

LINKING SYSTEMS, MATROIDS AND BIPARTITE GRAPHS

by

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In this talk the notion of a "linking system" is defined, a notion closely related to matroid theory. With this concept theorems on bipartite graphs and directed graphs, in relation to matroids, can be generalized. Linking systems can be interpreted as a special case of the "tabloids" of S. Hocquenghem [3].

DEFINITION. A *linking system* is a triple  $(X, Y, \Lambda)$  where  $X$  and  $Y$  are finite sets and  $\emptyset \neq \Lambda \subset \mathcal{P}(X) \times \mathcal{P}(Y)$ , such that:

- (i) if  $(X', Y') \in \Lambda$ , then  $|X'| = |Y'|$ ;
- (ii) if  $(X', Y') \in \Lambda$  and  $X'' \subset X'$ , then  $(X'', Y'') \in \Lambda$  for some  $Y'' \subset Y'$ ;
- (iii) if  $(X', Y') \in \Lambda$  and  $Y'' \subset Y'$ , then  $(X'', Y'') \in \Lambda$  for some  $X'' \subset X'$ ;
- (iv) if  $(X_1, Y_1) \in \Lambda$  and  $(X_2, Y_2) \in \Lambda$ , then there is an  $(X', Y') \in \Lambda$  such that  $X_1 \subset X' \subset X_1 \cup X_2$  and  $Y_2 \subset Y' \subset Y_1 \cup Y_2$ .

Examples of linking systems may be obtained as follows.

- (a) Let  $(X, Y, E)$  be a bipartite graph (i.e.  $E \subset X \times Y$ ) and  $\Lambda = \Delta_E = \{(X', Y') \mid \text{there exists a matching in } E \text{ between } X' \subset X \text{ and } Y' \subset Y\}$ . Then  $(X, Y, \Lambda)$  is a linking system. Axiom (iv) was proved by H. Perfect and J.S. Pym [6]. A linking system constructed in this way is called a *deltoid linking system*.
- (b) Let  $(Z, \Gamma)$  be a directed graph and  $X, Y \subset Z$ . Let furthermore:  $\Lambda = \{(X', Y') \mid \text{there are pairwise vertex-disjoint paths in } \Gamma \text{ between } X' \subset X \text{ and } Y' \subset Y, \text{ such that in each vertex of } X' \text{ starts a path and in each vertex of } Y' \text{ ends a path}\}$ . Then  $(X, Y, \Lambda)$  is a linking system. Axiom (iv) was proved by J.S. Pym [7]. Linking systems constructed in this way are called *gammoid linking systems*.
- (c) Let  $(X, Y, \phi)$  be a matrix over a field  $\mathbb{F}$  (i.e.  $\phi : X \times Y \rightarrow \mathbb{F}$ ), and let  $\Lambda = \{(X', Y') \mid \text{the submatrix generated by } X' \subset X \text{ and } Y' \subset Y \text{ is}$

regular}. Then  $(X, Y, \Lambda)$  is a linking system. Such a linking system is called *representable over  $\mathbb{F}$* .

Of course, example (a) is a special case of example (b): *each deltoid linking system is a gammoid linking system.*

There exist close relations between linking systems and matroids. In fact each linking system may be understood as a matroid with a fixed base (a *based matroid*).

THEOREM 1. *Let  $X$  and  $Y$  be disjoint finite sets. Then there exists a one-to-one relation between:*

- (1) *linking systems  $(X, Y, \Lambda)$ , and*
- (2) *matroids  $(X \cup Y, \mathcal{B})$  with  $X \in \mathcal{B}$  ( $\mathcal{B}$  is the collection of bases),*  
*given by:*

$$(X', Y') \in \Lambda \quad \text{iff} \quad (X \setminus X') \cup Y' \in \mathcal{B}.$$

The correspondence is such that the linking system is a deltoid linking system iff the matroid is a deltoid; likewise, this correspondence exists between gammoid linking systems and gammoids and between linking systems representable over a field  $\mathbb{F}$  and matroids representable over  $\mathbb{F}$ .

A second relation between linking systems and matroid theory gives the following theorem.

THEOREM 2. *Let  $(X, I)$  be a matroid ( $I$  is the collection of independent subsets of  $X$ ) and let  $(X, Y, \Lambda)$  be a linking system. Let furthermore:*

$$I * \Lambda = \{Y' \subset Y \mid \text{there exists an } X' \in I \text{ such that } (X', Y') \in \Lambda\}.$$

*Then  $(Y, I * \Lambda)$  is a matroid.*

The proof of this theorem makes use of theorem 1 and the fact that the union of two matroids is again a matroid.

As corollaries we have:

- (1) (J. Edmonds & D.R. Fulkerson [2]) if  $(X, Y, E)$  is a bipartite graph and  $J = \{Y' \subset Y \mid Y' \text{ is matched with some subset of } X\}$ , then  $(Y, J)$  is a matroid;
- (2) (H. Perfect [4]) if  $(Z, \Gamma)$  is a digraph,  $X, Y \subset Z$  and  $J = \{Y' \subset Y \mid \text{there are } |Y'| \text{ pairwise vertex-disjoint paths start-}$

- ing in  $X$  and ending in  $Y'$ }, then  $(Y, J)$  is a matroid;
- (3) (H. Perfect [5]) if  $(X, I)$  is a matroid,  $(X, Y, E)$  a bipartite graph and  $J = \{Y' \subset Y \mid Y' \text{ is matched with some } X' \in I\}$ , then  $(Y, J)$  is a matroid;
- (4) (R.A. Brualdi [1]) if  $(X, I)$  is a matroid,  $(Z, \Gamma)$  a digraph,  $X, Y \subset Z$  and  $J = \{Y' \subset Y \mid \text{there are } |Y'| \text{ pairwise vertex-disjoint paths starting in } X' \text{ and ending in } Y'\}$ , then  $(Y, J)$  is a matroid.

Of course, corollaries (1), (2) and (3) are also consequences of corollary (4).

Theorem 2 gave a kind of product of a matroid and a linking system. The next theorem gives in an analogue way a product of two linking systems.

**THEOREM 3.** *Let  $(X, Y, \Lambda_1)$  and  $(Y, Z, \Lambda_2)$  be linking systems. Let furthermore  $\Lambda_1 * \Lambda_2 = \{(X', Z') \mid \text{there is a } Y' \subset Y \text{ such that } (X', Y') \in \Lambda_1 \text{ and } (Y', Z') \in \Lambda_2\}$ . Then  $(X, Z, \Lambda_1 * \Lambda_2)$  is again a linking system.*

Again, the proof of this theorem uses theorem 1 and the union-theorem of matroids.

A linking system is partially determined by its "underlying" bipartite graph, as defined in the following theorem.

**THEOREM 4.** *Let  $(X, Y, \Lambda)$  be a linking system and let  $(X, Y, E)$  be the bipartite graph with:  $(x, y) \in E$  iff  $(\{x\}, \{y\}) \in \Lambda$ . Then:*

- (1) *if there is exactly one matching in  $E$  between  $X' \subset X$  and  $Y' \subset Y$ , then  $(X', Y') \in \Lambda$ ;*
- (2) *if  $(X', Y') \in \Lambda$ , then there exists at least one matching in  $E$  between  $X'$  and  $Y'$ .*

(2) means:  $\Lambda \subset \Delta_E$  (as defined in example (a)). Thus the maximum of all linking systems with the same underlying bipartite graph  $(X, Y, E)$  is the deltoid linking system  $(X, Y, \Delta_E)$ , since this last linking system has also  $(X, Y, E)$  as underlying bipartite graph.

Proofs and more details can be found in [8] and [9].

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