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Lattice based extended formulations for integer linear equality systems

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Lattice based extended formulations for integer linear equality systems

Karen Aardal Laurence A. Wolsey

February 12, 2007

Abstract

We study different extended formulations for the set $X = \{\mathbf{x} \in \mathbb{Z}^n \mid \mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{x}^0\}$ in order to tackle the feasibility problem for the set $X_+ = X \cap \mathbb{Z}_+^n$. Here the goal is not to find an improved polyhedral relaxation of $\text{conv}(X_+)$, but rather to reformulate in such a way that the new variables introduced provide good branching directions, and in certain circumstances permit one to deduce rapidly that the instance is infeasible. For the case that \mathbf{A} has one row \mathbf{a} we analyze the reformulations in more detail. In particular, we determine the integer width of the extended formulations in the direction of the last coordinate, and derive a lower bound on the Frobenius number of \mathbf{a} . We also suggest how a decomposition of the vector \mathbf{a} can be obtained that will provide a useful extended formulation. Our theoretical results are accompanied by a small computational study.

1 Introduction

Recently, several hard integer programming feasibility problems have been successfully tackled using a lattice reformulation proposed by Aardal et al. [2, 3]. These problems include various equality knapsacks of Cornuéjols et al. [7], Aardal and Lenstra [4], market split instances of Cornuéjols and Dawande [6, 1], and financial planning instances of Louveaux and Wolsey [14].

The approach proposed earlier is to replace the feasibility problem for the set $X = \{\mathbf{x} \in \mathbb{Z}_+^n \mid \mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{x}^0\}$ by a feasibility problem over an extended formulation for the set, namely the set $\{(\mathbf{x}, \boldsymbol{\mu}) \in \mathbb{Z}_+^n \times \mathbb{Z}^{n-m} \mid \mathbf{x} = \mathbf{x}^0 + \mathbf{Q}\boldsymbol{\mu}\}$ where \mathbf{Q} is a reduced basis of the lattice $\{\mathbf{y} \in \mathbb{Z}^n \mid \mathbf{A}\mathbf{y} = \mathbf{0}\}$. It turns out that both a special purpose branch-and-bound code and commercial mixed integer programming solvers are then much more successful at solving the test instances with the extended formulation than with the original formulation. In related work Aardal and Lenstra [4] have considered knapsack sets $\{\mathbf{x} \in \mathbb{Z}_+^n \mid \mathbf{a}\mathbf{x} = b\}$ where $\mathbf{a} = M_1\mathbf{p}^1 + M_2\mathbf{p}^2$, $M_1, M_2 \in \mathbb{Z}_{>0}$, $\mathbf{p}^1, \mathbf{p}^2 \in \mathbb{Z}^n$, where the vectors \mathbf{p}^1 and \mathbf{p}^2 are short compared to the length of \mathbf{a} . For such instances they have used the reduced basis approach to detect a good direction for branching and to demonstrate infeasibility for large values of b , and they theoretically derive a strong

lower bound on the Frobenius number of \mathbf{a} in the special case when $M_2 = 1$ and $\mathbf{p}^1 \in \mathbb{Z}_{>0}^n$.

Here we pursue this lattice viewpoint. In Section 2 we show that the formulations presented above are just two extremes of a family of extended formulations of the original set X taking the form $\{(\mathbf{x}, \boldsymbol{\mu}) \in \mathbb{Z}^n \times \mathbb{Z}^s \mid \mathbf{P}\mathbf{x} = \mathbf{P}\mathbf{x}^0 + \mathbf{T}\boldsymbol{\mu}\}$ with s additional variables and $m + s$ constraints with $0 \leq s \leq n - m$, where each row of \mathbf{A} can be expressed as an integer multiple of the rows of \mathbf{P} . Note that whereas in polyhedral combinatorics extended formulations are typically used to provide better polyhedral approximations of $\text{conv}(X)$, here the extended formulations do not change the underlying polyhedron. However by isolating good branching directions, the formulations are made more effective for treatment by branch-and-bound.

In Section 3, we consider the special case of knapsack sets when $m = 1$ and $\mathbf{a} = M_1\mathbf{p}^1 + M_2\mathbf{p}^2$. For the reformulation with two equations and one additional variable ($s = 1$), we calculate the integer width of the underlying polyhedron in the direction of the auxiliary variable μ . This in turn leads us to a lower bound on the Frobenius number, simplifying and generalizing the earlier proof from [4] cited above.

In Section 4.1 we make precise how hidden structure in \mathbf{A} can be detected by reduced basis calculations, and also how this leads to interesting reformulations. In Section 4.2 we demonstrate computationally examples of hidden structure, we test how effective the reformulations are in solving feasibility problems, and we examine the quality of the lower bounds on the Frobenius number.

1.1 Preliminaries

In the following we will frequently refer to lattices and reduced lattice bases. We will define and describe these briefly here. For a more detailed exposition, see for instance Cassels [5], Kannan [8], Lenstra [11, 12], and Lovász [13].

Let $\mathbf{b}^1, \dots, \mathbf{b}^l$ be linearly independent vectors in \mathbb{R}^n . The set

$$L = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{x} = \sum_{j=1}^l \lambda_j \mathbf{b}^j, \lambda_j \in \mathbb{Z}, 1 \leq j \leq l\}$$

is called a *lattice*. The set of vectors $\{\mathbf{b}^1, \dots, \mathbf{b}^l\}$ is called a *lattice basis*. The lattice generated by the basis \mathbf{B} is denoted by $L(\mathbf{B})$. If \mathbf{B} is clear from the context we write just L .

Suppose \mathbf{A} is an integer $m \times n$ matrix of full row rank. Then $N(\mathbf{A}) = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{A}\mathbf{x} = \mathbf{0}\}$, i.e., $N(\mathbf{A})$ is the null-space of \mathbf{A} . We use the notation $L(N(\mathbf{A}))$ to denote the lattice that is generated by a basis of all *integer vectors* in $N(\mathbf{A})$.

The *rank* of a given lattice L , $\text{rk } L$, is equal to the dimension of the Euclidean vector space generated by a basis of L .

Let $\mathbf{B} = (\mathbf{b}^1, \dots, \mathbf{b}^l)$ be a basis for a given lattice L , and let $\mathbf{b}^{1*}, \dots, \mathbf{b}^{n*}$ be the

associated Gram-Schmidt vectors, which are derived recursively as follows.

$$\mathbf{b}^{1*} = \mathbf{b}^1 \text{ and } \mathbf{b}^{j*} = \mathbf{b}^j - \sum_{k=1}^{j-1} \mu_{jk} \mathbf{b}^{k*}, \quad 2 \leq j \leq l,$$

where

$$\mu_{jk} = ((\mathbf{b}^j)^T \mathbf{b}^{k*}) / (\|\mathbf{b}^{k*}\|^2), \quad 1 \leq k < j \leq l.$$

The basis $\mathbf{B} = (\mathbf{b}^1, \dots, \mathbf{b}^l)$ of the lattice L is *reduced in the sense of Lenstra-Lovász* [10] if the following holds:

$$|\mu_{jk}| \leq \frac{1}{2} \quad \text{for } 1 \leq k < j \leq l,$$

$$\|\mathbf{b}^{j*} + \mu_{j,j-1} \mathbf{b}^{(j-1)*}\|^2 \geq \frac{3}{4} \|\mathbf{b}^{(j-1)*}\|^2 \quad \text{for } 1 < j \leq l.$$

Such a basis can be found in polynomial time using the so-called *LLL* algorithm [10].

We will also need to find a basis \mathbf{Q} of $L(N(\mathbf{A}))$ and a vector \mathbf{x}^0 satisfying $\mathbf{A}\mathbf{x}^0 = \mathbf{b}$, if such a vector exists. They can be found by reducing the basis of the lattice defined by the columns of the $(n+m+1) \times (n+1)$ -matrix

$$\mathbf{B} = \begin{pmatrix} \mathbf{I} & \mathbf{0} \\ \mathbf{0} & N_1 \\ N_2 \mathbf{A} & -N_2 \mathbf{b} \end{pmatrix},$$

where N_1 and N_2 are appropriately chosen positive integers, see [3]. The first $n-m+1$ columns of the reduced basis \mathbf{B}' will be

$$\begin{pmatrix} \mathbf{Q} & \mathbf{x}^0 \\ \mathbf{0} & \pm N_1 \\ \mathbf{0} & \mathbf{b} \end{pmatrix}. \tag{1}$$

If there does not exist vector \mathbf{x}^0 satisfying $\mathbf{A}\mathbf{x}^0 = \mathbf{b}$, then element $b'_{n+1, n-m+1}$ of \mathbf{B}' will be equal to $\pm k N_1$ for some integer $k > 1$, indicating that there exists a vector \mathbf{x} satisfying $\mathbf{A}\mathbf{x} = k\mathbf{b}$.

The *Hermite Normal Form* of a matrix $\mathbf{A} \in \mathbb{Z}^{m \times n}$ of full row rank, $\text{HNF}(\mathbf{A})$, is obtained by multiplying \mathbf{A} by an $n \times n$ unimodular matrix \mathbf{U} to obtain the form $(\mathbf{D}, \mathbf{0})$, where $\mathbf{D} \in \mathbb{Z}^{m \times m}$ is a nonsingular, nonnegative lower triangular matrix with the unique row maximum along the diagonal. The Hermite Normal Form can be calculated in polynomial time using for instance the *LLL* algorithm, see [15], or that of Kannan and Bachem [9]. Note that when $\mathbf{D} \neq \mathbf{I}$, the matrix $\mathbf{D}^{-1}\mathbf{A}$ is integral and $\text{HNF}(\mathbf{D}^{-1}\mathbf{A}) = (\mathbf{I}, \mathbf{0})$.

We will need to use one property concerning projections of equality sets over the reals.

Lemma 1 *Let \mathbf{C} and \mathbf{D} be rational matrices of dimension $m \times n$ and $m \times p$ respectively, and let \mathbf{b} be a rational m -vector. If*

$$T = \{\mathbf{x} \in \mathbb{R}^n \mid \text{there exists } \mathbf{y} \in \mathbb{R}^p \text{ with } \mathbf{C}\mathbf{x} + \mathbf{D}\mathbf{y} = \mathbf{b}\},$$

and if Δ is a basis of $N(\mathbf{D}^T)$, then

$$T = \{\mathbf{x} \in \mathbb{R}^n \mid \Delta^T \mathbf{C}\mathbf{x} = \Delta^T \mathbf{b}\}.$$

Proof: Multiplying by Δ^T , it is immediate that $\{\mathbf{x} \in \mathbb{R}^n \mid \text{there exists } \mathbf{y} \in \mathbb{R}^p \text{ with } \mathbf{C}\mathbf{x} + \mathbf{D}\mathbf{y} = \mathbf{b}\} \subseteq \{\mathbf{x} \in \mathbb{R}^n \mid \Delta^T \mathbf{C}\mathbf{x} = \Delta^T \mathbf{b}\}$ as $\Delta^T \mathbf{D} = \mathbf{0}$. If the inclusion is strict, there exists $\mathbf{x}^* \in \mathbb{R}^n$ such that $\Delta^T \mathbf{C}\mathbf{x}^* = \Delta^T \mathbf{b}$, but $\{\mathbf{y} \in \mathbb{R}^p \mid \mathbf{D}\mathbf{y} = \mathbf{b} - \mathbf{C}\mathbf{x}^*\} = \emptyset$. This implies the existence of a vector \mathbf{u} such that $\mathbf{u}\mathbf{D} = \mathbf{0}$ and $\mathbf{u}(\mathbf{b} - \mathbf{C}\mathbf{x}^*) \neq 0$. However as Δ is a basis of $N(\mathbf{D}^T)$, there exists \mathbf{v} such that $\mathbf{u} = \mathbf{v}\Delta^T$. But now $\mathbf{u}(\mathbf{b} - \mathbf{C}\mathbf{x}^*) = \mathbf{v}\Delta^T(\mathbf{b} - \mathbf{C}\mathbf{x}^*) = 0$, a contradiction. \square

The set of nonnegative (positive) integers in \mathbb{R}^n is denoted by \mathbb{Z}_+^n ($\mathbb{Z}_{>0}^n$). Similar notation is used for the nonnegative real numbers.

2 Formulations for equality constrained integer programs

Our goal in this section is to derive reformulations of the integer programming equality set

$$X = \{\mathbf{x} \in \mathbb{Z}^n \mid \mathbf{A}\mathbf{x} = \mathbf{b}\}$$

and the associated affine set

$$Y = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{A}\mathbf{x} = \mathbf{b}\},$$

where $\mathbf{A} \in \mathbb{Z}^{m \times n}$ and $\mathbf{b} \in \mathbb{Z}^m$. Later these will be used in testing feasibility or optimizing over the set $X^+ = X \cap \mathbb{Z}_+^n$.

Throughout the paper we will assume that $X \neq \emptyset$. This can be tested by calculating $\text{HNF}(\mathbf{A})$. Note that for any point $\mathbf{x}^0 \in X$, we can then write $X = \{\mathbf{x} \in \mathbb{Z}^n \mid \mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{x}^0\}$.

We will be dealing with the kernel lattice $L(N(\mathbf{A})) = \{\mathbf{y} \in \mathbb{Z}^n \mid \mathbf{A}\mathbf{y} = \mathbf{0}\}$. We assume that $\text{rank}(\mathbf{A}) = m$, so $\text{rk}(L(N(\mathbf{A}))) = n - m$.

The following is immediate as $\mathbf{x} \in X$ if and only if $\mathbf{x} - \mathbf{x}^0 \in L(N(\mathbf{A}))$.

Observation 2 *Let $\mathbf{Q} \in \mathbb{Z}^{n \times (n-m)}$ be a lattice basis of $L(N(\mathbf{A}))$. Then*

$$X = \{\mathbf{x}^0\} + L(N(\mathbf{A})) = \{\mathbf{x} \mid \mathbf{x} = \mathbf{x}^0 + \mathbf{Q}\boldsymbol{\mu}, \boldsymbol{\mu} \in \mathbb{Z}^{n-m}\}.$$

Now we derive a larger family of reformulations of the set X . Specifically suppose that two matrices $\mathbf{P} \in \mathbb{Z}^{(m+s) \times n}$ and $\mathbf{M} \in \mathbb{Z}^{m \times (m+s)}$ are given satisfying $\mathbf{A} = \mathbf{M}\mathbf{P}$. Two natural questions are:

1. Under what conditions does there exist an extended formulation for X of the form

$$X = \{x \in \mathbb{Z}^n \mid \mathbf{P}x = \mathbf{P}x^0 + \mathbf{T}\mu, \mu \in \mathbb{Z}^s\}$$

where $\mathbf{T} \in \mathbb{Z}^{(m+s) \times s}$?

2. How should one choose the matrices $\mathbf{P}, \mathbf{M}, \mathbf{T}$ so as to obtain “interesting” extended formulations?

We will use the following notation:

$$U^{\mathbf{P}, \mathbf{T}} = \{(x, \mu) \in \mathbb{Z}^n \times \mathbb{Z}^s \mid \mathbf{P}x = \mathbf{P}x^0 + \mathbf{T}\mu\} \text{ and } X^{\mathbf{P}, \mathbf{T}} = \text{proj}_x U^{\mathbf{P}, \mathbf{T}}.$$

$$V^{\mathbf{P}, \mathbf{T}} = \{(x, \mu) \in \mathbb{R}^n \times \mathbb{R}^s \mid \mathbf{P}x = \mathbf{P}x^0 + \mathbf{T}\mu\}, \text{ and } Y^{\mathbf{P}, \mathbf{T}} = \text{proj}_x V^{\mathbf{P}, \mathbf{T}}.$$

Here, $\text{proj}_x U^{\mathbf{P}, \mathbf{T}} = \{x \in \mathbb{Z}^n \mid \text{there exists } \mu \in \mathbb{Z}^s \text{ with } (x, \mu) \in U^{\mathbf{P}, \mathbf{T}}\}$. In this notation $X = X^{\mathbf{A}, \mathbf{0}}$ and Observation 2 states that $X = X^{\mathbf{I}, \mathbf{Q}}$ when \mathbf{Q} is a lattice basis of $N(L(\mathbf{A}))$.

In Propositions 3 and 4 below we address the first question, and derive conditions ensuring that $X = X^{\mathbf{P}, \mathbf{T}}$.

Proposition 3 *Suppose that \mathbf{A}, \mathbf{P} and \mathbf{M} are given with $\mathbf{P} \in \mathbb{Z}^{(m+s) \times n}$, $\mathbf{M} \in \mathbb{Z}^{m \times (m+s)}$ and $\mathbf{A} = \mathbf{M}\mathbf{P}$. Then*

$$X = X^{\mathbf{P}, \mathbf{T}}$$

if $\mathbf{T} \in \mathbb{Z}^{(m+s) \times s}$ is a lattice basis of $L(N(\mathbf{M}))$.

Proof: If $x \in X^{\mathbf{P}, \mathbf{T}}$, then there exists μ such that $(x, \mu) \in U^{\mathbf{P}, \mathbf{T}}$. Left multiplying by \mathbf{M} , we see that $\mathbf{M}\mathbf{P}x = \mathbf{M}\mathbf{P}x^0 + \mathbf{M}\mathbf{T}\mu = \mathbf{M}\mathbf{P}x^0$, or $\mathbf{A}x = \mathbf{A}x^0$. So $X^{\mathbf{P}, \mathbf{T}} \subseteq X$.

Conversely $x \in X$ implies that $\mathbf{A}x = \mathbf{A}x^0$, or that $\mathbf{M}\mathbf{P}(x - x^0) = \mathbf{0}$. As $\mathbf{P}(x - x^0) \in \mathbb{Z}^{m+s}$ and \mathbf{T} is a lattice basis of $L(N(\mathbf{M}))$, $\mathbf{P}(x - x^0) = \mathbf{T}\mu$ for some $\mu \in \mathbb{Z}^s$. Thus $X \subseteq X^{\mathbf{P}, \mathbf{T}}$. \square

Note that a slightly stronger statement can be made.

Proposition 4 *If the Hermite Normal Form of \mathbf{P} is of the form $(\mathbf{I}, \mathbf{0})$, then*

$$X = X^{\mathbf{P}, \mathbf{T}}$$

if and only if $\mathbf{T} \in \mathbb{Z}^{(m+s) \times s}$ is a lattice basis of $L(N(\mathbf{M}))$.

Proof: Necessarily if $X = X^{\mathbf{P}, \mathbf{T}}$, then the columns of \mathbf{T} lie in $L(N(\mathbf{M}))$. If they do not form a lattice basis, there exists $\mathbf{t}^* \in L(N(\mathbf{M}))$ that is not in the sublattice $L(\mathbf{T})$. Also, as $\text{HNF}(\mathbf{P}) = (\mathbf{I}, \mathbf{0})$, there exists \mathbf{x}^* such that $\mathbf{P}\mathbf{x}^* = \mathbf{t}^*$. Now the point $\mathbf{y}^* = \mathbf{x}^0 + \mathbf{x}^*$ lies in X as $\mathbf{A}\mathbf{y}^* - \mathbf{A}\mathbf{x}^0 = \mathbf{A}\mathbf{x}^* = \mathbf{M}\mathbf{P}\mathbf{x}^* = \mathbf{M}\mathbf{t}^* = \mathbf{0}$, but $\mathbf{P}(\mathbf{y}^* - \mathbf{x}^0) = \mathbf{P}\mathbf{x}^* = \mathbf{t}^* \neq \mathbf{T}\mu$ for any $\mu \in \mathbb{Z}^s$, and thus $X \neq X^{\mathbf{P}, \mathbf{T}}$. \square

Here we address the second question specifying one way to choose appropriate matrices \mathbf{P} and \mathbf{T} . The more restrictive conditions imposed will be used in Sections 3 and 4.1 to make “good” choices using reduced bases.

Consider a sublattice L' of $L(N(\mathbf{A}))$ of rank $0 \leq r \leq n - m$ with lattice basis $\mathbf{R} \in \mathbb{Z}^{n \times r}$, and $\mathbf{Q} = (\mathbf{R}, \mathbf{S})$ an extension to a basis of $L(N(\mathbf{A}))$. Let $\mathbf{P}^T \in \mathbb{Z}^{n \times n-r}$ be a lattice basis of $L(N(\mathbf{R}^T)) = \{\mathbf{y} \in \mathbb{Z}^n \mid \mathbf{R}^T \mathbf{y} = \mathbf{0}\}$, and $s = n - m - r$.

With \mathbf{P} constructed in this way, we have that:

- i) $\mathbf{A} = \mathbf{M}\mathbf{P}$ for some $m \times (m+s)$ integer matrix \mathbf{M} . $\mathbf{R} \subseteq \mathbf{Q}$ implies $L(N(\mathbf{Q}^T)) \subseteq L(N(\mathbf{R}^T))$, and as $\mathbf{A}^T \in L(N(\mathbf{Q}^T))$ and $\mathbf{P}^T \in L(N(\mathbf{R}^T))$, the claim follows.
- ii) $\mathbf{T} = \mathbf{P}\mathbf{S}$.

Theorem 5 For any lattice basis \mathbf{R} of a sublattice of $L(N(\mathbf{A}))$

$$\begin{aligned} X &= X^{\mathbf{P}, \mathbf{P}\mathbf{S}} \\ Y &= Y^{\mathbf{P}, \mathbf{P}\mathbf{S}}. \end{aligned}$$

Proof: We show that $X^{I, \mathbf{Q}} \subseteq X^{\mathbf{P}, \mathbf{P}\mathbf{S}} \subseteq X$. If $\mathbf{x} \in X^{I, \mathbf{Q}}$, then there exists $\boldsymbol{\mu}$ such that $(\mathbf{x}, \boldsymbol{\mu}) \in U^{I, \mathbf{Q}}$, and then multiplying through by \mathbf{P} , we see that $(\mathbf{x}, \boldsymbol{\mu}) \in U^{\mathbf{P}, \mathbf{P}\mathbf{S}}$ as $\mathbf{P}\mathbf{R} = \mathbf{0}$ and thus $\mathbf{x} \in X^{\mathbf{P}, \mathbf{P}\mathbf{S}}$. If $\mathbf{x} \in X^{\mathbf{P}, \mathbf{P}\mathbf{S}}$, then left multiplying by \mathbf{M} gives $\mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{x}^0 = \mathbf{b}$ as $\mathbf{M}\mathbf{P}\mathbf{S} = \mathbf{A}\mathbf{S} = \mathbf{0}$, and thus $\mathbf{x} \in X^{\mathbf{A}, \mathbf{0}}$. As $X^{I, \mathbf{Q}} = X^{\mathbf{A}, \mathbf{0}}$, equality holds for all \mathbf{P} .

$Y^{I, \mathbf{Q}} = Y^{\mathbf{P}, \mathbf{P}\mathbf{S}}$ follows immediately from Lemma 1 as \mathbf{P}^T is a basis for $L(N(\mathbf{R}^T))$, and $Y^{I, \mathbf{Q}} = Y^{\mathbf{A}, \mathbf{0}}$ follows from Lemma 1 as \mathbf{A}^T is a basis of $L(N(\mathbf{Q}))$. \square

Example 1 Consider a set $X = \{\mathbf{x} \in \mathbb{Z}^5 \mid \mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{x}^0\}$ of the form

$$\begin{array}{cccccc} x_1 & -5x_2 & -4x_3 & +11x_4 & +5x_5 & = & \mathbf{a}^1 \mathbf{x}^0 \\ -13x_1 & -2x_2 & -12x_3 & -11x_4 & +x_5 & = & \mathbf{a}^2 \mathbf{x}^0 \\ & & x & \in & \mathbb{Z}^5. & & \end{array}$$

Given

$$\mathbf{P} = \begin{pmatrix} 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & -1 & 1 & 0 \\ 0 & -1 & -1 & 2 & 1 \end{pmatrix} \text{ and } \mathbf{M} = \begin{pmatrix} 1 & 0 & 5 \\ -12 & -1 & 1 \end{pmatrix},$$

it is easily checked that $\mathbf{A} = \mathbf{M}\mathbf{P}$.

Now as $\mathbf{T} = \begin{pmatrix} -5 \\ 61 \\ 1 \end{pmatrix}$ is a basis of $L(N(\mathbf{M}))$, it follows from Proposition 3 that

$$\begin{array}{cccccc} 1x_1 & & +1x_3 & +1x_4 & & = & \mathbf{p}^1 \mathbf{x}^0 & -5\mu \\ 1x_1 & +1x_2 & -1x_3 & +1x_4 & & = & \mathbf{p}^2 \mathbf{x}^0 & +61\mu \\ & -1x_2 & -1x_3 & +2x_4 & +1x_5 & = & \mathbf{p}^3 \mathbf{x}^0 & +1\mu \\ & x & \in & \mathbb{Z}^5, & \mu & \in & \mathbb{Z}^1 & \end{array}$$

is an extended formulation for X .

An alternative is to calculate a basis \mathbf{Q} of $L(N(\mathbf{A}))$, namely

$$\mathbf{Q} = \begin{pmatrix} 1 & -1 & 13 \\ 0 & 2 & 16 \\ 0 & 1 & -25 \\ -1 & 0 & 7 \\ 2 & 3 & -22 \end{pmatrix}.$$

Taking \mathbf{R} to consist of the first two columns, and \mathbf{S} to be the last column, we have that \mathbf{P}^T from above is a basis of $L(N(\mathbf{R}^T))$ and $\mathbf{P}\mathbf{S} = \begin{pmatrix} -5 \\ 61 \\ 1 \end{pmatrix}$, so we arrive at the same extended formulation via the formulation of Theorem 5. \square

3 Knapsack sets replaced by two equations

Here we analyze the case $m = 1$ and $s = 1$ in more detail. Specifically we are interested in the sets X and Y when

$$\mathbf{a} = M_1\mathbf{p}^1 + M_2\mathbf{p}^2.$$

We suppose that $a_j > 0$ for all $1 \leq j \leq n$, that $\gcd(a_1, \dots, a_n) = 1$ and that $M_1, M_2 > 0$. Since $\gcd(a_1, \dots, a_n) = 1$, it follows that $\gcd(M_1, M_2) = 1$, which implies the existence of integers $\mathbf{q} \in \mathbb{Z}^2$ with $M_1q_1 + M_2q_2 = 1$. In addition we add the condition that $\text{HNF}(\mathbf{P}) = (\mathbf{I}, \mathbf{0})$. Note that if $\text{HNF}(\mathbf{P}) = (\mathbf{D}, \mathbf{0})$ with $\mathbf{D} \neq \mathbf{I}$, then it suffices to multiply the equation system by \mathbf{D}^{-1} and work with $\mathbf{P}' = \mathbf{D}^{-1}\mathbf{P}$.

From Proposition 3, we know that $X^{\mathbf{P}, \mathbf{T}} = X$, where $U^{\mathbf{P}, \mathbf{T}}$ is of the form

$$\begin{aligned} \mathbf{p}^1\mathbf{x} &= \mathbf{p}^1\mathbf{x}^0 + M_2\mu \\ \mathbf{p}^2\mathbf{x} &= \mathbf{p}^2\mathbf{x}^0 - M_1\mu \\ \mathbf{x} &\in \mathbb{Z}^n, \mu \in \mathbb{Z}^1. \end{aligned}$$

Note also that we can take $\mathbf{p}^i\mathbf{x}^0 = q_i b$ for $i = 1, 2$ as $M_1q_1 + M_2q_2 = 1$. This follows because $\mathbf{a}\mathbf{x}^0 - \mathbf{b} = M_1(\mathbf{p}^1\mathbf{x}^0 - q_1b) + M_2(\mathbf{p}^2\mathbf{x}^0 - q_2b) = 0$ and $\gcd(M_1, M_2) = 1$.

In the rest of this section we add a nonnegativity constraint on \mathbf{x} . Thus we consider

$$\begin{aligned} X_+ &= X \cap \mathbb{Z}_+^n = \{\mathbf{x} \in \mathbb{Z}_+^n \mid \mathbf{a}\mathbf{x} = b\} \text{ and} \\ Y_+ &= Y \cap \mathbb{R}_+^n = \{\mathbf{x} \in \mathbb{R}_+^n \mid \mathbf{a}\mathbf{x} = b\}. \end{aligned}$$

We derive two results. The first concerns the width of the polyhedron $V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}$ in the direction μ . The second uses the width to derive a lower bound on the Frobenius number, simplifying and generalizing the result of Aardal and Lenstra [4] that is valid under the assumptions that $\mathbf{p}^1 \in \mathbb{Z}_{>0}$ and $M_2 = 1$.

3.1 The integer width

The integer width of a rational polytope P in the integer direction \mathbf{d} , $w_I(P, \mathbf{d})$, is defined as

$$w_I(P, \mathbf{d}) = \lfloor \max\{\mathbf{d}^T \mathbf{x} \mid \mathbf{x} \in P\} \rfloor - \lceil \min\{\mathbf{d}^T \mathbf{x} \mid \mathbf{x} \in P\} \rceil + 1,$$

and is equal to the number of parallel lattice hyperplanes in direction \mathbf{d} that are intersecting P .

Our goal is to calculate the integer width of

$$V_+^{\mathbf{P}, \mathbf{PS}} = \{(\mathbf{x}, \mu) \in \mathbb{R}_+^n \times \mathbb{R} \mid \mathbf{p}^1 \mathbf{x} - M_2 \mu = q_1 b, \mathbf{p}^2 \mathbf{x} + M_1 \mu = q_2 b\}$$

To do this, let

$$\bar{V}_+^{\mathbf{P}, \mathbf{PS}} = \{(\mathbf{x}, \mu) \in \mathbb{R}_+^n \times \mathbb{R} \mid \mathbf{p}^1 \mathbf{x} - M_2 \mu = q_1, \mathbf{p}^2 \mathbf{x} + M_1 \mu = q_2\} \quad (2)$$

be the scaled down version of this polyhedron with $b = 1$.

Below we derive the values $\bar{z} = \max\{\mu \mid (\mathbf{x}, \mu) \in \bar{V}_+^{\mathbf{P}, \mathbf{PS}}\}$ and $\underline{z} = \min\{\mu \mid (\mathbf{x}, \mu) \in \bar{V}_+^{\mathbf{P}, \mathbf{PS}}\}$. Once we have the values \bar{z} and \underline{z} it will be straightforward to compute the width $w_I(V_+^{\mathbf{P}, \mathbf{PS}}, \mathbf{e}^{n+1})$ as $\lfloor b\bar{z} \rfloor - \lceil b\underline{z} \rceil + 1$.

Lemma 6 Consider formulation $\bar{V}_+^{\mathbf{P}, \mathbf{PS}}$ (2), and let $k = \arg \max\{i \mid p_i^1/a_i\}$ and $j = \arg \min\{i \mid p_i^1/a_i\}$. Then,

$$\bar{z} = \frac{p_k^1}{M_2 a_k} - \frac{q_1}{M_2} \text{ and } \underline{z} = \frac{p_j^1}{M_2 a_j} - \frac{q_1}{M_2}.$$

Proof: We consider the linear program

$$\begin{aligned} \bar{z} &= \max \mu \\ \text{s.t. } \mathbf{p}^1 \mathbf{x} - M_2 \mu &= q_1 & (3) \\ \mathbf{p}^2 \mathbf{x} + M_1 \mu &= q_2 & (4) \\ \mathbf{x} &\in \mathbb{R}_+^n, \quad \mu \in \mathbb{R}^1. \end{aligned}$$

Let γ be the dual variables corresponding to constraints (3)-(4). The corresponding dual problem is:

$$\bar{z} = \min \quad q_1 \gamma_1 + q_2 \gamma_2 \quad (5)$$

$$\text{s.t. } p_i^1 \gamma_1 + p_i^2 \gamma_2 \geq 0, \quad 1 \leq i \leq n, \quad (6)$$

$$-M_2 \gamma_1 + M_1 \gamma_2 = 1, \quad (7)$$

$$\gamma \in \mathbb{R}^2$$

From constraint (7) we obtain

$$\gamma_1 = \frac{M_1 \gamma_2 - 1}{M_2}. \quad (8)$$

Substituting for γ_1 in constraint (6) yields

$$p_i^1 \left(\frac{M_1 \gamma_2 - 1}{M_2} \right) + p_i^2 \gamma_2 \geq 0, \quad 1 \leq i \leq n.$$

Rewriting gives $\gamma_2(p_i^2 + p_i^1(M_1/M_2)) - p_i^1/M_2 \geq 0$ for $1 \leq i \leq n$, which in turn yields $\gamma_2 \geq \frac{p_i^1}{a_i}$, $1 \leq i \leq n$. We now obtain

$$\gamma_2 = \frac{p_k^1}{a_k}. \quad (9)$$

Finally, we substitute for $\boldsymbol{\gamma}$ in the dual objective function (5) using expressions (8) and (9) which yields the optimal dual objective value

$$\bar{z} = q_1 \left(\frac{M_1(p_k^1/a_k) - 1}{M_2} \right) + q_2 \frac{p_k^1}{a_k} = \frac{p_k^1}{a_k} \left(\frac{q_1 M_1 + q_2 M_2}{M_2} \right) - \frac{q_1}{M_2} = \frac{p_k^1}{M_2 a_k} - \frac{q_1}{M_2}.$$

The calculation of \underline{z} is almost identical. \square

Immediately we obtain the integer width.

Theorem 7

$$w_I(V_+^{\mathbf{P}, \mathbf{PS}}, \mathbf{e}^{n+1}) = \left\lfloor \frac{bp_k^1}{M_2 a_k} - \frac{bq_1}{M_2} \right\rfloor - \left\lceil \frac{bp_j^1}{M_2 a_j} - \frac{bq_1}{M_2} \right\rceil + 1,$$

where the indices j and k are defined as in Lemma 6.

Notice that the choice of a valid \mathbf{q} does not influence the width $w(V_+^{\mathbf{P}, \mathbf{PS}}, \mathbf{e}^{n+1})$. Suppose $\mathbf{q}' \in \mathbb{Z}^2$ satisfies $M_1 q'_1 + M_2 q'_2 = 1$. The set of all valid $(q_1, q_2)^T$ can be written as

$$\begin{pmatrix} q_1 \\ q_2 \end{pmatrix} = \begin{pmatrix} q'_1 \\ q'_2 \end{pmatrix} + \lambda \begin{pmatrix} -M_2 \\ M_1 \end{pmatrix},$$

where $\lambda \in \mathbb{Z}$. Thus a different choice of q_1 just means that the whole interval $[\underline{z}, \bar{z}]$ is shifted by an integer amount λ .

Observe also that given the choice of \mathbf{R} , any lattice basis \mathbf{P} of $L(N(\mathbf{R}^T))$ yields the same width. The multipliers M_1, M_2 as well as the values q_1, q_2 do however change with different choices of \mathbf{P} .

Example 2 Consider the following input vector \mathbf{a}

$$\mathbf{a} = (12223, 12224, 36674, 61119, 85569).$$

This is instance `cuw1` from Cornuéjols et al. [7]. With

$$\mathbf{P} = \begin{pmatrix} -1 & 0 & 2 & -1 & 1 \\ 2 & 1 & 1 & 6 & 6 \end{pmatrix}.$$

and $(M_1, M_2) = (12225, 12224)$, we have that $\mathbf{a} = \mathbf{M}\mathbf{P}$, $\text{HNF}(\mathbf{P}) = (\mathbf{I}, \mathbf{0})$.

Now we apply Theorem 7 with right-hand side $b = 89,643,481$, which is the Frobenius number of \mathbf{a} . We have $j = 1$, $k = 3$, $q_1 = 1$, $q_2 = -1$. We obtain

$$\begin{aligned} w_I(V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}, e^{n+1}) &= \\ &= \left\lfloor \frac{bp_k^1}{M_2 a_k} - \frac{bq_1}{M_2} \right\rfloor - \left\lfloor \frac{bp_j^1}{M_2 a_j} - \frac{bq_1}{M_2} \right\rfloor + 1 = \left\lfloor \frac{bp_3^1}{M_2 a_3} - \frac{bq_1}{M_2} \right\rfloor - \left\lfloor \frac{bp_1^1}{M_2 a_1} - \frac{bq_1}{M_2} \right\rfloor + 1 = \\ &= \left\lfloor \frac{89643481}{12224} \left(\frac{2}{36674} - 1 \right) \right\rfloor - \left\lfloor \frac{89643481}{12224} \left(\frac{-1}{12223} - 1 \right) \right\rfloor + 1 = \\ &= \lfloor -7333.00003 \rfloor - \lfloor -7333.9999 \rfloor + 1 = -7334 + 7333 + 1 = 0. \end{aligned}$$

It follows that $U_+^{\mathbf{P}, \mathbf{P}\mathbf{S}} = \emptyset$. Applying branch-and-bound, and branching first on the μ variable, this infeasibility would immediately be apparent. This is not the case using branch and bound starting from the original formulation $X_+^{\mathbf{A}, \mathbf{0}} = \{x \in \mathbb{Z}_+^n \mid \mathbf{a}\mathbf{x} = b\}$. In particular Cplex fails to prove infeasibility within 500 million nodes. \square

A natural question is whether the integer width differs if we use a different member of the family of extended formulations. Consider the sets

$$V_+^{\mathbf{I}, \mathbf{Q}} = \{(\mathbf{x}, \boldsymbol{\mu}) \in \mathbb{R}_+^n \times \mathbb{R}^{s+r} \mid \mathbf{I}\mathbf{x} = \mathbf{I}\mathbf{x}^0 + \mathbf{S}\boldsymbol{\mu}^S + \mathbf{R}\boldsymbol{\mu}^R\}$$

and

$$V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}} = \{(\mathbf{x}, \boldsymbol{\mu}) \in \mathbb{R}_+^n \times \mathbb{R}^s \mid \mathbf{P}\mathbf{x} = \mathbf{P}\mathbf{x}^0 + \mathbf{P}\mathbf{S}\boldsymbol{\mu}^S\}$$

as described in Theorem 5. Using Lemma 1, we have that

$$\text{proj}_{\mathbf{x}, \boldsymbol{\mu}^S} V_+^{\mathbf{I}, \mathbf{Q}} = V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}.$$

Thus we have

Proposition 8 $w_I(V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}, \mathbf{d}) = w_I(V_+^{\mathbf{I}, \mathbf{Q}}, (\mathbf{d}, \mathbf{0}))$, where \mathbf{d} is any integer cost vector over the $(\mathbf{x}, \boldsymbol{\mu}^S)$ variables.

In particular, when $m = 1$, $s = 1$, and \mathbf{d} is the unit vector corresponding to the last column of \mathbf{S} , then $w_I(V_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}, e^{n+1}) = w_I(V_+^{\mathbf{I}, \mathbf{Q}}, (e^{n+1}, \mathbf{0}))$.

3.2 A lower bound on the Frobenius number

The Frobenius number of \mathbf{a} , $F(\mathbf{a})$, is the largest integer value of b such that $\mathbf{a}\mathbf{x} = b$ does not have a nonnegative integer solution. Wlog we choose \mathbf{q} such that $|q_1| \leq M_2/2$. So, if $|q'_1| > M_2/2$, we can determine new valid values of q_1, q_2 such that $|q'_1| \leq M_2/2$ by identifying an appropriate value of λ . In this section we still assume that $\text{HNF}(\mathbf{P}) = (\mathbf{I}, \mathbf{0})$.

Theorem 9 Let $\mathbf{a} = M_1\mathbf{p}^1 + M_2\mathbf{p}^2$ with $\mathbf{a}, M_1, M_2, \mathbf{p}^1, \mathbf{p}^2$ satisfying the assumptions given in the beginning of Section 3. Moreover, let \underline{z}, \bar{z} and the indices j and k be as defined in Lemma 6.

If $(-M_2/2) \leq q_1 \leq 0$ and

$$1a) \frac{p_j^1}{a_j} > q_1$$

$$2a) \frac{p_k^1}{a_k} < M_2 + q_1$$

$$3a) \left(\frac{1-\bar{z}}{\bar{z}-\underline{z}}\right)\underline{z} \notin \mathbb{Z}$$

then

$$F(\mathbf{a}) \geq \frac{a_j a_k (M_2 + q_1) - p_k^1 a_j}{p_k^1 a_j - p_j^1 a_k} - \frac{M_2}{\frac{p_j^1}{a_j} - q_1}. \quad (10)$$

or if $0 < q_1 \leq M_2/2$ and

$$1b) \frac{p_j^1}{a_j} > -M_2 + q_1$$

$$2b) \frac{p_k^1}{a_k} < q_1$$

$$3b) \left(\frac{1+\underline{z}}{\bar{z}-\underline{z}}\right)\bar{z} \notin \mathbb{Z},$$

then

$$F(\mathbf{a}) \geq \frac{a_j a_k (M_2 - q_1) + p_j^1 a_k}{p_k^1 a_j - p_j^1 a_k} + \frac{M_2}{\frac{p_k^1}{a_k} - q_1}.$$

Proof:

We have already determined the width of $\bar{V}_+^{\mathbf{P}, \mathbf{P}\mathbf{S}}$ in the direction of μ corresponding to $b = 1$ in the proof of Lemma 6. Specifically we have shown that μ lies in the interval $[I_j, I_k]$, where

$$I_j := \underline{z} = \frac{p_j^1}{M_2 a_j} - \frac{q_1}{M_2} \text{ and } I_k := \bar{z} = \frac{p_k^1}{M_2 a_k} - \frac{q_1}{M_2},$$

whose width is

$$D := I_k - I_j = \frac{a_j p_k^1 - a_k p_j^1}{M_2 a_j a_k} > 0.$$

Any integer right-hand side value $b = t$ for which the corresponding interval $[tI_j, tI_k]$ does not contain an integer is a lower bound on the Frobenius number $F(\mathbf{a})$. Below we will show that

$$t \geq \frac{a_j a_k (M_2 + q_1) - p_k^1 a_j}{p_k^1 a_j - p_j^1 a_k} - \frac{M_2}{\frac{p_j^1}{a_j} - q_1}$$

is such a lower bound in the case that $-M_2/2 \leq q_1 < 0$. A sketch of the proof for the case $0 < q_1 \leq M_2/2$ is given in Appendix 1.

If $q_1 \leq 0$, Assumptions 1a and 2a imply that $0 < I_j < I_k < 1$. Moreover, since $q_1 \geq -M_2/2$ we obtain $I_k \leq p_k^1/(M_2 a_2) + 1/2$. Let $s := \frac{1-I_k}{D}$. Notice that $1 - I_k > 0$ since $I_k < 1$. The interval $[sI_j, sI_k]$ has length $1 - I_k$. Notice that $sI_j \notin \mathbb{Z}$ due to Assumption 3 of the theorem. Define $\ell := \lfloor sI_j \rfloor$ and $s' := \ell/I_j$. The number s' satisfies $s - \frac{1}{I_j} < s' < s$, and yields the interval $[I'_j, I'_k] := [s'I_j, s'I_k]$, with I'_j integral. The length of $[I'_j, I'_k]$ is less than the length $1 - I_k$ of $[sI_j, sI_k]$. Therefore, $[I'_j, I'_k + I_k]$ has length less than 1, and since I'_j is integral it follows that $(I'_j, I'_k + I_k)$ does not contain an integer.

Now, define $s^* := \lfloor s' \rfloor + 1$ and the interval $[I_j^*, I_k^*] := [s^*I_j, s^*I_k]$. We have $I'_j < I_j^* \leq I'_j + I_j$ and $I'_k < I_k^* \leq I'_k + I_k$. The result that $[I_j^*, I_k^*]$ does not contain an integer follows from the observation that $(I'_j, I'_k + I_k)$ does not contain an integer.

We finally observe that

$$s^* = \lfloor s' \rfloor + 1 > \lfloor s - \frac{1}{I_j} \rfloor + 1 \geq s - \frac{1}{I_j} - 1 + 1 = s - \frac{1}{I_j},$$

so we can conclude that $s - \frac{1}{I_j} = \frac{1-I_k}{D} - \frac{1}{I_j}$ yields a lower bound on the Frobenius number $F(\mathbf{a})$. Rewriting $\frac{1-I_k}{D} - \frac{1}{I_j}$ results in the expression

$$\frac{1 - I_k}{D} - \frac{1}{I_j} = \frac{1 - \frac{p_k^1}{M_2 a_k} + \frac{q_1}{M_2}}{\frac{a_j p_k^1 - a_k p_j^1}{M_2 a_j a_k}} - \frac{1}{\frac{p_j^1}{M_2 a_j} - \frac{q_1}{M_2}} = \frac{a_j a_k (M_2 + q_1) - p_k^1 a_j}{p_k^1 a_j - p_j^1 a_k} - \frac{M_2}{\frac{p_j^1}{a_j} - q_1}.$$

□

We notice the similarity with the expression for the lower bound on the Frobenius number derived by Aardal and Lenstra [4] for the case that $M_2 = 1$ and $\mathbf{p}^1 \in \mathbb{Z}_{>0}^n$. If we set $M_2 = 1$ and $q = 0$ in Expression (10) we obtain

$$\frac{a_j a_k - p_k^1 a_j}{p_k^1 a_j - p_j^1 a_k} - \frac{a_j}{p_j^1}.$$

The only difference in the two expressions is in the numerator of the first term, where we have $p_k^1 a_j$ instead of $2p_j^1 a_k$ in [4]. This is a result of a different choice of the number s in the proof. In [4] s was chosen as $s = (1 - 2I_j)/D$ under a constraint on the relationship between I_j and I_k .

4 Computation

4.1 Using reduced bases to find structure

Aardal and Lenstra [4] considered knapsack instances in which the input vector \mathbf{a} can be decomposed as $\mathbf{a} = M_1 \mathbf{p}^1 + M_2 \mathbf{p}^2$, and used the reformulation earlier suggested in

[3], cf. formulation $X^{I,Q}$:

$$\mathbf{x} = \mathbf{x}^0 + \mathbf{Q}\boldsymbol{\mu},$$

where \mathbf{x}^0 and \mathbf{Q} is as described in Section 2. They observed that if \mathbf{a} is long, \mathbf{p}^1 and \mathbf{p}^2 are short compared to \mathbf{a} , and if the basis \mathbf{Q} is reduced, then the first $n - 2$ basis vectors of \mathbf{Q} are short, and the last, $(n - 1)$ st basis vector is long. This can be explained as follows. First we observe that the orthogonal complement of the plane spanned by the vectors \mathbf{p}^1 and \mathbf{p}^2 is equal to $N(\mathbf{P}) \subset N(\mathbf{a})$. If \mathbf{p}^1 and \mathbf{p}^2 are short, the lattice $L(N(\mathbf{P}))$ contains short vectors yielding a relatively small lattice determinant. The rank of $L(N(\mathbf{P}))$, which is a sublattice of $L(N(\mathbf{a}))$, is just one less than the rank of $L(N(\mathbf{a}))$. Moreover, the determinant of the lattice $L(N(\mathbf{a}))$ is equal to the length of the vector \mathbf{a} . So, the large value of $d(L(N(\mathbf{a})))$ mainly has to be contributed by the basis vector that is in $L(N(\mathbf{a}))$ but not in $L(N(\mathbf{P}))$. Since basis reduction orders the basis vectors in nondecreasing order of length, up to a multiplier, this basis vector is the last one in a reduced basis.

In general, we can derive a suitable decomposition of \mathbf{A} , in case no such decomposition is known a priori, by using the following algorithm.

- i) Derive a reduced basis \mathbf{Q} of $L(N(\mathbf{A}))$, see (1) in Section 1.1.
- ii) Suppose \mathbf{Q} consists of s long vectors and $r = n - m - s$ short ones. How to define “long” and “short” is up to the user. (If all vectors of \mathbf{Q} are of approximately the same length we set $s = n - m$). We define \mathbf{R} to be the set of short vectors of \mathbf{Q} and \mathbf{S} to be the set of long ones.
- iii) Find a reduced basis \mathbf{P}^T of $L(N(\mathbf{R}^T))$.
- iv) Solve the system of equations $\mathbf{M}\mathbf{P} = \mathbf{A}$, $\mathbf{M} \in \mathbb{Z}^{m \times (m+s)}$ to find the matrix of multipliers \mathbf{M} .

Example 3 We consider the same instance as in Example 2 with

$$\mathbf{a} = (12223, 12224, 36674, 61119, 85569).$$

Here we show how its hidden structure can be uncovered.

A reduced basis of $L(N(\mathbf{a}))$ is equal to

$$\mathbf{Q} = \begin{pmatrix} 0 & -3 & -1 & 2059 \\ 1 & 1 & -3 & 157 \\ -1 & -1 & -1 & -3336 \\ -1 & 1 & 0 & 2687 \\ 1 & 0 & 1 & -806 \end{pmatrix}.$$

Here we observe that the last column of the reduced basis \mathbf{Q} is much longer than the other columns. Taking $r = 3$ and $s = 1$, \mathbf{R} will consist of the first three columns of

\mathbf{Q} , and \mathbf{S} will consist of the last column of \mathbf{Q} . A reduced basis \mathbf{P}^T for the lattice $L(N(\mathbf{R}^T))$ is

$$\mathbf{P}^T = \begin{pmatrix} -1 & 2 \\ 0 & 1 \\ 2 & 1 \\ -1 & 6 \\ 1 & 6 \end{pmatrix}.$$

The vector $(M_1, M_2) = (12225, 12224)$ solves $\mathbf{M}\mathbf{P} = \mathbf{a}$. We can now write $\mathbf{a} = 12225\mathbf{p}^1 + 12224\mathbf{p}^2$, with \mathbf{p}^1 being the first row of \mathbf{P} , and \mathbf{p}^2 being the second row of \mathbf{P} . Note that the matrix \mathbf{P} obtained is not unique. In Example 2 a closely related but different basis of $L(N(\mathbf{R}^T))$ is considered. \square

4.2 Feasibility testing and quality of the Frobenius bound

We tested the quality of the extended formulations for different choices of s on some instances of integer equality knapsacks and the Cornuéjols-Dawande market split problem. For all instances of both problem types we compute a reduced basis \mathbf{Q} and a vector \mathbf{x}^0 as described in Section 1.1, and derive matrices \mathbf{P} and \mathbf{M} as described in Section 4.1.

The integer knapsack instances were taken from Aardal and Lenstra [4]. Instances prob1–4 are such that the vector \mathbf{a} decomposes with short \mathbf{p}^1 , \mathbf{p}^2 , whereas for the instances prob11–14 the \mathbf{a} -coefficients, randomly generated from $U[10000, 150000]$, are of the same size on average as in prob1–4. Instances prob11–14 have no apparent structure, and the columns of a reduced basis \mathbf{Q} of $L(N(\mathbf{A}))$ are of approximately the same length. We use the Frobenius number of the vector \mathbf{a} as right-hand side coefficient for all knapsack instances. Instances prob1–4 have 8 variables and prob10–14 have 10 variables. For details of the instances, see [4].

The market split instances [6] are multiple row equality knapsack problems in $\{0, 1\}$ -variables with m rows and $n = 10(m - 1)$ variables. The elements of \mathbf{a}^i for each row i are generated randomly from $U[0, 99]$, and the right-hand side coefficients are calculated as $b_i = \lfloor (\sum_{j=1}^n a_j^i) / 2 \rfloor$. We generated two sets of market split instances with 4 constraints and 30 variables, and 5 constraints and 40 variables respectively.

In Tables 1–3 we report on the number of nodes used by the integer programming solver Xpress Version 16.01.01 [16] to solve the various reformulations. Column “orig” refers to the original formulation in \mathbf{x} -variables. Column “AHL” refers to the Aardal-Hurkens-Lenstra lattice reformulation in which the \mathbf{x} -variables have been removed from the formulation, i.e., the formulation $\{\boldsymbol{\mu} \in \mathbb{Z}^{n-1} \mid \mathbf{Q}\boldsymbol{\mu} \geq -\mathbf{x}^0\}$ in the knapsack case and the formulation $\{\boldsymbol{\mu} \in \mathbb{Z}^{n-m} \mid -\mathbf{x}^0 \leq \mathbf{Q}\boldsymbol{\mu} \leq 1 - \mathbf{x}^0\}$ in the market split case. For formulations $U_+^{\mathbf{P}, \mathbf{PS}}$ we report on results for different values of s . Notice that the formulations AHL and $U_+^{\mathbf{P}, \mathbf{PS}}$ for $s = n - m$ are mathematically equivalent, but the $U_+^{\mathbf{P}, \mathbf{PS}}$ -formulations contain the \mathbf{x} -variables with the identity matrix as coefficients.

Table 1: The number of branch-and-bound nodes needed to solve the various reformulations for the knapsack instances.

Instance	orig	AHL	$U_+^{P,PS}$							
			$s = 1$	$s = 2$	$s = 3$	$s = 4$	$s = 5$	$s = 6$	$s = 7$	$s = 9$
prob1	> 100 mill.	1	59	15	3	3	1	1	1	–
prob2	> 100 mill.	3	23	7	3	1	1	1	1	–
prob3	> 100 mill.	13	37	29	5	7	11	9	5	–
prob4	> 100 mill.	3	13	5	1	1	1	1	1	–
prob11	100,943	61	2237	7683	317	89	51	69	49	61
prob12	160,783	93	10,981	1105	967	523	179	105	117	71
prob13	188,595	91	10,205	12,261	239	321	35	57	39	59
prob14	140,301	87	2443	627	689	389	283	115	105	87

Since the solver reacts differently to the presence of the redundant \mathbf{x} -variables, this leads to slight deviations in the number of enumeration nodes needed.

Instances prob1–4, which decompose in short $\mathbf{p}^1, \mathbf{p}^2$, are very difficult to tackle with branch-and-bound applied to the original formulation. The Frobenius numbers for these instances are also large, see Table 4. None of the instances could be solved within 100 million nodes. As could be expected, the $U_+^{P,PS}$ -formulation with $s = 1$, which is a formulation with the \mathbf{x} -variables and one variable μ , is easy to solve and comparable to the AHL-formulation. In contrast, instances prob11–14 are solvable using the original formulation, mainly due to the smaller value of the right-hand side coefficients. Here, one could expect that we would need to set $s = n - m$ to see a noticeable improvement compared to the original formulation, but in fact even taking $s = 1$ reduces the number of enumeration nodes by at least an order of magnitude, and with s around 5 we obtain results comparable to those obtained with the AHL-formulation.

Table 2: The number of branch-and-bound nodes needed to solve the various reformulations: CD-instances 4×30 .

Instance	orig	AHL	$U_+^{P,PS}$ -ref					
			$s = 1$	$s = 5$	$s = 10$	$s = 15$	$s = 20$	$s = 26$
$4 \times 30_1$	157,569	281	124,695	71641	8033	1397	1021	607
$4 \times 30_2$	169,455	167	154,505	51989	3794	1487	610	535
$4 \times 30_3$	209,741	325	178,697	181,373	32,367	1831	1025	845
$4 \times 30_4$	202,513	199	156,047	4685	3583	829	493	9527
$4 \times 30_5$	115,173	311	73,151	17,201	1197	391	353	3135

Table 3: The number of branch-and-bound nodes needed to solve the various reformulations: CD-instances 5×40 .

Instance	orig	AHL	$U_+^{P,PS}$ -ref				
			$s = 5$	$s = 10$	$s = 20$	$s = 30$	$s = 35$
$5 \times 40_1$	> 10,000,000	5873	> 10,000,000	3,144,737	160,701	32,507	32,099
$5 \times 40_2$	> 10,000,000	1643	> 10,000,000	2,821,042	128,707	30,302	12,734
$5 \times 40_3$	> 10,000,000	7349	> 10,000,000	8,264,955	86,483	28,491	25,541
$5 \times 40_4$	> 10,000,000	6870	> 10,000,000	1,854,280	70,949	19,616	16,557
$5 \times 40_5$	> 10,000,000	6651	> 10,000,000	7,805,023	1,107,713	35,989	36,897

For the market split instances, which have no clear structure of the Q -matrix, we notice similar results to those obtained for the knapsack instances prob11–14. The algorithm of Section 4.1 prescribes $s = n - m$ for these types of instances. The computational results suggest that smaller values of s already yield significant computational improvement.

In Table 4 we report on the value of the Frobenius number as well as the value produced by the lower bound given in Theorem 9. For instances prob1–4 the lower bound is of the same order of magnitude as the Frobenius number, whereas for instances prob11–14 the bound is off by an order of magnitude. The bound might be improved by a different choice of the value s in the proof of the theorem.

Table 4: The value of the lower bound of the Frobenius number.

Instance	$F(\mathbf{a})$	lower bound on $F(\mathbf{a})$
prob1	33,367,335	26,061,675
prob2	14,215,206	10,894,273
prob3	58,424,799	31,510,625
prob4	60,575,665	56,668,034
prob11	577,134	98,774
prob12	944,183	113,114
prob13	765,260	67,752
prob14	680,230	60,476

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Appendix 1

Proof of Theorem 6 for the case $0 < q_1 \leq (M_2/2)$.

If $0 < q_1 \leq (M_2/2)$, Assumptions 1b and 2b imply that $-1 < I_j < I_k < 0$, so the interval $[I_j, I_k]$ does not contain an integer. In addition, $I_j \geq p_j^1/(M_2 a_j) - 1/2$.

Let $s := \frac{1+I_j}{D}$. The length of the interval $[sI_j, sI_k]$ is equal to $1 + I_j$, and since $-1 < I_j < 0$ we have that $0 < 1 + I_j < 1$.

Notice that $sI_k \notin \mathbb{Z}$ due to Assumption 3b of the theorem. Define $\ell := \lceil sI_k \rceil$ and $s' := \ell/I_k$. The number s' satisfies $s + \frac{1}{I_k} < s' < s$, and yields the interval $[I'_j, I'_k] := [s'I_j, s'I_k]$, with I'_k integral. The length of $[I'_j, I'_k]$ is less than the length $1 + I_j$ of $[sI_j, sI_k]$. Therefore, $[I'_j + I_j, I'_k]$ has length less than 1, and since I'_k is integral it follows that $[I'_j + I_j, I'_k)$ does not contain an integer.

Now, define $s^* := \lfloor s' \rfloor + 1$ and the interval $[I_j^*, I_k^*] := [s^*I_j, s^*I_k]$. We have $I'_j + I_j \leq I_j^* < I'_j$ and $I'_k + I_k \leq I_k^* < I'_k$. The result that $[I_j^*, I_k^*]$ does not contain an integer follows from the observation that $[I'_j + I_j, I'_k)$ does not contain an integer.

We finally observe that

$$s^* = \lfloor s' \rfloor + 1 > \lfloor s + \frac{1}{I_k} \rfloor + 1 \geq s + \frac{1}{I_k} - 1 + 1 = s + \frac{1}{I_k},$$

so we can conclude that $s + \frac{1}{I_k} = \frac{1+I_j}{D} + \frac{1}{I_k}$ yields a lower bound on the Frobenius number $F(\mathbf{a})$. Rewriting $\frac{1+I_j}{D} + \frac{1}{I_k}$ results in the expression

$$\frac{1 + I_k}{D} + \frac{1}{I_k} = \frac{1 + \frac{p_j^1}{M_2 a_j} - \frac{q_1}{M_2}}{\frac{a_j p_k^1 - a_k p_j^1}{M_2 a_j a_k}} + \frac{1}{\frac{p_k^1}{M_2 a_k} - \frac{q_1}{M_2}} = \frac{a_j a_k (M_2 - q_1) + p_j^1 a_k}{p_k^1 a_j - p_j^1 a_k} + \frac{M_2}{\frac{p_k^1}{a_k} - q_1}.$$