mu, x_1) < 0 < K_{xx}''(\mu, x_2)$ (5.14)

(except in the special case $K'_x(\mu, x) = K'_x(\mu, x_0)$). That gives two potential values for the a_k .

It easy to check that at most one a_k can be equal to x_1 . Indeed, we just have to consider a small variation in the form $\tilde{a}_1 = a_1 + \varepsilon$, $\tilde{a}_2 = a_2 - \varepsilon$, and we find $K''_{xx}(\mu, a_1) + K''_{xx}(\mu, a_2) \ge 0$ for a minimizer.

Hence we have to choose between two possibilities: either all a_k are equal to π/m (regular polygon), or all of them except one are equal (say to a number $x = x_2$), and the other one $(x_1 = \pi - (m-1)x)$ is different; x_1 and x_2 satisfy (5.14) and $K'_x(\mu, x_1) = K'_x(\mu, x_2)$. We can catch both possibilities by minimizing

$$G(\mu, m, x) := (m-1)K(\mu, x) + K(\mu, \pi - (m-1)x)$$

with respect to $\mu \in (0,1)$, $m \in \mathbb{N}$, and $x \in I_m$ given later. If the minimum satisfies $x = \pi/m$, then all a_k are equal; alternatively, if $x \neq \pi/m$, then the a_k are different.

The set I_m of admissible values of x is given by $I_m = [\pi/m, \pi/(m-1))$. This results from the following argument. Clearly $\pi/m \in I_m$; we do not need to take into account values $x < \pi/m$, since by (5.14) $x_1 = \pi - (m-1)x \le x_2 = x$; and $x \ge \pi/(m-1)$ corresponds to $x_1 \le 0$, which is also excluded, as mentioned above. Moreover we can restrict, from (5.14), to those values of (μ, m, x) such that $K''_{xx}(\mu, x) > 0$. Since K''_{xx} vanishes at most once in $(0, \pi)$ (cf. Appendix B), it is positive at least at one end of I_m . That is either

$$K_{xx}''(\mu, \pi/m) > 0$$

or $K_{xx}''(\mu, \pi/m) \le 0$ and $K_{xx}''(\mu, \pi/(m-1)) > 0$. (5.15)

The function G is pictured for M = 1/2, m = 4, in Figure 4; there is a clear minimum in this case with $x = \pi/4$, corresponding to a regular polygon for N_0 . Notice that G is not convex with respect to x (though we already know that it is convex with respect to μ).

If (μ, m, x) minimizes G, then x also minimizes the restricted function $x \mapsto G(\mu, m, x)$ for these specific values of μ and m. With this remark in mind we fix μ and m for the remainder of the proof, still assuming (5.15).

We will use the following lemma:

Lemma 10 Let $m \ge 2$ be an integer. The equation $G'_x(\mu, m, x) = 0$ has at most two solutions for x in the interval $I_m = \left[\frac{\pi}{m}, \frac{\pi}{m-1}\right]$. Moreover, if (5.15) holds with $K''_{xx}(\mu, \pi/m) \le 0$, this equation has only one solution.

The proof of the lemma relies heavily on an analytic expression of G'_x ; it is given in Appendix B. We continue here with the proof of the theorem.

One of the solutions is $x = \pi/m$; if $K''_{xx}(\mu, \pi/m) \le 0$, then it is the only one from the lemma, but it is not a minimizer: this is a contradiction since we assumed the opposite about (m, μ) .

Let us now assume that $K''_{xx}(\mu, \pi/m) > 0$. Then G attains a strict local minimum at $x = \pi/m$. Therefore, if G'_x vanishes only once in I_m , then G is increasing on I_m , and the Theorem is proved.

Alternatively, if G'_x vanishes at some other point $x' \in I_m$ ($x' \neq \pi/m$), we deduce that $G''_{xx}(\mu, m, x') \leq 0$ since G is an analytic function of x. Hence x' is a local maximum of G (or possibly an inflexion point if $G''_{xx} = 0$). So in any case, G does not have any other minimum in the interior of I_m .

This ends the proof of Theorem 7.

APPENDIX: ANALYTIC EXPRESSION OF THE FUNCTIONAL

We give here some indication on the way to compute explicitly the integral in K, or more precisely:

$$I(M,\mu,x) := -M^{-2} \int_0^x \Psi_1(\mu \cos t) dt = \int_0^x \frac{(1-\mu \cos t)}{M^2 + (1-\mu \cos t)^2} dt$$

Even with Maple, this does not come straightforwardly since the integrand is quite complicated. Anyway, one can see that it depends only on $2\cos t = e^{it} + e^{-it}$. So we can look for a primitive function in the form $J(e^{ix})$. We then have

$$izJ'(z) = 2z \frac{2z - \mu(1+z^2)}{4z^2M^2 + (2z - \mu(1+z^2))^2}.$$

Since the roots of the denominator can be expressed easily, we can find J. The more complicated part is to go back to a real function. At the end, we get

$$I = c_l \arctan\left(\frac{\sin x \cos \alpha}{\cos x - \sin \alpha \cos \beta}\right) + c_r \log\left(\frac{1 - \sin \alpha \cos(\beta - x)}{1 - \sin \alpha \cos(\beta + x)}\right)$$

where

$$c_l := \frac{\cos \alpha \cos^2 \beta}{\cos^2 \alpha + \sin^2 \alpha \sin^2 \beta}$$
 and $c_r := \frac{1}{4} \frac{\sin 2\beta}{\cos^2 \alpha + \sin^2 \alpha \sin^2 \beta}$

and the parameters α , β are linked to M, μ by the relations

$$\begin{split} \sqrt{2}\cos\alpha &= \sqrt{1-M^2-\mu^2+\nu} & \sqrt{2}\sin\alpha &= \sqrt{M^2+\mu^2+1-\nu} \\ \sqrt{2}\,\mu\cos\beta &= \sqrt{M^2+\mu^2+1-\nu} & \sqrt{2}\,\mu\sin\beta &= \sqrt{\mu^2-M^2-1+\nu} \\ \text{with } \nu &:= \sqrt{(1+M^2)^2-2\mu^2+2\mu^2M^2+\mu^4}. \end{split}$$

APPENDIX B. PROOF OF LEMMA 10

From formula (5.12), K'_x depends on x only by the value of $\cos x$. More precisely, we have $K'_x(\mu, x) = Q(\cos x) + \text{constant}$ (the constant was introduced by the normalization) where

$$Q(z) := \frac{2\mu^2 z^2 M^4 - \mu^2 M^4 + M^2 (1 - \mu z)^2 (1 + \mu^2) + (1 - \mu z)^4}{(M^2 + (1 - \mu z)^2)^2}.$$

With this notation, the derivative of G is

$$G'_x(m,x) = (m-1)[Q(\cos x) - Q(-\cos(m-1)x)].$$

Let us first assume that m=2. Then $G_x'(2,x)=0$ for $x\neq\pi/2$ implies Q(z)=Q(-z) for some $z\in(0,1]$. Let us prove that in fact Q(z)< Q(-z) for all $z\in(0,1]$. From the previous expression of Q, we get $Q(z)-Q(-z)=-z\mu M^2P(z^2)/[D(z)D(-z)]$ where D(z) is the (positive) denominator in the expression of Q, and

$$\begin{split} P(Z) := & \ (\mu^4 - 4\mu^4 M^2 - \mu^6) Z^2 + \\ & + (-2\mu^2 - 4\mu^2 M^4 + 2\mu^4 M^2 + 2\mu^4 - 2\mu^2 M^2) Z + \\ & + 2M^2 + 1 + 3\mu^2 M^4 + 2\mu^2 M^2 + M^4 - \mu^2. \end{split}$$

So we have to prove that P(Z) > 0 for all $Z \in [0,1]$. Note that this inequality holds at 0 and 1:

$$P(0) = 2M^{2} + 3\mu^{2}M^{4} + 2\mu^{2}M^{2} + M^{4} + 1 - \mu^{2} > 0$$

$$P(1) = (1 - \mu^{2})M^{4} + 2M^{2}(1 - \mu^{4}) + (1 - \mu^{2})^{3} > 0.$$

The derivative of P vanishes at $Z_m = A/B$ where

$$A := 2M^4 + (1 - \mu^2)(1 + M^2) > 0$$

(recall that $\mu \in (0,1)$) and

$$B := -u^2(-1 + 4M^2 + u^2).$$

We observe that

$$A - B = 2M^4 + 3\mu^2 M^2 + M^2 + 1 - 2\mu^2 + \mu^4 > 0$$

hence either B < 0 and $Z_m < 0$, or B > 0 and $Z_m > 1$ since A > B; in either case, P does not have a local extremum in [0,1]. It follows that that P > 0 in [0,1], and this proves the lemma for m = 2.

Let us now assume that $m \geq 3$, hence $\cos(m-1)x \leq 0$ in I_m . Here $G'_x(m,x) = 0$ with $x \neq \pi/m$, $x \in I_m$, is equivalent to the existence of a solution of $Q(z_1) = Q(z_2)$, with z_1 and z_2 in [0,1], $z_1 \neq z_2$. We will prove here that in [0,1], either Q is monotonic or Q' has only one root. In the first case, $Q(z_1) = Q(z_2)$ implies $z_1 = z_2$. In the second case, if a solution $x \neq \pi/m$ of $G'_x = 0$ exists, it is unique since the functions $\cos x$ and $\cos(m-1)x$ are monotonic in I_m . This will prove the first assertion of the lemma.

So we have to count the number of zeroes of Q' in [0,1]. We have

$$Q'(z) = \frac{2\mu M^2 N(z)}{(M^2 + (1 - \mu z)^2)^3}$$

with

$$N(z) := (-\mu^5 + \mu^3 - 2\mu^3 M^2) z^3 + (3\mu^4 - 3\mu^2) z^2 + (3\mu^3 M^2 - 3\mu^3 + 3\mu + 3\mu M^2 + 2\mu M^4) z + \mu^2 - 3\mu^2 M^2 - 1 - M^2.$$

We only have to count the zeroes of N in [0,1]. We will use the Theorem of Fourier and Budan [1, page 173], an improved version of the Dirichlet criterion, which asserts that the number of zeroes of the polynomial N in [0,1] cannot exceed $|\nu(0) - \nu(1)|$, where $\nu(z)$ is the number of changes of signs in the list $\ell(z) := [N(z), N'(z), N''(z), N'''(z)]$.

Now we have

$$\begin{split} \ell(0) = [\mu^2 - 1 - 3\mu^2 M^2 - M^2 \;, \quad 3\mu(\mu^2 M^2 + 1 - \mu^2 + M^2) + 2\mu M^4 \;, \\ 6\mu^2(\mu^2 - 1) \;, \quad 6\mu^3(1 - \mu^2 - 2M^2)]. \end{split}$$

We recall that $\mu \in (0,1)$, so the signs in this list are $[-,+,-,\sigma_0]$ where σ_0 is the sign of $1-\mu^2-2M^2$. Next we have

$$N'(1) = \mu \left[3M^2(1 - \mu^2) + 2M^4 + 3(\mu + 1)(1 - \mu)^3 \right] > 0,$$

also

$$N''(1) = 6\mu^{2} \left[-2\mu M^{2} - (\mu + 1)(\mu - 1)^{2} \right] < 0,$$

and obviously N'''(1) = N'''(0). The signs in the list $\ell(1)$ are $[\sigma_1, +, -, \sigma_0]$ where σ_1 is the sign of N(1). We see that $\nu(0) = \nu(1)$ if $\sigma_1 < 0$, and $\nu(0) = 1 + \nu(1)$ if $\sigma_1 > 0$. We get $|\nu(0) - \nu(1)| \le 1$; this ends the proof of the first assertion of the lemma.

We now turn to the second assertion, assuming that Q is not monotonic (otherwise there is nothing to prove), and assuming (5.15) with $K''_{xx}(\mu, \pi/m) \leq 0$, or equivalently $\pi/m \leq x_0 < \pi/(m-1)$ (we recall that x_0 is the root of K''_{xx} ; we have $z_0 = \cos x_0$, where z_0 satisfies $N(z_0) = 0$). Notice that, from our previous study, we must have N(1) > 0 in order to have a root for N in (0, 1], that is

$$M^2 \ge M_1^2 := \frac{(1-\mu)^2(1+\mu)}{2\mu}.\tag{5.16}$$

Moreover, Q is decreasing in $[0, z_0]$ and increasing in $[z_0, 1]$.

We will prove later on that

$$\forall h \in (0, z_0], \qquad Q(z_0 + h) > Q(z_0 - h). \tag{5.17}$$

Let us explain first how we can deduce the second assertion of the lemma from this. Let $x \in (\pi/m, \pi/(m-1))$ be given, and $x' := \pi - (m-1)x < \pi/m \le x_0$. If $x \le x_0$, then $\cos x' > \cos \frac{\pi}{m} > \cos x \ge z_0$ and therefore $Q(\cos x) < Q(\cos x')$ since Q is increasing in $[z_0, 1]$. This implies $K'_x(\mu, x) \ne 0$.

Let us now assume that $x > x_0$. Since $m \ge 3$ we have

$$1 + \cos\frac{\pi}{m-1} \ge 2\cos\frac{\pi}{m}.\tag{5.18}$$

(Indeed equality occurs for m = 3, and for $m \ge 4$ we have

$$1 + \cos\frac{\pi}{m-1} - 2\cos\frac{\pi}{m} > 1 + \left(1 - \frac{\pi^2}{2(m-1)^2}\right) - 2\left(1 - \frac{\pi^2}{2m^2} + \frac{\pi^4}{24m^4}\right)$$
$$= \frac{\pi^2}{2m^2} \left(2 - \frac{m^2}{(m-1)^2} - \frac{\pi^2}{6m^2}\right) \ge 0.$$

Now (5.18) implies

$$\cos x + \cos x' = \cos x - \cos(m-1)x > 2\cos\frac{\pi}{m} \ge 2z_0;$$

this follows from remarking that the map $y\mapsto\cos y-\cos(m-1)y-2\cos\frac{\pi}{m}$ is concave in I_m (the second-order derivative is negative), vanishes at $y=\pi/m$, and attains the nonnegative value $1+\cos\frac{\pi}{m-1}-2\cos\frac{\pi}{m}$ at $y=\pi/(m-1)$. Therefore, if we write $\cos x$ in the form z_0-h ($h\in(0,z_0]$), we have $\cos x'>z_0+h$, hence $Q(\cos x')>Q(z_0+h)>Q(z_0-h)=Q(\cos x)$ using (5.17). This proves that $K'(\mu,x)\neq 0$ as claimed in the lemma.

We finally need to prove (5.17). A computation of $\delta Q := Q(z_0 + h) - Q(z_0 - h)$ gives a complicated formula for a general z_0 . But since z_0 satisfies $Q'(z_0) = 0$, we have $\delta Q \in O(h^3)$ for small h. An exact computation gives the formula

$$\delta Q := 4M^2 \mu^3 h^3 \frac{\mu^2 A h^2 + 4M^2 B}{D(z_0 + h)D(z_0 - h)}$$

where

$$A := \mu z_0 - \mu^3 z_0 - 2M^2 \mu z_0 + 4M^2 - 1 + \mu^2$$

$$B := -2\mu^2 z_0^2 + M^2 \mu z_0 + 2\mu^3 z_0 + M^2 + 2\mu z_0 - 2\mu^2.$$

Hence it is sufficient to prove that A > 0, B > 0 for all (M, μ) such that $\mu \in (0, 1)$ and M satisfies (5.16); here z_0 is implicitly determined with respect to (μ, M) by the equation $N(z_0) = 0$, that is:

$$\begin{split} 0 &= (\mu^3 - 2M^2\mu^3 - \mu^5)z_0^3 + (-3\mu^2 + 3\mu^4)z_0^2 + \\ &\quad + (3\mu + 3\mu M^2 + 3M^2\mu^3 - 3\mu^3 + 2\mu M^4)z_0 - 3M^2\mu^2 - 1 + \mu^2 - M^2. \end{split}$$

It is sufficient to prove that $A.B \neq 0$ for all values of (μ, M) , since one can easily check that A > 0, B > 0 for some of these values: for instance, as $\mu \to 1$, we have $z_0 \to 1$, and then $A \to 2M^2 > 0$, $B \to 2M^2$.

In order to take into account (5.16), we write M^2 in the form M_1^2/t , hence $t \in (0,1]$. Then we have $A.B = (1 - \mu)(1 - \mu^2)C$ with (we write z instead of z_0 from now on):

$$C := (-\mu^5 - 5\mu^5t - 4\mu^5t^2 + \mu^3 - 4\mu^4t^2 - 11\mu^3t + \mu^4 - \mu^2)z^2 + (8\mu^3t^2 + 18\mu^4t - 3\mu^2 + 3\mu^4 + 3\mu + 8\mu^4t^2 - 3\mu^3 + 14\mu^2t)z + 2\mu^3 - 4\mu^3t^2 - 4\mu^2t^2 - 2\mu - 2\mu^2 + 2 - 13\mu^3t - 3\mu t$$

Since z is a root of N, we also have

$$0 = 2u(uz - 1)^{3}t^{2} + (u - 1)(uz - 1)(2u^{2}z^{2} + 2uz - 3u^{2} - 1)t - (u + 1)(u - 1)^{3}z.$$

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This is an equation of degree 2 in t. Substituting t=0 gives the value $(\mu+1)(1-\mu)^3z \ge 0$, and $t=(1-\mu)/(1-\mu z)$ gives the value $(\mu-1)^2(z-1)(2\mu^2z+1+2\mu+3\mu^2)\le 0$, hence there is always a root in $[0,\frac{1-\mu}{1-\mu z}]$, the other one being negative. This root can be expressed as follows:

$$t_1 := (1 - \mu) \frac{2\mu^2 z^2 + 2\mu z - 3\mu^2 - 1 + r}{4\mu(\mu z - 1)^2}$$

where $r := \sqrt{4\mu^4 z^4 + 8\mu^3 z^3 - 4\mu^4 z^2 - 20\mu^3 z + 4\mu z + 9\mu^4 + 6\mu^2 + 1 - 8\mu^2 z^2}$. Substituting $t = t_1$ in C, we get $4C = (\alpha r + \beta)(1 - \mu)/(1 - \mu z)^2$ with

$$\begin{split} \alpha := 22 \mu^3 z - 9 \mu^2 - 15 \mu^2 z^2 - \mu^4 z^2 + 10 \mu z - 6 \mu^4 - 1 \\ \beta := 2 \mu^6 z^4 - \mu^6 z^2 + 18 \mu^6 + 22 \mu^5 z^3 - 86 \mu^5 z + 76 \mu^4 z^2 + 33 \mu^4 - 34 \mu^4 z^4 + \\ + 10 \mu^3 z^3 - 50 \mu^3 z + 4 \mu^2 + 21 \mu^2 z^2 - 24 \mu z + 9. \end{split}$$

Hence C = 0 implies $\alpha^2 r^2 - \beta^2 = 0$, which is a polynomial expression in (μ, z) of the form $0 = 16(1 - \mu^2)(1 - \mu z)^2 p_1 p_2$ where

$$\begin{split} p_1 := 4\mu^2 z^2 + 5 - 11\mu z + 3\mu^2 - \mu^3 z \\ p_2 := 4\mu^4 z^4 - 3\mu^5 z^3 - \mu^3 z^3 + 3\mu^4 z^2 + \mu^2 z^2 - 2\mu^5 z - 9\mu^3 z - \mu z + 6\mu^4 + \mu^2 + 1. \end{split}$$

If we define $y := \mu z$, we have $y \in [0, 1)$, and

$$p_2 = (6 - 2y)\mu^4 + (-3y^3 + 1 + 3y^2 - 9y)\mu^2 + 4y^4 - y^3 - y + y^2 + 1.$$

The discriminant of this polynomial with respect to μ^2 is $(9y + 23)(y + 1)^2(y - 1)^3 < 0$, so $p_2 \neq 0$. Similarly we have $p_1 = (3 - y)\mu^2 + 4y^2 + 5 - 11y$, hence $p_1 = 0$ implies $\mu^2 = (4y^2 + 5 - 11y)/(y - 3)$. Then we get $\mu^2 - y^2 = (5 - y)(y - 1)^2/(y - 3) < 0$ which is a contradiction since $y^2 = \mu^2 z^2 \leq \mu^2$.

This ends the proof of the lemma.

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