

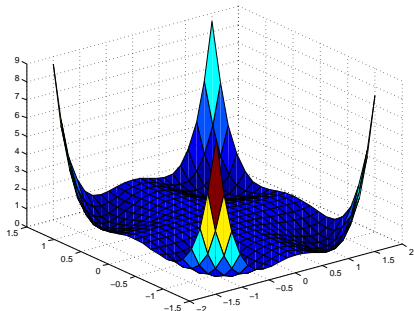
Optimization over Polynomials: Selected Topics



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What is polynomial optimization?



Minimize a polynomial function f over a region

(P)

$$K = \{x \in \mathbb{R}^n : g_1(x) \geq 0, \dots, g_m(x) \geq 0\}$$

defined by polynomial inequalities

SOME INSTANCES

Testing nonnegativity of polynomials

THE QUADRATIC CASE IS EASY

The quadratic form $x^T M x$ is nonnegative over \mathbb{R}^n if and only if the matrix M is **positive semidefinite**

This can be tested in **polynomial time**, using Gaussian elimination

THE QUARTIC CASE IS HARD

Testing matrix copositivity: co-NP complete [Kabadi-Murty 1987]

A symmetric matrix M is **copositive** if $x^T M x \geq 0$ for all $x \geq 0$

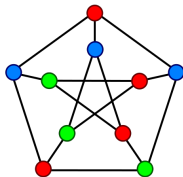
Equivalently, the polynomial $f_M = \sum_{i,j=1}^n M_{ij} x_i^2 x_j^2$ is nonnegative over \mathbb{R}^n

Testing convexity: NP-hard [Ahmadi et al. 2013]

A polynomial $f(x)$ is **convex** if and only if its Hessian matrix $H(f)(x)$ is positive semidefinite

Equivalently, the polynomial $F = y^T H(f)(x) y$ is nonnegative on $\mathbb{R}^n \times \mathbb{R}^n$

Two hard combinatorial problems over graphs



$$\alpha = 4 \quad \chi = 3$$

- **stability number** $\alpha(G)$:

maximum cardinality of a set of pairwise non-adjacent vertices (**stable set**)

- **coloring number** $\chi(G)$:

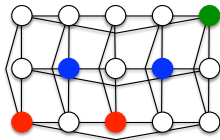
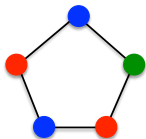
minimum number of colors needed to properly color the vertices of G .

$\alpha(G)$, $\chi(G)$ are NP-complete

[Karp 1972]

Chvátal's reduction:

$\chi(G)$ is the smallest integer c such that $\alpha(G \square K_c) = |V(G)|$



Polynomial optimization formulations for $\alpha(G)$

- Basic formulation:

$$\alpha(G) = \max \sum_{v \in V} x_v \quad \text{s.t.} \quad x_u x_v = 0 \ (uv \in E), \ x_v^2 = x_v \ (v \in V)$$

- Motzkin-Straus formulation:

$$\frac{1}{\alpha(G)} = \min x^T (I + A_G) x \quad \text{s.t.} \quad \sum_{v \in V} x_v = 1, \ x_v \geq 0 \ (i \in V)$$

- Copositive formulation:

$$\alpha(G) = \min \lambda \quad \text{s.t.} \quad \lambda(I + A_G) - J \text{ is copositive}$$

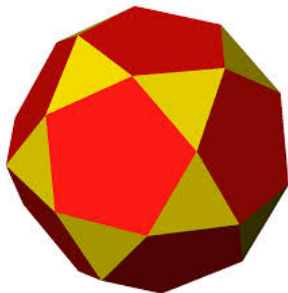
Bounds for $\alpha(G)$ and $\chi(G)$?

Linear Programming & Semidefinite Programming

Optimize a linear function over

a polyhedron

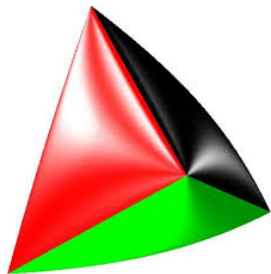
$$a_j^T x = b_j, \quad x \geq 0$$



LP

a convex set (spectrahedron)

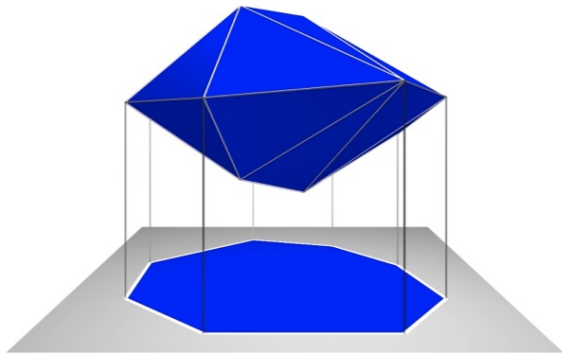
$$\langle A_j, X \rangle = b_j, \quad X \succeq 0$$



SDP

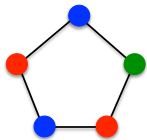
There are efficient algorithms to solve **LP** and **SDP**
(up to any precision).

One more idea: Lift to higher dimensional space



Add new variables modeling all pairwise products $x_i x_j$ of original variables, or higher order products $x_i x_j x_k$, etc.

Semidefinite bounds for $\alpha(G)$ and $\chi(G)$



$$S \text{ stable} \rightsquigarrow x = (1, 0, 0, 1, 0)^T \rightsquigarrow X = \frac{1}{|S|} xx^T$$

$$X \succeq 0 \quad (X \text{ is positive semidefinite})$$

Lovász' theta number:

[Lovász 1979]

$$\vartheta(G) = \max \sum_{i,j \in V} X_{ij} \quad \text{s.t.} \quad \text{Tr}(X) = 1, X_{uv} = 0 \ (uv \in E), X \succeq 0$$

Sandwich inequalities: $\alpha(G) \leq \vartheta(G) \leq \chi(\overline{G})$

Stronger bounds?

Stronger semidefinite bounds for $\alpha(G)$ and $\chi(G)$

$$S \text{ stable} \rightsquigarrow x = (1, 0, 0, 1, 0)^T \rightsquigarrow X = \frac{1}{|S|} xx^T \succeq 0, \succeq 0$$

Stronger bound for $\alpha(G)$: [McEliece et al. 1978, Schrijver 1979]

$$\vartheta'(G) = \max \sum_{i,j \in V} X_{ij} \text{ s.t. } \text{Tr}(X) = 1, X_{uv} = 0 (uv \in E), X \succeq 0, X \succeq 0$$

Stronger bound for $\chi(\overline{G})$: [Szegedy 1994]

$$\vartheta^+(G) = \max \sum_{i,j \in V} X_{ij} \text{ s.t. } \text{Tr}(X) = 1, X_{uv} \leq 0 (uv \in E), X \succeq 0$$

Sandwich inequalities: $\alpha(G) \leq \vartheta'(G) \leq \vartheta(G) \leq \vartheta^+(G) \leq \chi(\overline{G})$

Systematic construction of stronger bounds?

Use *higher order* semidefinite relaxations

GENERAL APPROACH TO POLYNOMIAL OPTIMIZATION

Strategy

$$(P) \quad f_{\min} = \min_{x \in K} f(x)$$

Approximate **(P)** by a hierarchy of **convex (semidefinite) relaxations**

Such relaxations can be constructed using

sums of squares of polynomials

and

the dual theory of moments

Shor (1987), Nesterov (2000), **Lasserre, Parrilo** (2000–)

SUMS OF SQUARES

Strategy (use sums of squares)

$$(P) \quad f_{\min} = \min_{x \in K} f(x) = \sup_{\lambda \in \mathbb{R}} \lambda \quad \text{s.t.} \quad f(x) - \lambda \geq 0 \quad \forall x \in K$$

Testing whether a polynomial f is nonnegative is **hard**

but one can test the *sufficient condition*:

f is a sum of squares of polynomials (SOS)

using semidefinite programming

Use SDP to find sums of squares

$f(x, y) = x^4 + 2x^3y + 3x^2y^2 + 2xy^3 + 2y^4$ is SOS?

Gram matrix method:

$$f(x, y) = \begin{pmatrix} x^2 & xy & y^2 \end{pmatrix} \underbrace{\begin{pmatrix} a & b & c \\ b & d & e \\ c & e & f \end{pmatrix}}_{M \succeq 0} \begin{pmatrix} x^2 \\ xy \\ y^2 \end{pmatrix}$$

$M \succeq 0 \rightsquigarrow M = \sum_i p_i p_i^T \rightsquigarrow f = \sum_i p_i(x)^2$

Equate coefficients on both sides:

$$x^4: a = 1 \quad x^3y: 2b = 2 \quad x^2y^2: 2c + d = 3 \quad xy^3: 2e = 2 \quad y^4: f = 2$$

$$M = \begin{pmatrix} 1 & 1 & c \\ 1 & 3 - 2c & 1 \\ c & 1 & 2 \end{pmatrix} \succeq 0 \iff -1 \leq c \leq 1$$

$$c = -1 \rightsquigarrow f = (x^2 + xy - y^2)^2 + (y^2 + 2xy)^2$$

$$c = 0 \rightsquigarrow f = (x^2 + xy)^2 + \frac{3}{2}(xy + y^2)^2 + \frac{1}{2}(xy - y^2)^2$$

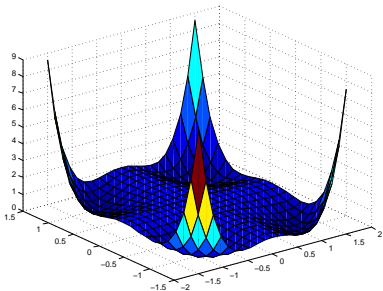
Are all nonnegative polynomials SOS?



Hilbert [1888]: *Every nonnegative polynomial in n variables and even degree d is a sum of squares of polynomials if and only if $n = 1$, or $d = 2$, or $(n = 2$ and $d = 4)$.*

Hilbert's 17th problem [1900]: *Is every nonnegative polynomial is a sum of squares of rational functions?*

Artin [1927]: Yes



Motzkin [1967]:

$$p = x^4y^2 + x^2y^4 + 1 - 3x^2y^2$$

is nonnegative,

not a sum of squares, but

$(x^2 + y^2)^2 p$ is SOS!

Are many nonnegative polynomials sums of squares?

Theorem: [Blekherman 2003]

Few SOS polynomials

when **fixing the degree** and letting the number of variables grow:

$$\frac{\text{vol}(\text{POS}_{n,2d})}{\text{vol}(\text{SOS}_{n,2d})} = \Theta\left(n^{\frac{d-1}{2}D}\right)$$

$$[D = \binom{n+2d-1}{2d} - 1]$$

Theorem: [Lasserre 2006] [Lasserre-Netzer 2006]

SOS polynomials are **dense** within nonnegative polynomials,
when **fixing the number of variables** and letting the degree grow:

If $f \geq 0$ on $[-1, 1]^n$, then

$\forall \epsilon > 0 \exists k \in \mathbb{N}$ such that $f + \epsilon \left(1 + \sum_{i=1}^n x_i^{2k}\right)$ is SOS

Positivity certificates over K

$$K = \{x \mid g_1(x) \geq 0, \dots, g_m(x) \geq 0\}$$

Quadratic module: $Q(g) = \{s_0 + s_1g_1 + \dots + s_mg_m \mid s_j \text{ SOS}\}$

Preordering: $P(g) = \{\sum_{e \in \{0,1\}^m} s_e g_1^{e_1} \cdots g_m^{e_m} \mid s_e \text{ SOS}\}$

Theorem: Assume K compact.

- [Schmüdgen 1991] $f > 0$ on $K \implies f \in P(g)$.
- [Putinar 1993] **Archimedean condition:** $\exists R : R - \sum_i x_i^2 \in Q(g)$.
 $f > 0$ on $K \implies f \in Q(g)$.

Positivstellensatz: [Krivine 1964, Stengle 1974]

$$f > 0 \text{ on } K \iff \exists p, q \in P(g) \quad pf = q + 1$$

$$f \geq 0 \text{ on } K \iff \exists p, q \in P(g) \exists k \in \mathbb{N} \quad pf = f^{2k} + q$$

SOS relaxations for (P)

Truncated quadratic module:

$$Q(g)_t := \left\{ \underbrace{s_0}_{\text{deg} \leq 2t} + \underbrace{s_1 g_1}_{\text{deg} \leq 2t} + \dots + \underbrace{s_m g_m}_{\text{deg} \leq 2t} \mid s_j \text{ SOS} \right\}$$

Replace

$$(P) \quad f_{\min} = \inf_{x \in K} f(x) = \sup \lambda \text{ s.t. } f - \lambda \geq 0 \text{ on } K$$

by

$$(SOS_t) \quad f_t^{\text{SOS}} = \sup \lambda \text{ s.t. } f - \lambda \in Q(g)_t$$

- ▶ Each bound f_t^{SOS} can be computed with SDP.
- ▶ $f_t^{\text{SOS}} \leq f_{t+1}^{\text{SOS}} \leq f_{\min}$.
- ▶ **Asymptotic convergence:** $\lim_{t \rightarrow \infty} f_t^{\text{SOS}} = f_{\min}$. [Lasserre 2001]

Degree bounds? Convergence?

- For the general **Positivstellensatz**, recent degree bounds by [Lombardi-Perrucci-Roy 2014] (depending on n , m and the maximum degree, exponential with 5 towers)
- For the **Positivstellensatz of Schmüdgen**, degree bounds and error estimates by [Schweighofer 2004]: There exist constant $c, c' > 0$ such that, for any polynomial f of degree d :

(i) If $f > 0$ on K then $f \in P_t(g)$ for $t \leq cd^2 \left(1 + \left(d^2 n^d \frac{L(f)}{f_{\min}}\right)^c\right)$.

(ii) $f_{\min} - f_t^{\text{SOS}} \leq c' L(f) \frac{d^4 n^{2d}}{c' \sqrt{t}}$ for any $t \geq c' d^{c'} n^{c' d}$.

Sharper estimates for $K = [0, 1]^n$ by [De Klerk-L 2010], roughly $c = c' = 1$. Also for the standard simplex by [DeKlerk-Parrilo-L 2006] (convergence in $1/t$).

- For **Putinar's Positivstellensatz**, results by [Nie-Schweighofer 2007]:

If $f > 0$ on K then $f \in Q_t(g)$ for $t \leq c'' \exp\{(2d^2 n^d)^{c''}\}$.

- When $K \subseteq \{0, 1\}^n$, convergence in n steps.

For $K = \{0, 1\}^n$, there are linear lower bounds [L 2003].

MOMENTS

$$\begin{aligned}
 f_{\min} = \inf_{x \in K} f(x) &= \inf_{\mu} \int_K f(x) d\mu \quad \text{s.t. } \mu \text{ is a probability measure on } K \\
 &= \inf_{L \in \mathbb{R}[x]^*} L(f) \quad \text{s.t. } L \text{ has a representing measure } \mu \text{ on } K
 \end{aligned}$$

Deciding if a linear functional $L \in \mathbb{R}[x]^*$ has a representing measure μ on K is the (difficult) **classical moment problem**.

But one can use the **necessary condition**:

L is nonnegative on the quadratic module $Q(g) = \{s_0 + \sum_j s_j g_j : s_j \text{ SOS}\}$:

$$L(p^2) \geq 0 \quad \forall p, \quad \text{i.e.,} \quad M(L) = (L(x^{\alpha+\beta}))_{\alpha, \beta \in \mathbb{N}^n} \succeq 0$$

$$\text{and} \quad L(g_j p^2) \geq 0 \quad \forall p, \quad \text{i.e.,} \quad M(g_j L) = (L(g_j(x) x^{\alpha+\beta}))_{\alpha, \beta \in \mathbb{N}^n} \succeq 0$$

$M(L)$ is a **moment matrix** and $M(g_j L)$ are **localizing moment matrices**

Moment relaxations for (P)

$$(P) \quad f_{\min} = \inf_{L \in \mathbb{R}[x]^*} L(f) \quad \text{s.t. } L \text{ has a representing measure } \mu \text{ on } K$$

Truncate at degree $2t$:

$$(MOMt) \quad f_t^{\text{mom}} = \inf_{L \in \mathbb{R}[x]_{2t}^*} L(f) \quad \text{s.t. } L(1) = 1, L \geq 0 \text{ on } Q(g)_t$$

i.e., $M_t(L) \succeq 0, M_{t-d_j}(g_j L) \succeq 0 \quad \forall j$

$$(SOST) \quad f_t^{\text{sos}} = \sup \lambda \quad \text{s.t. } f - \lambda \in Q(g)_t$$

$$f_t^{\text{sos}} \leq f_t^{\text{mom}} \leq f_{\min}$$

Sufficient condition for representing measure

$$M_t(L) = \begin{array}{|c|c|} \hline M_{t-1}(L) & \\ \hline & \\ \hline \end{array}$$

Theorem [Curto-Fialkow 1996 - L 2005: short algebraic proof]

If $M_t(L) \succeq 0$ and $\text{rank } M_t(L) = \text{rank } M_{t-1}(L)$,

then L has a representing measure $\mu: L(f) = \int f(x)\mu(dx)$ for $\deg(f) \leq 2t$

- ▶ Extend L to $L \in \mathbb{R}[x]^*$ with $\text{rank } M(L) = \text{rank } M_t(L) =: r$
- ▶ $M(L) \succeq 0$ with finite rank $r \implies L$ has a r -atomic measure μ
 1. the **kernel** $I = \text{Ker } M(L)$ is a **real radical ideal** in $\mathbb{R}[x]$
 2. the **quotient algebra** $\mathbb{R}[x]/I$ has **finite dimension** r
 3. the **variety** $V(I)$ has **r points in \mathbb{C}^n** , in fact $\mathbb{R}^n \rightsquigarrow$ **support of μ**
 4. it can be computed with the **eigenvalue method**
 5. define the **positive measure** μ (using interpolation polynomials at the points of $V(I)$)

Optimality criterion for moment relaxation (MOMt)

$$K = \{x \mid g_1(x) \geq 0, \dots, g_m(x) \geq 0\}$$

$$d_K = \max_j \lceil \deg(g_j)/2 \rceil$$

Theorem [CF 2000 + Henrion-Lasserre 2005 + Lasserre-L-Rostalski 2008]

Assume L is an optimal solution of (MOMt) such that

$$\text{rank } M_s(L) = \text{rank } M_{s-d_K}(L) \text{ for some } d_K \leq s \leq t.$$

- Then the relaxation is **exact**: $f_t^{\text{mom}} = f_{\min}$.
- Moreover, one can compute the **global minimizers**:

$$V(\text{Ker } M_s(L)) \subseteq \{ \text{global minimizers of } f \text{ on } K \},$$

with **equality** if $\text{rank } M_t(L)$ is **maximum** ($\text{rank} = \#$ minimizers).

Properties

- ▶ Interior point algs for SDP give a **maximum rank** optimal solution
- ▶ Algorithm for computing the (finitely many) **real roots** of polynomial equations (and real radical ideals)
 - [Lasserre-L-Rostalski 2008,2009]
 - [Lasserre-L-Mourrain-Rostalski-Trebuchet 2013]
- ▶ **Finite convergence** holds in the **finite variety case** [L 2007]
in the **convex case** [Lasserre 2009, de Klerk-L 2011]
- ▶ **Finite convergence** holds **generically** [Nie 2013]
- ▶ Several implementations: GloptiPoly [Henrion-Lasserre], SOSTOOLS [Prajna et al.], SparsePOP [Waki et al.], YALMIP [Löfberg]

APPLICATIONS TO
 $\alpha(G)$ AND $\chi(G)$

Semidefinite hierarchies for $\alpha(G)$, $\chi(G)$

$$\alpha(G) = \max \sum_{i \in V} x_i \quad \text{s.t.} \quad x_i x_j = 0 \quad (ij \in E), \quad x_i^2 = x_i \quad (i \in V)$$

$$\text{las}_t(G) = \max L\left(\sum_{i \in V} x_i\right) \quad \text{s.t.} \quad M_t(L) \succeq 0, \quad L(1) = 1, \quad L(x_i x_j) = 0 \quad (ij \in E), \\ L = 0 \text{ on truncated ideal } (x_i^2 - x_i : i \in [n])_{2t}$$

$$\chi(G) = \min c \quad \text{s.t.} \quad \alpha(G \square K_c) = |V(G)|$$

$$\text{Las}_t(G) = \min c \quad \text{s.t.} \quad \text{las}_t(G \square K_c) = |V(G)|$$

- ▶ $\alpha(G) \leq \text{las}_t(G)$, with equality if $t = \alpha(G)$.
- ▶ $\text{Las}_t(G) \leq \chi(G)$, with equality if $t = n$. [Gvozdrenović-L 2008]
- ▶ At $t = 1$, get theta number: $\text{las}_1(G) = \vartheta(G)$, $\text{Las}_1(G) = \vartheta(\overline{G})$.
- ▶ These hierarchies refine other known hierarchies [L 2003] [GL 2008]

Applications

- ▶ **Coding problem:** Find the maximum cardinality of an error correcting binary code of length N
- ▶ Compute the stability number $\alpha(G_N)$ of a Hamming graph G_N :
 $V = \{0, 1\}^N$, edges = pairs $\{u, v\}$ at small Hamming distance.
- ▶ Big graph ($|V| = 2^N$), but with a large automorphism group.
- ▶ $\text{las}_t(G_N)$: SDP of size $O(N^{2^t-1})$ instead of $O(|V|^t = 2^{tN})$
[L 2007]
- ▶ Best known upper bounds for $\alpha(G_N)$ obtained by computing (variations of) the Lasserre bound of order $t = 2$.
Also bounds for $\chi(G_N)$ (and other symmetric graphs).
[Gijswijt, Gvozdenović, L, Mittelman, Regts, Schrijver, Vallentin...]
- ▶ Extensions to geometric problems: **kissing number problem**
[Bachoc-Vallentin 2008], **coloring of the Euclidean space**
[Bachoc-Nebe-Oliveira-Vallentin 2009] (α, χ in infinite graphs)

Concluding remarks

- ▶ SDP hierarchies are used for **approximation algorithms** in TCS
- ▶ SDP hierarchies are used for **noncommutative** polynomials
 - ▶ Evaluate polynomials at matrices or operators (instead of scalars)
 - ▶ **[Helton 2002]** $f(X_1, \dots, X_n) \succeq 0$ for all $X_1, \dots, X_n \in \mathcal{S}^d$ ($\forall d \geq 1$)
 $\iff f$ is a sum of hermitian squares
 - ▶ SDP hierarchies for quantum analogues of $\alpha(G)$ and $\chi(G)$?
- ▶ $M_G = \alpha(G)(I + A_G) - J \rightsquigarrow f_G = \sum_{i,j \in V} x_i^2 x_j^2 (M_G)_{ij} \geq 0$

Conjecture:

$f_G (\sum_{i \in V} x_i^2)^{\alpha(G)-1}$ is a sum of squares

[de Klerk-Pasechnik 2002]

Partial proof [Gvozdenović-L 2007]

- ▶ **Question** [DeKlerk-L 2010] What is the smallest constant C_n such that $x_1 \cdots x_n + C_n \in \mathcal{Q}_n(x_i^2 - x_i : i \in [n])$? $C_n = \frac{1}{n(n+2)}$?

THANK YOU

Example

Compute the real roots of the polynomial equations:

$$g_1 = 5x_1^9 - 6x_1^5x_2 + x_1x_2^4 + 2x_1x_3,$$

$$g_2 = -2x_1^6x_2 + 2x_1^2x_2^3 + 2x_2x_3,$$

$$g_3 = x_1^2 + x_2^2 - 0.265625.$$

order t	rank sequence	accuracy
5	1 4 8 16 25 34	—
6	1 3 9 15 22 26 32	—
7	1 3 8 10 12 16 20 24	—
8	1 4 8 8 8 12 16 20 24	4.6789e-5

8 real roots (and 20 complex roots).