# Contractions in Comparing Concurrency Semantics

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We define for a simple concurrent imperative language both operational and denotational semantic models as fixed points of contractions on complete metric spaces. Next, we develop a general method for comparing different semantic models by relating their defining contractions and exploiting the fact that contractions have a unique fixed point.

#### **0. INTRODUCTION**

We present a study of a simple concurrent imperative language, called  $L_0$ . We shall define an *operational semantics*  $\mathfrak{O}_0$  and a *denotational semantics*  $\mathfrak{O}_0$  for it and give a comparison of the two models. (We shall use the terms *semantics* and *semantic model* as synonyms.) This *comparison* is the main subject of our paper, rather than the specific nature of the language itself or the particular properties of its semantics.

The language  $L_0$  has been defined and studied already in much detail in [BMOZ1,2] and [BKMOZ], on which we rely heavily. It belongs to the wide class of *concurrent (parallel) imperative* programming languages. We shall discuss parallel execution through interleaving (*shuffle*) of elementary actions. Further,  $L_0$  contains constructs for sequential composition, local nondeterminacy, and recursion.

For our semantic definitions we shall use *metric* structures, rather than order-theoretic domains. The metric approach is particularly felicitous for problems where histories, computational traces and tree-like structures of some kind are essential. Moreover, it allows for the definition of the notion of *contraction*, which we discuss in more detail in a moment. Our operational model  $\theta_0$  is based on the transition system technique of Hennessy and Plotkin [HP] and Plotkin [Pl2, Pl3]. It is closely related to the one defined in [BKMOZ], but there are some differences. Our denotational model  $D_0$  is almost exactly the same as in [BKMOZ]. It is defined compositionally, giving the meaning of a compound statement in terms of the meaning of its components, and tackling recursion with the help of fixed points.

Although the semantic models presented here are (roughly) the same as in [BKMOZ], there is one major difference, being the way in which they are defined. In this paper we define both the operational and denotational models as fixed points of contractions.

A contraction  $f: M \to M$  on a complete metric space M has the useful property that there exists one and only one element  $x \in M$  satisfying f(x) = x. This elementary fact is known as *Banach's fixed point theorem*. Such a fixed point x is entirely determined by the definition of f:

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any other element  $y \in M$  satisfying the same properties as x, that is, satisfying f(y)=y, is equal to x. The contractions  $\Phi$  we use in this paper are always of type  $\Phi:(M_1 \to M_2) \to (M_1 \to M_2)$ , that is, they are defined on a complete metric function space  $M_1 \to M_2$ . Then the fixed point of  $\Phi$  is a function from  $M_1$  to  $M_2$ .

The fact that our denotational model can be obtained as fixed point of suitable contraction is not very surprising, fixed points playing traditionally an important role in denotational semantics. It is interesting, however, to observe that the same method applies to the definition of the *operational* model. One might wonder whether a model thus obtained still deserves to be called operational. That this is the case follows from the fact (not proved here) that it equals the operational model defined in the usual manner, without the use of a contraction.

The main advantage of this style of defining semantic models as fixed points is that it enables us to compare them more easily. This brings us to the discussion of what has been announced above to be the main subject of this paper: the *comparison* of operational and denotational semantic models, which we shall also call the study of their *semantic equivalence*. About the question why this would be an interesting problem we want to be brief. Different semantic models of a given language can be regarded as different views of the same object. So they are in some way related. Their precise relationship we want to capture in some formal statement.

Let us now sketch the way we use contractions in our study of semantic equivalence. Let L be a language. Suppose an operational model  $\emptyset$  for L is given as the fixed point of a contraction

$$\Phi:(L \to M) \to (L \to M),$$

where M is a complete metric space. Suppose furthermore that we have a denotational model  $\mathfrak{D}$  for L of the same type as  $\mathfrak{O}$ , that is, with  $\mathfrak{D}: L \to M$ , for which we can prove  $\Phi(\mathfrak{D}) = \mathfrak{D}$ . Then it follows from the uniqueness of the fixed point of  $\Phi$  that  $\mathfrak{O} = \mathfrak{D}$ .

In the context of *complete partial ordering structures* similar approaches exist (see, e.g., [HP] and [AP]). There, the operational semantics  $\emptyset$  can be characterised as the (with respect to the pointwise ordering) smallest function  $\mathfrak{F}$  satisfying  $\Phi(\mathfrak{F})=\mathfrak{F}$ , for some continuous function  $\Phi$ . Then it follows from  $\Phi(\mathfrak{N})=\mathfrak{N}$  that  $\emptyset$  is smaller than  $\mathfrak{N}$ . In order to establish  $\mathfrak{O}=\mathfrak{N}$  it is proved that  $\emptyset$  satisfies the defining equations for  $\mathfrak{N}$ , from which it follows that  $\mathfrak{N}$  is smaller than  $\emptyset$ . Please note that within the metric setting we can omit the second part of the proof.

In general  $\emptyset$  and  $\mathfrak{D}$  have different types, that is, they are mappings from L to different mathematical domains. In the language we consider, this difference is caused by the fact that recursion is treated in the denotational and operational semantics with and without the use of so-called environments, respectively. Therefore,  $\emptyset$  and  $\mathfrak{D}$  cannot be fixed points of the same contraction. Now suppose  $\emptyset$  and  $\mathfrak{D}$  are defined as fixed points of  $\Phi:(L \to M_1) \to (L \to M_1)$  and  $\Psi:(L \to M_2) \to (L \to M_2)$ , respectively, where  $M_1$  and  $M_2$  are different complete metric spaces. Then we can relate  $\emptyset$  and  $\mathfrak{D}$  by defining an intermediate semantic model for L as the fixed point of a contraction  $\Phi':(L \to M') \to (L \to M')$ , and by relating  $\Phi$ ,  $\Phi'$  and  $\Psi$  as follows. If we define

$$f_1:(L \to M_1) \to (L \to M')$$
, and  $f_2:(L \to M_2) \to (L \to M')$ ,

and we next succeed in proving the commutativity (indicated by \*) of the next diagram:

then we will be able to deduce the following relation between 0 and D:

$$f_2(\mathfrak{N}) = f_1(\mathfrak{O}).$$

It is straightforward from  $*_1$  and  $*_2$ , and the fact that  $\Phi$ ,  $\Phi'$ , and  $\Psi$  are contractions.

This will be the procedure we follow for the models  $\mathcal{C}_0$  and  $\mathfrak{D}_0$  of  $L_0$  in section 1. There  $f_1$  and  $f_2$  are such that for closed statements (i.e., containing no free statement variables)  $s \in L_0$ , we have:  $\mathcal{C}_0(s) = \mathfrak{D}_0(s)$ . This result is not new: It was already proved in [BMOZ1,2] and [BKMOZ]. However, the proofs given there are quite complicated and not so easy to understand. Furthermore, it seems to be difficult to extend and generalise them.

Given the definitions of  $\mathfrak{O}_0$  and  $\mathfrak{O}_0$ , it is intuitively obvious that they yield the same values for closed statements. In other words, the result that  $\mathfrak{O}_0 = \mathfrak{D}_0$  is not very surprising, neither. In that respect, the method applied in this paper for deriving it might seem disproportionally complex. Therefore, we would like to stress what we consider to be the main contribution of this paper: We have developed a method which can be easily generalised for proving the semantic equivalence of operational and denotational semantics for languages much more complicated than  $L_0$ . In section 2, we shall illustrate this by briefly describing some languages for which we have proved semantic equivalence in this manner (references to some corresponding papers will be given there).

In section 3, some conclusions and remarks about future research are formulated. Section 4 gives the references. For the basic definitions of metric topology we refer to [Du] and [En]. Most of what we need is repeated in [BKMOZ].

This paper is in fact an extended abstract of [KR], to which the reader is referred for a more detailed description of our ideas. (In [KR] all the proofs can be found that are omitted here.)

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# 1. A SIMPLE LANGUAGE $(L_0)$

### 1.1 Syntax

For the definition of the language studied in this paper we need two sets of basic elements. Let A, with typical elements  $a, b, \ldots$ , be the set of *elementary actions*. For A we take an arbitrary, possibly infinite, set. Further, let *Stmv*, with typical elements  $x, y, \ldots$ , be the set of statement variables. For *Stmv* we take some infinite set of symbols.

DEFINITION 1.1 (Syntax for  $L_0$ ): We define the set of *statements*  $L_0$ , with typical elements  $s,t, \ldots$ , by the following syntax:

$$s::= a | s_1; s_2 | s_1 \cup s_2 | s_1 || s_2 | x | \mu x[t]$$

where  $t \in L_0^x$ , the set of statements which are guarded for x, to be defined below.

A statement s is of one of the following six forms: (1) an elementary action a; (2) the sequential composition  $s_1$ ;  $s_2$  of statements  $s_1$  and  $s_2$ ; (3) the nondeterministic choice  $s_1 \cup s_2$ , also known as *local nondeterminism* [FHLR]:  $s_1 \cup s_2$  is executed by executing either  $s_1$  or  $s_2$  chosen nondeterministically; (4) the *concurrent execution*  $s_1 || s_2$ , modeled by the arbitrary interleaving *(shuffle)* of the elementary actions of  $s_1$  and  $s_2$ ; (5) a statement variable x, which is (normally) used in: (6) the recursive construct  $\mu x[t]$ : its execution amounts to execution of t where occurrences of x in t are executed by (recursively) executing  $\mu x[t]$ . For example, with the definition to be proposed presently, the intended meaning of  $\mu x[(a;x) \cup b]$  is the set  $a^* \cdot b \cup \{a^{\omega}\}$ .

An important restriction of our language is that we consider only recursive constructs  $\mu x[t]$  for which t is guarded for x:  $t \in L_0^x$ . Intuitively, a statement t is guarded for x when all occurrences of x in t are preceded by some statement. More formally:

DEFINITION 1.2 (Syntax for  $L_0^x$ ): The set  $L_0^x$  of statements which are guarded for x is given by

 $t::= a | t;s | t_1 \cup t_2 | t_1 ||t_2 | y | \mu x[t] | \mu y[t']$ 

where  $s \in L_0$ ,  $y \neq x$ , and  $t' \in L_0^x \cap L_0^y$ .

It appears to be useful to have the languages under consideration contain a special element, denoted by E, which can be regarded as the empty statement. From now on E is considered to be an element of  $L_0$ , and  $L_0^x$ . We shall still write  $L_0$  for  $L_0 \cup \{E\}$  and  $L_0^x$  for  $L_0^x \cup \{E\}$ . Please note that syntactic constructs like s; E or  $E \parallel s$  are not in  $L_0$ .

Now that we have formulated the notion of guardedness for x, we can easily generalise this:

DEFINITION 1.3 (Guarded statements): The set  $L_0^x$  of guarded statements (guarded for all x) is defined as  $L_0^x = \bigcap_{x \in Stmv} L_0^x$ .

As  $L_0$  and  $L_0^x$ , also  $L_0^x$  has a simple inductive structure:

**LEMMA** 1.4: The set L<sub>b</sub> can be given by the following syntax:

$$x_{1} := a | t_{1} | s_{1} | t_{1} | t_{2} | \mu x[t]$$

where  $s \in L_0$ .

We have the usual notion of *free variables*, that is, variables that are not bound by any operator  $\mu$ . A statement containing no free variables is called *closed*. We define for  $L = L_0$ ,  $L_0^s$ , and  $L_0^{cl}: L^{cl} = \{s \mid s \in L \mid \text{closed}(s)\}$ . We have:  $(L_0)^{cl} = (L_0^s)^{cl} = (L_0^s)^{cl}$ .

We expect that the reader may benefit from a few examples. First, we observe that  $L_0^{\ell} \subseteq L_0^{\ell} \subseteq L_0$ . Further, we have that

 $\begin{aligned} x \in L_0, \ x \notin L_0^x, \ y; x \in L_0^x, \ y; x \notin L_0^x, \ y; x \notin L_0^x, \ \mu_x[y; x] \in L_0, \ \mu_y[y; x] \notin L_0, \ a; \mu_x[y; x] \in L_0^x \cap L_0^x, \ \mu_y[a; \mu_x[y; x]] \in L_0. \end{aligned}$ 

#### 1.2 Operational semantics

We first introduce a semantic universe for both the operational and the denotational semantics for  $L_0$ .

DEFINITION 1.5 (Semantic universe  $P_0$ ): Let  $A^{\infty}$ , the set of finite and infinite words over A, be given by  $A^{\infty} = A^* \cup A^{\omega}$ . For the empty word we use the special symbol  $\epsilon$ . Let  $d_{A^{\infty}}$  denote the usual metric on  $A^{\infty}$ . We define  $P_0 = \mathcal{P}_{nc}(A^{\infty})$ , with typical elements  $p,q,\ldots$ , the set of all non-empty, compact subsets of  $A^{\infty}$ . As a metric on  $P_0$  we take  $d_{P_0} = (d_{A^{\infty}})_H$ , the Hausdorff distance induced by  $d_{A^{\infty}}$ . We have that  $P_0$  together with the metric  $d_{P_0}$  is a complete metric space.

The operational semantics for  $L_0$  is based on the notion of a *transition relation:* 

DEFINITION 1.6 (Transition relation for  $L_{\delta}^{g}$ ): We define a transition relation  $\rightarrow \subseteq L_{\delta}^{g} \times A \times L_{0}$ (writing  $s \rightarrow s'$  for  $(s, a, s') \in \rightarrow$ ) as the smallest relation satisfying

(i) 
$$a \rightarrow E$$
 (for all  $a \in A$ )

(ii) for all  $a \in A$ ,  $s, t \in L_0^{\delta}$ ,  $s', \overline{s} \in L_0$ : if  $s' \neq E$ , then:

$$s \xrightarrow{a} s' \Rightarrow (s; \overline{s} \xrightarrow{a} s'; \overline{s} \land s \cup t \xrightarrow{a} s' \land t \cup s \xrightarrow{a} s'$$
$$\land s || t \xrightarrow{a} s' || t \land t || s \xrightarrow{a} t || s' \land \mu x[s] \xrightarrow{a} s'[\mu x[s]/x]),$$

where the latter statement is obtained by replacing all free occurrences of x in s by  $\mu x[s]$ ; and if s' = E, then:

$$s \xrightarrow{a} E \Rightarrow (s; \overline{s} \xrightarrow{a} \overline{s} \land s \cup t \xrightarrow{a} E \land t \cup s \xrightarrow{a} E$$
$$\land s \| t \xrightarrow{a} t \land t \| s \xrightarrow{a} t \land \mu x[s] \xrightarrow{a} E).$$

Intuitively,  $s \rightarrow s'$  tells us that s can do the elementary action a as a first step, resulting in the statement s'. We now give the definition of  $\mathcal{O}_0$ , the operational semantics for  $L_0^{cl}$ . (It is defined on *closed* statements only, because we do not want to give an operational meaning to, e.g., a;x: what should it be?) It will be the fixed point of the following contraction.

DEFINITION 1.7 ( $\Phi_0$ ): Let  $\Phi_0:(L_0^{cl} \to P_0) \to (L_0^{cl} \to P_0)$  be given, for  $F \in L_0^{cl} \to P_0$  and  $s \in L_0^{cl}$ , by

$$\Phi_0(F)(s) = \begin{cases} \{\epsilon\} & \text{if } s = E \\ \bigcup \{a \cdot F(s') | s' \in L_0^{cl} \land a \in A \land s \to s'\} & \text{if } s \neq E. \end{cases}$$

It is straightforward to prove that  $\Phi_0$  is contracting. (As a metric on  $L_0^{cl} \rightarrow P_0$  we take  $d(F_1, F_2) = \sup_{s \in L_0^{cl}} \{ d_{P_0}(F_1(s), F_2(s)) \}.$ )

**DEFINITION** 1.8 :  $\mathfrak{O}_0 = \text{Fixed Point}(\Phi_0)$ 

We give yet another characterisation of  $\theta_0$ . It is based on the following definition and will be the one we use in proving semantic equivalence.

DEFINITION 1.9 (Initial steps): We define a function  $I: L_{\delta} \to \mathcal{P}_{fin}(A \times L_{0})$  (where  $\mathcal{P}_{fin}(X) = \{Y \mid Y \subseteq X \land \text{ finite } (Y)\}$ ) by induction on  $L_{\delta}$ :

- (i)  $I(E) = \emptyset$ , and  $I(a) = \{(a, E)\}$
- (ii) Suppose  $I(s) = \{(a_i, s_i)\}, I(t) = \{(b_j, t_j)\}$  for  $s, t \in L_0^s, a_i, b_j \in A, s_i, t_j \in L_0$ . (The variables *i* and *j* range over some finite sets of indices, which we have omitted.) Then

$$I(s;\bar{s}) = \{(a_i, s_i;\bar{s})\} \text{ (for } \bar{s} \in L_0), I(s \cup t) = I(s) \cup I(t)$$
$$I(s||t) = \{(a_i, s_i||t)\} \cup \{(b_j, s||t_j)\}, I(\mu x[s]) = \{(a_i, s_i[\mu x[s]/x])\}.$$

This definition is motivated by the following lemma, which can be easily proved.

LEMMA 1.10:  $\forall a \in A \forall s \in L_0^{a} \forall s' \in L_0 [s \rightarrow s' \Leftrightarrow (a, s') \in I(s)]$ 

COROLLARY 1.11:  $\Phi_0(F)(s) = \bigcup \{a \cdot F(s') | (a,s') \in I(s)\}, \text{ for } F: L_0^{cl} \to P_0, s \in L_0^{cl} \setminus \{E\}.$ 

### 1.3 Denotational semantics

The second semantic function we define for  $L_0$  will be *denotational*: We call a semantic function  $F:L_0 \to M$  (where M is some mathematical domain) denotational if it is compositionally defined and tackles recursion with the help of fixed points. The first condition is satisfied if for every syntactic operator op in  $L_0$  we can define a corresponding semantic operator  $\tilde{op}: M \times M \to M$  (assuming op to be binary) such that

$$F(s_1 ops_2) = F(s_1) \tilde{op} F(s_2).$$

As semantic domain for the denotational semantics of  $L_0$  we take again  $P_0$ . The semantic operators corresponding with ;,  $\cup$  and  $\parallel$ , the syntactic operators in  $L_0$ , will be of type  $P_0 \times P_0 \rightarrow P_0$ .

DEFINITION 1.12 (Semantic operators)

The operators  $\tilde{i}, \cup, \parallel: P_0 \times P_0 \to P_0$  are defined as follows. Let  $p, q \in P_0$ , then

(i) 
$$p \tilde{;} q = \begin{cases} q & \text{if } p = \{\epsilon\} \\ \bigcup \{a \cdot (p_a \tilde{;} q) \mid p_a \neq \emptyset\} \text{ otherwise} \end{cases}$$
  
(ii)  $p \tilde{\cup} q = p \cup q \text{ (set-theoretic union)}$   
(iii)  $p \tilde{\parallel} q = \begin{cases} p & \text{if } q = \{\epsilon\} \\ q & \text{if } p = \{\epsilon\} \\ \bigcup \{a \cdot (p_a \tilde{\parallel} q) \mid p_a \neq \emptyset\} \cup \bigcup \{a \cdot (p \tilde{\parallel} q_a) \mid q_a \neq \emptyset\} \text{ otherwise,} \end{cases}$ 

where for every  $p \in P_0$  and  $a \in A$  we define:

 $p_a = \{ w \mid w \in A^{\infty} \land a \cdot w \in p \}.$ 

(We often write op rather than  $\tilde{op}$  if no confusion is possible.)

**Remarks 1.13** 

Definitions (i) and (iii) are self-referential and need some justification. We shall give it for i and leave the case of i to the reader. We define a mapping:

 Φ:(P<sub>0</sub>×P<sub>0</sub>→P<sub>0</sub>)→(P<sub>0</sub>×P<sub>0</sub>→P<sub>0</sub>) by

$$\Phi(F)(p,q) = \begin{cases} q & \text{if } p = \{\epsilon\} \\ \bigcup \{a \cdot F(p_a,q) \mid p_a \neq \emptyset\} & \text{otherwise.} \end{cases}$$

It is not difficult to show that  $\Phi$  is contracting. Then we define:  $\tilde{;} = Fixed Point(\Phi)$ , which satisfies the equation of definition 1.16 above.

(2) If we define the *left-merge* operator  $\parallel$  by

$$p \bigsqcup q = \begin{cases} \varnothing & \text{if } p = \{\epsilon\} \\ \bigcup \{a \cdot (p_a \parallel q) \mid p_a \neq \varnothing\} \text{ otherwise,} \end{cases}$$

then we will have that  $p ||q = p ||_q \cup q ||_p$  (using the fact that p' ||q' = q' ||p', for all p' and q'). This abbreviation will be helpful in some future proofs.

We shall treat recursion with the help of environments, which are used to store and retrieve meanings of statement variables. They are defined in

**DEFINITION 1.14** (Semantic environments)

The set  $\Gamma$  of semantic environments, with typical elements  $\gamma$ , is given by  $\Gamma = Stmv \rightarrow fin P_0$ . We write  $\gamma\{p/x\}$  for a variant of  $\gamma$  which is like  $\gamma$  but with  $\gamma\{p/x\}(x)=p$ .

Now we have defined everything we need to introduce the denotational semantics for  $L_0$ .

# Definition 1.15 ( $\Psi_0$ , $D_0$ )

We shall define  $D_0$  as the fixed point of  $\Psi_0: (L_0 \to \Gamma \to {}^1P_0) \to (L_0 \to \Gamma \to {}^1P_0)$ , which is given by induction on  $L_0$ . (Here  $\Gamma \to {}^1P_0$  denotes the set of non-distance-increasing functions from  $\Gamma$  to  $P_0$ .) Let  $F \in L_0 \to \Gamma \to {}^1P_0$ , then:

- (i)  $\Psi_0(F)(a)(\gamma) = \{a\}, \Psi_0(F)(x)(\gamma) = \gamma(x), \Psi_0(F)(E)(\gamma) = \{\epsilon\}$
- (ii)  $\Psi_0(F)(s \text{ op } t)(\gamma) = \Psi_0(F)(s)(\gamma) \tilde{op} \Psi_0(F)(t)(\gamma)$
- (*iii*)  $\Psi_0(F)(\mu x[s])(\gamma) = \Psi_0(F)(s)(\gamma \{F(\mu x[s])(\gamma)/x\}) \text{ for } s \in L_0^x,$

for op = ;,  $\cup$ ,  $\parallel$ , and  $\tilde{op}$  as in definition 1.12. (We define  $\Psi_0(F)$  only for those s and  $\gamma$ , such that  $FV(s) \subseteq dom(\gamma)$ .) Now we set  $D_0$  = Fixed Point( $\Psi_0$ ).

We have:  $D_0[[\mu x[s]]](\gamma) = D_0[[s]](\gamma \{D_0[[\mu x[s]]](\gamma)/x\}).$ 

The fact that we consider only guarded recursion is essential for the proof (omitted here) that  $\Psi_0$  is contracting.

# 1.4 Semantic equivalence of $\mathfrak{G}_0$ and $\mathfrak{N}_0$

An important difference between  $\mathfrak{N}_0$  and  $\mathfrak{C}_0$  is that recursion is treated with and without semantic environments, respectively. We have

$$\mathfrak{O}_{0}\llbracket\mu x[s]\rrbracket(\gamma) = \mathfrak{O}_{0}\llbracket s\rrbracket(\gamma\{\mathfrak{O}_{0}\llbracket\mu x[s]\rrbracket(\gamma/x\})$$

and

$$\mathcal{O}_0[[\mu x[s]]] = \mathcal{O}_0[[s[\mu x[s]/x]]].$$

In the latter case the statement  $\mu x[s]$  is syntactically substituted for all free statement variables x in s, whereas in the first case the environment  $\gamma$  is changed by setting x to the semantic value of  $\mu x[s]$ . We shall compare  $\theta_0$  and  $\theta_0$  by relating both to an intermediate semantic function  $\theta_0'$ , which takes syntactic instead of semantic environments as arguments. It will be defined such that for syntactic environments  $\delta$ :

$$\mathfrak{O}_0'\llbracket\mu x[s]\rrbracket(\delta) = \mathfrak{O}_0'\llbracket s\rrbracket(\delta\{\mu x[s]/x\}).$$

Here  $\delta$  is changed, the new value of x is the statement  $\mu x[s]$ . By first comparing  $\mathcal{O}_0$  and  $\mathcal{O}_0'$  and next  $\mathcal{O}_0'$  and  $\mathfrak{D}_0$  we are able to prove the main result of this section:  $\mathcal{O}_0[s] = D_0[s](\gamma)$ , for all  $s \in L_0^{cl}$  and arbitrary  $\gamma \in \Gamma$ . For the definition of  $\mathcal{O}_0'$ , we need

DEFINITION 1.16 (Syntactic environments)

The set  $\Delta$  of syntactic environments, with typical elements  $\delta$ , is defined by

 $\Delta = \{\delta \mid \delta \in (Stmv \to {}^{fin} L_0) \land (\delta \text{ is normal})\},\$ 

where the notion of *normal* environments is given in:

DEFINITION 1.17 (Normal environments) A syntactic environment  $\delta$  is called *normal* whenever

- (i)  $\forall x \in dom(\delta) [\delta(x) \in L_0^x]$
- (ii)  $\forall s \in L_0 [FV(s) \subseteq dom(\delta) \Rightarrow \exists k \ge 0 [s[\delta]^k \in L_0^{cl}]],$

where  $s[\delta]^0 = s$ ,  $s[\delta]^1 = s[\delta(x_1)/x_1, \ldots, \delta(x_n)/x_n]$  (with  $FV(s) = \{x_1, \ldots, x_n\}$ ) and  $s[\delta]^{n+1} = (s[\delta])[\delta]^n$ . For  $\delta$  normal and  $s \in L_0$ , with  $FV(s) \subseteq dom(\delta)$ , we define  $s < \delta > = s[\delta]^k$ , where  $k = \min\{m \mid s[\delta]^m \in L_0^{cl}\}$ .

**Remarks** 1.18

- (1) From now on we shall assume whenever we consider  $s \in L_0$  and  $\delta \in \Delta$  together (as two arguments for a function, or as a pair) that  $FV(s) \subseteq dom(\delta)$ .
- (2) Let  $\delta \in Stmv \rightarrow fin L_0$  be such that for  $x, y \in Stmv$ :  $\delta(x) = y$  and  $\delta(y) = x$ . Such an environment is *not* normal. It does not give us any useful information about the values of x and y.
- (3) It would be too restrictive to require for all  $\delta \in Stmv \rightarrow fin L_0$  that  $\forall x \in dom(\delta) [x[\delta] \in L_0^{cl}]$ . An example may illustrate this. Let  $\delta$  be defined such that  $dom(\delta) = \{x, y\}$ , and

 $\delta(y) = \mu y[b;x;y], \quad \delta(x) = \mu x[a;\mu y[b;x;y]].$ 

Such an environment we shall encounter when computing  $\mathbb{O}_0' \llbracket \mu x[a; \mu y[b; x; y]] \rrbracket$ . Now  $y[\delta] = \delta(y) \notin L_0^{cl}$ , but  $y[\delta]^2 \in L_0^{cl}$ .

Now that we have introduced syntactic environments, we can formulate a principle of induction for the set  $L_0 \times \Delta$ , which we shall heavily use in the sequel.

THEOREM 1.19 (Induction principle for  $L_0 \times \Delta$ ): Let  $\Xi \subseteq L_0 \times \Delta$ . If:

- (1)  $A \times \Delta \subseteq \Xi$
- (2)  $\{s,t\} \times \Delta \subseteq \Xi \implies \{s; \overline{s}, s \cup t, s \| t\} \times \Delta \subseteq \Xi \text{ for } s, t, \overline{s} \in L_0$
- (3)  $\{s\} \times \Delta \subseteq \Xi \Rightarrow \{\mu x[s]\} \times \Delta \subseteq \Xi \text{ for } s \in L_0^x$
- (4)  $(\delta(x), \delta) \in \Xi \implies (x, \delta) \in \Xi$  for  $x \in Stmv$  and  $\delta \in \Delta$ ,

then:

$$\Xi = L_0 \times \Delta$$
.

We cannot reason about a free statement variable x unless we know what statement it is bound to. Therefore, we consider non-closed statements together with syntactic environments, which give information about the free variables they contain. This explains why we have formulated an induction principle for  $L_0 \times \Delta$  instead of  $L_0$  only.

Now let  $\Xi \subseteq L_0 \times \Delta$ . The first three conditions of the principle suffice to prove that  $L_{\delta}^{\delta} \times \Delta \subseteq \Xi$ , since they express exactly the syntactic structure of  $L_{\delta}^{\delta}$  (see lemma 1.4). (We have chosen  $L_{\delta}^{\delta}$  here instead of  $L_{0}^{cl}$ , because the latter set has no simple inductive structure.) Thus also  $L_{0}^{cl} \times \Delta (\subseteq L_{\delta}^{\delta} \times \Delta) \subseteq \Xi$ . Adding condition (4) enables us to prove  $L_{0} \times \Delta \subseteq \Xi$ . This may be motivated by the following. For every statement  $s \in L_{0}$  and normal environment  $\delta \in \Delta$  there exists an  $l \in \mathbb{N}$  such that  $s[\delta]^{l} \in L_{0}^{cl} \subseteq L_{\delta}^{\ell}$ . Let us call  $k \in \mathbb{N}$  with  $k = \min\{l \mid s[\delta]^{l} \in L_{0}^{cl}\}$  the degree of closedness of s with respect to  $\delta$ . Please note that every  $s \in L_{0}^{cl}$  has degree 0, and arbitrary  $s \in L_{0}$  has, for arbitrary  $\delta$ , a finite degree. Therefore, this degree can be used as a measure for the complexity of statements. Our induction principle is indeed a principle of induction on the degree 0. They form, so to speak, the basis of the principle. Condition (4) expresses the "step part": if  $\Xi$  holds for  $(\delta(x), \delta)$ , which has degree k, say, then  $\Xi$  holds for  $(x, \delta)$ , which then has degree k + 1.

We now proceed with the definition of  $\mathfrak{O}_0'$ . It will be of type  $\mathfrak{O}_0':L_0\to\Delta\to P_0$ , which could be called intermediate between  $\mathfrak{O}_0:L_0'\to P_0$  and  $D_0:L_0\to\Gamma\to P_0$ . Instead of basing the definition of  $\mathfrak{O}_0'$  on some transition relation (as in definition 1.7) we use a variant of the initial step function (definition 1.9).

DEFINITION 1.20 (Initial steps with syntactic environments): We define a function  $I': L_0 \to \Delta \to \mathfrak{P}_{fin}(A \times L_0 \times \Delta)$ , using the induction principle for  $L_0 \times \Delta$ . The predicate  $\Xi \subseteq L_0 \times \Delta$ we use is defined as:

 $\Xi(s,\delta) \equiv I'(s)(\delta)$  is defined.

We shall define I' such that  $\Xi$  satisfies the induction conditions. Thus we ensure that I' is defined for every  $s \in L_0$  and  $\delta \in \Delta$  (with  $FV(s) \subseteq dom(\delta)$ ).

 $I'(E)(\delta) = \emptyset$ , and  $I'(a)(\delta) = \{(a, E, \delta)\}$ , for all  $a \in A$ ,  $\delta \in \Delta$ . (1)

(2)Suppose  $I'(s) = \lambda \delta \{ (a_i, s_i, \delta_i) \}, I'(t) = \lambda \delta \{ (b_j, t_j, \delta_j) \}$  for  $s, t, s_i, t_j \in L_0, a_i, b_j \in A, \delta_i, \delta_j \in \Delta$ . (The variables i and j range over some finite sets of indices, which are omitted.) Then:

$$I'(s;\overline{s})(\delta) = \{(a_i, s_i;\overline{s}, \delta_i)\} \quad (for \ \overline{s} \in L_0)$$
$$I'(s \cup t)(\delta) = I'(s)(\delta) \cup I'(t)(\delta)$$
$$I'(s||t)(\delta) = \{(a_i, s_i||t, \delta_i)\} \cup \{(b_i, s||t_i, \delta_i)\}$$

For the definition of  $I'(\mu x[s])$  we have to consider possible clashes of variables. There-(3)fore, we distinguish between two cases (supposing that I'(s) has already been defined):

$$I'(\mu x[s])(\delta) = \begin{cases} I'(s)(\delta\{\mu x[s]/x\}) & \text{if } x \notin dom(\delta) \\ I'(\overline{s})(\delta\{\mu \overline{x}[s]/\overline{x}\}) & \text{if } x \in dom(\delta), \end{cases}$$

- where  $\overline{x}$  is some fresh variable with  $\overline{x} \notin dom(\delta)$  and  $\overline{s} = s[\overline{x}/x]$ . (4)
  - Suppose  $I'(\delta(x))(\delta)$  has already been defined. We set:

$$I'(x)(\delta) = I'(\delta(x))(\delta).$$

Note that if  $I'(s)(\delta) = \{(a_i, s_i, \delta_i)\}$ , then for all *i* and  $x \in Stmv$ : if  $x \in dom(\delta) \cap dom(\delta_i)$ , then  $\delta(x) = \delta_i(x)$ .

DEFINITION 1.21 ( $\Phi_0'$ ): We define  $\Phi_0':(L_0 \to \Delta \to P_0) \to (L_0 \to \Delta \to P_0)$  by

$$\Phi_0'(F)(s)(\delta) = \begin{cases} \{\epsilon\} & \text{if } s = E \\ \bigcup \{a \cdot F(s')(\delta') \mid (a, s', \delta') \in I'(s)(\delta) \} & \text{otherwise} \end{cases}$$

for  $F \in L_0 \to \Delta \to P_0$ ,  $s \in L_0$ , and  $\delta \in \Delta$  with  $FV(s) \subseteq dom(\delta)$ .

DEFINITION 1.22:  $\mathfrak{O}_0' = \text{Fixed Point}(\Phi_0')$ 

Next, we compare  $\mathfrak{G}_0$  and  $\mathfrak{G}_0'$ . We can do this by relating I and I', since we have:

$$\begin{split} \mathfrak{O}_0\llbracket s \rrbracket &= \bigcup \left\{ a \cdot \mathfrak{O}_0\llbracket s' \rrbracket | (a,s') \in I(s) \right\}, \text{ for } s \in L_0^{c'}, \ s \neq E \\ \mathfrak{O}_0'\llbracket s \rrbracket(\delta) &= \bigcup \left\{ a \cdot \mathfrak{O}_0'\llbracket s' \rrbracket(\delta') | (a,s',\delta') \in I'(s)(\delta) \right\}, \text{ for } s \in L_0, \ s \neq E, \ \delta \in \Delta. \end{split}$$

**THEOREM** 1.23 (Relating I and I'): For all  $s \in L_0$  and  $\delta \in \Delta$ , with  $FV(s) \subseteq dom(\delta)$ , we have:

$$\forall a \in A \forall s' \in L_0 \forall \delta' \in \Delta \left[ (a, s', \delta') \in I'(s)(\delta) \Leftrightarrow (a, s' < \delta' >) \in I(s < \delta >) \right].$$

(For the definition of  $s < \delta >$  see definition 1.17.)

The proof should generalise the intuitively obvious fact that, for s with x occurring freely in  $s: (a,s',\delta') \in I'(s)(\delta\{\mu x[s]/x\}) \Leftrightarrow (a,s' < \delta' >) \in I(s[\mu x[s]/x]).$ 

We formulate the relation of  $\mathfrak{G}_0$  and  $\mathfrak{G}_0'$  in terms of their defining contractions  $\Phi_0$  and  $\Phi_0'$ . This can be elegantly done using the following

DEFINITION 1.24: We define  $\langle \rangle: (L_0^{cl} \to P_0) \to (L_0 \to \Delta \to P_0)$ , for every  $F \in L_0^{cl} \to P_0$ , by  $\langle \rangle(F) = F^{\langle \rangle}$  (notation)  $= \lambda s \in L_0 \cdot \lambda \delta \in \Delta \cdot F(s < \delta >).$ 

This mapping links two kinds of semantic functions, of which the first uses syntactic environments whereas the second does not. If  $F \in L_0^{cl} \to P_0$ , then  $F^{<>}$  is a in a sense extended version of F: it can take as an argument also statements  $s \in L_0$  that are not closed, provided it is supplied with a syntactic environment, which is to give the (syntactic) values for the free variables in s.

THEOREM 1.25 (Relating  $\Phi_0$  and  $\Phi_0'$ ):  $\forall F \in L_0^{cl} \to P_0 [\Phi_0'(F^{<>}) = (\Phi_0(F))^{<>}]$ 

**PROOF:** The theorem is an immediate consequence of theorem 1.23. Let  $F \in L_0^{cl} \to P_0$ , let  $s \in L_0$ ,  $s \neq E$ .

$$\Phi_0'(F^{<>})(s)(\delta) = \bigcup \{a \cdot F^{<>}(s')(\delta') | (a,s',\delta') \in I'(s)(\delta)\}$$
  
= 
$$\bigcup \{a \cdot F(s' < \delta' >) | (a,s',\delta') \in I'(s)(\delta)\}$$
  
= 
$$[\text{theorem 1.23}] \bigcup \{a \cdot F(s' < \delta' >) | (a,s' < \delta' >) \in I(s < \delta >)\}$$
  
= 
$$\Phi_0(F)(s < \delta >) = (\Phi_0(F))^{<>}(s)(\delta).$$

Because  $\Phi_0$  and  $\Phi_0'$  are contractions with  $\theta_0$  and  $\theta_0'$  as their respective fixed points, we have:

COROLLARY 1.26  $(\mathfrak{G}_0' = \mathfrak{G}_0^{<>})$ :  $\forall s \in L_0 \ \forall \delta \in \Delta \ [\mathfrak{G}_0'[s](\delta) = \mathfrak{G}_0[s < \delta >]]$ .

Finally we relate  $\mathfrak{G}_0': L_0 \to \Delta \to P_0$  and  $\mathfrak{H}_0: L_0 \to \Gamma \to P_0$ . For this purpose we define the following mapping:

Definition 1.27: We define  $\sim :(L_0 \rightarrow \Gamma \rightarrow P_0) \rightarrow (L_0 \rightarrow \Delta \rightarrow P_0)$  by:

 $\sim (F) = \tilde{F} \text{ (notation)} = \lambda s \in L_0 \cdot \lambda \delta \in \Delta \cdot F(s)(\tilde{\delta}^F)$ 

for  $F \in L_0 \to \Gamma \to P_0$ , where  $\tilde{\delta}^F$  is given by  $\tilde{\delta}^F = \lambda x \in dom(\delta) \cdot F(\delta(x))(\tilde{\delta}^F)$ . (We often write  $\tilde{\delta}$  rather than  $\tilde{\delta}^F$  if from the context it is clear which F should be taken.)

We have to justify the self-referential definition of  $\delta$ . For this purpose we define

 $\Xi(s,\delta) \equiv \forall x \in FV(s) \ [s \notin L_0^x \to (\tilde{\delta}(x) \text{ is well defined})],$ 

for  $s \in L_0$  and  $\delta \in \Delta$ , and use the induction principle to prove:  $\Xi = L_0 \times \Delta$ . Then it follows for all  $x \in Stmv$  with  $x \in dom(\delta)$  that  $\tilde{\delta}(x)$  is well defined. Conditions (1) through (3) of the induction principle are trivially fulfilled. We prove condition (4). Suppose  $(\delta(x), \delta) \in \Xi$ . Thus  $\tilde{\delta}(y)$  is well defined for all  $y \in FV(\delta(x))$ . This implies that  $\tilde{\delta}(x)$  is well defined, since  $\tilde{\delta}(x) = F(\delta(x))(\delta)$ .

In the same way as  $\langle \rangle$ , also  $\sim$  links two different kinds of semantic functions, one using *syntactic*, and the other using *semantic* environments. Again  $\tilde{F}$  is an extended version of F in the sense that it takes syntactic environments as an argument instead of semantic ones. In the definition above, a syntactic environment  $\delta \in \Delta$  is changed into a *semantic version* (according to the semantic function F)  $\tilde{\delta}$  of it, which then is supplied as an argument to F.

Next, we come to the main theorem of this chapter. It relates the denotational semantics  $\mathfrak{D}_0$  and the operational semantics  $\mathfrak{O}'_0$ , which is a fixed point of  $\Phi'_0$ , by stating that also  $\mathfrak{D}_0$  is a fixed point of  $\Phi'_0$ . From this it follows that  $\mathfrak{D}_0' = \mathfrak{D}_0$ .

Theorem 1.28:  $\Phi_0'(\tilde{\mathfrak{D}}_0) = \tilde{\mathfrak{D}}_0$ 

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PROOF: Let  $\Xi \subseteq L_0 \times \Delta$  be defined by

(3)

(4)

$$\Xi(s,\delta) \equiv \Phi_0'(\bar{\mathfrak{D}}_0)(s)(\delta) = \tilde{\mathfrak{D}}_0(s)(\delta)$$

for  $(s, \delta) \in L_0 \times \Delta$ . We use the induction principle for  $L_0 \times \Delta$  to show that  $\Xi = L_0 \times \Delta$ . Let  $\delta \in \Delta$ .

- (1) For  $a \in A$  we have  $\Phi_0'(\tilde{\Phi}_0)(a)(\delta) = \{a\} = \tilde{\Phi}_0(a)(\delta)$ , so  $A \times \Delta \subseteq \Xi$ .
- (2) Let  $s,t \in L_0$  and suppose  $\Xi(s,\delta)$  and  $\Xi(t,\delta)$ . We show:  $\Xi(s||t,\delta)$ .

 $\Phi_0'(\tilde{\mathfrak{D}}_0)(s||t)(\delta) = [\text{definition } \Phi_0' \text{ and } I'(s||t)]$  $\bigcup \{a' \cdot \tilde{\mathfrak{D}}_0(s' || t)(\delta') | (a', s', \delta') \in I'(s)(\delta) \} \cup$  $\bigcup \{ b' \cdot \tilde{\mathfrak{D}}_0(s || t')(\delta') | (b', t', \delta') \in I'(t)(\delta) \}$  $= \bigcup \{a' \cdot (\tilde{\mathfrak{P}}_0(s')(\delta') \| \tilde{\mathfrak{P}}_0(t)(\delta')) | (a', s', \delta') \in I'(s)(\delta) \} \cup$  $\bigcup \left\{ b' \cdot (\tilde{\mathfrak{D}}_0(s)(\delta') \| \tilde{\mathfrak{D}}_0(t')(\delta')) \right\} (b', t', \delta') \in I'(t)(\delta) \right\}$ = [see remark after definition 1.20]  $\bigcup \left\{ a' \cdot (\tilde{\mathfrak{D}}_0(s')(\delta') || \tilde{\mathfrak{D}}_0(t)(\delta)) | (a', s', \delta') \in I'(s)(\delta) \right\} \cup$  $\bigcup \left\{ b' \cdot (\tilde{\mathfrak{P}}_0(s)(\delta) \| \tilde{\mathfrak{P}}_0(t')(\delta')) \| (b', t', \delta') \in I'(t)(\delta) \right\}$ = [definition  $\parallel$  (see remark 1.13(2))]  $((\bigcup \{a' \cdot \tilde{\mathfrak{P}}_0(s')(\delta') \mid (a', s', \delta') \in I'(s)(\delta)\}) \sqcup \tilde{\mathfrak{P}}_0(t)(\delta)) \cup$  $((\bigcup \{b' \cdot \tilde{\mathfrak{P}}_{0}(t')(\delta') \mid (b',t',\delta') \in I'(t)(\delta)\}) \sqsubseteq \tilde{\mathfrak{P}}_{0}(s)(\delta))$ = [definition  $\Phi_0'$ ]  $(\Phi_0'(\tilde{\mathfrak{T}}_0)(s)(\delta) \| \tilde{\mathfrak{T}}_0(t)(\delta)) \cup (\Phi_0'(\tilde{\mathfrak{T}}_0)(t)(\delta) \| \tilde{\mathfrak{T}}_0(s)(\delta))$ = [we have  $\Xi(s, \delta)$  and  $\Xi(t, \delta)$ ]  $(\tilde{\mathfrak{D}}_{0}(s)(\delta) \sqcup \tilde{\mathfrak{D}}_{0}(t)(\delta)) \cup (\tilde{\mathfrak{D}}_{0}(t)(\delta) \sqcup \tilde{\mathfrak{D}}_{0}(s)(\delta))$  $= \tilde{\mathfrak{D}}_{0}(s)(\delta) \| \tilde{\mathfrak{D}}_{0}(t)(\delta) = \tilde{\mathfrak{D}}_{0}(s \| t)(\delta).$ This proves  $\Xi(s || t, \delta)$ . The cases  $\Xi(s; \overline{s}, \delta)$  and  $\Xi(s \cup t, \delta)$  are very similar. Let  $s \in L_0^x$  and suppose  $\{s\} \times \Delta \subseteq \Xi$ . We show:  $\Xi(\mu x[s], \delta)$ . Assume (without loss of generality) that  $x \notin dom(\delta)$ . Then

$$\begin{split} \Phi_{0}'(\tilde{\mathfrak{P}}_{0})(\mu x\,[s\,])(\delta) &= [\text{definition } \Phi_{0}' \text{ and } I'(\mu x\,[s\,])(\delta); \text{ let } \delta' = \delta\{\mu x\,[s\,]/x\}] \\ & \bigcup \{a'.\tilde{\mathfrak{P}}_{0}(s')(\delta') \mid (a',s',\delta') \in I'(s)(\delta')\} \\ &= \Phi_{0}'(\tilde{\mathfrak{P}}_{0})(s)(\delta') \\ &= [\text{we have } \Xi(s,\delta')] \quad \tilde{\mathfrak{P}}_{0}(s)(\delta') = \mathfrak{P}_{0}[\![s\,]](\tilde{\delta}') \\ &= [\text{definition } \tilde{\delta}'] \quad \mathfrak{P}_{0}[\![s\,]](\tilde{\delta}\{\mathfrak{P}_{0}[\![\mu x\,[s\,]]](\tilde{\delta})/x\}) \\ &= [\text{definition } \mathfrak{P}_{0}] \quad \mathfrak{P}_{0}[\![\mu x\,[s\,]](\tilde{\delta}) = \tilde{\mathfrak{P}}_{0}(\mu x\,[s\,])(\delta) \end{split}$$
This proves  $\Xi(\mu x\,[s\,],\delta)$ . Let  $x \in Stmv$ , suppose  $\Xi(\delta(x),\delta)$ . Now  $\Phi_{0}'(\tilde{\mathfrak{P}}_{0})(x)(\delta) = [\text{definition } \Phi_{0}' \text{ and } I'(x)(\delta)] \quad \Phi_{0}'(\tilde{\mathfrak{P}}_{0})(\delta(x))(\delta) \end{split}$ 

= [because 
$$\Xi(\delta(x), \delta)$$
]  $\tilde{\mathfrak{D}}_{0}(\delta(x))(\delta) = \mathfrak{D}_{0}[\delta(x)](\tilde{\delta})$ 

= [definition  $\tilde{\delta}$ ]  $\tilde{\delta}(x) = \mathfrak{D}_0[x](\tilde{\delta}) = \mathfrak{D}_0(x)(\delta)$ .

Thus  $\Xi(x, \delta)$ .

The induction principle now implies:  $\Xi = L_0 \times \Delta$ .  $\Box$ 

As an immediate consequence of this theorem, we have

COROLLARY 1.29  $(\mathfrak{V}_0' = \tilde{\mathfrak{N}}_0)$ :  $\forall s \in L_0 \ \forall \delta \in \Delta \ [\mathfrak{V}_0' [s]](\delta) = \ \mathfrak{N}_0 [s][\tilde{\delta}].$ 

The combination of corollaries 1.26 and 1.29 yields the main theorem of this section.

Theorem 1.30  $(\mathbb{O}_0^{<>} = \tilde{\mathbb{O}}_0)$ ;  $\forall s \in L_0 \ \forall \delta \in \Delta \ [\mathbb{O}_0[s < \delta > ]] = \ \mathbb{O}_0[s](\tilde{\delta})].$ 

COROLLARY 1.31: For all  $s \in L_0^{cl}$ , and arbitrary  $\gamma \in \Gamma$ :  $\mathfrak{O}_0[s] = \mathfrak{N}_0[s](\gamma)$ .

### 1.5 Summary of section 1

It may be useful to give a short overview of this section. We have defined an operational semantics  $\mathfrak{G}_0$  for  $L_0$  as the fixed point of  $\Phi_0$ , and a denotational semantics  $\mathfrak{D}_0$  as the fixed point of  $\Psi_0$ . We have related  $\mathfrak{G}_0$  and  $\mathfrak{D}_0$  via an intermediate semantic function  $\mathfrak{G}_0'$ , defined as the fixed point of  $\Phi_0'$ . To be more precise, we have related  $\Phi_0$ ,  $\Psi_0$ , and  $\Phi_0'$  using mappings <> and  $\sim$ , for which we have proved some properties, schematically represented by the following diagram:

The \* in the upper rectangle indicates that it commutes, the symbol  $*_{fix}$  in the lower rectangle indicates that it commutes only for the fixed point of  $\Psi_0$  (that is,  $\mathfrak{P}_0$ ). Please note that \* has been formulated as theorem 1.25, and  $*_{fix}$  as theorem 1.28. The main result of section 1 (theorem 1.30) follows from this diagram, because \* implies:  $\mathfrak{O}_0^{<>} = \mathfrak{O}_0'$  and  $*_{fix}$  implies:  $\mathfrak{O}_0^{<>} = \mathfrak{O}_0'$  and  $*_{fix}$  implies:

### 2. Semantic equivalence for other languages

In [KR], the full paper of which this is an extended abstract, the method of proving semantic equivalence defined in the previous section is applied to two other languages,  $L_1$  and  $L_2$ , which we shall briefly describe here. Finally, we shall mention two other parallel languages (POOL and Concurrent Prolog) to which this method has been successfully applied.

For  $L_1$  we introduce some structure to the (possibly infinite) alphabet A of elementary actions. Let  $C \subseteq A$  be a subset of so-called *communications*. From now on let c range over C and a,b over A. Similarly to CCS [Mi] or CSP [Ho], we stipulate a bijection  $-:C \rightarrow C$  with  $-\circ^- = id_C$ . It yields for every  $c \in C$  a matching communication -(c), which will be denoted by  $\overline{c}$ . In  $A \setminus C$  we have a special element  $\tau$  denoting a successful communication. Let Stmv, with typical elements  $x, y, \ldots$ , be again the set of statement variables.

DEFINITION 2.1 (Syntax for  $L_1$ ): The set  $L_1$ , with typical elements  $s, t, \ldots$ , is given by

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$$s ::= a |s_1; s_2| s_1 + s_2 |s_1| |s_2| x |\mu x[t]$$

where t is guarded for x. Note that  $a \in A \supseteq C$ .

In [KR], an operational semantics  $\mathfrak{O}_1: L_1 \rightarrow P_1$  and a denotational semantics  $\mathfrak{O}_1: L_1 \rightarrow \Gamma \rightarrow \overline{P}_1$ are defined along the lines of the previous section. An importance difference is the use of a socalled *reflexive domain*  $\overline{P}_1$  for the denotational semantics of  $L_1$  (as will be the case for  $L_2$ , described below), being a solution of some domain equation in the style of Plotkin ([P11]) and Scott ([Sc]). In a metric setting these domain equations have been treated in [BZ] and [AR]. Then the method of section 1 is straightforwardly generalised. A slight complication in proving the semantic equivalence of  $\mathfrak{O}_1$  and  $\mathfrak{O}_1$  is the difference between the domains  $P_1$  and  $P_1$ : the first contains sets of *sequences*, whereas the latter has tree-like structures for its elements. (This difference is sometimes characterised by the terms *linear time* semantics versus *branching time* semantics.) As a consequence of this, we compare  $\mathfrak{O}_1$  and  $\mathfrak{O}_1$  via *two* intermediate models instead of just one. It is shown that the following diagram commutes:

where (as in subsection 1.5) \* indicates commutativity and  $*_{fix}$  indicates commutativity with respect to the fixed point of  $\Psi_1$  (that is,  $\mathfrak{D}_1$ );  $\Phi$ ,  $\Phi'$ ,  $\Psi$  and  $\Psi'$  are suitably defined contractions; and  $\alpha: \overline{P}_1 \rightarrow P_1$  is an abstraction operation, mapping branching structures onto sets of sequences.

From this diagram it follows that for all  $s \in L_1^{cl}$  and arbitrary  $\gamma \in \Gamma$ :

$$\mathfrak{O}_1\llbracket s\rrbracket = \alpha(\mathfrak{O}_1\llbracket s\rrbracket(\gamma)).$$

The third language discussed in [KR] is a nonuniform language. Elementary actions are no longer uninterpreted but taken as either assignments or tests. Communication actions c and  $\overline{c}$ are refined to actions c?v and c!e (with v variable and e an expression), and successful communication now involves two effects: both synchronisation (as in the language  $L_1$ ), and value passing: the (current) value of e is assigned to v. Thus, we have here the synchronous handshaking variety of message passing in the sense of CCS or CSP. In the definition of the syntax of  $L_2$ , we need three new syntactic categories, viz.: the set Var, with elements v, w, of individual variables; the set Exp, with elements e, of expressions; and the set Bexp, with elements b, of boolean expressions. We shall not specify a syntax for Exp and Bexp. We assume that (boolean) expressions are of an elementary kind; in particular, they have no side effects and their evaluation always terminates. Statement variables  $x, y, \ldots$  are as before, as are the communications c?v or c!e.

**DEFINITION 2.2** (Syntax for  $L_2$ )

$$s::=v:=e |b| c?v |c!e|s_1;s_2|s_1+s_2|s_1||s_2|x|\mu x[t],$$

where t is guarded for x.

The semantic domains for the operational semantics  $\mathfrak{O}_2$  and the denotational semantics  $\mathfrak{O}_2$  of  $L_2$  are somewhat more intricate than the semantics of  $L_1$ : they now involve the notion of *state*. But this turns out to be irrelevant for the proof of the semantic equivalence of  $\mathfrak{O}_2$  and  $\mathfrak{O}_2$  (defined similarly to  $\mathfrak{O}_1$  and  $\mathfrak{O}_1$ ), which is established in exactly the same way as for  $L_1$ .

We would like to conclude this section by mentioning two other examples. Along the lines of this paper, we have proved the semantic equivalence of an operational and a denotational semantics (defined in [ABKR1] and [ABKR2], respectively) for POOL, which is an acronym for parallel object-oriented language (defined in [Am]). At first sight, these two semantics seem to be quite different; a major problem is the fact that the denotational semantics uses *continua-tions*, whereas the operational semantics does not. Moreover, the denotational semantics has for its semantic domain a rather intricate version of Plotkin's domain of resumptions ([P11]). Nevertheless, also this language fits smoothly into our approach (see [Ru2]). Finally, it is also possible to apply the method in the domain of (concurrent) logic programming. In [Ko1], a compositional semantics for Concurrent Prolog is defined. The main idea is to describe the meaning of a program with the help of *substitution* transforming processes rather than state transforming processes. This semantics can be related to an operational one, which is based on the use of transition systems, by the method described above. There are some complications due to the atomic execution of guards, but the skeleton of the proof remains the same. The result will be described in [Ko2].

### 3. CONCLUSIONS

We have developed a uniform method of comparing different semantic models for imperative concurrent programming languages. We have defined operational and denotational semantic models for such languages as fixed points of contractions on complete metric spaces, and have related them by relating their corresponding contractions. Here, we benefit from the metric structure of the underlying mathematical domains, which ensures the uniqueness of the fixed point of such contractions (Banach's theorem). It turns out that once this method has been applied to a certain (simple) language  $(L_0)$ , it can be easily generalised to more complex languages  $(L_1 \text{ and } L_2)$ . This we consider to be the strength of our approach. Recently, we have investigated possible extensions of this method to deal with yet other languages, containing, e.g., program constructs for process creation. This has resulted (in [Ru2]) in an equivalence proof for POOL, a parallel object-oriented language defined in [Am]. An equivalence proof for Concurrent Prolog will be presented in [Ko2]. In [BM], a number of concurrent languages, containing constructs for simultaneous recursion, is presented for which equivalence proofs are given along the lines of this paper.

Our investigations are related to the question of *full abstraction*, which at the same time is a topic for further research. If L is a language with semantics 0 and  $\mathfrak{N}$ , then we call  $\mathfrak{N}$  *fully abstract with respect to* 0 if

$$\forall s \in L \forall t \in L \ [\mathfrak{N}[s]] = \mathfrak{N}[t]] \Leftrightarrow \forall C(\cdot) \ [\mathfrak{N}[C(s)]] = \mathfrak{N}[C(t)]],$$

where  $C(\cdot)$  ranges over the set of *contexts* for L, that is, the set of statements in L containing one or more holes. An example would be  $s_i(\cdot)$ , where  $(\cdot)$  denotes the hole. Given such a context  $C(\cdot)$  and a statement s, the statement C(s) is obtained by substituting s for all the holes in  $C(\cdot)$ . The issue of full abstraction is mostly raised with respect to a model  $\Theta$  that is *operational*, expressing a notion of observability, and a model  $\Theta$  that is *compositional*. Then it follows from a relation between  $\emptyset$  and  $\mathfrak{P}$  of the form  $\emptyset = \alpha \circ \mathfrak{P}$  that for all s and  $t \in L$ :

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$$\mathfrak{N}[s] = \mathfrak{N}[t] \Longrightarrow \forall C(\cdot) [\mathfrak{O}[C(s)] = \mathfrak{O}[C(t)]].$$

(This property is sometimes called: *correctness* of  $\mathfrak{D}$  with respect to  $\mathfrak{O}$ .) Thus, our result of proving  $\mathfrak{O} = \alpha \mathfrak{o} \mathfrak{P}$  partly solves the problem of full abstraction. In [Ru1], a semantics for a simple language like  $L_0$  is defined with the use of *failure* sets (introduced in [BHR]), which is shown to be fully abstract with respect to a given operational semantics.

## 4. References

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