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On probability distributions arising from points on a graph

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A.R. Bloemena

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1. Introduction

Given a set of n points, numbered 1,...,n, and a n x n matrix M, with elements m_{ij} , satisfying

$$(1.1)$$
 $m_{ij} = m_{ji}$ $(i \neq j)$,

$$(1,2)$$
 $= 0,$

(1.3) for each i $m_{ij} \neq 0$ for at least one j, and

$$(1.4)$$
 $0 \le m_{1j} < \infty$.

In the special case that all m_{ij} are integers, the set of points and the matrix M can be interpreted as a finite multigraph (cf. C. BERGE (1958), D. KOENIG (1936)), where the number of joins between point i and j is equal to m_{ij} . If $m_{ij} = 0$, this means in this case that there is no join between i and j. Assumption (1.2) states that there are no loops. Assumption (1.3) implies that no point is isolated.

From the n points two samples are taken. We shall consider two cases.

Case I "non free sampling": from the points 1,...,n r_1 and r_2 points are chosen at random without replacement $(r_1+r_2 \le n)$. The r_1 points will be denoted as black (B) points, the r_2 points as white (W) ones, while finally the $n-r_1-r_2$ remaining points are the red (R) ones.

Case II "free sampling": n independent trials are performed, each trial resulting in the event B with probability p_1 , in the event W with probability p_2 , and in the event R with probability $1-p_1-p_2$. Point number i is alotted the colour indicated by the outcome of the i-th trial.

outcome of the i-th trial. (W) (B) Consider the random variables x_{ij} , x_{ij} , y_{ij} (i, j=1,...,n) defined by

$$(B)$$

$$X_{ii} = 0 spr 0,$$

$$y_{ij} = 0$$
 spr 0,

and for i / j

$$\frac{(B)}{x_{ij}} = \begin{cases} 1 & \text{if point i and j are both black} \\ 0 & \text{if not,} \end{cases}$$

$$\frac{y}{1\hat{J}} = \left\{ \begin{array}{c} \text{1 if one of the points i and j is black and the} \\ \text{other is white} \\ \text{0 if not.} \end{array} \right.$$

Obviously

$$(W)$$
 (W) $X_{ij} = X_{ji}$, (B) (B) (B) $X_{ij} = X_{ji}$, (B) $(B$

Define

$$\frac{\mathbf{x}_{W}}{\mathbf{i},\mathbf{j}} = \sum_{\mathbf{m}_{\mathbf{i},\mathbf{j}}} \mathbf{m}_{\mathbf{i},\mathbf{j}} \frac{\mathbf{x}_{\mathbf{i},\mathbf{j}}}{\mathbf{B}},$$

$$(1.5) \qquad \frac{\mathbf{x}_{B}}{\mathbf{x}_{B}} = \sum_{\mathbf{i},\mathbf{j}} \mathbf{m}_{\mathbf{i},\mathbf{j}} \frac{\mathbf{x}_{\mathbf{i},\mathbf{j}}}{\mathbf{1},\mathbf{j}},$$

$$\frac{\mathbf{y}}{\mathbf{i},\mathbf{j}} = \sum_{\mathbf{i},\mathbf{j}} \mathbf{m}_{\mathbf{i},\mathbf{j}} \frac{\mathbf{y}_{\mathbf{i},\mathbf{j}}}{\mathbf{1},\mathbf{j}},$$

We also introduce a set of random variables z_{ij} , taking the values 0 or 1, (z_{ii} = 0 spr 0), and a random variable

We attribute to \underline{z}_{ij} and to \underline{z} all properties that \underline{x}_{ij} , \underline{x}_{ij} , \underline{y}_{ij} and \underline{x}_{W} , \underline{x}_{B} and \underline{y} have in common. Thus \underline{z} is a generalization of \underline{x}_{W} , \underline{x}_{B} and \underline{y} .

In the following we shall give results on the stochastic properties of \underline{x}_W , \underline{x}_B , \underline{y} and \underline{z} . The proofs will be given in a forthcoming thesis.

2. Previous work on the subject

F.A.P. MORAN (1948) considers a "statistical map", equivalent to our graph for $m_{i,j}=0$ or 1, where the points are chosen by "free" and "non free" sampling. He gives for both cases the first and second moments of the number of black-black joins (thus for ϵ_B) and the third and fourth moment for the case of free sampling. He proves the asymptotic normality of ϵ_B and ϵ_B (free sampling) for a rectangular twodimensional lattice, where there are joins between neighbouring points in the direction of both axis (cf. also P.A.P. MORAN (1947)).

P.V. Kalshwa LYBR (1978-1953). He only deals with rectangular lattices, where neighbouring points are joined in the direction of both axis, but also diagonal joins are considered in a number of his papers. The results of KRISHNA IYER are mostly on the first four mements or cumulants, and statements about asymptotic normality.

A report by VAN EEDEN and BLOEMENA (1959) contains a number of exact results for rectangular lattices (non-free samples). The present report is an outgrowth of the last mentioned paper, which arose from a study of the distribution of a statistic, obtained in a psychological test.

Some older papers on the subject are by H. TODD (1940) and D.J. FILLING (1940).

3. Some graphtheomatical notions

Consider a set S of points and a subset U of the set of all possible joins between these points. The combination (S,U) is usually called a graph. For a detailed treatment of theory of graphs, we refer to D. KORNIG (1936) and C. BERGE (1958).

In this report the word "graph" is used in two different ways. In section i it has been shown that in the case that m_{ij} are non negative integers, the set of points from which the samples are taken, and the matrix M can be interpreted as a graph. In the following we use the word "graph" in a different situation.

For the purposes of the following sections we use the word "graph" to denote a set of k oriented joins, labelled J_1,\ldots,J_k ,

between ℓ ($2 \le \ell \le 2k$) points, such that no points are isolated (are not connected to at least one other point), and loops do not occur. Multiple joins are admitted.

A point to which join J_i is connected will be called the second point of J_i if the orientation of the join is towards the point; if not, it will be called the first point of J_i .

To each graph there corresponds a symmetrical 2k x 2k matrix A, consisting of k^2 2 x 2 block-matrices A_{ij} (i,j = 1,...,k), with elements 0 if i=j and for i \neq j and μ , λ = 1,2:

$$a_{\text{i}\mu,\text{j}\lambda} = \begin{cases} \text{1 if the } \mu\text{-th point of } J_{\text{i}} \text{ coincides with} \\ \text{the } \lambda\text{-th point of } J_{\text{j}}. \\ \text{0 if not.} \end{cases}$$

All graphs having the same matrix A are considered as equivalent.

have as matrix

and are therefore equivalent.

Two graphs that are not equivalent will be called distinct. The $k \times k$ matrix with elements

$$b_{ij} = \sum_{\mu=0}^{1} \sum_{\lambda=0}^{1} a_{i\mu}, j\lambda$$

will be called the <u>configuration matrix</u>. Here b_{ij} ($i \neq j$) indicates the number of common endpoints of join J_i and J_j , thus b_{ij} either 0, 1 or 2. For i=j $b_{ij}=0$. The orientation of the joins does not influence the configuration of the graph.

Consider two graphs G_1 and G_2 , each based on ℓ points and k (labelled and oriented) joins. If G_1 and G_2 are not equivalent, but a permutationmatrix P exists such that for the configuration-

matrices B₁ and B₂ the relation

holds, we shall say that G_1 and G_2 have the same <u>configuration</u>. If two graphs G_1 and G_2 have the same configuration, this means that permuting the numbers of the joins and/or reversing the orientation of some joins of configuration G_1 can make G_2 equivalent to G_2 .

A graph G = (S,U) is called connected if from every point ies one can reach any other point of S by travelling along the joins of the set U. neglecting the orientation of the joins. A graph which is not connected, can be decomposed in a number of connected components. This decomposition is unique (cf. D. KONIG, 1936, p.15). A configuration-matrix of a not connected graph (if necessary after premultiplication with a permutationmatrix P, and postmultiplication with P`) is a logical sum of the configuration-matrices of each of the connected components.

A connected graph with k joins has at most (k+1) points. It has at least two points. For λ satisfying

there exist finitely many, say $q_{k,\ell}$, different configurations corresponding to connected graphs, based on k joins and ℓ points. Let $C_{k,\ell}^{(\alpha)}$ be the α -th one $(\alpha=1,\ldots,q_{k,\ell})$. The configuration of a graph having h connected components $(1 \le h \le \lceil \frac{\ell}{2} \rceil)$ can now be indicated symbolically by

$$\frac{h}{\sum_{i=1}^{C} C_{ki}^{2}}$$

if the i-th connected component has a configuration C_{k,j,ℓ_j} . If among the h connected components g_j have the same configuration (α_j) C_{k,j,ℓ_j} , we may also write $\sum_{j=1}^{g} g_j C_{k,\ell_j}$ as the symbol of the configuration of the graph.

By means of the operator N(...), operating on the symbol of a configuration, we indicate the number of **distinct** graphs, having this configurations. It can be proved that

(3.1)
$$N(\sum_{j=1}^{s} g_{j} C_{k_{j}, \ell_{j}}^{(\alpha_{j})}) = k! \prod_{j=1}^{s} \frac{1}{g_{j}!} \left\{ \frac{N(C_{k_{j}, \ell_{j}})}{k_{j}!} \right\}$$
The calculation of $N(C_{k_{j}, \ell_{j}}^{(\alpha_{j})})$ proceeds by means of recurrence relations.

relations.

4. A general expression for the moments

In order to calculate the k-th moment of z, we have to consider products

$$(4.1) \qquad \frac{z}{2} v_{1,1}, v_{1,2} \qquad \frac{z}{2} v_{2,1}, v_{2,2} \qquad \frac{z}{2} v_{k,1}, v_{k,2}, v_{k,2}$$

where v_1, v_2, v_3, v_4 are integers from the range 1, ..., n. If for some j=1, ..., k

(4.1) is zero a.c. by assumption. We shall therefore only consider the case

for all $j = 1, \dots, k$.

Assume that among $v_{1,1},\dots,v_{k,2}$, say ℓ different integers occur (2 \leq / \leq 2k). We shall denote these by λ_1 , ..., λ_l .

To each product (4.1) there corresponds a graph: let each subscript of (4.1) corresponds to a point. If two subscripts are equal, they correspond to the same point, thus there are & points in all. Let the first subscript $\forall_{j,1}$, of $z_{\forall_{j,1}}$, $\forall_{j,2}$ (j=1,...,k) correspond to the first point of a join, and the second subscript to the second point. Now we have obtained a graph with k oriented joins and & points. Loops do not occur because of (4.2). Multiple joins between points correspond to powers of z. Let, the graph corresponding to (4.1) have the configuration $\sum_{i=1}^{h} C_{k_i, l_i}^{(\alpha_1)}$, then in the following sections we show that for z_{ij} for $i \neq j$ holds:

For each k = 1, ..., the expectation of (4.1) does not depend on the actual values of $v_{1,1}, \dots, v_{k,2}$, but only on the configuration $\sum_{i=1}^{h} C_{k_i,k_i}^{(\alpha_i)}$.

We can therefore use the following notation for the expectation of (4.1):

$$\mathbb{E}(\underline{z}^{(1)}) \cdot \cdot \cdot \cdot \underline{z}^{(k)} | \frac{h}{\sum_{i=1}^{h} C_{k_i, \ell_i}^{(\alpha_i)}}.$$

In calculating the k-th moment of \underline{z} , we also need ℓ -fold sums of the type

(4.3)
$$\sum_{\theta_1=1}^{n} \cdots \sum_{\theta_{\ell}=1}^{m} m_{\theta_{\ell}} \cdots \sum_{\mu_{1},1}^{m} \mu_{2,2} \cdots \mu_{2,1}^{m} \mu_{2,2} \cdots \mu_{k,1}^{m} \mu_{k,2}$$

where among the subscripts of the Θ 's in the general term of the sum all integers 1,..., ℓ occur. The summation is restricted by a condition D^{*} , yet to be specified.

If for some j = 1, ..., k

the sum is equal to zero by (1.2). We therefore consider only the case

$$(4.4)$$
 $W_{j,1} = W_{j,2}$

for $j = 1, \dots, k$.

In the same way used to construct a graph corresponding to the subscripts in (4.1), we now construct a graph corresponding to the subscripts of the Θ 's. Let each subscript $\mu_1, 1, \dots, \mu_k, 2$ correspond to a point. If two are equal they correspond to the same point, thus there are ℓ points in all.

Let the subscript $\mu_{j,1}$ of m_{θ} $\mu_{j,1}$ $\mu_{j,2}$ correspond to the first point of a join, and the subscript $\mu_{j,2}$ to the second point. Now we have obtained a graph with k oriented joins and ℓ points. Loops do not occur because of (4.4). Let the graph have the configuration $\sum_{i=1}^{k} C_{k_i,\ell_i}^{(\alpha_i)}$, then the following notation for (4.3) will be used:

1) if there is no restriction D^{*} :

$$\sum \left\{ m^{(1)} \dots m^{(k)} \middle| \frac{h}{\sum_{i=1}^{h} C_{k_i, l_i}^{(\alpha_i)} \right\},$$

2) if restriction $D^{\frac{x}{2}}$ is that in the summation indices $\theta_1, \ldots, \theta_\ell$ are all unequal:

$$\sum_{i=1}^{\infty} \left\{ m^{(1)} \cdot m^{(k)} \right| \sum_{i=1}^{h} C_{k_{i}, \ell_{i}}^{(\alpha_{i})} \cdot m^{(k)}$$

Now one can write

$$(4.5) \quad \mathbb{E}_{\underline{z}^{k}} = \sum_{\ell=2}^{2k} \sum_{h=1}^{\left[\frac{\ell}{2}\right]} \sum_{k=1}^{n} \sum_{k_{1}=k, \sum \ell_{1}=\ell, N} \sum_{k_{1}=\ell}^{n} \sum_{k_{1}, \ell_{1}}^{n} \sum_{k_{1}, \ell_{1}}^{$$

where $\sum_{i=1}^{n} \frac{h}{k_i = k}$, $\sum_{i=1}^{n} \ell_i = \ell_i$ means a summation over all configurations satisfying the indicated restrictions $\sum_{i=1}^{n} k_i = k$, and $\sum_{i=1}^{n} \ell_i = \ell$.

5. The moments of \underline{x}_{W} and \underline{x}_{B}

The moments of x can be found by replacing r_1 or p_1 in the corresponding formulae for x_B by r_2 or p_2 respectively.

a) non-free sampling

(5.1)
$$\mathbb{E}(\underline{\mathbf{x}}_{\mathrm{B}}^{(1)}...\underline{\mathbf{x}}_{\mathrm{B}}^{(k)}|\underline{\underline{\mathbf{x}}}_{\mathrm{i=1}}^{(\alpha_{i})}\mathbf{c}_{k_{i},\ell_{i}}^{(\alpha_{i})} = \frac{\binom{r}{\ell_{i}}}{\binom{n}{\ell_{i}}},$$

where $\sum_{i=1}^{h} l_i = l$.

From (4.5) we find after some simplifications

$$E = \frac{r_1(r_1-1)}{n(n-1)} m_{++},$$

$$\sigma^{2} = E \frac{x_{B}^{2} - (E x_{B})^{2}}{n^{2}} = 4 \frac{r_{1}(r_{1}-1)(r_{1}-2)(n-r_{1})}{n(n-1)(n-2)(n-3)} \sum_{i} (m_{i+} - \frac{1}{n}m_{++})^{2} + \frac{2r_{1}(r_{1}-1)(n-r_{1})(n-r_{1}-1)}{n^{2}(n-1)^{2}(n-2)(n-3)} \left\{ n(n-1) \sum_{i,j} m_{i,j}^{2} - m_{++}^{2} \right\}.$$

If m_{i+} does not depend on i, the first term of σ^2 is equal to zero.

b) free sampling

(5.2)
$$E(\underline{x}_{B}^{(1)}, \underline{x}_{B}^{(k)} | \sum_{i=1}^{h} C_{k_{i}}^{(\alpha_{i})}) = p^{\ell},$$

SO

$$E x_{B} = p_{1}^{2} \sum_{i,j} m_{i,j},$$

$$\sigma^{2} = 2p_{1}^{2} (1-p_{1})^{2} \sum_{i,j} m_{i,j}^{2} + 4p^{3} (1-p_{1}) \sum_{i} m_{i,+}^{2}$$

6. The moments of y

In order to calculate

$$\mathbb{E}\left\{\underline{\mathbf{y}}^{(1)},\underline{\mathbf{y}}^{(k)}\big| \sum_{i=1}^{h} \mathbf{C}_{k_{i},\ell_{i}}^{(\alpha_{i})}\right\}$$

we first take a point P_i of the i-th connected component (i=1,..,h) as a reference point. Colour P_i white, next all points connected by a join to P_i are coloured black, then all points connected to these black points are coloured white. If in repeating this procedure one arrives at a point which has already been given one colour, but should be coloured by the just-mentioned rule in the other colour as well, then we conclude that the i-th connected component is not bichromatic.

If no such situation arises one arrives at a stage, where all points have been allotted a colour, viz τ_i points are white and ℓ_i - τ_i black; we then say that the i-th connected component is bichromatic. The fact wether a graph is bichromatic or not does

not depend on the choice of the initial point.

Define (6.1) B($\sum_{i=1}^{h} C_{k_i, \ell_i}^{(\alpha_i)}$) = $\begin{cases} 1 & \text{if all connected components of } \sum_{i=1}^{h} C_{k_i, \ell_i}^{(\alpha_i)} \\ 0 & \text{if not.} \end{cases}$

a) non free sampling

$$(6.2) \ \mathbb{E}\left\{\underline{y}^{(1)} ... \underline{y}^{(k)} \middle| \sum_{i=1}^{h} C_{k_{i}, \ell_{i}}^{\alpha_{i}} \right\} = \mathbb{B}\left(\sum_{i=1}^{h} C_{k_{i}, \ell_{i}}^{(\alpha_{i})}\right) \frac{(n-\ell)!}{n!} \sum_{i=1}^{h} \sum_{\rho_{i}=0}^{1} \frac{\sum_{i=1}^{h} C_{i}^{\alpha_{i}}}{(r_{1}-\sum_{i}(1-\rho_{i}) \tau_{i}-\sum_{i}\rho_{i}(\ell_{i}-\tau_{i}))!} \frac{r_{2}!}{(r_{2}-\sum_{i}\rho_{i}\tau_{i}-\sum_{i}(\ell_{i}-\tau_{i})(1-\rho_{i}))!}$$

So

$$E y = \frac{2r_{1}r_{2}}{n(n-1)} \sum_{i,j} m_{i,j},$$

$$\sigma^{2} = \sum_{i} \left(\sum_{j} m_{i,j} - \frac{\sum_{i,j} m_{i,j}}{n} \right)^{2} \left\{ \frac{r_{1}r_{2}(r_{2}-1)}{n(n-1)(n-2)} + \frac{r_{2}r_{1}(r_{1}-1)}{n(n-1)(n-2)} - \frac{4r_{1}r_{2}(r_{1}-1)(r_{2}-1)}{n(n-1)(n-2)(n-3)} \right\}$$

$$+ 4 \sum_{i,j} m_{i,j}^{2} \left\{ \frac{r_{1}r_{2}}{n(n-1)} - \frac{r_{1}r_{2}(r_{2}-1)}{n(n-1)(n-2)} - \frac{r_{2}r_{1}(r_{1}-1)}{n(n-1)(n-2)} + \frac{2r_{1}r_{2}(r_{1}-1)(r_{2}-1)}{n(n-1)(n-2)(n-3)} \right\}$$

$$+ 4 \left(\sum_{i,j} m_{i,j} \right)^{2} \frac{r_{1}r_{2}n(r_{1}+r_{2}+3)-r_{1}r_{2}(2r_{1}r_{2}+r_{1}+r_{2}+2)}{n^{2}(n-1)^{2}(n-2)(n-3)}.$$

b) free sampling

(6.3)
$$E(\underline{y}^{(1)}...\underline{y}^{(k)}|\sum_{i=1}^{h} c_{k_{i},l_{i}}^{(\alpha_{i})} =$$

$$= B(\sum_{i=1}^{h} c_{k_{i},l_{i}}^{(\alpha_{i})}) \xrightarrow{h} (p_{1}^{\tau_{1}} p_{2}^{l_{1}-\tau_{i}} + p_{1}^{l_{1}-\tau_{i}} p_{2}^{\tau_{i}}),$$

thus

$$E_{\underline{y}} = 2p_{1}p_{2} \sum_{ij} m_{ij},$$

$$\sigma^{2} = 4p_{1}p_{2}(p_{1}+p_{2}-4p_{1}p_{2}) \sum_{ijk} m_{ij}m_{ik} + 4p_{1}p_{2}(1-p_{1}-p_{2}+2p_{1}p_{2}) \sum_{ij} m_{ij}^{2}.$$

7. Tendency towards the normal distribution

The following theorems can be proved.

Theorem 7.1

i If r₁ and n tend to infinity such that

$$\lim_{n \to \infty} \frac{r_1}{n} = \delta_1, \qquad 0 < \delta_1 < 1,$$

and if for all i

$$m_1 + < C$$

where C is a constant independent of i and n, then in the non-free sampling case the distribution of

$$\{\underline{x}_{B} - \underline{E} \underline{x}_{B}\} \sigma(\underline{x}_{B})^{-1}$$

tends to the standard normal one E_{X_B} and $O(x_B)^2$ have been given in section 5

- ii The same result holds for \underline{x}_w if r_1 is replaced by r_2
- iii If the assumptions of part i of this theorem are satisfied and if moreover

$$\lim_{n \to \infty} \frac{r_2}{n} = \delta_2, \qquad 0 < \delta_2 \le 1 - \delta.$$

then in the non-free sampling case the distribution of

$$(y - Ey) o(y)^{-1}$$

tends to the standard normal one. Ey and $\sigma^2(y)$ have been given in section 6.

Theorem 7.2

If n tends to infinity and p_1 to a limit $p_1^*(0 < p_1^* < 1)$, and if for all i

$$m_{3+} < C$$

where C is a constant independent of i and n, then in the free sampling case the distribution of

$$\{x_B - E x_B\} \sigma(x_B)^{-1}$$

tends to the standard normal one. E \underline{x}_B and $\sigma^2(\underline{x}_B)$ have been given in section 5.

- ii The same result holds for x_i if p_1 is replaced by p_2 .
- iii If the assumption of part 1 holds, and 1f also p_2 tends to a limit $p_2^{*}(0 < p_2^{*} < 1 p_1^{*})$ then in the free sampling case the distribution of

$$(y - Ey) o(y)^{-1}$$

tends to the standard normal one. Ey and $\sigma^{*}(y)$ have been given in section 6.

8. Tendency towards the compound Poisson-distribution

Theorem 8.1

i If ra and n tend to infinity such that

$$\lim \frac{r_1}{n} = 0,$$

$$\lim \frac{r_1^2}{n^2} m_{++} = 2\lambda, \qquad 0 < \lambda < \infty,$$

and for all ∞ and $k \ge 2$,

(8.1)
$$\lim_{k \to 1} \left(\frac{r_1}{n}\right)^{k+1} \sum_{k \to 1} \left\{m^{(1)} \cdot m^{(k)} | c_{k,k+1}^{(\alpha)} \right\} = 0,$$

and if for all i and j

$$m_{1j} < C_{1j}$$

where C_1 does not depend on i, j and n, then the distribution of $\frac{1}{2}x_B$ tends to a compound Poisson distribution with moment generating function

$$\sum_{k=0}^{\infty} \frac{Z^{k}}{k!} \lim \mathbb{E}(\frac{1}{2}X_{B})^{k} = \exp\{\lambda \sum_{i=1}^{\infty} m_{i}^{*} \frac{Z^{i}}{i!}\},$$

where

$$m_h^{*} = \lim_{h \to 0} \frac{\sum_{j=1}^{m} m_{ij}}{m_{i+1}}, \quad h = 1, 2, ...$$

Assumption (13.1) is satisfied if for all i $m_{i+} \le C_2$, where C_2 does not depend on i and

$$\lim_{n \to \infty} \frac{1}{n} c_2 = 0,$$

thus e.g. when Co is a constant not dependent on n.

- The same result holds it \underline{x}_B and r_1 is replaced by \underline{x}_W and r_2 respectively.
- iii If in part ii and iii $\frac{r_1}{n}$ is replaced by p_1 , and $\frac{r_2}{n}$ by p_2 , then the corresponding results for the free sampling case is obtained.

Theorem 13.2

i If r₁,r₂ and n tend to infinity, such that

$$\lim_{n \to \infty} \frac{r_1}{n} = 0,$$

$$\lim_{n \to \infty} \frac{r_1 r_2}{n^2} m_{++} = \lambda, \qquad 0 < \lambda < \infty,$$

and for all α and k = 2, ...

(13.2)
$$\lim_{n \to \infty} \frac{r_1^{j_2}}{r_1^{k+1}} = 0, \quad j=1, \dots, K,$$

and if for all i and j

$$m_{1j} < C_{1j}$$

where C_1 does not depend on i, j and n, then in the non-free sampling case the distribution of $\frac{1}{2}y$ tends to a compound Poisson-distribution with

$$\sum_{k=0}^{\infty} \frac{Z^{k}}{k!} \lim E(\frac{1}{2}Z)^{k} = \exp\left\{\lambda \sum_{i=1}^{\infty} \frac{m^{*}Z^{i}}{i!}\right\},\,$$

with

$$m_h^{\star} = \lim_{m \to \infty} \frac{\sum_{m = 1, 2, \dots, m} h}{m_{++}}, \qquad h = 1, 2, \dots.$$

Assumption (13.2) is satisfied if for all i $m_{i+} \le C_2$, where C_2 does not depend on i and

$$\frac{1}{1}m - \frac{2}{n} = 0$$

thus e.g. when C₂ is a constant not dependent on n.

If in part i $\frac{r_1}{n}$ is replaced by p_1 , and $\frac{r_2}{n}$ by p_2 , the corresponding result for the free sampling case is obtained.

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