CUMULATIVE EFFECTIVE HÖLDER EXPONENT BASED INDICATOR FOR REAL-TIME FETAL HEARTBEAT ANALYSIS DURING LABOUR

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We introduce a special purpose cumulative indicator, capturing in real time the cumulative deviation from the reference level of the exponent \( h \) (local roughness, Hölder exponent) of the fetal heartbeat during labour. We verify that the indicator applied to the variability component of the heartbeat coincides with the fetal outcome as determined by blood samples. The variability component is obtained from running real time decomposition of fetal heartbeat into independent components using an adaptation of an oversampled Haar wavelet transform. The particular filters used and resolutions applied are motivated by obstetrical insight/practice. The methodology described has the potential for real-time monitoring of the fetus during labour and for the prediction of the fetal outcome, alerting the attending staff in the case of (threatening) hypoxia.

1 Introduction

Methods of wavelet transform modulus maxima (WTMM) based multifractal analysis (MF) and detrended fluctuation analysis (DFA) have been demonstrated to be suitable for capturing scaling and correlation characteristics of the fluctuations in human heartbeat intervals\(^1,2,3,4\). These characteristics, obtained under a variety of conditions, have also been shown to reflect deviations in the heartbeat due to a variety of malfunctions\(^5,6,7\) and physiological behaviour\(^8,9,10\). Obviously, these results can be considered for clinical applications.

Unfortunately, such standard methods of statistical analysis of heartbeat signals are not directly applicable to the practical problem of evaluating (the characteristics of) the fetal heartbeat in real-time during labour.

There are several reasons for this. One is that statistical techniques use long stretches of data to provide estimates of global measures (entities), like correlation exponents or multifractal spectra. A typical measurement requires over 30,000 samples \((2^{15})\) to provide reliable estimates of scaling for the extraction of exponents and reliable transformation from scaling exponents to the domain of multifractal spectra.

The typical heart rate of a fetus is about 130 beats per minute. The required time stretch for acquiring a sufficiently long data set \((2^{15})\) is thus about 250 minutes. By this time, the baby is often already born. Decisions about an intervention (such
as a Caesarean section) have to be taken on the basis of 10 – 60 minutes long observations of the heartbeat.\(^a\)

In addition to this, correlation exponents and multifractal spectra derived from them are rather sensitive to spikes, missing data, noise bursts and boundary effects.\(^b\) Such erroneous data can cause a dramatic alteration of the results, which is particularly bad due to the lack of indication of where the errors come from\(^c\) - a problem inherent to global statistical techniques. Fetal heartbeats during labour are recorded in difficult circumstances and subject to frequent data fall out and a high level of noise. Missing data in fetal heartbeat records can amount to about 20 – 40\%. This does not include spikes and other noise.

Another serious problem for standard methods of analysis is the presence of the so-called decelerations in fetal heartbeat. These are sudden drops in the heart rate of the fetus, which can be caused by a number of events such as compression of the umbilical cord, increased intracranial pressure of the fetus during contractions or (temporary) hypoxia. The deficiency of oxygen caused by the contractions is compensated for by slowing down the heart rate (the so-called whale effect). Thus the presence of these 20 – 200 beats long drops in the heart rate does not necessarily imply a severe condition of hypoxia. However, they severely distort any standard method of heart rate analysis - the amplitude of the decelerations can be about one degree of magnitude larger than that of the residual fluctuations of the heartbeat.

Lastly, but importantly, global statistical techniques are usually computationally expensive. However, the most unsuitable for real-time applications is the lack of update mechanism on new samples. Taken as they are, such techniques would require recalculation of all the coefficients of the time series on each new sample - an unacceptable approach even in the days of cheap computational power.

Although these constraints practically disqualify standard methods from being used in medical practice, adaptations of standard approaches are possible. We have, therefore, considered the above-mentioned problems and designed a methodology which is capable of providing the required characteristics of fetal heartbeat in real-time.

The steps taken were thus the design of a running, incremental real-time decomposition scheme\(^d\), which is capable of separating meaningful components of the fetal heartbeat. The criterium for the decomposition used here is not arbitrary (or driven by properties of the decomposition as in standard wavelet decomposition, but designed to capture the unique features of the fetal heartbeat. These features are meant to reflect the components of the heartbeat which are analysed by obstetricians in standard clinical practice. The effect of such a decomposition is that the high frequency variability component can be analysed separately from the deceleration component. In this way, the influence of decelerations on the spectrum of exponents can be minimized. Additionally, this way of decomposing the signal gives the possibility of providing the obstetrician with estimates reflecting

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\(^a\)It has to be noted that fetal heartbeat is the only indicator of the state of the fetus. Therefore the characteristics determined from it are crucial in taking the decision to carry out an operative delivery in case of suspected hypoxia.

\(^b\)This can particularly affect higher moment calculations, resulting in serious errors in the MF spectrum.\(^{11,12}\)

\(^c\)despite the fact that techniques like WTMM provide localised information.
traditionally observed entities.

Instead of the standard correlation analysis on long stretches of data, a simplified (effective) Hölder exponent estimate $h$ has been used\textsuperscript{14}. It has been proven to provide useful roughness characteristics in the context of heartbeat or financial analysis\textsuperscript{10,15}. In this work, we use it to analyse the local roughness of the variability component. This is a novel approach in obstetrics, since the standard way of estimating variability level refers to amplitude sensitive standard deviation rather than scale-free characteristics like the local roughness exponent.

By introducing a special cumulative indicator, we have been able to verify that the increase of the exponent $h$ (local roughness exponent) of the variability component of the fetal heartbeat relates to adverse blood gas values of the fetus (hypoxia condition). It has, therefore, a potential for monitoring the fetus and for the prediction of the fetal outcome. This observation confirms the reported observations on adults, where the increase in the (global) correlation exponent corresponding to the loss of anti-correlation has been attributed to a number of malfunctions in the cardiac system.\textsuperscript{d}

The contents of this paper are divided as follows. In section 2, we introduce a running time decomposition of the fetal heartrate (FHR). Most of the technology used here is self-contained, but the reader may want to check Ref.\textsuperscript{13} for technical details of real-time, Haar-type, wavelet decomposition. In section 3, basic operators are introduced, which act on the decomposition coefficients. The operators reveal and enhance collective behaviour in the fluctuations of the coefficients. Finally, in section 4, a cumulative operator is defined, which is next applied to the effective Hölder exponent of the variability component of the fetal heartbeat. Section 5 closes the paper with conclusions and future plans.

2 Separating Meaningful Components of Fetal Heartbeat

Fetal heartbeat is monitored during labour, as it is the only indicator of the well-being of the fetus. It is, therefore, used to alert the attending staff of possible hypoxia requiring direct intervention - a Caesarean section or pH and Base Excess estimation from a fetal scalp blood sample taken during labour. The heartbeat is usually analysed from the point of view of its three main characteristics:

- the level of the baseline - the low frequency outline of the heartbeat without spikes, high frequency variability and without decelerations and accelerations
- the presence and frequency of decelerations and accelerations
- the level of variability - the high frequency ‘noise’ of the heartbeat.

Using these characteristics, obstetricians can predict a good outcome very well. However, in cases of ‘bad’ fetal heartrate patterns, half the time the fetal outcome is good and operative intervention may have been carried out unnecessarily. It turns out that we can conveniently approximate these characteristics in an appropriate decomposition.

\textsuperscript{d}It should be noted here that most malfunctions correspond with an insufficient supply of oxygen.
Unlike in the more traditional multiresolutions schemes with dyadic resolution separation,\textsuperscript{16,17} we apply only two resolutions (scales) of approximation at the large separation of one decade (i.e. resolutions $a_1 = 200$ and $a_2 = 20$). The total decomposition plane is, therefore, partitioned into three sections.

The resolution $a_1 = 200$ beats is intended to approach the so-called baseline of the heartbeat - the low frequency ‘backbone’ of the fluctuations. This is where the adaptive filter proves necessary. The resolution of $a_1 = 200$ beats is suitable for approximating the baseline, but not in the presence of decelerations (or accelerations, sudden jumps of the heartbeat). The moving average filter performing approximation of the heartbeat at $a_1 = 200$ beats is thus equipped with a threshold mechanism which does not accept jumps or drops larger than one standard deviation from the (historic $N$ samples) mean value of the signal.

$$MAA_{a_1}(f_i) = \frac{1}{a_1} \sum_{i=-a_1/2}^{a_1/2} (f_i) \delta(i)$$

(1)

where

$$\delta(i) = \begin{cases} 1 & \text{for } (f_i - \text{mean}(f_i, i = i - N, \ldots, i)) < \text{stdv}(f_i, i = i - N, \ldots, i) \\ 0 & \text{otherwise} \end{cases}$$

The second approximation level, centred at $a_2 = 20$ beats, uses a simple block smoothing function. It is intended to separate the highest frequencies, which we attribute to the so-called variability component.

$$MAA_{a_2}(f_i) = \frac{1}{a_2} \sum_{i=-a_2/2}^{a_2/2} (f_i)$$

(2)

Just like in the standard wavelet decomposition, the multiresolution bands of decomposition are obtained from subtracting the multiresolution approximations at subsequent resolutions. As we have used only two levels of approximation, three bands of resolution are obtained:

1. The first band of our decomposition is the entire low frequency component separated by the adaptive MA filter at the $a_1 = 200$ resolution level. It captures features of resolution less than $a_1 = 200$ and amplitude less than one standard deviation from the (historic) mean value of the signal. The filter used to define the baseline approximation level, Eqn. 1, is a low-pass filter, therefore the entire resolution band of low frequencies - the baseline, simply becomes:

$$B_i = MAA_{200}(f_i)$$

(3)

2. The second band is obtained from subtracting the baseline approximation level from the variability approximation level. This contains the middle range of frequencies, capturing combined accelerations and decelerations.

$$AD_i = MAA_{20}(f_i) - MAA_{200}(f_i)$$

(4)
3. Finally, the variability range of resolutions is obtained by subtracting the original time series from the approximation at the resolution level $a_2 = 20$. This variability is thus the signal, less baseline fluctuations, and less decelerations and accelerations component.

\[ V_i = f_i - MA_{20}(f_i) \]  

The result of applying such a procedure is a complete orthogonal decomposition into three components of the time series: the baseline, the combined line of accelerations and decelerations, plus the residual variability component. Of course, the original time series can be restored by simply summing up all three components, see figure 1.

3 Constructing Meaningful Real-time Indicators

The components of the fetal heartbeat thus obtained carry information, which is (visually) analysed by the obstetrician. In order to mimic a visual evaluation of the trends and collective behaviour of the fluctuations and features in the decomposition, we apply running $MA_{1000}$ filters.

The local average effective acceleration/deceleration obtained in this way, see figure 2, indicates the effective level of deceleration which can be monitored and evaluated on-line. We will, however, not further pursue here the discussion of the
relevance of this characteristic, leaving it to a separate communication. Rather, we intend to focus exclusively on the diagnostic capabilities of variability, or rather its roughness exponent.

![Graphs showing real-time indicators](image)

Figure 2. Real-time indicators, from top to bottom: local average dec-/acceleration $MA_{1000}(DA_i)$, local average variability $MAV_{1000}(V_i)$, local ‘Hölder’ exponent $h_{eff}(V_i)$. Both the $MAV_{1000}(V_i)$ and $h_{eff}(V_i)$ have been rescaled by a factor 10.

One could be tempted to apply a similar moving average filter to the variability component. Of course, this time it would have to be applied to the square amplitude, as the variability is usually perceived as the (mean) amplitude of high frequency deviations:

$$MAV_a(V_i) = \sqrt{\frac{1}{a} \sum_{i=-a/2}^{i=a/2} V_i^2}.$$  \hspace{1cm} (6)

Such a fixed resolution indicator (for example at $a = 1000$) would perhaps be considered an adequate measure of variability. However, it is known that our visual system picks scale-free characteristics when evaluating measures of roughness or variability. Therefore, even from the point of view of a visual evaluation, a fixed scale measure is not necessarily the best indicator.

It has been demonstrated [1-10] that scale-free measures of variability may be
more suitable for diagnostic purposes. There are a number of methods providing scale-free characteristics, most of them are, however, unsuitable for real-time local analysis of non-stationary time series. Therefore, for this study we use an adaptation of the effective Hölder exponent measure of local roughness. The original concept has already been used in the study of adult heartbeat, using the WTMM representation.

The local effective roughness of the variability component \(V_i\) is defined as the logarithmic increase of the (standard deviation) of variability across scales/resolutions:

\[
h_{eff}(V_i) = \frac{\log(\text{MAV}_{a_1}(V_i)) - \log(\text{MAV}_{a_2}(V_i))}{\log(a_1) - \log(a_2)}.
\]  

(7)

Two relatively rough resolutions \((a_1 = 1000 \text{ and } a_2 = 10000)\) have been used for the evaluation of the local \(h\). Also, we have used a simplification of the local effective exponent concept from Ref., in that a simple block function (moving average filter) is used instead of the wavelet. Using the moving average filters makes possible incorporating the local \(h\) evaluation in the real-time incremental decomposition framework, as described above. Of course the local \(h\) analysis with smoothing block kernels is only possible due to the fact that the variability component \(V\) (as defined in Eqn. 5) is effectively free of any trends.

4 Cumulative Hölder Exponent Based Real-time Indicator

There is no reason why the local Hölder exponent of the variability \(h(V_i)\) should be stationary. It reflects dynamic changes in the condition of the fetus and the degree of stress to which it is subjected. Despite the fact that stress has a rapid effect on the heartbeat, the effects on the state of the fetus can be long term. This is why short dynamic changes in the heartbeat characteristic may not be relevant and not representative to the state of the fetus.

Rather than using a long observation window which would capture trend behaviour, we use a cumulative indicator, which still has the resolution of the mean local \(h\) used in the previous section. The cumulative \(h\) is defined from the beginning of the observation and with respect to some normal reference level \(h_{ref}\):

\[
h_{cum}(V_i) = - \sum_{i=1}^{i}(h_{eff}(V_i) - h_{ref}).
\]  

(8)

The minus sign is introduced to give the \(h_{cum}\) indicator increasing direction when the level of local correlations is lower than \(h_{ref}\). This corresponds with a healthy condition. The case of higher correlations is associated with problems and, therefore, the accumulation of positive difference \((h_{eff}(V_i) - h_{ref})\) will lead to decreasing cumulative \(h\).

*Of course, this does not exclude using amplitude based measures of variability in parallel.

†Note that the actual (temporal) resolution of the local \(h\) so obtained is defined by the higher (finer) resolution level - the course reference resolution can be accumulated from past historic samples.
Figure 3. Six different time series analysed using the cumulative Hölder exponent based real-time indicator. The time series correspond with three good outcomes (healthy) and three bad outcomes (hypoxia). The good outcomes can be identified by the indicator oscillating near zero or steadily increasing. In the case of hypoxia, the indicator plunges (down towards negative values). Problems can occur at any moment during labour, even after a stable condition, as is visible in the last of the six plots (lowest row, right). The first part of the plot is flat since this period is required for initialisation - acquiring a reference for the upper value for the Hölder exponent evaluation. Both the cumulative Hölder exponent $h_{\text{cum}}[V_i]$ (red line) and the deviation of the Hölder from the reference value $h_{\text{ref}} = 0.05$ (blue filled curve) are plotted. The $h_{\text{cum}}[V_i]$ has been rescaled by a factor 0.01.
We have tested several examples of fetal heartbeats and found a good correlation with the fetal outcome, as determined by the blood tests. In figure 3, we plot six cases where three represent good outcomes and three bad outcomes. The cumulative indicator steadily increasing or remaining within some margin of fluctuations indicates no problems and a good prediction. When the indicator plunges down, it calls for intervention. This can, of course, happen at any moment during labour. The nature of this process is dramatically non-stationary, and a period of positive evaluation can be interrupted at any stage (for example by the occlusion of the umbilical cord due to movement). One of our examples (figure 3 lower right), shows the cumulative indicator plunging after a prolonged homeostasis.

5 Concluding Remarks

Fetal heartbeat during labour is a highly non-stationary process which needs to be monitored in real-time.

We have presented a methodology of decomposition of fetal heartbeat into meaningful components suitable for real-time monitoring of the fetus. We have also introduced a real-time cumulative indicator, based on the effective Hölder exponent of the variability component of fetal heartbeat. The indicator has been demonstrated to provide insight into the highly non-stationary nature of the variability properties of the fetal heartbeat. It has also shown correlation with the blood samples, motivating its use as a monitoring and a predictive tool.

The exact parameters of the decomposition are subject to tuning. Also, other local measures of roughness of the variability component may provide better and more detailed insight. Combining the observations derived from (all) the components of the heartbeat (and possibly external knowledge) into a predictive tool may result in a substantially better predictive power.

References

10. Z. R. Struzik, Revealing Local Variability Properties of Human Heartbeat Intervals with the Local Effective Hölder Exponent. Fractals 9, No 1, (2001).