Twisted cohomology and likelihood ideals

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Abstract

A likelihood function on a smooth very affine variety gives rise to a twisted de Rham complex. We show how its top cohomology vector space degenerates to the coordinate ring of the critical points defined by the likelihood equations. We obtain a basis for cohomology from a basis of this coordinate ring. We investigate the dual picture, where twisted cycles correspond to critical points. We show how to expand a twisted cocycle in terms of a basis, and apply our methods to Feynman integrals from physics.

1 Introduction

Very affine varieties are closed subvarieties of an algebraic torus. They have applications in algebraic statistics [13] and particle physics [20]. We study smooth such varieties given by hypersurface complements in the algebraic torus. Fix ℓ Laurent polynomials $f_1, \ldots, f_{\ell} \in \mathbb{C}[x_1^{\pm 1}, \ldots, x_n^{\pm 1}]$ in n variables. Localizing at the product $f_1 \cdots f_{\ell}$ gives the very affine variety

$$X = \{x \in (\mathbb{C}^*)^n : f_i(x) \neq 0, \text{ for all } i\} = (\mathbb{C}^*)^n \setminus V(f_1 \cdots f_\ell).$$
 (1)

In statistics and physics applications, the functions f_i arise from a likelihood function

$$L(x) = f^{-s} x^{\nu} = f_1^{-s_1} \cdots f_{\ell}^{-s_{\ell}} x_1^{\nu_1} \cdots x_n^{\nu_n}, \tag{2}$$

encountered as the integrand of a generalized Euler integral [1, 26]. These are Bayesian integrals in statistics, and Feynman integrals in physics. Outside these applications, generalized Euler integrals are interesting objects in their own right. They represent hypergeometric functions and solutions to GKZ systems [8, 17]. Computations with these integrals can be done in a twisted cohomology vector space $H^n(X,\omega)$ associated to X and L [1]. This paper establishes a crucial relation between $H^n(X,\omega)$ and an ideal in the coordinate ring of X, called the likelihood ideal. It makes computations in $H^n(X,\omega)$ explicit, by showing how to compute a basis and how to find coefficients in this basis.

We think of the exponents s, ν in (2) as complex parameters, so the likelihood L is multivalued. The logarithm of L is the *log-likelihood function*, whose derivatives are single valued and well-defined on X. The complex critical points of the log-likelihood function are the solutions of $\omega(x) = 0$, where ω is the one-form

$$\omega(x) = \operatorname{dlog} L(x) = -s_1 \operatorname{dlog} f_1 - \dots - s_\ell \operatorname{dlog} f_\ell + \frac{\nu_1 \operatorname{d} x_1}{x_1} + \dots + \frac{\nu_n \operatorname{d} x_n}{x_n}.$$

Expanding $\omega = g_1 dx_1 + \cdots + g_n dx_n$ in the basis dx_1, \ldots, dx_n gives n equations $g_1 = \cdots = g_n = 0$ on X. The g_i generate an ideal I in the coordinate ring $\mathcal{O}(X)$ of X, called the *likelihood ideal*. June Huh has showed that, for generic s, ν , the likelihood ideal defines $|\chi(X)|$ critical points, with $\chi(X)$ the *Euler characteristic* [13]. This means that $\dim_{\mathbb{C}} \mathcal{O}(X)/I = |\chi(X)|$.

The Euler characteristic also counts the dimension of the twisted cohomology $H^n(X, \omega)$ of X [1]. We briefly recall the definition. The form ω is regular on X, in the algebraic sense. We write $\omega \in \Omega^1(X)$. More generally, $\Omega^k(X)$ denotes the regular k-forms on X. Our vector space $H^n(X,\omega)$ is the n-th cohomology of the twisted de Rham complex $0 \to \Omega^0(X) \to \Omega^1(X) \to \cdots \to \Omega^n(X) \to 0$, where the differential is $d + \omega \wedge$. In symbols:

$$H^{n}(X, \omega) = \Omega^{n}(X) / (d + \omega \wedge)(\Omega^{n-1}(X)).$$

Using an identification $\Omega^n(X) \simeq \mathcal{O}(X)$, we can write this alternatively as $H^n(X,\omega) = \mathcal{O}(X)/V$, where $V \subset \mathcal{O}(X)$ is a vector space which is *not* an ideal. We will sometimes write $V(\omega)$ to emphasize the dependence of V on the twist ω .

Our first aim is to relate bases of the $|\chi(X)|$ -dimensional vector spaces $\mathcal{O}(X)/I$ and $\mathcal{O}(X)/V$, defined by the likelihood ideal I and the image V of the twisted differential. In the physics literature, a basis of $\mathcal{O}(X)/V$ (or, the corresponding set of Feynman integrals) is called a set of master integrals [12]. It is an important computational problem to find such a basis. Computing a basis for $\mathcal{O}(X)/I$ can be done by computing the critical points numerically, which is a task of numerical nonlinear algebra [1, Section 5]. For an element $g \in \mathcal{O}(X)$, let $[g]_I$ be its residue class in $\mathcal{O}(X)/I$, and $[g]_V$ its residue class in $\mathcal{O}(X)/V$.

Theorem 1.1. Let $(s, \nu) \in \mathbb{C}^{\ell+n}$ be generic complex parameters in the sense of Assumption 1 and let $\{[\beta_1]_I, \ldots, [\beta_\chi]_I\}$ be a basis for $\mathcal{O}(X)/I$. The set $\{[\beta_1]_{V(\omega/\delta)}, \ldots, [\beta_\chi]_{V(\omega/\delta)}\}$ is a basis for $H^n(X, \omega/\delta) = \mathcal{O}(X)/V(\omega/\delta)$, for almost all $\delta \in \mathbb{C} \setminus \{0\}$.

Under stronger assumptions (Remark 4.1) one can use $\delta = 1$ in this theorem. However, there are special choices of s, ν and $[\beta_i]_I$ for which this does not work, see Example 4.2.

We also prove an analog of Theorem 1.1 over the field $K = \mathbb{C}(s, \nu)$ of rational functions in s and ν . We use the notation X_K for our very affine variety, but now defined over K. The cohomology module of the twisted de Rham complex is the K-vector space $\mathcal{O}(X_K)/V_K = H^n(X_K, \omega)$. Here $V_K \subset \mathcal{O}(X_K)$ is the image of $d + \omega \wedge$ in our twisted de Rham complex $(\Omega^{\bullet}(X_K), d + \omega \wedge)$ over K. The likelihood ideal is here reinterpreted as an ideal I_K in $\mathcal{O}(X_K)$.

Theorem 1.2. The K-vector spaces $\mathcal{O}(X_K)/V_K$ and $\mathcal{O}(X_K)/I_K$ have dimension $|\chi(X)|$. If $\{\beta_1, \ldots, \beta_{\chi}\} \subset \mathcal{O}(X_K)$ represents a constant basis of $\mathcal{O}(X_K)/I_K$, in the sense of Definition 3, then $\{[\beta_1]_{V_K}, \ldots, [\beta_{\chi}]_{V_K}\}$ is a K-basis of $\mathcal{O}(X_K)/V_K$.

Next to finding bases of cohomology, we also address the following problem. Given a basis $[\beta_1]_{V_K}, \ldots, [\beta_\chi]_{V_K}$ of $\mathcal{O}(X_K)/V_K$ and an element $[g] \in \mathcal{O}(X_K)/V_K$, find the coefficients $c_i \in K$ of g in this basis: $[g] = c_1 [\beta_1]_{V_K} + \cdots + c_\chi [\beta_\chi]_{V_K}$. We show that $\mathcal{O}(X_K)/V_K$ is isomorphic to a quotient of a non-commutative ring of difference operators R by a left ideal $J \subset R$. This is an isomorphism of left R-modules: $\mathcal{O}(X_K)/V_K \simeq R/J$ (Theorem 2.2). The unknown coefficients $c_i \in K$ are found from a set of contiguity matrices for J. These are $\chi \times \chi$ matrices over K which encode how the difference operators act on the basis elements $[\beta_i]_{V_K}$.

We show how to compute these matrices and provide an implementation. Our algorithm, inspired by border basis algorithms [22], exploits the fact that a basis for $\mathcal{O}(X_K)/V_K$ can be computed a priori. For the physics application, it offers an alternative for Laporta's algorithm to systematically compute all integration by parts relations among Feynman integrals [14].

The intuition for the connection between twisted cohomology and the likelihood ideal comes from a degeneration. We introduce a new parameter δ , so that making δ move from 1 to 0 turns $\mathcal{O}(X_K)/V_K$ into $\mathcal{O}(X_K)/I_K$. This degeneration also appears in [18], where it was used to relate the cohomology intersection pairing to Grothendieck's residue pairing. It can be defined over \mathbb{C} as well, and turns Theorems 1.1 and 1.2 into practice: bases of cohomology turn into bases of the likelihood quotient. The cohomology intersection pairing over K is characterized as a unique bilinear pairing compatible with the K-module structure mentioned above (Theorem 4.1). Contiguity matrices for $\delta \to 0$ become pairwise commuting K-linear maps representing multiplication modulo I_K (Theorem 5.1).

The dual vector space of the twisted cohomology $H^n(X, \omega)$ is the twisted homology $H_n(X, -\omega) = \operatorname{Hom}_{\mathbb{C}}(\mathcal{O}(X)/V, \mathbb{C})$ [1, Section 2]. A preferred basis of $H_n(X, -\omega)$ in this article consists of the Lefschetz thimbles [28, Section 3]. These are called Lagrangian cycles in [2, Section 4.3]. There is one Lefschetz thimble $\Gamma_j \subset X$ for each critical point $x^{(j)}$ satisfying $\omega(x^{(j)}) = 0$, with the property that $x^{(j)} \in \Gamma_j$. They represent the linear functionals

$$[g]_V \longmapsto \int_{\Gamma_i} g(x) \cdot L(x) \frac{\mathrm{d}x_1}{x_1} \wedge \dots \wedge \frac{\mathrm{d}x_n}{x_n}.$$

In Section 4, we will show that when $\delta \to 0$, these Lefschetz thimbles degenerate to the evaluation functionals $[g]_I \longmapsto g(x^{(j)})$ on the likelihood quotient $\mathcal{O}(X)/I$.

The paper is organized as follows. Section 2 recalls the twisted de Rham complex and establishes the isomorphism $\mathcal{O}(X_K)/V_K \simeq R/J$. Section 3 introduces the likelihood ideal and sets up the degeneration which takes the twisted de Rham cohomology to the likelihood quotient. It contains a proof of Theorem 1.2. In Section 4, we prove Theorem 1.1 via our degeneration and a perfect pairing of cohomology. We also discuss a different perfect pairing with twisted homology, whose degeneration turns Lefschetz thimbles into evaluation at critical points. Section 5 deals with our computational goals: computing bases for cohomology and computing expansions in this basis. We implement our algorithms in Julia. The code uses the packages HomotopyContinuation.jl [6] and Oscar.jl [23]. It is made available at https://mathrepo.mis.mpg.de/TwistedCohomology. In Section 6, we apply our methods to compute contiguity matrices in several examples, including some Feynman integrals.

2 Twisted de Rham cohomology

Fix ℓ Laurent polynomials $f_1, \ldots, f_{\ell} \in \mathbb{C}[x_1^{\pm 1}, \ldots, x_n^{\pm 1}]$ and let $X_{\mathbb{C}} = X$ be as in (1). As alluded to in the introduction, we will need analogous schemes X_A over different rings A. In our setting, the ring A satisfies $A = \mathbb{C}$ or $\mathbb{C}[s_1, \ldots, s_{\ell}, \nu_1, \ldots, \nu_n] \subset A$. Our schemes X_A are

$$X_A = \operatorname{Spec} A[x_1^{\pm 1}, \dots, x_n^{\pm 1}]_{f_1 \cdots f_\ell}.$$

The A-module of regular k-forms on X_A is denoted by

$$\Omega^k(X_A) = \left\{ \sum_{1 \le j_1 < \dots < j_k \le n} g_{j_1, \dots, j_k} \, \mathrm{d}x_{j_1} \wedge \dots \wedge \mathrm{d}x_{j_k} \, \middle| \, g_{j_1, \dots, j_k} \in \sum_{(a,b) \in \mathbb{Z}^{\ell+n}} A \cdot f^a \, x^b \right\}. \tag{3}$$

To construct the algebraic twisted de Rham complex, we consider the one-form

$$\omega = -s_1 \operatorname{dlog} f_1 - \dots - s_\ell \operatorname{dlog} f_\ell + \frac{\nu_1 \operatorname{d} x_1}{x_1} + \dots + \frac{\nu_n \operatorname{d} x_n}{x_n}$$

$$= \sum_{j=1}^n \left(\frac{\nu_j}{x_j} - s_1 \frac{\frac{\partial f_1}{\partial x_j}}{f_1} - \dots - s_\ell \frac{\frac{\partial f_\ell}{\partial x_j}}{f_\ell} \right) \operatorname{d} x_j \in \Omega^1(X_A).$$
(4)

When $A = \mathbb{C}$, s and ν in this formula are generic tuples of complex numbers. The precise meaning of generic is given in Definition 1. When $\mathbb{C}[s,\nu] \subset A$, the coefficients of ω are variables. The one-form ω is the logarithmic differential of our likelihood function (2). The twisted differential $\nabla_{\omega}: \Omega^k(X_A) \to \Omega^{k+1}(X_A)$ is given by $\nabla_{\omega}(\phi) = (d + \omega \wedge) \phi$. Here d acts on $g \in A[x, x^{-1}]$ by exterior derivation in x. This gives a cochain complex

$$(\Omega^{\bullet}(X_A), \nabla_{\omega}): 0 \longrightarrow \Omega^{0}(X_A) \xrightarrow{\nabla_{\omega}} \Omega^{1}(X_A) \xrightarrow{\nabla_{\omega}} \cdots \xrightarrow{\nabla_{\omega}} \Omega^{n}(X_A) \longrightarrow 0.$$
 (5)

The cohomology of this complex $H^k(\Omega^{\bullet}(X_A), \nabla_{\omega})$ is denoted by $H^k(X_A, \omega)$ for simplicity. We are mainly interested in the top cohomology. This is the A-module

$$H^{n}(X_{A}, \omega) = \frac{\Omega^{n}(X_{A})}{\nabla_{\omega}(\Omega^{n-1}(X_{A}))} = \mathcal{O}(X_{A})/V_{A}, \tag{6}$$

where $\mathcal{O}(X_A) = A[x_1^{\pm 1}, \dots, x_n^{\pm 1}]_{f_1 \dots f_\ell}$ is the ring of regular functions on X_A , and V_A is the image $\nabla_{\omega}(\Omega^{n-1}(X_A)) \subset \mathcal{O}(X_A)$ under the identification $\Omega^n(X_A) \simeq \mathcal{O}(X_A)$ which takes $1 \in \mathcal{O}(X_A)$ to the canonical volume form $\frac{\mathrm{d}x}{x} = \frac{\mathrm{d}x_1}{x_1} \wedge \dots \wedge \frac{\mathrm{d}x_n}{x_n}$ on the *n*-dimensional algebraic torus. Concretely, $\mathcal{O}(X_A) \ni g \sim g \frac{\mathrm{d}x}{x} \in \Omega^n(X_A)$ and $\mathcal{O}(X_A)/V_A \ni [g]_{V_A} \sim [g \frac{\mathrm{d}x}{x}] \in H^n(X_A, \omega)$.

Example 2.1. It is instructive to explicitly write down some elements of $\nabla_{\omega}(\Omega^{n-1}(X_A))$. An (n-1)-form in $\Omega^{n-1}(X_A)$ is an A-linear combination of elements of the form

$$f^a x^b \, \mathrm{d}x_{\hat{j}} = f^a x^b \, \mathrm{d}x_1 \wedge \dots \wedge \mathrm{d}x_{j-1} \wedge \mathrm{d}x_{j+1} \wedge \dots \wedge \mathrm{d}x_n. \tag{7}$$

The image of (7) under the twisted differential ∇_{ω} is

$$\nabla_{\omega}(f^a x^b \, \mathrm{d}x_{\hat{j}}) = f^a x^b \left(\frac{\nu_j + b_j}{x_j} - \sum_{i=1}^{\ell} (s_i - a_i) \frac{\frac{\partial f_i}{\partial x_j}}{f_i} \right) \mathrm{d}x_1 \wedge \dots \wedge \mathrm{d}x_n.$$

If A is a field, e.g. $A = \mathbb{C}$ or $A = K = \mathbb{C}(s, \nu)$, then $H^n(X_A, \omega)$ in an A-vector space. Theorem 2.1 below shows that its dimension depends only on the topology of $X_{\mathbb{C}}$.

Before stating this dimension result, we clarify the meaning of generic s, ν . Consider a smooth projective compactification \bar{X} of $X = X_{\mathbb{C}}$ such that the boundary $D = \bar{X} \setminus X$ is a simple normal crossing divisor, with irreducible decomposition $D = \bigcup_{k=1}^{\ell+n} D_k$. From this compactification, we define a \mathbb{Z} -linear form $\operatorname{Res}_{D_k}(s,\nu)$ for each divisor D_k . The coefficients are the orders of vanishing of f_i^{-1}, x_i along D_k , see Example 4.2 and [1, Lemma A.2].

Definition 1. The parameters $(s, \nu) \in \mathbb{C}^{\ell+n}$ are generic if $\operatorname{Res}_{D_k}(s, \nu) \notin \mathbb{Z}$ for any k.

This notion of genericity is not a Zariski open condition in $\mathbb{C}^{\ell+n}$. It is, however, a mild requirement: generic (s, ν) are open and dense in the standard topology of $\mathbb{C}^{\ell+n}$.

Theorem 2.1. If $A = \mathbb{C}$ and s, ν are generic in the sense of Definition 1, or $A = K = \mathbb{C}(s, \nu)$, then $\dim_A H^n(X_A, \omega) = (-1)^n \cdot \chi(X_{\mathbb{C}})$, where $\chi(\cdot)$ denotes the Euler characteristic.

The proof of Theorem 2.1 will make use of a technical lemma. Let \bar{X}_K be a smooth projective compactification of X_K obtained from $\bar{X} = \bar{X}_{\mathbb{C}}$ above via the base extension $\mathbb{C} \to K$. For $A = \mathbb{C}$ or K, let $\Omega^p_{A,\log}$ denote the sheaf of p-forms on \bar{X}_A , logarithmic along D. Moreover, we write $\Omega^p_{A,\log}(kD) = \Omega^p_{A,\log} \otimes_A \mathcal{O}_{\bar{X}_A}(kD)$ for any integer k.

Lemma 2.1. If $A = \mathbb{C}$ and s, ν are generic in the sense of Definition 1, or $A = K = \mathbb{C}(s, \nu)$, then the Hodge-to-de Rham spectral sequence

$$E_1^{p,q} = \mathbb{H}^q(\bar{X}_A; \Omega_{A,\log}^p(kD)) \Rightarrow \mathbb{H}^{p+q}(\bar{X}_A; (\Omega_{A,\log}^{\bullet}(kD), \nabla_{\omega}))$$
 (8)

degenerates at the E_1 stage for sufficiently large k, and $\dim_A H^n(X_A, \omega)$ equals

$$\dim_A \mathbb{H}^n(\bar{X}_A; (\Omega_{A,\log}^{\bullet}(kD), \nabla_{\omega})) = \sum_{p+q=n} \dim_A \mathbb{H}^q(\bar{X}_A; \Omega_{A,\log}^p(kD)). \tag{9}$$

Proof. The degeneration of (8) is a consequence of the vanishing theorem by Grothendieck and Serre, see [9, Proposition 2.6.1]. The second claim follows from that degeneration.

Proof of Theorem 2.1. We set $\Omega_{A,\log}^p(*D) := \Omega_{A,\log}^p \otimes_A \mathcal{O}_{\bar{X}_A}(*D)$, with $\mathcal{O}_{\bar{X}_A}(*D)$ the sheaf of rational functions on \bar{X}_A with poles along D. Our cohomology vector space equals the hypercohomology group

$$H^{n}(X_{A},\omega) = \mathbb{H}^{n}(\bar{X}_{A}; (\Omega_{A}^{\bullet}(*D), \nabla_{\omega})). \tag{10}$$

The canonical morphism $(\Omega_{A,\log}^{\bullet}(kD), \nabla_{\omega}) \to (\Omega_{A}^{\bullet}(*D), \nabla_{\omega})$ is a quasi-isomorphism for any $k \in \mathbb{Z}$. This follows from the same argument as [7, Properties 2.9]. Therefore, (10) implies $H^{n}(X_{A}, \omega) = \mathbb{H}^{n}(\bar{X}_{A}; (\Omega_{A,\log}^{\bullet}(kD), \nabla_{\omega}))$. Applying (9), we have for sufficiently large k that

$$\dim_A H^n(X_A, \omega) = \sum_{p+q=n} \dim_A \mathbb{H}^q(\bar{X}_A; \Omega^p_{A,\log}(kD)).$$

Here, to apply Lemma 2.1 for $A = \mathbb{C}$ we need the genericity assumption (Definition 1). If $A = \mathbb{C}$, the statement is proved, as the righthand side equals $(-1)^n \cdot \chi(X_{\mathbb{C}})$. For A = K, note that $\dim_K \mathbb{H}^q(\bar{X}_K; \Omega^p_{K,\log}(kD)) = \dim_{\mathbb{C}} \mathbb{H}^q(\bar{X}_{\mathbb{C}}; \Omega^p_{\mathbb{C},\log}(kD))$, as there is a canonical isomorphism $\mathbb{H}^q(\bar{X}_K; \Omega^p_{K,\log}(kD)) \simeq \mathbb{H}^q(\bar{X}_{\mathbb{C}}; \Omega^p_{\mathbb{C},\log}(kD)) \otimes_{\mathbb{C}} K$. This gives

$$\sum_{p+q=n} \dim_K \mathbb{H}^q(\bar{X}_K; \Omega^p_{K,\log}(kD)) = \sum_{p+q=n} \dim_{\mathbb{C}} \mathbb{H}^q(\bar{X}_{\mathbb{C}}; \Omega^p_{\mathbb{C},\log}(kD)).$$

We conclude $\dim_K H^n(X_K, \omega) = (-1)^n \cdot \chi(X_{\mathbb{C}})$, and we are done.

For applications in physics, where our likelihood function is a Feynman integrand in Lee-Pomeransky representation [15], the relevant case is $\ell = 1$. A basis for $H^n(X_A, \omega)$ corresponds to a set of master integrals [12]. Relations between Feynman integrals come from A-linear relations modulo V_A . Computing such bases and relations is the topic of Section 5. Our algorithms rest on the main result of this section, which is Theorem 2.2 below.

We set $A = K = \mathbb{C}(s, \nu)$. We introduce a non-commutative ring of difference operators $R = K\langle \sigma_{s_1}^{\pm 1}, \dots, s_{s_\ell}^{\pm 1}, \sigma_{\nu_1}^{\pm 1}, \dots, \sigma_{\nu_n}^{\pm 1} \rangle$, generated by σ_s, σ_{ν_j} and their inverses, with relations

$$[\sigma_{s_i}, \sigma_{s_j}] = [\sigma_{s_i}, \sigma_{\nu_j}] = [\sigma_{\nu_i}, \sigma_{\nu_j}] = 0, \quad [\sigma_{s_i}, s_j] = \delta_{ij}\sigma_{s_j}, \quad [\sigma_{\nu_i}, \nu_j] = \delta_{ij}\sigma_{\nu_i}.$$
 (11)

Here [a, b] = ab - ba is the commutator in the ring R and δ_{ij} is Kronecker's delta. Let e_j be the j-th standard basis vector. The difference operators σ_{s_i} and σ_{ν_j} act on $\mathcal{O}(X_K)$ by

$$\sigma_{s_i} \bullet g(s, \nu) = f_i^{-1} \cdot g(s + e_i, \nu), \quad \sigma_{\nu_i} \bullet g(s, \nu) = x_j \cdot g(s, \nu + e_j). \tag{12}$$

The notation $g(s,\nu)$ emphasizes the dependence of the regular function $g \in \mathcal{O}(X_K)$ on s and ν . The action of R is obtained by extending (12) K-linearly. This action turns $\mathcal{O}(X_K)$ into a left R-module. Moreover, using notation from Example 2.1, the observation that $\sigma_{s_i} \bullet \nabla_{\omega}(f^a x^b \mathrm{d} x_{\hat{j}}) = \nabla_{\omega}(f^{a-e_i} x^b \mathrm{d} x_{\hat{j}})$ and $\sigma_{\nu_k} \bullet \nabla_{\omega}(f^a x^b \mathrm{d} x_{\hat{j}}) = \nabla_{\omega}(f^a x^{b+e_k} \mathrm{d} x_{\hat{j}})$ shows that the R-action is well defined modulo V_K , so that $\mathcal{O}(X_K)/V_K$ is a left R-module as well. Our proof of the next theorem relies on D-module theory, in particular on results from [16]. It briefly recalls the main relevant concepts. The reader is referred to [16, 24, 25] for details.

Theorem 2.2. As a left R-module, the cohomology $H^n(X_K, \omega) = \mathcal{O}(X_K)/V_K$ is isomorphic to the quotient R/J of R by the left ideal $J \subset R$ generated by

$$1 - \sigma_{s_i} f_i(\sigma_{\nu}), \text{ for } i = 1, \dots, \ell, \quad \text{ and } \quad \sigma_{\nu_j}^{-1} \nu_j - \sum_{i=1}^{\ell} s_i \, \sigma_{s_i} \frac{\partial f_i}{\partial x_j}(\sigma_{\nu}), \text{ for } j = 1, \dots, n. \quad (13)$$

Moreover, the isomorphism sends the residue class of $\sigma_s^a \sigma_\nu^b$ to $[f^{-a} x^b]_{V_K} \in \mathcal{O}(X_K)/V_K$.

Proof. Let $T_A^{\ell+n} = \operatorname{Spec} A[x_1^{\pm 1}, \dots, x_n^{\pm 1}, z_1^{\pm 1}, \dots, z_\ell^{\pm 1}]$ be the $(\ell+n)$ -dimensional algebraic torus over a field A. Its Weyl algebra $D_{\ell+n,A} = D_{T_A^{\ell+n}}$ consists of linear differential operators in the $\ell+n$ variables x,z with coefficients in $A[x^{\pm 1},z^{\pm 1}]$. Our very affine variety X is naturally embedded into $T_{\mathbb{C}}^{\ell+n}$ via $x\mapsto (x_1,\dots,x_n,f_1(x)^{-1},\dots,f_\ell(x)^{-1})$. The local cohomology of $X\subset T_{\mathbb{C}}^{\ell+n}$ is the $D_{\ell+n,\mathbb{C}}$ -module $M=D_{\ell+n,\mathbb{C}}/H$, where H is the left $D_{\ell+n,\mathbb{C}}$ -ideal generated by

$$1 - z_i f_i$$
, for $i = 1, \dots, \ell$, and $-x_j \partial_{x_j} + \sum_{i=1}^{\ell} z_i \partial_{z_i} z_i x_j \frac{\partial f_i}{\partial x_j}$, for $j = 1, \dots, n$. (14)

We consider two different ways to construct a left R-module from M:

(1) The Mellin transform $\mathcal{M}\{\cdot\}: D_{\ell+n,\mathbb{C}} \to R$ is the ring map which replaces $-x_j\partial_{x_j}$ with ν_j , $-z_i\partial_{z_i}$ with s_i , x_j with σ_{ν_j} , and z_i with σ_{s_i} . We claim that $\mathcal{M}\{\cdot\}: M \to R/J$ is well-defined modulo H, with J as in the theorem. Moreover, we have $\mathcal{M}\{M\} = R/J$.

(2) We construct the left $D_{\ell+n,K}$ -module $M(s,\nu) \bullet z^s x^{\nu}$ by applying linear differential operators in $D_{\ell+n,K}$ to $z^s x^{\nu}$, and regarding the result modulo $H_K \bullet z^s x^{\nu}$, where H_K is the left $D_{\ell+n,K}$ -ideal generated by (14). In symbols, $M(s,\nu) = M \otimes_{\mathbb{C}[s,\nu]} K$. We consider the push-forward $\mathcal{H}\{M\} = \pi_+(M(s,\nu) \bullet z^s x^{\nu})$ in the sense of D-modules under the constant map $\pi: T_K^{\ell+n} \to \operatorname{Spec} K$. We claim that $\mathcal{H}\{M\} = H^n(X_K, \omega) = \mathcal{O}(X_K)/V_K$.

The theorem follows from these claims, as $\mathcal{M}\{M\} \simeq \mathcal{H}\{M\}$ by a result of Loeser and Sabbah [16, Lemme 1.2.2]. Claim (1) is easily verified by observing that $\mathcal{M}\{D_{\ell+n,\mathbb{C}}\}=R$ and $\mathcal{M}\{\cdot\}$ turns the generators in (14) into (29). For claim (2), let $Z \subset T_K^{n+\ell}$ be the natural embedding of X_K in $T_K^{n+\ell}$. Its equations are $1-z_1f_1(x)=\cdots=1-z_\ell f_\ell(x)=0$. We write $Z \stackrel{\iota}{\hookrightarrow} T_K^{n+\ell}$ for the inclusion. In view of Kashiwara's equivalence [5, Chapter VI, Theorem 7.13] and following the notation of [5], we obtain a sequence of isomorphisms

$$\mathcal{H}\{M\} = \pi_{+} \left(\mathbb{R} \Gamma_{Z} \mathcal{O}_{T_{K}^{n+\ell}}[\ell] \otimes \mathcal{O}z^{s} x^{\nu} \right) = \pi_{+} \left(\iota_{+} \iota^{!} \mathcal{O}_{T_{K}^{n+\ell}}[\ell] \otimes \mathcal{O}z^{s} x^{\nu} \right)$$

$$\simeq \pi_{+} \left(\iota_{+} \mathcal{O}_{Z} z^{s} x^{\nu} \right) \simeq \pi_{+} \left(\iota_{+} \mathcal{O}_{Z} f^{-s} x^{\nu} \right) \simeq (\pi \circ \iota)_{+} \mathcal{O}_{Z} f^{-s} x^{\nu}$$

$$= H^{n}(X_{K}, \omega).$$

$$(15)$$

Here passing from (15) to (16) uses $\iota^! \mathcal{O}_{T_K^{n+\ell}}[\ell] \simeq \mathcal{O}_Z$.

Remark 2.1. The authors of [4] exploit the difference module structure only in the ν -variables, for $\ell = 1$. In fact, the parametric annihilator ideal in that paper arises from the Mellin transform of H in the z-direction, viewed as a module over the Weyl algebra $D_{n,K}$. One recovers $H^n(X_K,\omega)$ by applying the Mellin transform in the x-direction.

Example 2.2 $(n = 2, \ell = 3)$. Consider the very affine surface $X = (\mathbb{C}^*)^2 \setminus V(f_1 f_2 f_3)$, where $f_1 = x - 1, f_2 = y - 1, f_3 = x - y$. This variety can be identified with the moduli space $\mathcal{M}_{0,5}$ of five points on \mathbb{P}^1 [26, Section 2]. Its real part is the complement of an arrangement of five lines in \mathbb{R}^2 . By Varchenko's theorem [26, Proposition 1], the Euler characteristic equals the number of bounded polygons in that complement, which is two. The generators of J are

$$1 - \sigma_{s_1}(\sigma_{\nu_1} - 1), \quad 1 - \sigma_{s_2}(\sigma_{\nu_2} - 1), \quad 1 - \sigma_{s_3}(\sigma_{\nu_1} - \sigma_{\nu_2}),$$

$$\sigma_{\nu_1}^{-1}\nu_1 - s_1\sigma_{s_1} - s_3\sigma_{s_3}, \quad \sigma_{\nu_2}^{-1}\nu_2 - s_2\sigma_{s_2} + s_3\sigma_{s_3}.$$

$$(17)$$

Theorem 2.2 reduces computations in the cohomology $H^n(X_K, \omega) = \mathcal{O}(X_K)/V_K$ to computations in the difference ring R modulo the left ideal J. Our algorithm in Section 5 is inspired by a generalization of commutative Gröbner bases, called *border bases* [22]. It makes use of the fact that a K-basis of $\mathcal{O}(X_K)/V_K$ is known a priori via Theorems 1.1 and 1.2.

3 Degeneration and likelihood ideals

Theorem 2.2 expresses our cohomology vector space $H^n(X_K, \omega)$ as a quotient of a non-commutative ring R by a left ideal J. In this section, we introduce a degeneration which turns the cohomology into a quotient of the commutative ring $\mathcal{O}(X_K)$ by the likelihood ideal. For the moment, we will switch back to our general setting where X_A is defined over a ring

A, which is either \mathbb{C} or contains $\mathbb{C}[s,\nu]$. Our degeneration is interesting for at least two reasons. First, it preserves bases in the sense of Theorem 1.2, which allows us to compute a basis for $H^n(X_A,\omega)$ from a basis of the likelihood quotient. This section features a proof of Theorem 1.2. Second, the degeneration provides new insights into the relation between critical points and twisted homology. This will be explored in Section 4.

The term likelihood comes from maximum likelihood estimation, where one seeks to maximize the log-likelihood function $\log L(x)$, with L(x) as in (2). The likelihood equations are obtained by equating its partial derivatives with respect to x_1, \ldots, x_n to zero. This leads to $\omega = 0$, where $\omega \in \Omega^1(X_A)$ is as in (4). The critical points form a zero-dimensional subscheme of X_A , defined by an ideal $I_A \subset \mathcal{O}(X_A)$ called the likelihood ideal:

$$I_A = \left\langle \frac{\nu_j}{x_j} - s_1 \frac{\frac{\partial f_1}{\partial x_j}}{f_1} - \dots - s_\ell \frac{\frac{\partial f_\ell}{\partial x_j}}{f_\ell}, \ j = 1, \dots, n \right\rangle \subset \mathcal{O}(X_A). \tag{18}$$

Note that, for A = K, the similarity of these generators with (29) hints at a strong connection between $\mathcal{O}(X_K)/I_K$ and $H^n(X_K,\omega) = \mathcal{O}(X_K)/V_K$. This section explores that connection.

Identifying $\mathcal{O}(X_A)$ with regular *n*-forms $\Omega^n(X_A)$, we observe that I_A is the image of the map $\Omega^{n-1}(X_A) \to \Omega^n(X_A)$ given by $\phi \mapsto \omega \wedge \phi$. Together with (6), this gives

$$H^{n}(X_{A},\omega) = \frac{\Omega^{n}(X_{A})}{(d+\omega\wedge)\Omega^{n-1}(X_{A})}, \quad \mathcal{O}(X_{A})/I_{A} = \frac{\Omega^{n}(X_{A})}{\omega\wedge\Omega^{n-1}(X_{A})}.$$
 (19)

These equations are the ingredients to explain our intuition behind this section's degeneration. To go from left to right in (19), it suffices to drop the 'd' in the twisted differential. This motivates us to introduce a parameter δ into the twisted de Rham complex (5) as follows. We replace the twisted differential $\nabla_{\omega} = d + \omega \wedge$ by $\nabla_{\omega}^{\delta} = \delta d + \omega \wedge$. When $\delta = 1$, we recover our original complex (5). When $\delta = 0$, we obtain a complex of $\mathcal{O}(X_A)$ -modules, which is the dual Koszul complex of the likelihood ideal (18) (more precisely, of its n generators g_1, \ldots, g_n). Since $g_1, \ldots, g_n \in \mathcal{O}(X_A)$ form a regular sequence, this dual Koszul complex is a free resolution. This implies that all its cohomology modules are zero, except at level n, where it equals our likelihood quotient $\mathcal{O}(X_A)/I_A$. Below, we will make this more precise.

Remark 3.1. The deformation parameter δ corresponds to the reciprocal of the ϵ -parameter in dimensional regularization from physics (substitute $d = d_0 - 2\epsilon$ in formula (2.5) of [15]).

To formally introduce the degeneration parameter δ into our cochain complex, we add it to our field $K = \mathbb{C}(s, \nu)$. Since we want to analyze what happens near $\delta = 0$, we choose to work over the power series ring $K[\![\delta]\!]$. To simplify the notation, we will write $X_{\delta} = X_{K[\![\delta]\!]}$. The δ -twisted differential $\nabla_{\omega}^{\delta} : \Omega^{k}(X_{\delta}) \to \Omega^{k+1}(X_{\delta})$ is given by $\nabla_{\omega}^{\delta}(\phi) = (\delta d + \omega \wedge) \phi$. Here regular k-forms $\Omega^{k}(X_{\delta})$ are defined as in (3) with $A = K[\![\delta]\!]$. The k-th cohomology group of

$$(\Omega^{\bullet}(X_{\delta}), \nabla^{\delta}_{\omega}): 0 \longrightarrow \Omega^{0}(X_{\delta}) \xrightarrow{\nabla^{\delta}_{\omega}} \Omega^{1}(X_{\delta}) \xrightarrow{\nabla^{\delta}_{\omega}} \cdots \xrightarrow{\nabla^{\delta}_{\omega}} \Omega^{n}(X_{\delta}) \longrightarrow 0$$
 (20)

is denoted by $H^k(X_\delta, \omega_\delta)$. Tensoring (20) with the Laurent series $K((\delta))$ we obtain the cochain complex $(\Omega^{\bullet}(X_{K((\delta))}), \nabla^{\delta}_{\omega})$, with cohomology $H^k(X_{K((\delta))}, \omega_\delta)$. We will see below (Corollary 3.1) that the dimension for k = n is the signed Euler characteristic, which is reminiscent of Theorem 2.1. For $A = K[\![\delta]\!]$, the analogous statement is the following.

Theorem 3.1. The cohomology $H^n(X_{\delta}, \omega_{\delta})$ is a free $K[\![\delta]\!]$ -module of rank $(-1)^n \cdot \chi(X_{\mathbb{C}})$.

Before proving Theorem 3.1, it is convenient to formalize the notion of 'driving δ to 0'.

Definition 2. For a $K[\![\delta]\!]$ -module M, we define the K-vector space $\lim_{\delta\to 0} M = M/(\delta\cdot M)$.

Example 3.1. One checks that
$$\lim_{\delta\to 0} \Omega^k(X_{\delta}) = \Omega^k(X_K)$$
.

This justifies our claim that cohomology degenerates to the likelihood quotient:

Lemma 3.1. The limit $\lim_{\delta\to 0} H^n(X_\delta,\omega_\delta)$ is $\mathcal{O}(X_K)/I_K$ and has dimension $(-1)^n \cdot \chi(X_\mathbb{C})$.

Proof. We first observe that our limit equals

$$\lim_{\delta \to 0} H^n(X_{\delta}, \omega_{\delta}) = \frac{H^n(X_{\delta}, \omega_{\delta})}{\delta \cdot H^n(X_{\delta}, \omega_{\delta})} = \frac{\Omega^n(X_{\delta})}{\nabla^{\delta}_{\omega}(\Omega^{n-1}(X_{\delta})) + \delta \cdot \Omega^n(X_{\delta})}.$$

Using $\Omega^k(X_\delta) = K[\![\delta]\!] \otimes_K \Omega^k(X_K)$, we see that the denominator on the right equals

$$(\delta d + \omega \wedge) (K \llbracket \delta \rrbracket \otimes_K \Omega^{n-1}(X_K)) + \delta \cdot \Omega^n(X_\delta) = \omega \wedge \Omega^{n-1}(X_K) + \delta \cdot \Omega^n(X_\delta).$$

Together with Example 3.1 this leads to $\lim_{\delta\to 0} H^n(X_\delta, \omega_\delta) = \frac{\Omega^n(X_K)}{\omega\wedge\Omega^{n-1}(X_K)} = \mathcal{O}(X_K)/I_K$. The statement about the dimension follows from [13, Theorem 1].

Our proof of Theorem 3.1 will also use the following two lemmas.

Lemma 3.2. Let M be a finitely generated $K[\delta]$ -module, with free part of rank r. We have

- 1. $\dim_{K((\delta))} K((\delta)) \otimes_{K[\![\delta]\!]} M = r \ and$
- 2. $\dim_K \lim_{\delta \to 0} M \ge r$, where equality holds if and only if M is free.

Proof. The proof requires only elementary commutative algebra. We present a sketch and leave details to the reader. For the first statement, the torsion part of M is annihilated by the tensor product, since $K((\delta)) \otimes_{K[\![\delta]\!]} K[\![\delta]\!]/\langle \delta^p \rangle = 0$ for any p. For the second statement, note that a torsion component $K[\![\delta]\!]/\langle \delta^p \rangle$ has nonzero contribution to the dimension $\dim_K \lim_{\delta \to 0} M = \dim_K M/(\delta \cdot M)$. Indeed, we have $\lim_{\delta \to 0} K[\![\delta]\!]/\langle \delta^p \rangle = K$.

The final lemma is an analog of Lemma 2.1 over $K\llbracket \delta \rrbracket$ and $K((\delta))$.

Lemma 3.3. If $A = K[\delta]$ or $A = K((\delta))$, then the Hodge-to-de Rham spectral sequence

$$E_1^{p,q} = \mathbb{H}^q(\bar{X}_A; \Omega_{A,\log}^p(kD)) \Rightarrow \mathbb{H}^{p+q}(\bar{X}_A; (\Omega_{A,\log}^{\bullet}(kD), \nabla_{\omega}^{\delta}))$$
 (21)

degenerates at the E_1 stage for sufficiently large k. In particular, $\dim_{K((\delta))} H^n(X_{K((\delta))}, \omega_{\delta})$ is

$$\dim_{K((\delta))} \mathbb{H}^n(\bar{X}_{K((\delta))}; (\Omega^{\bullet}_{K((\delta)),\log}(kD), \nabla^{\delta}_{\omega})) = \sum_{p+q=n} \dim_{K((\delta))} \mathbb{H}^q(\bar{X}_{K((\delta))}; \Omega^p_{K((\delta)),\log}(kD)).$$
 (22)

The proof of this lemma is the same as that of Lemma 2.1. The following is a consequence.

Corollary 3.1. The dimension of the $K((\delta))$ -vector space $H^n(X_{K((\delta))}, \omega_{\delta})$ is $(-1)^n \cdot \chi(X_{\mathbb{C}})$.

Proof. The proof is identical to that of Theorem 2.1, replacing Lemma 2.1 by Lemma 3.3.

Proof of Theorem 3.1. We first show that $H^n(X_\delta, \omega_\delta)$ is finitely generated over $K[\![\delta]\!]$. Because the residue of the δ -connection $(\mathcal{O}_{X_\delta}(kD), \nabla_\omega^\delta)$ along a component D_j is $\mathrm{Res}_{D_j}(s, \nu) + k\delta$, the natural morphism $(\Omega_{\delta,\log}^{\bullet}(kD), \nabla_\omega^\delta) \to (\Omega_{\delta,\log}^{\bullet}(*D), \nabla_\omega^\delta)$ is a quasi-isomorphism by the argument in the proof of [7, Properties 2.9]. It follows that

$$H^n(X_{\delta}, \omega_{\delta}) \simeq \mathbb{H}^n(\bar{X}_{\delta}; (\Omega_{\delta,\log}^{\bullet}(*D), \nabla_{\omega}^{\delta})) \simeq \mathbb{H}^n(\bar{X}_{\delta}; (\Omega_{\delta,\log}^{\bullet}(kD), \nabla_{\omega}^{\delta})).$$

By Lemma 3.3, this implies that $H^n(X_\delta, \omega_\delta)$ is finitely generated over $K[\![\delta]\!]$. By Lemma 3.1,

$$\dim_K \lim_{\delta \to 0} H^n(X_\delta, \omega_\delta) = (-1)^n \cdot \chi(X_\mathbb{C}). \tag{23}$$

Tensoring (20) with $K((\delta))$ we obtain

$$\dim_{K((\delta))} K((\delta)) \otimes_{K[\![\delta]\!]} H^n(X_\delta, \omega_\delta) = \dim_{K((\delta))} H^n(\Omega^{\bullet}(X_{K((\delta))}), \nabla^{\delta}_{\omega}) = (-1)^n \cdot \chi(X_{\mathbb{C}}), \quad (24)$$

where the second equality is Corollary 3.1. Lemma 3.2, (23) and (24) show that $H^n(X_{\delta}, \omega_{\delta})$ is free of rank $(-1)^n \cdot \chi(X_{\mathbb{C}})$.

Our next goal is to prove Theorem 1.2. We first need to define *constant bases*. Recall that $[g]_{I_K}$ denotes the residue class of $g \in \mathcal{O}(X_K)$ in the likelihood quotient $\mathcal{O}(X_K)/I_K$.

Definition 3. A subset $\{\beta_1, \ldots, \beta_{\chi}\} \subset \mathcal{O}(X_K)$ is said to represent a constant basis for $\mathcal{O}(X_K)/I_K$ if $\beta_1, \ldots, \beta_{\chi} \in \mathcal{O}(X_{\mathbb{C}})$ and $\{[\beta_1]_{I_K}, \ldots, [\beta_{\chi}]_{I_K}\}$ forms a K-basis of $\mathcal{O}(X_K)/I_K$.

Our proof of Theorem 1.2 uses the notation $V_A = \nabla_{\omega}^{\delta}(\Omega^{n-1}(X_A))$ for $A = K[\![\delta]\!]$ or $K(\!(\delta)\!)$.

Proof of Theorem 1.2. By assumption, $\{\beta_1, \ldots, \beta_{\chi}\} \subset \mathcal{O}(X) = \mathcal{O}(X_{\mathbb{C}})$ and $\chi = |\chi(X)|$. Consider the $K[\![\delta]\!]$ -submodule $N \subset H^n(X_{\delta}, \omega_{\delta})$ generated by $\{[\beta_1]_{V_{K[\![\delta]\!]}}, \ldots, [\beta_{\chi}]_{V_{K[\![\delta]\!]}}\}$. Here $[\beta_i]_{V_{K[\![\delta]\!]}}$ is the residue class of $\beta_i \in \mathcal{O}(X) \subset \mathcal{O}(X_{\delta})$ in $H^n(X_{\delta}, \omega_{\delta})$. By our assumption, we have $\lim_{\delta \to 0} H^n(X_{\delta}, \omega_{\delta})/N = 0$. Nakayama's lemma implies $H^n(X_{\delta}, \omega_{\delta}) = N$. By Equation (24), $H^n(X_{K(\!(\delta)\!)}, \omega_{\delta})$ has dimension χ , and therefore $\{[\beta_1]_{V_{K(\!(\delta)\!)}}, \ldots, [\beta_{\chi}]_{V_{K(\!(\delta)\!)}}\}$ is a basis. Next, we consider a field extension $\iota: K \hookrightarrow K(\!(\delta)\!)$ given by

$$K \ni a(s,\nu) \stackrel{\iota}{\mapsto} a(s/\delta,\nu/\delta) \in K((\delta))$$
 (25)

and define a morphism of $K((\delta))$ -vector spaces $\varphi: K((\delta)) \otimes_K H^n(X_K, \omega) \to H^n(X_{K((\delta))}, \omega_\delta)$:

$$h \otimes [g(s,\nu)]_{V_K} \xrightarrow{\varphi} \left[h \cdot g\left(\frac{s}{\delta}, \frac{\nu}{\delta}\right) \right]_{V_{K((\delta))}}.$$
 (26)

Note that φ is well-defined: if $g(s,\nu) = \nabla_{\omega}(\phi(s,\nu))$ with $\phi \in \Omega^{n-1}(X_K)$, we have

$$h \cdot g\left(\frac{s}{\delta}, \frac{\nu}{\delta}\right) = h \cdot \left(d + \omega\left(\frac{s}{\delta}, \frac{\nu}{\delta}\right) \wedge\right) \phi\left(\frac{s}{\delta}, \frac{\nu}{\delta}\right) = \nabla_{\omega}^{\delta}\left(\frac{h}{\delta} \cdot \phi\left(\frac{s}{\delta}, \frac{\nu}{\delta}\right)\right) \in V_{K((\delta))}.$$

Since φ is a surjective map of equidimensional $K((\delta))$ -vector spaces (Theorems 2.1 and 3.1), it is an isomorphism. Since $H^n(X_\delta, \omega_\delta) = N$, we know that $[\beta_1]_{V_K((\delta))}, \ldots, [\beta_\chi]_{V_K((\delta))}$ is a basis for $H^n(X_{K((\delta))}, \omega_\delta)$. Because $\beta_i \in \mathcal{O}(X)$, we have $[\beta_i]_{V_K((\delta))} = \varphi(1 \otimes [\beta_i]_{V_K})$. It follows easily that $[\beta_1]_{V_K}, \ldots, [\beta_\chi]_{V_K}$ is a basis for $H^n(X_K, \omega)$. The theorem is proved.

The proof of Theorem 1.2 immediately implies the following corollary.

Corollary 3.2. If $\{\beta_1, \ldots, \beta_{\chi}\} \subset \mathcal{O}(X_K)$ represents a constant basis of $\mathcal{O}(X_K)/I_K$, then $\{[\beta_1]_{V_K[\![\delta]\!]}, \ldots, [\beta_{\chi}]_{V_K[\![\delta]\!]}\}$ is a free basis of $H^n(X_{\delta}, \omega_{\delta})$.

Finally, we link the degeneration back to Theorem 2.2 by bringing δ into our ring of difference operators R. We set $R_{\delta} = K[\![\delta]\!]\langle \sigma_{s_1}^{\pm 1}, \ldots, s_{s_{\ell}}^{\pm 1}, \sigma_{\nu_1}^{\pm 1}, \ldots, \sigma_{\nu_n}^{\pm 1} \rangle$. Now δ commutes with any element of R_{δ} , and the remaining commutator rules are as follows:

$$[\sigma_{s_i}, \sigma_{s_j}] = [\sigma_{s_i}, \sigma_{\nu_j}] = [\sigma_{\nu_i}, \sigma_{\nu_j}] = 0, \quad [\sigma_{s_i}, s_j] = \delta_{ij}\delta\sigma_{s_j}, \quad [\sigma_{\nu_i}, \nu_j] = \delta_{ij}\delta\sigma_{\nu_i}. \tag{27}$$

Note that when $\delta = 1$, we recover the relations (11). On the other hand, when $\delta = 0$, R_0 is the (commutative!) coordinate ring of the $(n + \ell)$ -dimensional algebraic torus $T_K^{n+\ell} = (K \setminus \{0\})^{n+\ell}$. The action of R_δ on $g(s, \nu) \in \Omega^n(X_\delta)$, generalizing (12), is

$$\sigma_{s_i} \bullet g(s, \nu) = f_i^{-1} \cdot g(s + \delta \cdot e_i, \nu), \quad \sigma_{\nu_i} \bullet g(s, \nu) = x_j \cdot g(s, \nu + \delta \cdot e_j). \tag{28}$$

This makes $\Omega^n(X_{\delta})$ a left R_{δ} -module. Also, (28) is well-defined on cohomology, as

$$\sigma_{s_i} \bullet \nabla^{\delta}_{\omega}(f^a x^b \mathrm{d} x_{\hat{j}}) = \nabla^{\delta}_{\omega}(f^{a-e_i} x^b \mathrm{d} x_{\hat{j}}) \quad \text{and} \quad \sigma_{\nu_k} \bullet \nabla^{\delta}_{\omega}(f^a x^b \mathrm{d} x_{\hat{j}}) = \nabla^{\delta}_{\omega}(f^a x^{b+e_k} \mathrm{d} x_{\hat{j}}).$$

Hence, also $H^n(X_\delta, \omega_\delta)$ is a left R_δ -module. Here is a version of Theorem 2.2 in this setting.

Theorem 3.2. As a left R_{δ} -module, the cohomology $H^n(X_{\delta}, \omega_{\delta})$ is isomorphic to the quotient R_{δ}/J_{δ} of R_{δ} by the left ideal $J_{\delta} \subset R_{\delta}$ generated by

$$1 - \sigma_{s_i} f_i(\sigma_{\nu}), \text{ for } i = 1, \dots, \ell, \quad \text{ and } \quad \sigma_{\nu_j}^{-1} \nu_j - \sum_{i=1}^{\ell} s_i \, \sigma_{s_i} \frac{\partial f_i}{\partial x_j}(\sigma_{\nu}), \text{ for } j = 1, \dots, n. \quad (29)$$

Moreover, the isomorphism sends the residue class of $\sigma_s^a \sigma_\nu^b$ to $[f^{-a} x^b \frac{dx}{x}] \in H^n(X_\delta, \omega_\delta)$. In particular, $R_\delta/J_\delta \simeq H^n(X_\delta, \omega_\delta)$ as $K[\![\delta]\!]$ -modules and $\lim_{\delta \to 0} R_\delta/J_\delta = \mathcal{O}(X_K)/I_K$.

Proof. We set $M_{\delta} = R_{\delta}/J_{\delta}$. Since $\bigcap_{n=0}^{\infty} \delta^{n} M_{\delta} = 0$ and $\dim_{K} \lim_{\delta \to 0} M_{\delta} = \dim_{K} \mathcal{O}(X_{K})/I_{K} = \chi < \infty$, M_{δ} is finitely generated by [19, Theorem 8.4]. On the other hand, one can prove that the naturally induced morphism $\psi : K((\delta)) \otimes_{K[\![\delta]\!]} M_{\delta} \to H^{n}(X_{K((\delta))}, \omega_{\delta})$ is an isomorphism. This is because ψ is the base extension of the isomorphism $R/J \to H^{n}(X_{K}; \omega)$ of Theorem 2.2 via the field extension $\iota : K \to K((\delta))$ given by (25). It follows that M_{δ} is a free $K[\![\delta]\!]$ -module by Lemma 3.2. The theorem follows from the obvious fact that the morphism $M_{\delta} \to H^{n}(X_{\delta}; \omega_{\delta})$ is surjective.

We end the section by illustrating some of its results in a one-dimensional example.

Example 3.2. We take $n=\ell=1$ and $f(x)=1-x^3$. As a basis of the likelihood quotient, we take $\{[1]_{I_K}, [x]_{I_K}, [x^2]_{I_K}\} \subset \mathcal{O}(X_K)/I_K$. By Theorem 1.2, $\{[\frac{\mathrm{d}x}{x}], [\mathrm{d}x], [x\mathrm{d}x]\}$ is a K-basis of $H^1(X_K, \omega)$. Through the isomorphism $H^1(X_K, \omega) \simeq R/J$ of Theorem 2.2, it corresponds to a set $\{[1], [\sigma_{\nu}], [\sigma_{\nu}^2]\} \subset R/J$. On the other hand, Corollary 3.2 implies that the set

 $\{[1], [\sigma_{\nu}], [\sigma_{\nu}^2]\}$ is a free basis of $R_{\delta}/J_{\delta} \simeq H^1(X_{\delta}, \omega_{\delta})$. The representation matrix of the $K[\![\delta]\!]$ -linear map $\sigma_{\nu}: H^1(X_{\delta}, \omega_{\delta}) \to H^1(X_{\delta}, \omega_{\delta})$ is given by

$$\begin{pmatrix}
0 & 0 & \frac{\nu}{\nu - 3s + 3\delta} \\
1 & 0 & 0 \\
0 & 1 & 0
\end{pmatrix}.$$
(30)

We will show how to compute such matrices in general in Section 5 (Algorithm 2). Taking the limit $\delta \to 0$ in (30), the matrix (30) converges to the representation matrix of the multiplication map $\mathcal{O}(X_K)/I_K \to \mathcal{O}(X_K)/I_K$ which sends $[g]_{I_K}$ to $[x \cdot g]_{I_K}$, with respect to the basis $\{[1]_{I_K}, [x]_{I_K}, [x^2]_{I_K}\}$. The eigenvalues of this matrix for $\delta \to 0$ are solutions to the likelihood equation $\omega = 0$, see Theorem 5.1.

4 Perfect pairings

A main goal in this paper is to compare $H^n(X,\omega)$ to the likelihood quotient $\mathcal{O}(X)/I$. This section illustrates how the degeneration in Section 3 turns certain bilinear pairings between $H^n(X,\omega)$ and its dual into pairings between $\mathcal{O}(X)/I$ and its dual. On the non-commutative side, i.e. the side of $H^n(X,\omega)$, we will discuss *period pairings* and *intersection pairings*. When $\delta \to 0$, these turn into *evaluation pairings* and *Grothendieck residue pairings* respectively.

4.1 Period pairing

Dual to the twisted cohomology $H^n(X,\omega) = H^n(X_{\mathbb{C}},\omega)$ is the twisted homology $H_n(X,-\omega)$. Its elements $[\Gamma] \in H_n(X,-\omega)$ are twisted cycles. A representative Γ of $[\Gamma]$ is a singular cycle, together with a choice of a branch of the likelihood function L(x) on Γ . The minus sign in the notation $H_n(X,-\omega)$ is justified by the observation that these branches are local solutions ϕ to the differential equation $\nabla_{-\omega}(\phi) = (\mathrm{d} - \omega \wedge)\phi = 0$. See $[2, \mathrm{Chapter}\ 2]$, or $[1, \mathrm{Section}\ 2]$ for more details. The period pairing between cohomology and homology leads to the generalized Euler integrals mentioned in the introduction, including marginal likelihood integrals and Feynman integrals. We denote this period pairing by $\langle \cdot, \cdot \rangle_{\mathrm{per}}^{\omega}$, and use the short notation $\langle g^+, \Gamma^- \rangle_{\mathrm{per}}^{\omega} = \langle [g^+]_V, [\Gamma^-] \rangle_{\mathrm{per}}^{\omega}$. The signs in this notation record the fact that cohomology is defined with the twist $+\omega \wedge$, and homology with $-\omega \wedge$. The definition of the period pairing is $\langle \cdot, \cdot \rangle_{\mathrm{per}}^{\omega} : H^n(X,\omega) \times H_n(X,-\omega) \to \mathbb{C}$, with

$$\langle g^+, \Gamma^- \rangle_{\text{per}}^{\omega} = \int_{\Gamma^-} g^+(x) \cdot L(x) \frac{\mathrm{d}x_1}{x_1} \wedge \dots \wedge \frac{\mathrm{d}x_n}{x_n}.$$
 (31)

Here the likelihood function $L(x) = f^{-s}x^{\nu}$ is as in (2), and the dependence on ω is through $L = \exp(\int \omega)$. Note that $\langle \cdot, \cdot \rangle_{\text{per}}^{\omega}$ is a \mathbb{C} -bilinear map on $H^n(X, \omega) \times H_n(X, -\omega)$. The period pairing is *perfect*, meaning that it identifies $H^n(X, \omega)$ as the vector space dual of $H_n(X, -\omega)$, and vice versa. Throughout the section, when we work over \mathbb{C} , we assume genericity of s, ν as in Definition 1, and we set $\chi = (-1)^n \cdot \chi(X)$. When a basis $[\beta_1^+]_V, \ldots, [\beta_{\chi}^+]_V$ for $H^n(X, \omega)$

and a basis $[\Gamma_1^-], \ldots, [\Gamma_{\chi}^-]$ for $H_n(X, -\omega)$ are fixed, the period pairing is represented by a square matrix $P(\omega)$ of size $\chi \times \chi$, see Theorem 2.1. Its entries are

$$P(\omega)_{ij} = \langle b_i^+, \Gamma_j^- \rangle_{\text{per}}^{\omega}$$

Flipping the sign of ω in cohomology and homology, we also have a period pairing $\langle \cdot, \cdot \rangle_{\text{per}}^{-\omega}$: $H^n(X, -\omega) \times H_n(X, \omega) \to \mathbb{C}$, so that the formula for $\langle g^-, \Gamma^+ \rangle_{\text{per}}^{-\omega}$ is similar to (31):

$$\langle g^-, \Gamma^+ \rangle_{\text{per}}^{-\omega} = \int_{\Gamma^+} g^-(x) \cdot L(x)^{-1} \frac{\mathrm{d}x_1}{x_1} \wedge \dots \wedge \frac{\mathrm{d}x_n}{x_n}. \tag{32}$$

Here $[g^-]_{V(-\omega)} \in H^n(X, -\omega)$, where $V(-\omega) \simeq \nabla_{-\omega}(\Omega^{n-1}(X))$ is defined for $-\omega$ as V was defined for ω , $\Gamma^+ \in H_n(X, \omega)$ and L(x) is as in (2). We fix a basis $[\beta_1^-]_{V(-\omega)}, \ldots, [\beta_{\chi}^-]_{V(-\omega)}$ for $H^n(X, -\omega)$ and a basis $[\Gamma_1^+], \ldots, [\Gamma_{\chi}^+]$ for $H_n(X, \omega)$ to obtain a matrix $P(-\omega)_{ij} = \langle b_i^-, \Gamma_j^+ \rangle_{\text{per}}^{-\omega}$.

4.2 Lefschetz thimbles and intersection pairing

We will now fix basis cycles Γ_j^- and Γ_j^+ , using a construction from Morse theory. The cycles we will use are called *Lefschetz thimbles* or *Lagrangian cycles*. This works nicely under some mild assumptions on L(x), which we will now specify. Let

$$\operatorname{Hess}(x) = \det \left(\frac{\partial^2 \log L(x)}{\partial x_i \partial x_j} \right)$$

be the Hessian determinant of $\log L(x)$. Equivalently, $\operatorname{Hess}(x)$ is the Jacobian determinant of the n generators in (18). Let $\log L(x) = G(x) + \sqrt{-1} \cdot H(x)$, with G and H real valued.

Assumption 1. The parameters s, ν are generic in the sense of Definition 1. The log-likelihood function $\log L(x)$ has χ critical points $x^{(1)}, \ldots, x^{(\chi)}$, and $h_j = \operatorname{Hess}(x^{(j)}) \neq 0$ for $j = 1, \ldots, \chi$. Moreover, the values $H(x^{(j)}), j = 1, \ldots, \chi$ are distinct, and so are the $G(x^{(j)})$.

This gives a notion of genericity for s, ν which is slightly stronger than Definition 1. We will make Assumption 1 throughout the rest of the section. The construction of the Lefschetz thimbles is classical, but quite technical. It is explained at length in [2, Section 4.3]. The summary is as follows. By the Cauchy-Riemann equations, the real critical points of $(u, v) \mapsto G(u + \sqrt{-1} \cdot v)$ coincide with the complex critical points $x = u + \sqrt{-1} \cdot v$ of $\log L(x)$. We denote these critical points by $x^{(1)}, \ldots, x^{(\chi)}$. The function G defines a vector field on X which is a slight modification of its gradient field [2, §4.3.4]. Along trajectories x(t) of this field, G increases and H is constant:

$$\frac{\mathrm{d}G(x(t))}{\mathrm{d}t} > 0, \quad \frac{\mathrm{d}H(x(t))}{\mathrm{d}t} = 0. \tag{33}$$

For each critical point $x^{(j)}$, the Lefschetz thimbles Γ_j^- and Γ_j^+ are unions of trajectories:

$$\Gamma_j^{\mp} = \left\{ x_0 \in X : \text{the trajectory } x(t) \text{ with } x(0) = x_0 \text{ satisfies } \lim_{t \to \pm \infty} x(t) = x^{(j)} \right\}.$$

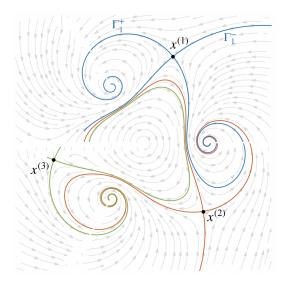


Figure 1: Lefschetz thimbles for the data from (34).

Both Γ_j^- and Γ_j^+ are *n*-dimensional real manifolds containing $x^{(j)}$. By (33) and Assumption 1, they do not contain any of the other critical points $x^{(i)}, i \neq j$. When restricted to Γ_j^- (Γ_j^+), G reaches a maximum (minimum) at $x^{(j)}$, and tends to $-\infty$ ($+\infty$) away from $x^{(j)}$. Intuitively, this explains why the integrals (31) and (32) converge when $\Gamma^{\mp} = \Gamma_j^{\mp}$.

Example 4.1 (n = 1). Figure 1 visualizes (part of) the Lefschetz thimbles for the data

$$n = \ell = 1,$$
 $f = 1 - x^3,$ $s = 1/2 + 3\sqrt{-1},$ $\nu = 1/7 + 7\sqrt{-1}.$ (34)

The Mathematica code used to generate this picture is available at https://mathrepo.mis.mpg.de/TwistedCohomology. The Euler characteristic of X is $\chi(X) = -\chi = -3$. The three critical points of $\log L(x)$ are the black dots in the picture. The thimbles Γ_j^+ and Γ_j^- are shown in the same color (blue, orange or green), for j=1,2,3. They are flow lines of a vector field that is a scaled version of the gradient field of $G(x) = \text{Re}(\log f^{-s}x^{\nu})$ [2, §4.3.4], visualized in the background of the figure. The points flowing towards/away from the critical point are Γ_j^-/Γ_j^+ . We plotted this using ContourPlot on the imaginary part H(x), see (33). This is tricky because H is multi-valued. Figure 1 shows the level lines $\{H(x) = H(x^{(j)}) + k \cdot \pi\}$, for a few integer values of k.

To turn our Lefschetz thimbles into twisted cycles, we need to choose which branch of our multi-valued likelihood function L to integrate in (31) and (32). We do this by selecting a value $L(x_0)^{\pm 1}$ at some $x_0 \in \Gamma_j^{\pm}$, and analytically continuing along x(t) for $t \in \mathbb{R}$.

Lemma 4.1. Under Assumption 1, the Lefschetz thimbles $[\Gamma_i^{\pm}]$ form a basis for $H_n(X, \pm \omega)$.

Proof. Under Assumption 1, we have $\dim_{\mathbb{C}} H_n(X, \pm \omega) = \chi$. By the discussion preceding [2, Theorem 4.7], the Lefschetz thimbles generate $H_n(X, \pm \omega)$. This implies the Lemma.

One of the advantages of using Lefschetz thimbles as a basis for twisted homology is that it gives an easy formula for the *intersection pairing* between the cohomology spaces $H^n(X,\omega)$ and $H^n(X,-\omega)$. This is a bilinear map $\langle \cdot,\cdot \rangle_{\mathrm{ch}}: H^n(X,\omega) \times H^n(X,-\omega) \to \mathbb{C}$ with

$$\langle g^+, g^- \rangle_{\text{ch}}^{\omega} = \sum_{j=1}^{\chi} \langle g^+, \Gamma_j^- \rangle_{\text{per}}^{\omega} \cdot \langle g^-, \Gamma_j^+ \rangle_{\text{per}}^{-\omega}.$$
 (35)

This formula is a special instance of [18, Equation (2.1)] and [20, Equation (18)], which holds when Lefschetz thimbles are used as bases for homology. Just like the period pairing, the intersection pairing is perfect. It has gained recent interest in physics, as it turns out to compute scattering amplitudes in some special cases [20]. It follows from the formula (35) that the matrix $Q(\omega)$ of $\langle \cdot, \cdot \rangle_{\text{ch}}^{\omega}$, using the (arbitrary) bases β_i^+, β_i^- for cohomology as above, is $Q(\omega) = P(\omega) \cdot P(-\omega)^\top$. We also point out the following shift relations:

$$\langle f_i^{-1}g^+, f_ig^-\rangle_{\mathrm{ch}}^{\omega(s,\nu)} = \langle g^+, g^-\rangle_{\mathrm{ch}}^{\omega(s+e_i,\nu)}, \quad \langle x_jg^+, x_j^{-1}g^-\rangle_{\mathrm{ch}}^{\omega(s,\nu)} = \langle g^+, g^-\rangle_{\mathrm{ch}}^{\omega(s,\nu+e_j)}, \quad (36)$$

which will be useful later. Here $\omega(s,\nu)$ emphasizes the dependence of ω on s,ν .

4.3 Intersection pairing over K

While twisted homology is only defined over \mathbb{C} , previous sections have used purely algebraic descriptions of $H^n(X_A, \omega)$ over different rings A. This subsection discusses the cohomology intersection pairing $\langle \cdot, \cdot \rangle_{\text{ch}}^{\omega}$ over the field $K = \mathbb{C}(s, \nu)$. Our first result says that the function $(s, \nu) \mapsto \langle g^+, g^- \rangle_{\text{ch}}^{\omega(s, \nu)}$ belongs to K.

Proposition 4.1. For $g^{\pm} \in H^n(X, \pm \omega)$, the function $(s, \nu) \mapsto \langle g^+, g^- \rangle_{\mathrm{ch}}^{\omega(s, \nu)}$ is rational.

Proof. Recall that Serre's duality pairing is a composition

$$H^0(\bar{X}, \Omega^n_{\log}(kD)) \times H^n(\bar{X}, \mathcal{O}_{\bar{X}}(-(k+1)D)) \xrightarrow{\cup} H^n(\bar{X}, \Omega^n_{\bar{X}}) \xrightarrow{\operatorname{tr}} \mathbb{C}$$
 (37)

of the *cup product* \cup and the *trace map* tr [11, Chapter 3, §7]. By the degeneration of the spectral sequence (8) in Lemma 2.1, we obtain the following representations of $H^n(X, \pm \omega)$:

$$H^{n}(X,\omega) = \frac{H^{0}(\bar{X},\Omega_{\log}^{n}(kD))}{\operatorname{im}\left(\nabla_{\omega}: H^{0}(\bar{X},\Omega_{\log}^{n-1}(kD)) \to H^{0}(\bar{X},\Omega_{\log}^{n}(kD))\right)},$$

$$H^{n}(X,-\omega) = \ker\left(\nabla_{-\omega}: H^{n}(\bar{X},\mathcal{O}_{\bar{X}}(-(k+1)D)) \to H^{n}(\bar{X},\Omega_{\log}^{1}(-(k+1)D))\right).$$
(38)

Via (38), Serre duality (37) induces a bilinear pairing $H^n(X,\omega) \times H^n(X,-\omega) \to \mathbb{C}$, which is identical to $\langle \cdot, \cdot \rangle_{\mathrm{ch}}^{\omega}$ [18, Eq. (2.3)]. This construction works over $K = \mathbb{C}(s,\nu)$, as Serre duality holds for any projective scheme defined over a field. The K-valued pairing

$$\langle \cdot, \cdot \rangle_{\mathrm{ch},K}^{\omega} : H^n(X_K, \omega) \times H^n(X_K, -\omega) \to K$$
 (39)

obtained from Serre duality specializes to $\langle \cdot, \cdot \rangle_{\mathrm{ch}}^{\omega}$ for s, ν generic as in Definition 1.

The cohomology intersection pairing $\langle \cdot, \cdot \rangle_{\operatorname{ch},K}^{\omega}$ over K is distinguished from other perfect pairings by its compatibility with the R-action on twisted cohomology groups, where R is the ring of difference operators from (11). The rest of this subsection makes this statement precise. We define another action \bullet_{-} of R on $\mathcal{O}(X_K)$, slightly different from (12):

$$\sigma_{s_i} \bullet_- g(s, \nu) = f_i \cdot g(s + e_i, \nu), \quad \sigma_{\nu_i} \bullet_- g(s, \nu) = x_i^{-1} \cdot g(s, \nu + e_i). \tag{40}$$

As in the discussion around (12), the action (40) induces an R-action on $H^n(X_K, -\omega)$. The ring R also acts on K via the shifts $\sigma_{s_i} \bullet a(s, \nu) = a(s + e_i, \nu)$ and $\sigma_{\nu_j} \bullet a(s, \nu) = a(s, \nu + e_j)$. A K-bilinear pairing $\langle \cdot, \cdot \rangle : H^n(X_K, \omega) \times H^n(X_K, -\omega) \to K$ is compatible with R if

$$\langle \sigma \bullet [g_+], \sigma \bullet_- [g_-] \rangle = \sigma \bullet \langle [g_+], [g_-] \rangle \tag{41}$$

holds for any $[g_{\pm}] \in H^n(X_K, \pm \omega)$ and $\sigma = \sigma_{s_i}, \sigma_{\nu_j}$. Here is a K-version of (36).

Proposition 4.2. The cohomology intersection pairing (39) is compatible with R.

Proof. Let us write $[\xi_{\pm}(s,\nu)] \in H^n(X_K,\pm\omega)$ for the cohomology classes in the right-hand side of (38). Then, $\sigma_{s_i} \bullet [\xi_+(s,\nu)]$ (resp. $\sigma_{s_i} \bullet_- [\xi_-(s,\nu)]$) is represented by a cohomology class $[f_i^{-1}\xi_+(s+e_i,\nu)] \in H^0(\bar{X}_K,\Omega^n_{\log}(kD-\operatorname{div}f_i))$ (resp. $[f_i\xi_-(s+e_i,\nu)] \in H^n(\bar{X}_K,\mathcal{O}_{\bar{X}_K}(-(k+1)D+\operatorname{div}f_i))$). Here, $\operatorname{div}f_i$ denotes the divisor of f_i viewed as a rational function on \bar{X}_K . We obtain a sequence of identities

$$\langle \sigma_{s_{i}} \bullet [\xi_{+}(s,\nu)], \sigma_{s_{i}} \bullet_{-} [\xi_{-}(s,\nu)] \rangle_{\text{ch},K}^{\omega} = \text{tr}([f_{i}^{-1}\xi_{+}(s+e_{i},\nu)] \cup [f_{i}\xi_{-}(s+e_{i},\nu)])$$

$$= \text{tr}([\xi_{+}(s+e_{i},\nu)] \cup [\xi_{-}(s+e_{i},\nu)])$$

$$= \sigma_{s_{i}} \bullet \text{tr}([\xi_{+}(s,\nu)] \cup [\xi_{-}(s,\nu)])$$

$$= \sigma_{s_{i}} \bullet \langle [\xi_{+}(s,\nu)], [\xi_{-}(s,\nu)] \rangle_{\text{ch},K}^{\omega}.$$

Theorem 4.1. Up to a non-zero scalar multiplication by \mathbb{C} , $\langle \cdot, \cdot \rangle_{\mathrm{ch},K}^{\omega}$ is the unique perfect K-bilinear pairing $\langle \cdot, \cdot \rangle : H^n(X, \omega) \times H^n(X, -\omega) \to K$ compatible with R.

Our proof of Theorem 4.1 uses the following Lemma.

Lemma 4.2. Let N be a left R-module that is finite dimensional over K. If N is a simple R-module, then the dimension of $\operatorname{End}_R(N)$ over $\mathbb C$ is 1.

Proof. Let $\varphi \in \operatorname{End}_R(N)$. Writing \bar{K} for the algebraic closure of K, the action of R on K extends to that on \bar{K} . Thus, we may regard φ as an element of $\operatorname{End}_{\bar{K} \otimes_K R}(\bar{N})$ where we set $\bar{N} := \bar{K} \otimes_K N$. We first prove that any eigenvalue of φ is in \mathbb{C} . Let us take an eigenvector $v \in \bar{N}$ of φ . It is straightforward to see that $\sigma_{s_1}^i v$ is an eigenvector with eigenvalue $\sigma_{s_1}^i \alpha$. Therefore, there exists an integer i so that $\sigma_{s_1}^i \alpha = \alpha$. Similarly, we can prove that α is periodic for all $s_1, \ldots, s_\ell, \nu_1, \ldots, \nu_n$. Since such a function $\alpha \in \bar{K}$ must be a constant function, it must belong to \mathbb{C} . Now, suppose that $\dim_{\mathbb{C}} \operatorname{End}_R(N) \geq 2$ and take a morphism $\varphi \in \operatorname{End}_R(N)$ linearly independent from id_N over \mathbb{C} . For any eigenvalue $\alpha \in \mathbb{C}$ of φ , $\alpha \cdot \operatorname{id}_N - \varphi$ has a non-trivial kernel, which is a non-trivial R-submodule of N. This is a contradiction.

Proof of Theorem 4.1. By Kashiwara's equivalence [5, Chapter VI, Theorem 7.13], the local cohomology group M defined by (14) is a simple $D_{\ell+n,\mathbb{C}}$ -module. It follows from [16, Theorem 1.2.1] that $H^n(X_K,\omega)$ is a simple R-module. Any pair of K-bilinear pairings $\langle \cdot, \cdot \rangle, \langle \cdot, \cdot \rangle' : H^n(X_K,\omega) \times H^n(X_K,-\omega) \to K$ compatible with R gives rise to an R-morphism $H^n(X_K,\omega) \to H^n(X_K,\omega)$. Now, the theorem follows from Lemma 4.2.

4.4 Degeneration of pairings

We now turn to perfect pairings for the likelihood quotient $\mathcal{O}(X)/I$. The dual vector space $(\mathcal{O}(X)/I)^{\vee}$ consists of all linear functionals on $\mathcal{O}(X)$ which vanish on the likelihood ideal I. The evaluation pairing $\langle \cdot, \cdot \rangle_{\text{ev}} : \mathcal{O}(X)/I \times (\mathcal{O}(X)/I)^{\vee} \to \mathbb{C}$ is given by

$$\langle q, v \rangle_{\text{ev}} = v(q).$$

Here g is short for $[g]_I$, and $v \in (\mathcal{O}(X)/I)^{\vee}$ is such that v(I) = 0. A canonical basis of $(\mathcal{O}(X)/I)^{\vee}$ is v_1, \ldots, v_{χ} , where $v_j(g) = g(x^{(j)})/\sqrt{\eta_j}$ represents evaluation at the j-th critical point. This is normalized by $\sqrt{\eta_j} = \sqrt{\operatorname{Hess}(x^{(j)})}$. Together with a basis $[\beta_1]_I, \ldots, [\beta_{\chi}]_I$ of the likelihood quotient, the evaluation pairing has a matrix representation $E_{ij} = \langle \beta_i, v_j \rangle_{\text{ev}} = \beta_i(x^{(j)})/\sqrt{\eta_j}$. Since the evaluation pairing is perfect, this matrix is invertible.

In analogy with $Q(\omega) = P(\omega) \cdot P(-\omega)^{\top}$, we can also consider the bilinear map represented by the matrix $G = E \cdot E^{\top}$. This is the *Grothendieck residue pairing* $\langle \cdot, \cdot \rangle_{res}$, given by

$$\mathcal{O}(X)/I \times \mathcal{O}(X)/I \to \mathbb{C}$$
, with $\langle g, h \rangle_{\text{res}} = \sum_{j=1}^{\chi} \langle g, v_j \rangle_{\text{ev}} \cdot \langle h, v_j \rangle_{\text{ev}} = \sum_{j=1}^{\chi} \frac{g(x^{(j)})h(x^{(j)})}{\eta_j}$.

We are now ready to bring in our deformation parameter δ . In Section 3, we did this by replacing ∇_{ω} with ∇_{ω}^{δ} . As we have seen in the proof of Theorem 1.2, this is equivalent to replacing ω with ω/δ . Here is what this looks like for our period pairings:

$$\langle g^{\pm}, \Gamma^{\mp} \rangle_{\mathrm{per}}^{\pm \omega/\delta} = \int_{\Gamma^{\mp}} g^{\pm}(x) \cdot L(x)^{\pm \frac{1}{\delta}} \frac{\mathrm{d}x_1}{x_1} \wedge \dots \wedge \frac{\mathrm{d}x_n}{x_n}.$$

We view this as a function of δ . If Γ_j^- is a Lefschetz thimble, $\log L(x)^{\pm \frac{1}{\delta}}$ has constant imaginary part, and its real part reaches a maximum at $x^{(j)}$, see (33). When $\delta \to 0$, this maximum value at $x^{(j)}$ grows, and the contribution of the rest of the integration contour is more and more suppressed. This is the intuition behind the Proposition 4.3, which roughly says that for $\delta \to 0$, integration over the Lefschetz thimble turns into evaluation at $x^{(j)}$.

Proposition 4.3. Let Γ_j^{\mp} be the Lefschetz thimbles associated to the j-th critical point $x^{(j)}$ of $\log L(x)$. Under Assumption 1, we have the following formulae as $\delta \to 0$:

$$\langle g^+, \Gamma_i^- \rangle_{\text{per}}^{\omega/\delta} = (-2\pi\delta)^{\frac{n}{2}} \cdot e^{\frac{1}{\delta} \log L(x^{(j)})} \cdot \langle g^+, v_j \rangle_{\text{ev}} \cdot (1 + O(\delta)), \tag{42}$$

$$\langle g^{-}, \Gamma_{j}^{+} \rangle_{\text{per}}^{-\omega/\delta} = (-2\pi\delta)^{\frac{n}{2}} (\sqrt{-1})^{-n} \cdot e^{-\frac{1}{\delta} \log L(x^{(j)})} \cdot \langle g^{-}, v_{j} \rangle_{\text{ev}} \cdot (1 + O(\delta)). \tag{43}$$

Similarly, for the cohomology intersection pairing, we have

$$\langle g^+, g^- \rangle_{\rm ch}^{\omega/\delta} = (2\pi\sqrt{-1}\delta)^n \cdot \langle g^+, g^- \rangle_{\rm res} \cdot (1 + O(\delta)). \tag{44}$$

Proof. The formulae (42)-(43) follow from stationary phase approximation [10, Chapter I]. Equation (44) follows from (35) and (42)-(43). It appears in [18, Theorem 2.4].

Propositions 4.1 and 4.3 lead to a proof of Theorem 1.1:

Proof of Theorem 1.1. Let $[\beta_1]_I, \ldots, [\beta_{\chi}]_I$ be a basis for the likelihood quotient $\mathcal{O}(X)/I$, and let $P(\pm \omega/\delta)_{ij} = \langle \beta_i, \Gamma_j^{\mp} \rangle_{\mathrm{per}}^{\pm \omega/\delta}$ be the period pairing matrices. Proposition 4.3 implies

$$Q(\omega/\delta) = P(\omega/\delta) \cdot P(\omega/\delta)^{\top} = (2\pi\sqrt{-1}\delta)^n \cdot G \cdot (1 + O(\delta)).$$

Since the $[\beta_i]_I$ are a basis, the matrix G is invertible, and hence also $Q(\omega/\delta)$ is invertible for $\delta \to 0$. Since the entries of $Q(\omega/\delta)$ are rational functions of δ , see Proposition 4.1, this implies that the classes of the β_i form a basis for $H^n(X, \pm \omega/\delta)$, for almost all $\delta \in \mathbb{C}$.

Preferably, we would like to use $\delta = 1$ in Theorem 1.1. Unfortunately, for this, genericity of s, ν in the sense of Assumption 1 is not enough. Here is an example.

Example 4.2. Let n=1 and f(x)=1-x. The Euler characteristic of X is -1. Genericity in Definition 1 means $\nu, -s, s-\nu \notin \mathbb{Z}$. These three linear forms correspond to the three boundary points $\{0\}, \{1\}, \{\infty\}$ in the compactification $X \subset \mathbb{P}^1$. In $H^1(X, \omega)$, we have

$$\left[\frac{x+1}{x^2}\right]_{V(\omega)} = \left[\left(\frac{2\nu - s - 1}{\nu - 1}\right)\right]_{V(\omega)}.$$
 (45)

If $\nu = 1/4$, s = -1/2, (45) implies that this is not a basis for $H^1(X, \omega)$. However, $\left[\frac{x+1}{x^2}\right]_I$ is a basis of $\mathcal{O}(X)/I$. Still, $\left[\frac{x+1}{x^2}\right]_{V(\omega/\delta)} \in H^1(X, \omega/\delta)$ is a basis for generic δ .

Remark 4.1. We can set $\delta = 1$ if we make a stronger genericity assumption on s, ν . In addition to Assumption 1, we assume that $\det Q(\omega(s,\nu))$ is neither 0 nor ∞ at s,ν . Here $Q(\omega(s,\nu)) \in K^{\times \times}$ is the matrix of rational functions in s,ν which represents the cohomology intersection pairing for the functions $\beta_i^{\pm} = \beta_i$ from Theorem 1.1, see Proposition 4.1. Its determinant is a nonzero rational function, because $Q(\omega(s/\delta,\nu/\delta))$ is given by (44).

5 Bases for cohomology and contiguity matrices

This section is about computation. First, we show how to compute a basis for $H^n(X_K, \omega)$. By Theorem 1.2, it suffices to compute a subset of $\mathcal{O}(X_K)$ which represents a constant basis of $\mathcal{O}(X_K)/I_K$ in the sense of Definition 3. Our strategy relies on numerical computation. It is based on some heuristics. However, in practice, it is highly reliable and effective.

We start by plugging in generic complex values of s and ν in the likelihood function L(x) from (2). We then solve $\omega = \operatorname{dlog} L(x) = 0$ numerically, using the homotopy continuation technique explained in [1, Section 5]. This reliably computes all $\chi = (-1)^n \cdot \chi(X)$ complex critical points, even for large Euler characteristics. See [26] for an example with $\chi = 3628800$. A list of regular functions $\beta_1, \ldots, \beta_{\chi} \in \mathcal{O}(X)$ gives a basis of $\mathcal{O}(X)/I$ if and only if the evaluation pairing from Section 4.4 gives an invertible $\chi \times \chi$ -matrix $E_{ij} = \langle \beta_i, v_j \rangle_{\text{ev}}$. Algorithm 1 exploits this observation. It takes the likelihood equations as input, as well as

a list $\mathcal{G} \subset \mathcal{O}(X)$ of constant regular functions. The output is a subset of \mathcal{G} that is maximal independent in $\mathcal{O}(X_K)/I_K$, i.e. it has the largest possible cardinality such that its elements are K-linearly independent mod I_K . One strategy to generate \mathcal{G} is as follows. For fixed $d \geq 1$, we set $\mathcal{G}_d = \{f^{-a}x^b\}_{|a|+|b|\leq d}$, with $|a| = a_1 + \cdots + a_\ell$, $a_i \geq 0$, and similarly for b. If the list returned by Algorithm 1 for $\mathcal{G} = \mathcal{G}_d$ contains $m < \chi$ elements, then \mathcal{G}_d does not contain a basis. In that case, we increase d and repeat. We note that $\mathcal{O}(X_K)/I_K$ is spanned by the union $\bigcup_{d=0}^{\infty} \mathcal{G}_d$. Both the computation of the critical points and the rank tests in this algorithm are numerical, but this works well in practice.

Algorithm 1 Compute a maximal independent subset of constant functions mod I_K

```
Input: \omega(s,\nu) = \operatorname{dlog} L(x), \ \mathcal{G} = \{g_1,\ldots,g_N\} \subset \mathcal{O}(X), \ g_1 \notin I_K
Output: \{\beta_1,\ldots,\beta_m\} \subset \mathcal{G} such that [\beta_1]_{I_K},\ldots,[\beta_m]_{I_K} is maximal independent \omega \leftarrow \omega(s^*,\nu^*) for generic complex s^*,\nu^* \{x^{(1)},\ldots,x^{(\chi)}\} \leftarrow solutions of \omega(x)=0
E \leftarrow the row vector (g_1(x^{(j)}))_{j=1,\ldots,\chi}
\beta_1 \leftarrow g_1, \ell \leftarrow 2, k \leftarrow 2
while \operatorname{rank}(E) < \chi and k \leq N do
E' \leftarrow \operatorname{append} \text{ the row } (g_k(x^{(j)}))_{j=1,\ldots,\chi} \text{ to } E
if \operatorname{rank} E' > \operatorname{rank} E then
E \leftarrow E', \ \beta_\ell \leftarrow g_k, \ \ell \leftarrow \ell + 1
end if k \leftarrow k + 1
end while
\operatorname{return} \ \{\beta_1,\ldots,\beta_{\ell-1}\}
```

Next, our goal is to compute *contiguity matrices* for a given basis $[\beta_1]_{V_K}, \ldots, [\beta_{\chi}]_{V_K}$. These are $\chi \times \chi$ matrices with entries in K encoding how the difference operators $\sigma_{s_i}, \sigma_{\nu_j} \in R$ act on the basis elements. For instance, the contiguity matrix C_{s_1} satisfies

$$\sigma_{s_1} \bullet \begin{pmatrix} [\beta_1]_{V_K} \\ \vdots \\ [\beta_{\chi}]_{V_K} \end{pmatrix} = \begin{pmatrix} \sigma_{s_1} \bullet [\beta_1]_{V_K} \\ \vdots \\ \sigma_{s_1} \bullet [\beta_{\chi}]_{V_K} \end{pmatrix} = C_{s_1}(s, \nu) \cdot \begin{pmatrix} [\beta_1]_{V_K} \\ \vdots \\ [\beta_{\chi}]_{V_K} \end{pmatrix}.$$

Notice that, although the difference operators σ_{s_i} , σ_{ν_j} are pairwise commuting, the contiguity matrices are not. This is easily seen in an example:

$$\sigma_{s_i}\sigma_{\nu_j}\bullet[\beta]_{V_K}=\sigma_{s_i}\bullet C_{\nu_j}(s,\nu)\cdot[\beta]_{V_K}=C_{\nu_j}(s+e_i,\nu)\cdot(\sigma_{s_i}\bullet[\beta]_{V_K})=C_{\nu_j}(s+e_i,\nu)\cdot C_{s_i}(s,\nu)\cdot[\beta]_{V_K}$$

Here the second equality applies (11). Expanding this in the opposite order shows that

$$C_{\nu_i}(s + e_i, \nu) \cdot C_{s_i}(s, \nu) = C_{s_i}(s, \nu + e_j) \cdot C_{\nu_i}(s, \nu). \tag{46}$$

More generally, for $a, b \geq 0$, contiguity matrices can be used to compute $\sigma_s^a \sigma_\nu^b \bullet [\beta]_{V_K}$ via

$$\sigma_s^a \sigma_\nu^b \bullet [\beta]_{V_K} = \mathcal{C}_{\nu_n} \cdot \dots \cdot \mathcal{C}_{\nu_1} \cdot \mathcal{C}_{s_\ell} \cdot \dots \cdot \mathcal{C}_{s_1} \cdot [\beta]_{V_K}, \tag{47}$$

where the calligraphic C's denote the following ordered products of matrices:

$$C_{\nu_j} = \prod_{q=1}^{b_j} C_{\nu_j} (s + a, \nu + \sum_{k < j} b_k \cdot e_k + (b_j - q) \cdot e_j), \quad C_{s_i} = \prod_{q=1}^{a_i} C_{s_i} (s + \sum_{k < i} a_k \cdot e_k + (a_i - q) \cdot e_i, \nu).$$

Importantly, here, the order of the factors matters: $\prod_{q=1}^{m} C(q) := C(1)C(2)\cdots C(m)$. As in (46), there are many different ways to expand this as a product of contiguity matrices with shifts in s and ν . When a, b have negative entries, the formula changes slightly.

If the basis elements β_i are of the form $\beta_i = f^{-a_i}x^{b_i}$, which will be the case in our algorithm below, Equation (47) can easily be used to express any cohomology class $[g]_{V_K}$ as a K-linear combination of the basis elements in $[\beta]_{V_K}$. The coefficients c_i in $[f^{-a}x^b]_{V_K} = c_1 [\beta_1]_{V_K} + \cdots + c_{\chi} \cdot [\beta_{\chi}]_{V_K}$ are read from the i-th row of (47) for $\sigma_s^{a-a_i}\sigma_{\nu}^{b-b_i} \bullet [\beta]_{V_K}$.

We now turn to our algorithm for computing contiguity matrices. This uses Theorem 2.2, which says that $[f^{-a}x^b]_{V_K} = c_1 [\beta_1]_{V_K} + \cdots + c_{\chi} \cdot [\beta_{\chi}]_{V_K}$ is equivalent to

$$\sigma_s^a \sigma_\nu^b - \left(c_1 \, \sigma_s^{a_1} \sigma_\nu^{b_1} + \dots + c_\chi \, \sigma_s^{a_\chi} \sigma_\nu^{b_\chi} \right) \in J \subset R. \tag{48}$$

Let $B = \{\sigma_s^{a_i}\sigma_{\nu}^{b_i}, i = 1, ..., \chi\}$ be the difference operators corresponding to our cohomology basis $\{[f^{-a_i}x^{b_i}]_{V_K}, i = 1, ..., \chi\}$. Consider a larger, finite set E of difference operators of the form $\sigma_s^a\sigma_{\nu}^b$, containing B. It is easy to see that $J \cap \operatorname{span}_K(E)$ has dimension $|E \setminus B|$: a K-basis consists of one element of the form (48) for each $\sigma_s^a\sigma_{\nu}^b$ in $E \setminus B$. Since our goal is to compute the contiguity matrices C_{s_i}, C_{ν_i} , we will use a subspace $E \supset B$ containing

$$E_{s_i} = \sigma_{s_i} \bullet B, i = 1, \dots, \ell$$
 and $E_{\nu_j} = \sigma_{\nu_j} \bullet B, j = 1, \dots, n$.

It is convenient to ensure that the span of E contains the $\ell + n$ generators from (29). Let $E_{\rm gen}$ be the set of all monomials $\sigma_s^a \sigma_\nu^b$ that occur with a nonzero coefficient in (29). We set

$$E = B \cup E_{s_1} \cup \dots \cup E_{s_\ell} \cup E_{\nu_1} \cup \dots \cup E_{\nu_n} \cup E_{\text{gen}}. \tag{49}$$

Our goal is to compute a basis for $J \cap \operatorname{span}_K(E)$. We are given the subspace $\mathcal{V} \subset J \cap \operatorname{span}_K(E)$ generated by the $\ell + n$ generators of J. Very often, this is a strict inclusion, and we need to find more elements in $J \cap \operatorname{span}_K(E)$. To do this, we introduce the *plus operator* \cdot^+ , which is inspired by the *border basis* literature [22]. For a K-subspace $S \subset R$, we define

$$S^{+} = S + \sigma_{s_1} \bullet S + \dots + \sigma_{s_{\ell}} \bullet S + \sigma_{s_1}^{-1} \bullet S + \dots + \sigma_{s_{\ell}}^{-1} \bullet S,$$

and $S^{[k]}$ is $(\cdots ((S^+)^+ \cdots)^+$, where the plus operator is applied k times. Clearly, $\mathcal{V}^{[k]} \subset J$ for any k, and $\bigcup_{k=0}^{\infty} \mathcal{V}^{[k]} = J$. The ascending chain of subspaces

$$\mathcal{V} \subset \mathcal{V}^+ \cap \operatorname{span}_K(E) \subset \cdots \subset \mathcal{V}^{[k]} \cap \operatorname{span}_K(E) \subset \cdots$$
 (50)

of E stabilizes at finite $k = k^*$, and $\mathcal{V}^{[k^*]} \cap \operatorname{span}_K(E) = J \cap \operatorname{span}_K(E)$. A first, naive algorithm computes a basis for each vector space in the chain (50), until it detects that

 $\dim_K(\mathcal{V}^{[k]} \cap \operatorname{span}_K(E)) = |E \setminus B|$, which implies that $k = k^*$. This only involves linear algebra with matrices over K, as we now expain.

We start with some notation. Let $S_1, S_2 \subset R$ be finite subsets, such that the elements of S_2 are K-linearly independent and $S_1 \subset \operatorname{span}_K(S_2)$. We define a matrix $M(S_1, S_2) \in K^{|S_1| \times |S_2|}$ whose rows are indexed by S_1 , and the columns are indexed by S_2 . The row indexed by $s_1 \in S_1$ is given by the coefficients of the unique expansion of s_1 in terms of S_2 . That is, the entry in row $s_1 \in S_1$ and column $s_2 \in S_2$ has the coefficient c_{s_2} standing with s_2 in $s_1 = \sum_{s_2 \in S_2} c_{s_2} s_2$. The row space of $M(S_1, S_2)$ represents $\operatorname{span}_K(S_1) \subset \operatorname{span}_K(S_2)$. Finally, for a subset $S_2 \subset S_2$, $M(S_1, S_2)_{S_2}$ is the submatrix of columns indexed by S_2 .

Let $E^{[k]}$ be the monomial basis $\{\sigma_s^a \sigma_\nu^b \mid \sigma_s^a \sigma_\nu^b \in \operatorname{span}_K(E)^{[k]}\}$ of $\operatorname{span}_K(E)^{[k]}$ and let $V^{[k]}$ be a set of generators for $\mathcal{V}^{[k]}$. At the k-th step in the chain (50), we construct the matrix $M(V^{[k]}, E^{[k]})$. This represents $\mathcal{V}^{[k]} \subset \operatorname{span}_K(E)^{[k]}$. To intersect with $\operatorname{span}_K(E)$, we compute linear combinations of the rows which annihilate the entries in the columns $E^{[k]} \setminus E$. That is, we compute a cokernel (i.e. left nullspace) matrix L_k of $M(V^{[k]}, E^{[k]})_{E^{[k]} \setminus E}$. We have

$$L_k \cdot M(V^{[k]}, E^{[k]})_{E^{[k]} \setminus E} = 0$$
 and set $M_k = L_k \cdot M(V^{[k]}, E^{[k]})_E$. (51)

The following easy lemma states that M_k represents the k-th vector space in (50).

Lemma 5.1. The matrix M_k from (51) is $M(W^{[k]}, E)$, where $W^{[k]}$ generates $\mathcal{V}^{[k]} \cap \operatorname{span}_K(E)$.

Checking if $k = k^*$ amounts to checking that rank $M_k = |E \setminus B|$. One then replaces M_k by $|E \setminus B|$ of its rows which are linearly independent, and reads off the contiguity relations (48) from the rows of $(M_k)_{E \setminus B}^{-1} \cdot M_k$. The algorithm suggested by this discussion has the advantage that it is easy to explain and implement, but it has the disadvantage that it is not very efficient: the size of the set $E^{[k]}$ increases rapidly with k. In the rest of the section, we present an improvement which deals with smaller matrices. This will result in Algorithm 2.

Let $\mathcal{V} \subset \operatorname{span}_K(E)$ be as above and fix a positive integer k. We define a sequence $\mathcal{V} = \mathcal{V}_{k,0} \subset \mathcal{V}_{k,1} \subset \mathcal{V}_{k,2} \subset \cdots$ of subspaces of $\operatorname{span}_K(E)$ defined recursively as

$$\mathcal{V}_{k,q} = \mathcal{V}_{k,q-1}^{[k]} \cap \operatorname{span}_K(E).$$

This chain stabilizes at finite $q = q^*$, and $\mathcal{V}^{[k]} \cap \operatorname{span}_K(E) \subset \mathcal{V}_{k,q^*} \subset J \cap \operatorname{span}_K(E)$. The first inclusion is usually strict, i.e. $\mathcal{V}^{[k]} \cap \operatorname{span}_K(E) \subsetneq \mathcal{V}_{k,q^*}$. In fact, and most importantly, we often have $\mathcal{V}_{k,q^*} = J \cap \operatorname{span}_K(E)$ for $k < k^*$ (recall that k^* is the smallest k such that $\mathcal{V}^{[k]} \cap \operatorname{span}_K(E) = J \cap \operatorname{span}_K(E)$). It is computationally much less expensive to increase q than to increase k: $\mathcal{V}_{k,q}$ can be computed using matrices of the form $M(-, E^{[k]})$, for any q. Hence, this gives us a way to compute $J \cap \operatorname{span}_K(E)$ by working with smaller matrices.

We present the details of computing \mathcal{V}_{k,q^*} for fixed k. We do this by computing a matrix $M_{k,q^*} = M(V_{k,q^*}, E)$ where V_{k,q^*} is a set of generators of \mathcal{V}_{k,q^*} . This is done recursively, starting from $M(V_{k,0}, E)$, where $\mathcal{V}_{k,0} = \mathcal{V}$. Having computed $V_{k,q-1}$, we proceed by constructing $M(V_{k,q-1}^{[k]}, E^{[k]})$, where $V_{k,q-1}^{[k]}$ is a set of generators for $\mathcal{V}_{k,q-1}^{[k]}$ (which is easily computed from $V_{k,q-1}$). Similar to what we did in (51), we intersect with $\operatorname{span}_K(E)$ by computing the cokernel matrix $L_{k,q}$ of $M(V_{k,q-1}^{[k]}, E^{[k]})_{E^{[k]}\setminus E}$, and then setting

$$M_{k,q} = M(V_{k,q}, E) = L_{k,q} \cdot M(V_{k,q-1}^{[k]}, E^{[k]})_E.$$

The stopping criterion for the iteration is that $q = q^*$ if rank $M_{k,q+1} = \operatorname{rank} M_{k,q}$. It rank $M_{k,q^*} = \dim_K \mathcal{V}_{k,q^*} < |E \setminus B|$, we increase k and repeat. This is Algorithm 2.

Algorithm 2 Compute contiguity matrices with respect to a basis B

```
Input: B, a list of generators V of \mathcal{V}
Output: the contiguity matrices C_{s_1}, \ldots, C_{s_\ell}, C_{\nu_1}, \ldots, C_{\nu_n}
E \leftarrow \text{the set of monomials } \sigma_s^a \sigma_\nu^b \text{ from (49)}
k \leftarrow 0, r \leftarrow 0
while r < |E \setminus B| do
     k \leftarrow k+1, q \leftarrow 0, r \leftarrow 0
     M_{k,q} \leftarrow M(V,E) = M(V_{k,0},E)
     while r < \operatorname{rank} M_{k,q} < |E \setminus B| do
           r \leftarrow \operatorname{rank} M_{k,q}
           q \leftarrow q + 1
           L_{k,q} \leftarrow \text{cokernel matrix of } M(V_{k,q-1}^{[k]}, E^{[k]})_{E^{[k]} \setminus E}
           M_{k,q} \leftarrow L_{k,q} \cdot M(V_{k,q-1}^{[k]}, E^{[k]})_E = M(V_{k,q}, E)
     end while
end while
M_{k,q} \leftarrow \text{submatrix of } M_{k,q} \text{ consisting of rank } M_{k,q} \text{ linearly independent rows}
M_{k,q} \leftarrow (M_{k,q})_{E \setminus B}^{-1} \cdot M_{k,q}
for \alpha \in \{s_1, ..., s_{\ell}, \nu_1, ..., \nu_n\} do
     Construct C_{\alpha} by reading the contiguity relations for \sigma_{\alpha} \bullet B from the rows of M_{k,q}
end for
return C_{s_1}, \ldots, C_{s_\ell}, C_{\nu_1}, \ldots, C_{\nu_n}
```

Example 5.1. For the data in Example 3.2, we have $B = \{1, \sigma_{\nu}, \sigma_{\nu}^2\}$ and Equation (49) gives $E = \{\sigma_{\nu}^3, \sigma_s \sigma_{\nu}^2, \sigma_s \sigma_{\nu}, \sigma_s, \sigma_s \sigma_{\nu}^3, 1, \sigma_{\nu}, \sigma_{\nu}^2\}$. For k = 1, we find that $q^* = 2$ and $\mathcal{V}_{1,2} \cap \operatorname{span}_K(E) = J \cap \operatorname{span}_K(E)$ is represented by the row span of the following 5×8 matrix $M_{1,2} = M(V_{1,2}, E)$:

$$M_{1,2} = \begin{pmatrix} \frac{\sigma_{\nu}^{3}}{3s - \nu - 3} & \sigma_{s}\sigma_{\nu}^{2} & \sigma_{s}\sigma_{\nu} & \sigma_{s} & \sigma_{s}\sigma_{\nu}^{3} & 1 & \sigma_{\nu} & \sigma_{\nu}^{2} \\ \frac{3s - \nu - 3}{\nu} & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 3s & 0 & 0 & 0 & 0 & 0 & \nu - 3s + 2 \\ 0 & 0 & 1 & 0 & 0 & 0 & \frac{\nu - 3s + 1}{3s} & 0 \\ 0 & 0 & 0 & 1 & \frac{-\nu + 3s}{\nu} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & \frac{\nu - 3s}{3s} & 0 & 0 \end{pmatrix}.$$

Note that rank $M_{1,2} = 5 = |E \setminus B|$. The first row of $M_{1,2}$ reads $\nu^{-1}(3s - \nu - 3)\sigma_{\nu}^3 + 1 \in J$. By inverting the leftmost 5×5 submatrix, we compute C_{ν} in Example 6.1. It equals (30) transposed with $\delta = 1$. For q = 1, we have rank $M_{1,1} = 4$. Here $M_{1,1} = M_1$ from Lemma 5.1. The matrices used to compute $M_{1,2}$ have $|E^+| = |E^{[1]}| = 20$ columns. The naive algorithm implied by Lemma 5.1 requires to compute $M_2 = M_{2,1}$, using matrices of size $|E^{[2]}| = 36$. \diamond

We point out that there might be ways to make Algorithm 2 more efficient, but this is beyond the scope of the present paper. We also note that our algorithm is related to *Laporta's*

algorithm from particle physics [14], which is tailor-made for Feynman integrals. However, in [14] there is no mention of contiguity matrices, and the algorithm is more dependent on choices. We believe Algorithm 2 will provide a more systematic way of dealing with families of Feynman integrals, and generalized Euler integrals from [1].

We end the section with a link to degeneration. By the proof of Theorem 1.2, the set $\{[\beta_1]_{V_{K[\![\delta]\!]}},\ldots,[\beta_\chi]_{V_{K[\![\delta]\!]}}\}$ is a basis for $H^n(X_\delta,\omega_\delta)$ as a free $K[\![\delta]\!]$ -module. It is straightforward to define contiguity matrices for the R_δ -action on $H^n(X_\delta,\omega_\delta)$: the matrix $C_{\alpha,\delta}$ has entries in $K[\![\delta]\!]$ and satisfies $\sigma_\alpha \bullet [\beta]_{V_{K[\![\delta]\!]}} = C_{\alpha,\delta}(s,\nu,\delta) \cdot [\beta]_{V_{K[\![\delta]\!]}}$, for $\alpha \in \{s_1,\ldots,s_\ell,\nu_1,\ldots,\nu_n\}$. We set

$$C_{\alpha,\delta}(s,\nu,\delta) = C_{\alpha,\delta}(s,\nu)_0 + C_{\alpha,\delta}(s,\nu)_1 \cdot \delta + C_{\alpha,\delta}(s,\nu)_2 \cdot \delta^2 + \cdots$$

The matrix $C_{\alpha,\delta}(s,\nu,\delta)$ is related to $C_{\alpha}(s,\nu)$ by the relation

$$C_{\alpha,\delta}(s,\nu,\delta) = C_{\alpha}(s/\delta,\nu/\delta).$$

Let $[g]_{V_{K[\![\delta]\!]}} = \sum_{i=1}^{\chi} c_i \cdot [\beta_i]_{K[\![\delta]\!]}$ be the expansion of g in terms of the basis elements, and let $\lim_{\delta \to 0} [g]_{V_{K[\![\delta]\!]}} \in \mathcal{O}(X_K)/I_K$ be the image of $[g]_{V_{K[\![\delta]\!]}}$ under the limit map $H^n(X_\delta, \omega_\delta) \to \lim_{\delta \to 0} H^n(X_\delta, \omega_\delta) = \mathcal{O}(X_K)/I_K$ (see Lemma 3.1). One easily checks using (28) that

$$\lim_{\delta \to 0} \left(\sigma_{s_i} \bullet [g]_{V_{K[\delta]}} \right) = [f_i^{-1} g]_{I_K} = c_1' \cdot [\beta_1]_{I_K} + \dots + c_{\chi}' \cdot [\beta_{\chi}]_{I_K}, \tag{52}$$

where the vector of coefficients $c' = (c'_1, \ldots, c'_{\chi})^{\top} \in K^{\chi}$ is obtained as $C_{s_i, \delta}(s, \nu)_0^{\top} \cdot (c_1, \ldots, c_{\chi})^{\top}$. A similar relation for σ_{ν_j} leads to the following theorem.

Theorem 5.1. Let $\{\beta_i\}_{i=1}^{\chi}$ represent a constant basis for $\mathcal{O}(X_K)/I_K$. Let $C_{\alpha,\delta} \in K[\![\delta]\!]^{\chi \times \chi}$ be as above. The $\chi \times \chi$ matrices $C_{s_i,\delta}(s,\nu)_0^{\top}$ and $C_{\nu_j,\delta}(s,\nu)_0^{\top}$ with entries in K represent multiplication with f_i^{-1} , resp. x_j , in $\mathcal{O}(X_K)/I_K$, w.r.t. this basis. Their eigenvalues in the algebraic closure \bar{K} are the evaluations of f_i^{-1} , resp. x_j , at the χ solutions of $\omega(s,\nu) = 0$.

Proof. The claim about multiplication in the likelihood quotient $\mathcal{O}(X_K)/I_K$ follows from (52) and its analog for $\alpha = \nu_j$. The statement about eigenvalues follows from the *eigenvalue theorem* in computational algebraic geometry, see for instance [27, Theorem 3.1.1].

Remark 5.1. By Theorem 5.1, the matrices $M_{s_i} = C_{s_i,\delta}(s,\nu)_0^{\top}$ and $M_{\nu_i} = C_{\nu_j,\delta}(s,\nu)_0^{\top}$ are pairwise commuting. They share a set of eigenvectors [27, Theorem 3.1.1]. For a regular function $g = \sum_i c_i f^{-a_i} x^{b_i} \in \mathcal{O}(X_K)$, the eigenvalues of $M_g = \sum_i c_i M_s^{a_i} M_{\nu}^{b_i}$ are the evaluations of g at the solutions of g at the solutions of g at the solutions of g and g and g are section 4.

6 Computational examples

We have implemented Algorithms 1 and 2 in Julia (v1.8.3). Our code is available at https://mathrepo.mis.mpg.de/TwistedCohomology. The numerical solution of $\omega(x) = 0$ in Algorithm 1 relies on the package HomotopyContinuation.jl (v2.6.4) [6]. The symbolic computations in Algorithm 2 are done using Oscar.jl (v0.10.0) [23], and they require that

 f_i have rational coefficients. We tested our implementation for several low-dimensional very affine varieties X. This section describes these varieties, and the results. The output of Algorithm 2 consists of $n + \ell$ matrices of size $\chi \times \chi$. Most often, the size of the rational functions in their entries prohibits us from including this output in the paper. All output is available in the form of .txt files at https://mathrepo.mis.mpg.de/TwistedCohomology. We used a 16 GB MacBook Pro with an Intel Core i7 processor working at 2.6 GHz.

Example 6.1 (Third roots of unity). Let $n = 1, \ell = 1$ and let $f = 1 - x^3$ as in Examples 3.2, 4.1 and 5.1. We keep using the basis $B = \{1, \sigma_{\nu}, \sigma_{\nu}^2\}$. As mentioned in Example 5.1, we can work with k = 1, for which $q^* = 2$. The contiguity matrices are

$$C_{\nu} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ \frac{\nu}{\nu - 3s + 3} & 0 & 0 \end{pmatrix}, \quad C_{s} = \begin{pmatrix} \frac{-\nu + 3s}{3s} & 0 & 0 \\ 0 & \frac{-\nu + 3s - 1}{3s} & 0 \\ 0 & 0 & \frac{-\nu + 3s - 2}{3s} \end{pmatrix}.$$

This can be computed very fast. The same computation for $f = 1 - x^{50}$, using $B = \{1, \sigma_{\nu}, \sigma_{\nu}^{2}, \dots, \sigma_{\nu}^{49}\}$ takes about half a minute $(k = 1, q^{*} = 25)$. The reason for this efficiency is that the rational functions in the contiguity matrices are simple. When adding more terms to f, the computation time increases. Optimizing our implementation is left as future work. \diamond Example 6.2 (Five points on the line). We continue Example 2.2, where $X = \mathcal{M}_{0,5}$. This space and the associated generalized Euler integrals appear in physics in the context of five point string amplitudes, see [3, Equation (4.7)] and [20, Appendix A]. In the basis $B = \{1, \sigma_{\nu_1}\}$, we need k = 1 and $q^* = 2$ to compute the contiguity relations. We find that

$$C_{\nu_1} = \begin{pmatrix} 0 & 1 \\ r_1 & r_2 \end{pmatrix}, \quad C_{\nu_2} = \begin{pmatrix} \frac{\nu_1 + \nu_2 - s_3}{\nu_2 - s_2 - s_3 + 1} & \frac{-\nu_1 + s_1 + s_3 - 1}{\nu_2 - s_2 - s_3 + 1} \\ r_3 & r_4, \end{pmatrix}$$

where r_1, r_2, r_3, r_4 are the rational functions

$$r_{1} = \frac{\nu_{1}(-\nu_{1} - \nu_{2} + s_{3})}{(\nu_{1} - s_{1} - s_{3} + 2)(\nu_{1} + \nu_{2} - s_{1} - s_{2} - s_{3} + 2)},$$

$$r_{2} = \frac{\nu_{1}(2\nu_{1} + 2\nu_{2} - 2s_{1} - s_{2} - 3s_{3} + 4) - \nu_{2}(s_{1} + s_{3} - 2) + s_{3}(s_{1} + s_{2} + s_{3} - 3) - s_{1} - s_{2} + 2}{(\nu_{1} - s_{1} - s_{3} + 2)(\nu_{1} + \nu_{2} - s_{1} - s_{2} - s_{3} + 2)},$$

$$r_{3} = \frac{\nu_{1}(\nu_{1} + \nu_{2} - s_{3})}{(\nu_{2} - s_{2} - s_{3} + 1)(\nu_{1} + \nu_{2} - s_{1} - s_{2} - s_{3} + 2)},$$

$$r_{4} = \frac{\nu_{1}(-\nu_{1} + s_{1} + s_{3} - 1) + \nu_{2}(\nu_{2} - s_{2} - s_{3} + 1)}{(\nu_{2} - s_{2} - s_{3} + 1)(\nu_{1} + \nu_{2} - s_{1} - s_{2} - s_{3} + 2)}.$$

The algorithm also returns the matrices C_{s_1} , C_{s_2} , C_{s_3} , whose entries are slightly more complicated. While this runs in less than a second, the same computation for the three-dimensional moduli space $\mathcal{M}_{0,6}$ (with Euler characteristic -6) does not terminate within reasonable time. The parameters are $n=3, \ell=6$ and the f_i are the bottom two rows of [26, Equation (6)]. This is a nice computational challenge for future improvements of Algorithm 2. \Leftrightarrow Example 6.3 ($k \neq 1$). We set $n=2, \ell=1$ and consider $f=1+x^2+y^3+x^2y^3$. The Euler characteristic is 6. Algorithm 1 selects $B=\{1,\sigma_{\nu_2},\sigma^2_{\nu_2},\sigma_{\nu_1},\sigma_{\nu_1},\sigma_{\nu_1},\sigma_{\nu_2},\sigma^2_{\nu_2}\}$ among

all monomials of degree at most three. In this example, for k = 1, we have $q^* = 1$ and rank $M_{1,1} = 4 < |E \setminus B| = 14$. It suffices to increase k by 1: for k = 2, we find $q^* = 2$ and rank $M_{2,2} = 14$. The computation takes less than three seconds in total.

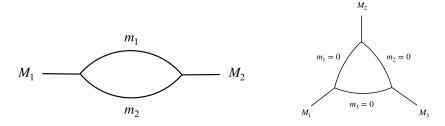


Figure 2: Massive bubble diagram and triangle diagram with zero internal masses.

Example 6.4 (Fermat hypersurfaces). This example uses $n=2,3,4,\ \ell=1$ and $f=x_1^d+\cdots+x_n^d-1$, for $d\geq 1$. The very affine variety X is the complement of a Fermat hypersurface in the n-dimensional torus. Its Euler characteristic is d^n . We use the basis $B=\{\sigma_{\nu_1}^{d_1}\cdots\sigma_{\nu_n}^{d_n}:0\leq d_i\leq d-1\}$. For n=2, we compute contiguity matrices for the Fermat curve of degree d=10 within less than five minutes. The matrices are obtained from M_{k,q^*} with $k=1,q^*=11$. For surfaces (n=3), the computation for d=4 runs in about five minutes, and the result is obtained for $k=1,q^*=8$. For $n=4,k=1,q^*=4$, it takes about 30 seconds to compute the five contiguity matrices for the quadratic threefold $x_1^2+x_2^2+x_3^2+x_4^2-1=0$.

Example 6.5 (Feynman integrals). Feynman integrals from physics are of the form (31). They are associated to a graph G, called Feynman diagram, which encodes particle interaction patterns. In this context $\ell = 1$, and the polynomial f in the likelihood function $L = f^s x^{\nu}$ is the graph polynomial associated to G. The graph polynomial is the sum of the first and second Symanzik polynomials of G. The number of variables is the number of internal edges f. Details are in [4, 15, 21]. Here, we apply our algorithm for two different graphs. Both are examples of one-loop diagrams [21, Section 2.5]. They are shown in Figure 2. The first one is known in physics as the bubble diagram. The very affine variety is the complement of

$$f_{\text{bubble}} = c_{11}x_1^2 + c_{12}x_1x_2 + c_{22}x_2^2 + x_1 + x_2 = 0$$

in $(\mathbb{C}^*)^2$, where the c_{ij} depend on masses and momenta. Here n=2, and the internal edges are those labeled m_1 , m_2 . We arbitrarily chose $(c_{11}, c_{12}, c_{22}) = (7, 12, 3)$. The Euler characteristic is $\chi(X) = 3$. With basis $B = \{1, \sigma_{\nu_1}, \sigma_{\nu_2}\}$, the contiguity matrices are found for $k = 1, q^* = 2$. The second diagram is the *triangle diagram* with massless internal particles:

$$f_{\text{triangle}} = c_{12}x_1x_2 + c_{13}x_1x_3 + c_{23}x_2x_3 + x_1 + x_2 + x_3.$$

The very affine variety X is a threefold, i.e. n=3. We set $(c_{12}, c_{13}, c_{23}) = (2, -6, -8)$. The Euler characteristic is -4. Our algorithm computes the $n+\ell=4$ contiguity matrices of size 4×4 within less than a second. We used $B = \{1, \sigma_{\nu_1}, \sigma_{\nu_2}, \sigma_{\nu_3}\}$, and $k=1, q^*=2$.

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